



# Separating Signal from Noise in Radar-Rainfall Fields

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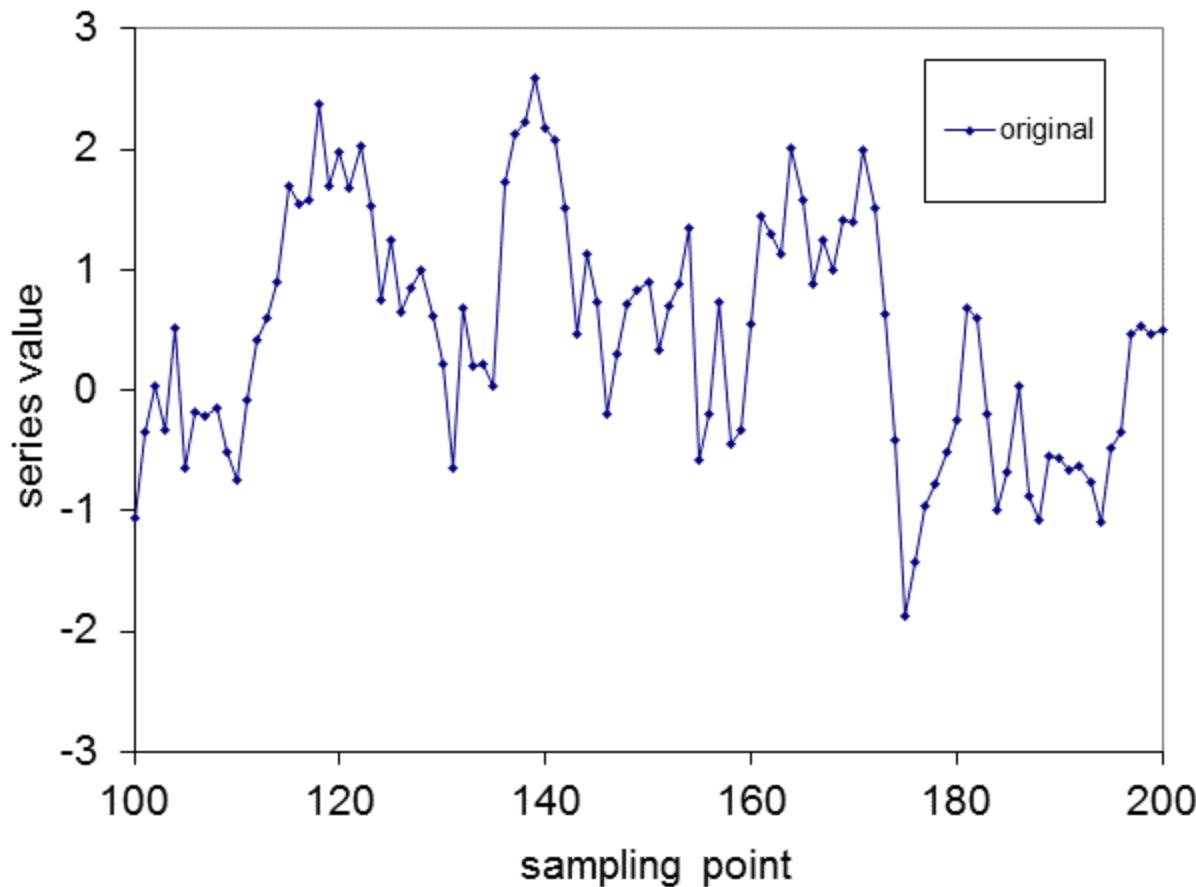
# The problem statement

- How do we generate meaningful stochastic ensembles of radar estimates of rainfall?
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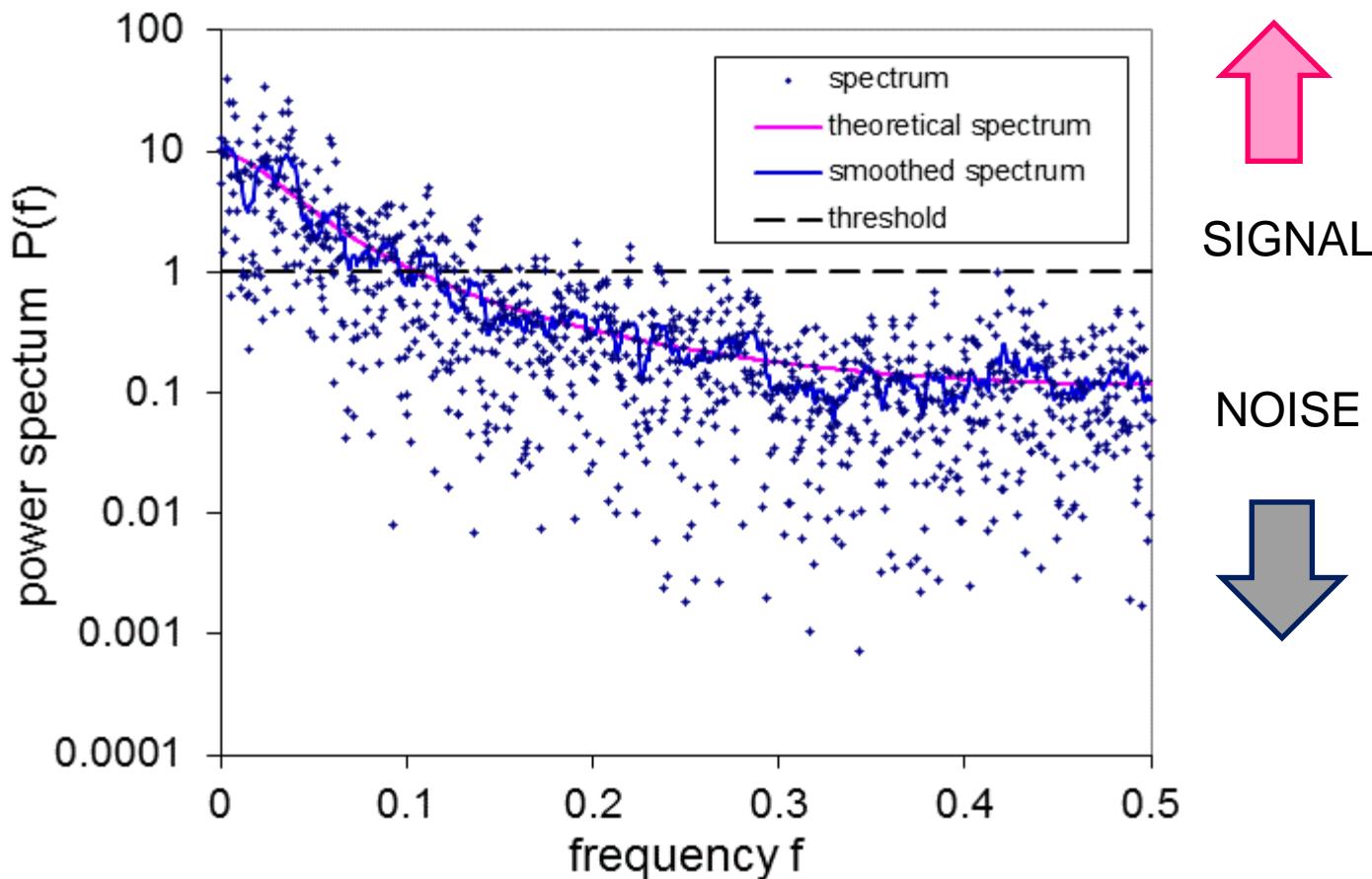
- How do we generate meaningful stochastic ensembles of radar estimates of rainfall?
- How do we avoid variance inflation?
  - [Bias is a separate issue]
  - We need to define signal & noise separation in context

# A simple 1-D AR(1) example: $\rho = 0.8$

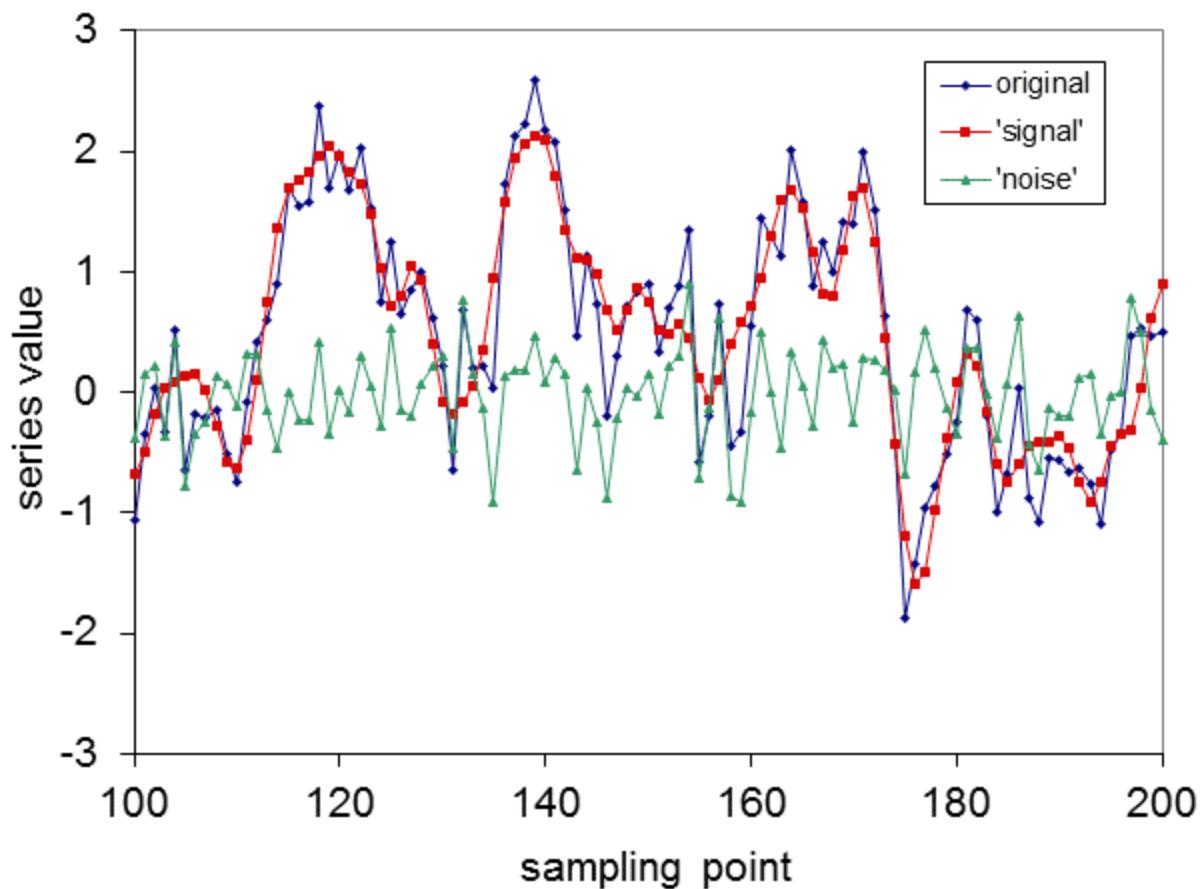


A 100-unit clip from a 1024 sequence:  $X(t) = \rho X(t-1) + a(t)$

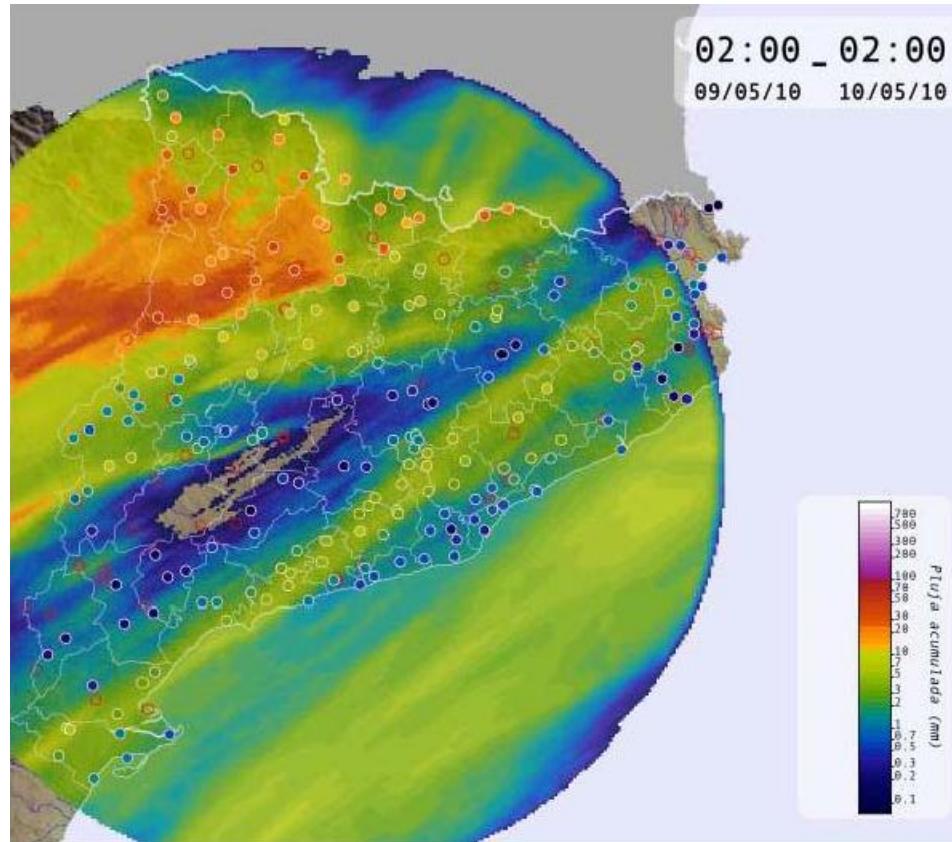
# Its Spectrum & partitioning



# The result after reverse transformation



# Consider a well-conditioned radar rainfall estimate – where is the error?



# The suggestion:

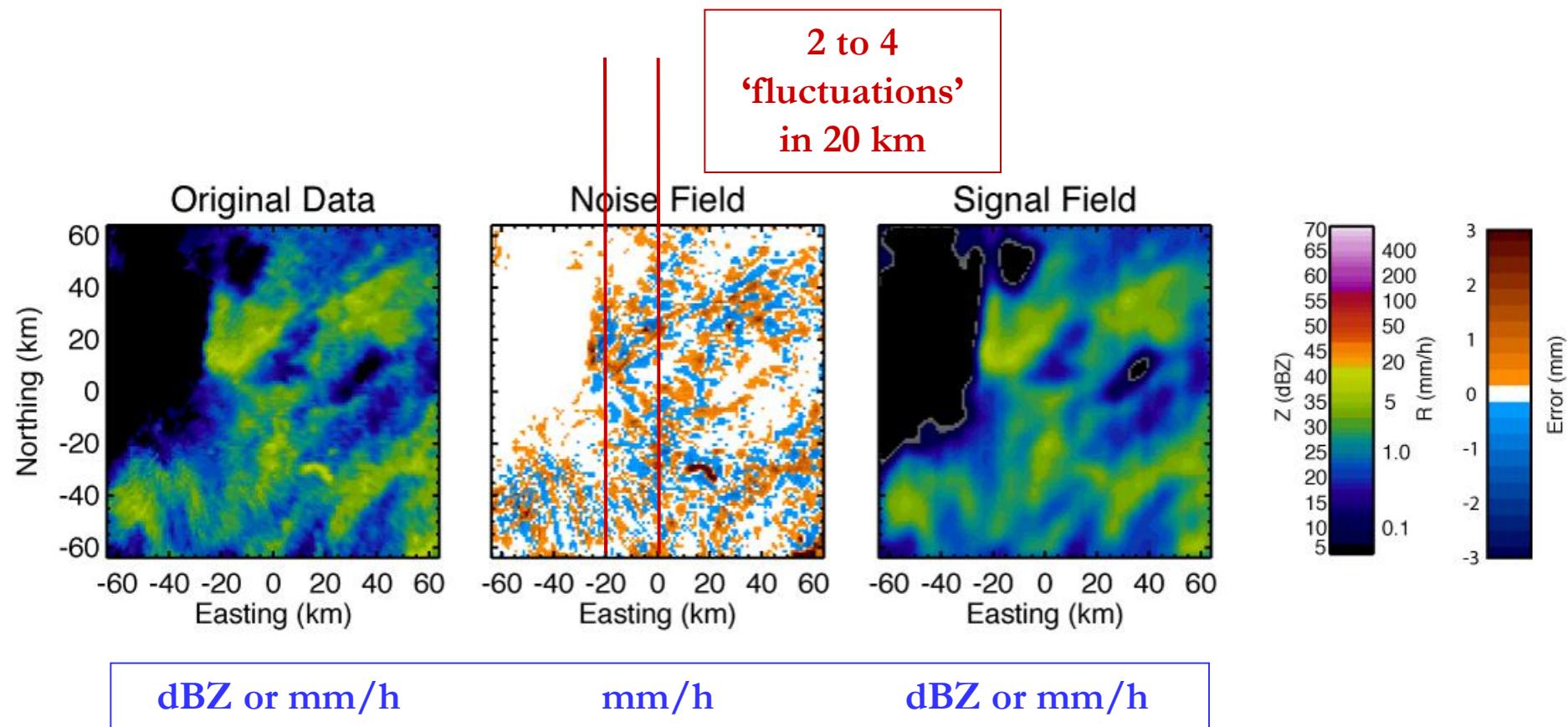
For each of a sequence of radar rainfall images:

- Use a simple spectral method to **separate** each image into signal and noise
- Simulate an alternative noise field, with the same spectrum as the original noise, and combine it with the signal field
  - hence no variance inflation -
- Procedure generates an ensemble member, *with the same stats as original*, to perform sensitivity studies.

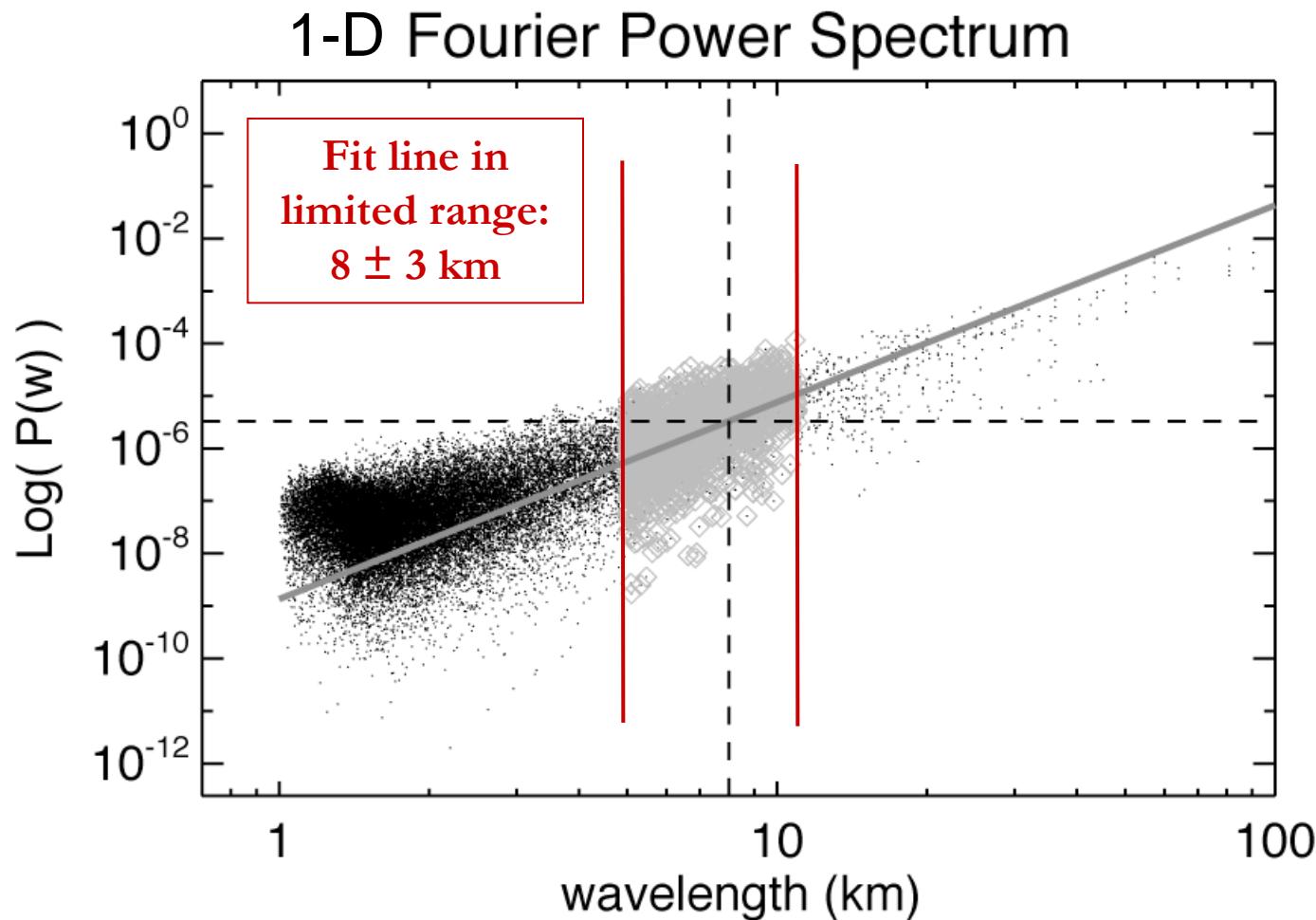
# Analysis (briefly):

1. Trim radar field  $\text{Rad}(x)$  at  $< 18\text{dBZ}$ .  
 $R(x) = \ln[\text{Rad}(x)]$  (or 0). Its mean is  $m$ .  
Put  $Z(x) = R(x) - m$ .
2.  $\text{FFT}[Z(x)] \rightarrow Z(s)$  to get its spectrum and find a suitable *horizontal* noise threshold
3. Split  $Z(s)$  into 2 components, signal  $S(s)$  & noise  $\delta(s)$ :  
 $Z(s) = S(s) + \delta(s)$
4. Simulate noise  $\delta^*(s)$  with the same spectrum as  $\delta(s)$
5. Add  $\delta^*(s)$  to  $S(s)$  to create the alternative to  $Z(s)$  as:  
 $E(s) = S(s) + \delta^*(s)$
6.  $\text{FFT}^{-1}[E(s)]$  to obtain ensemble member:  $m + \exp\{E(x)\}$

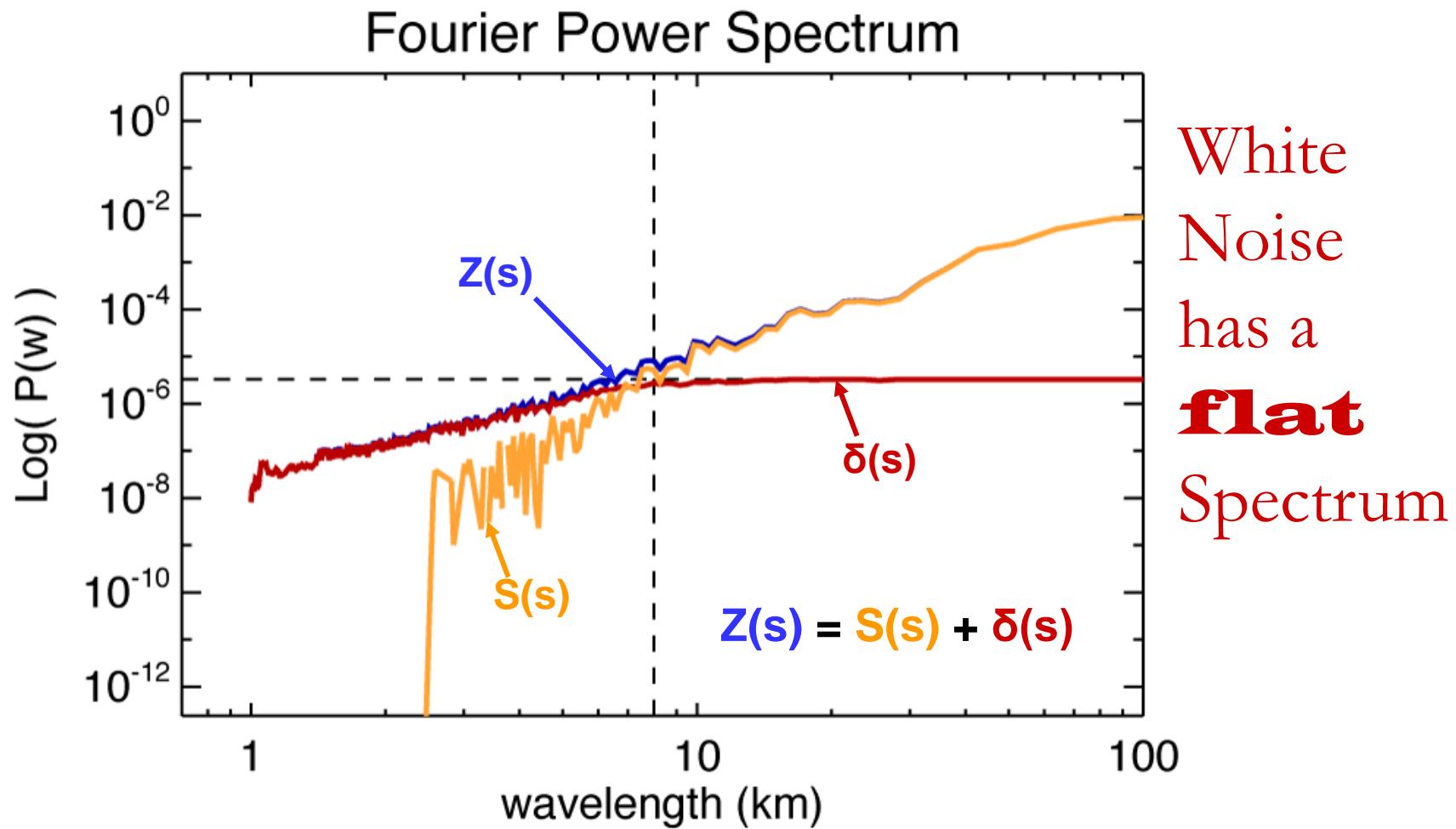
# Decomposition



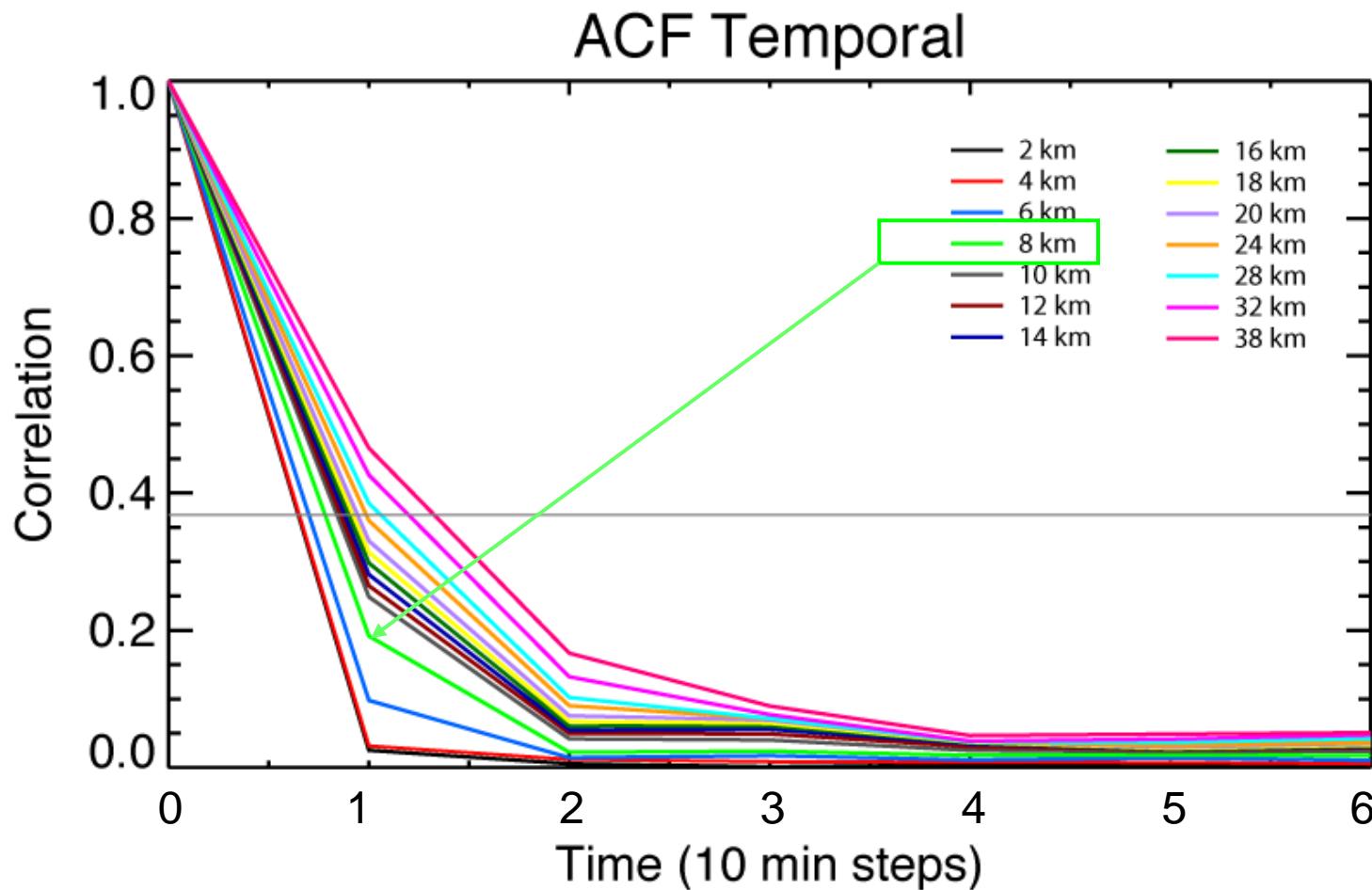
# Threshold | wavelength (for low scc)



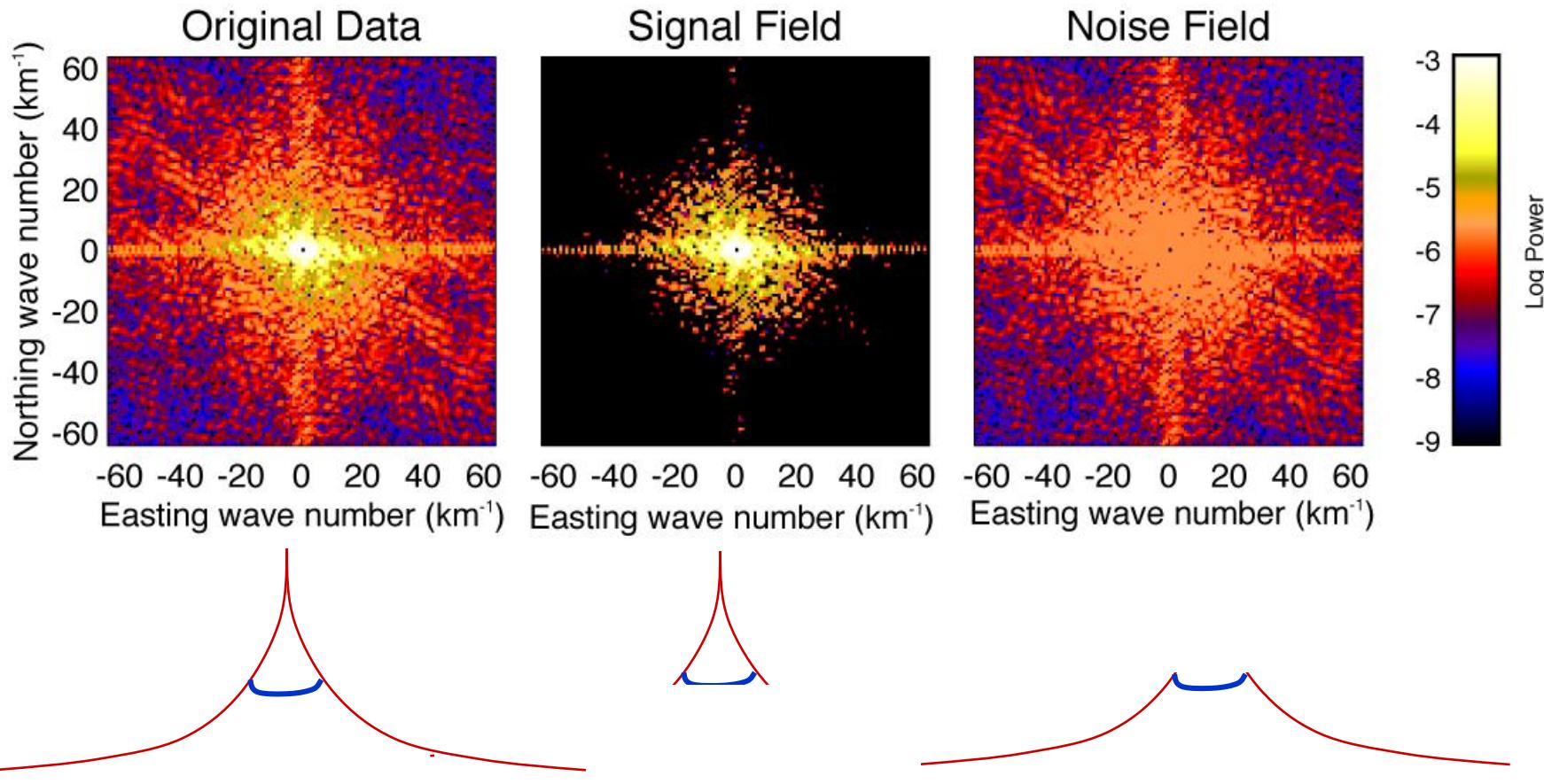
# Define threshold in 1D Spectrum



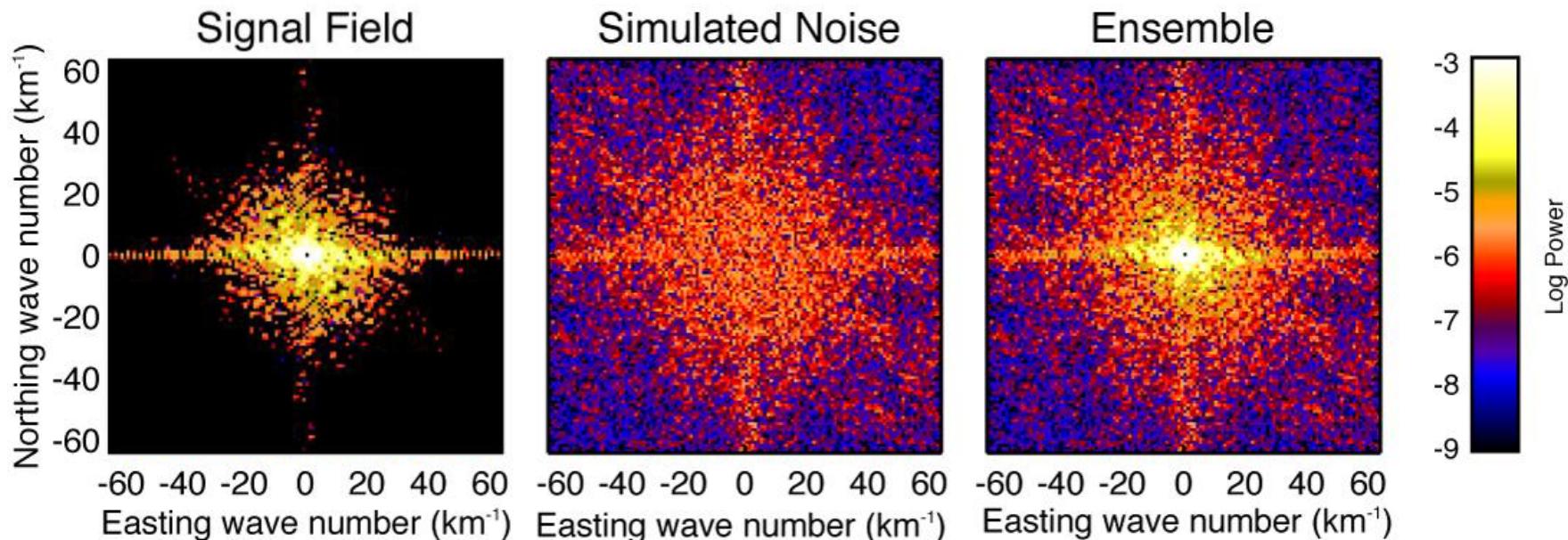
# Choose wavelength by SCC of noise



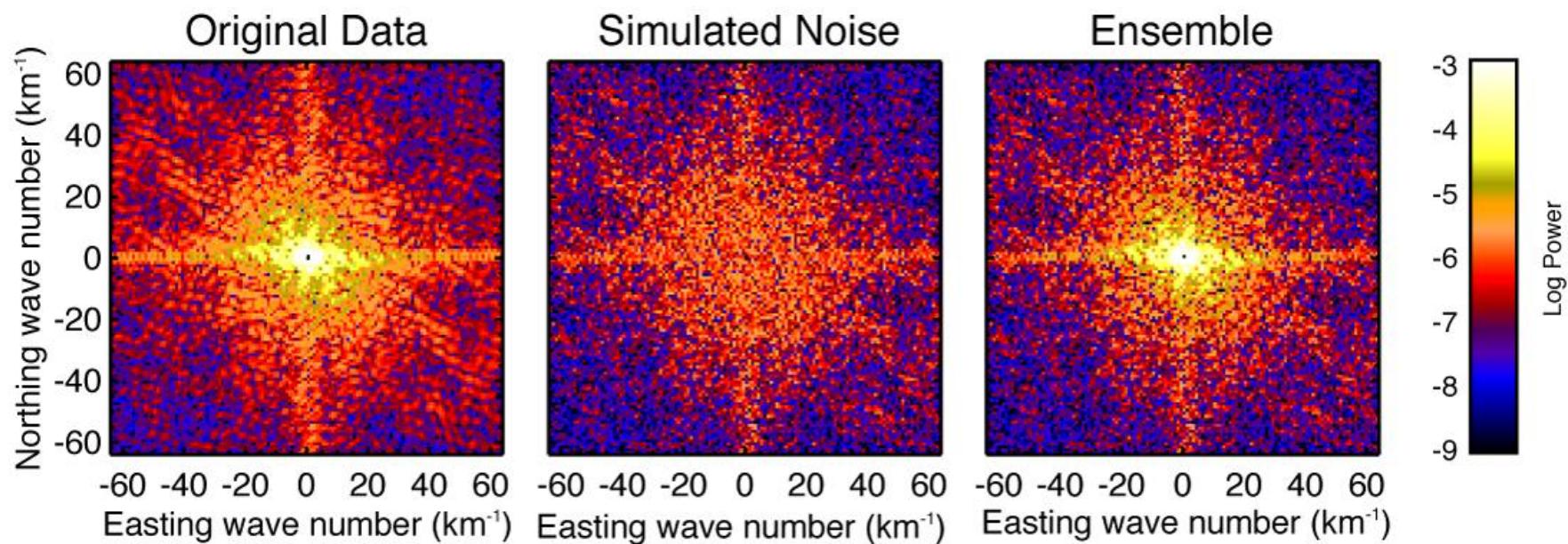
# 2D spectra of Data, Signal & Noise in frequency domain



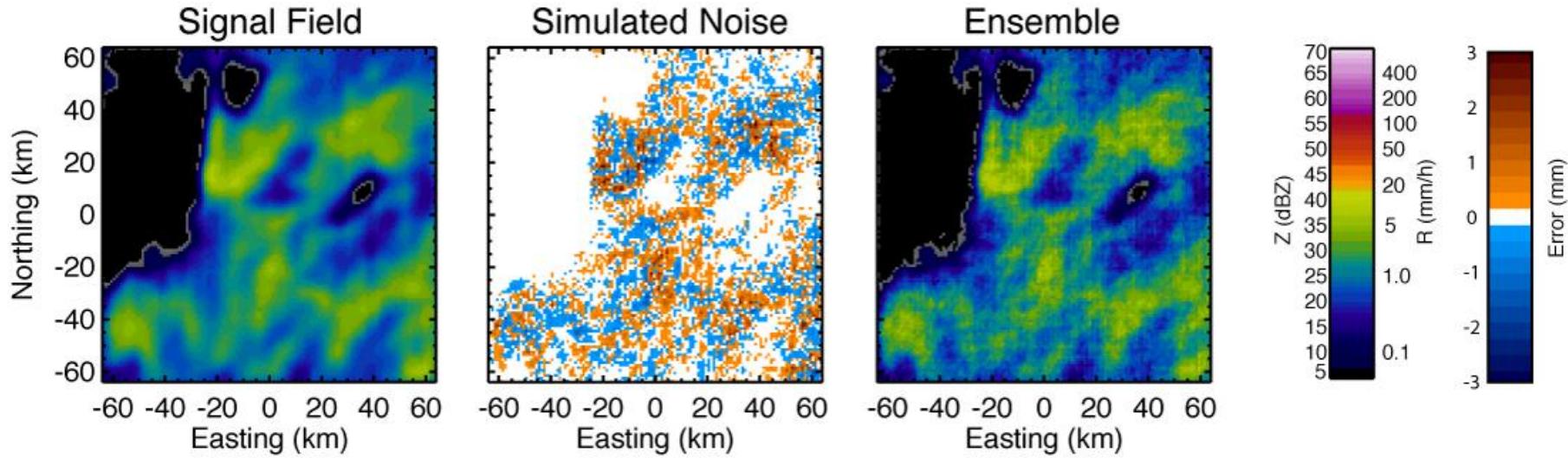
# Spectra: Signal + Simulated Noise = Ensemble



# Spectra: comparisons

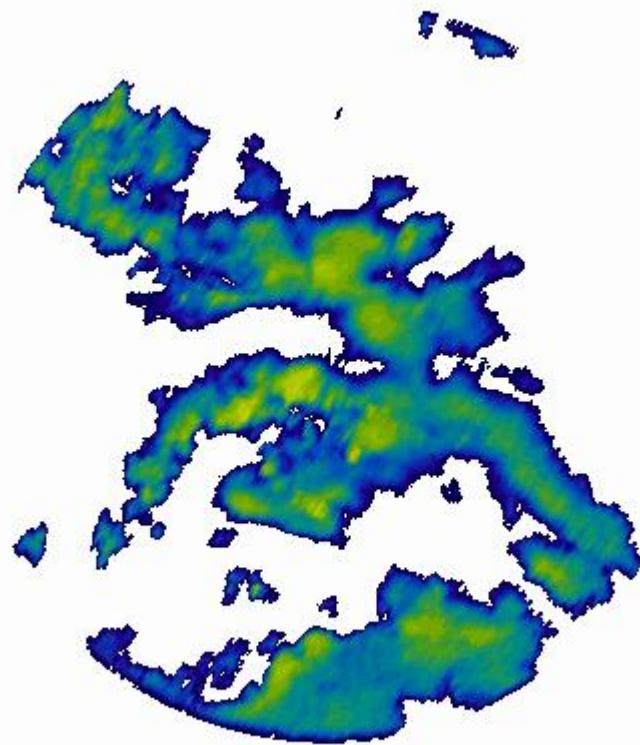


# & after Inverse FFT we get ...

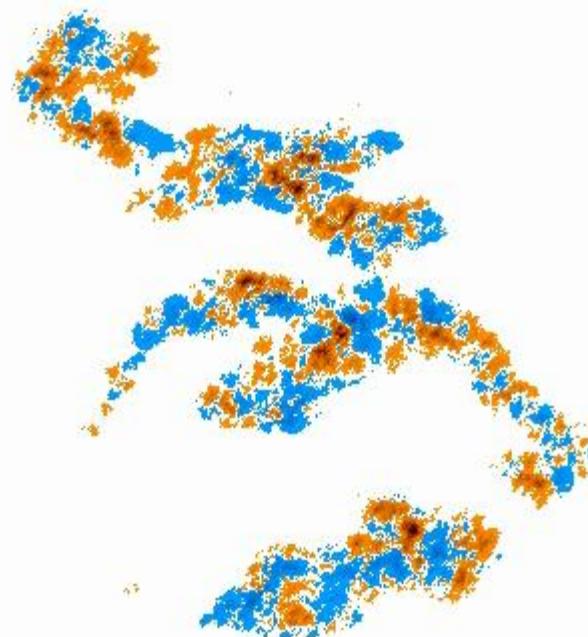
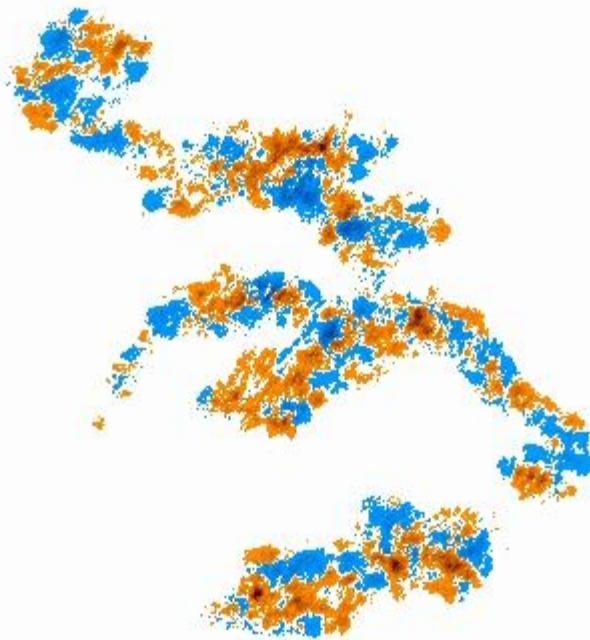


Non-raining areas not affected  
Noise is a bit gridded due to FFT on square  
Solved by sampling on the disc

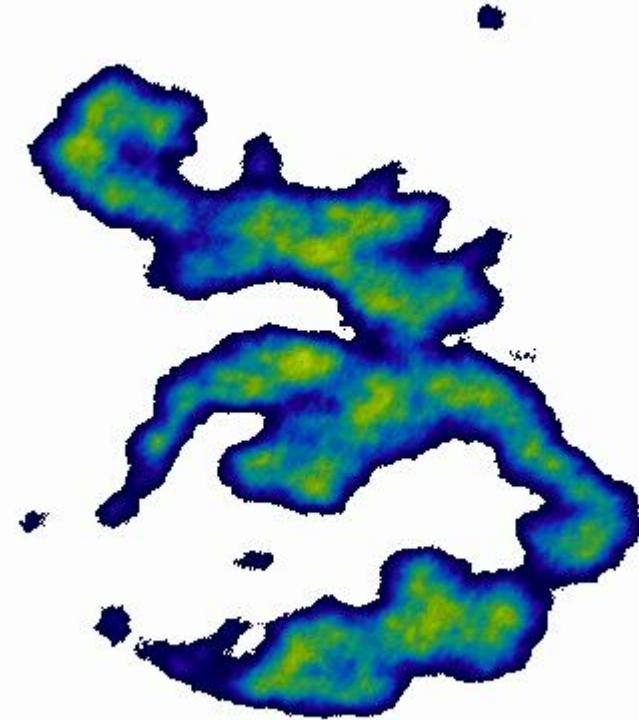
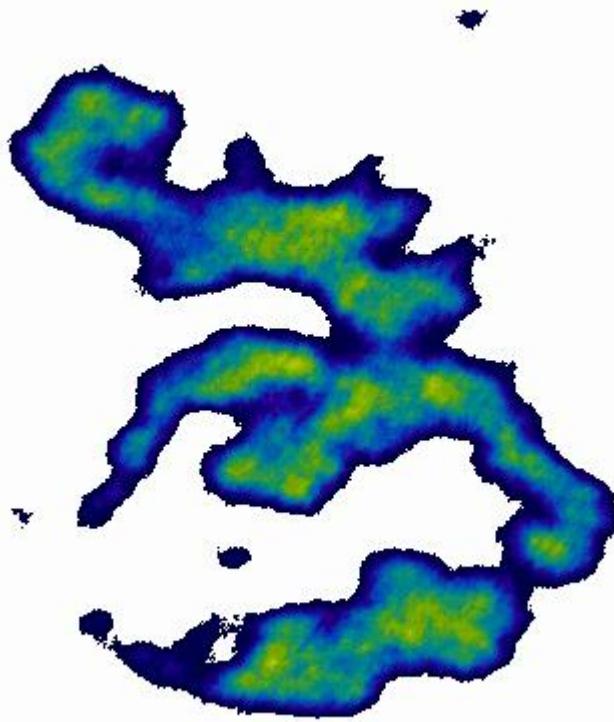
# Some movies: The original sequence



# Two generated noise fields (mm/h)



# 2 Ensembles



*fin*