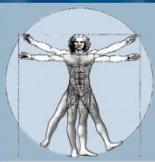


Recent advances in optimizing field campaigns

Jun.-Prof. Dr.-Ing. Wolfgang Nowak, M.Sc.
Stochastic Modeling of Hydrosystems Group

Chair for Hydromechanics and Modelling of Hydrosystems
Institute for Modelling Hydraulic and Environmental Systems

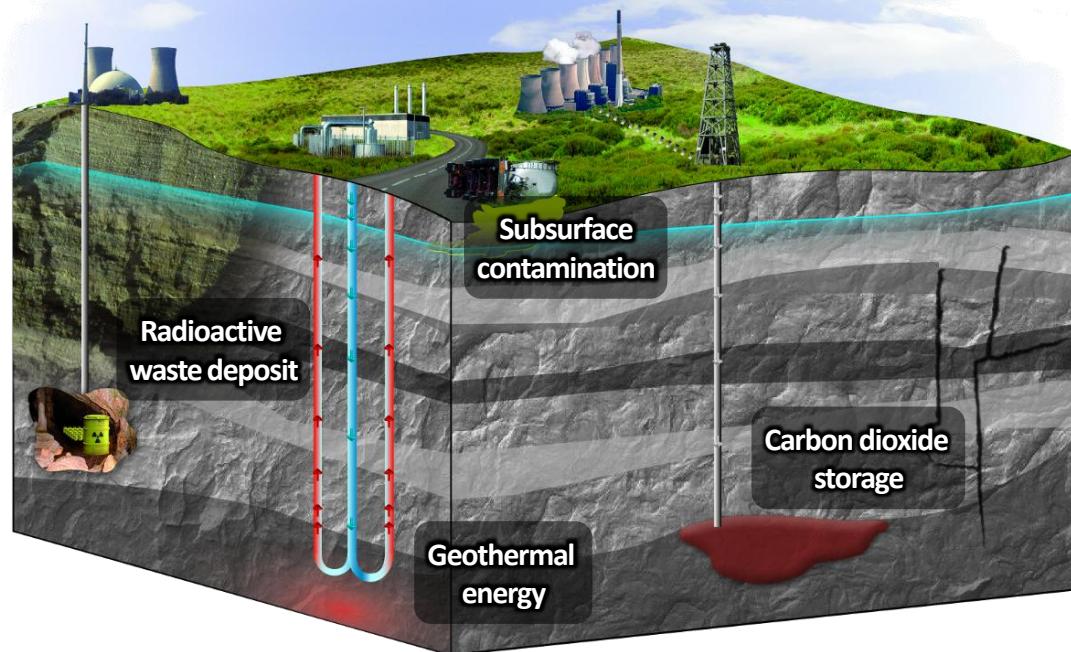
University of Stuttgart
Germany

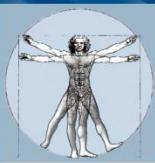


Prediction Uncertainty

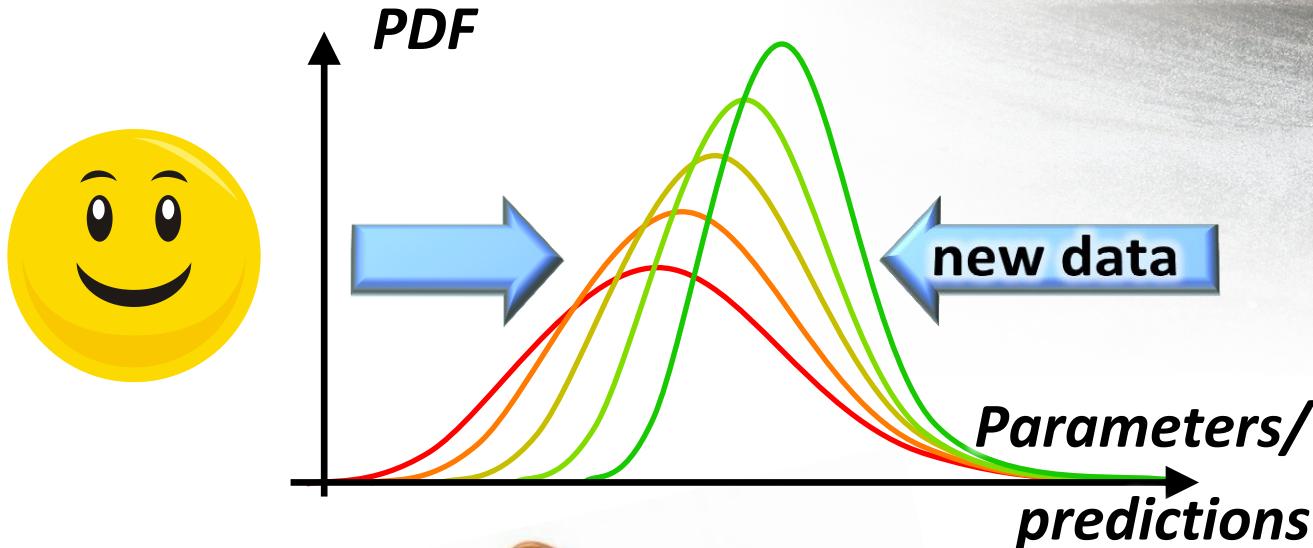
...an omnipresent challenge:

- Open system
(boundaries, forcing)?
- Model concepts
- Scales of
heterogeneity
- Scarce data
- Measurement
errors

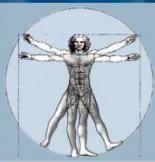




Field Investigation?



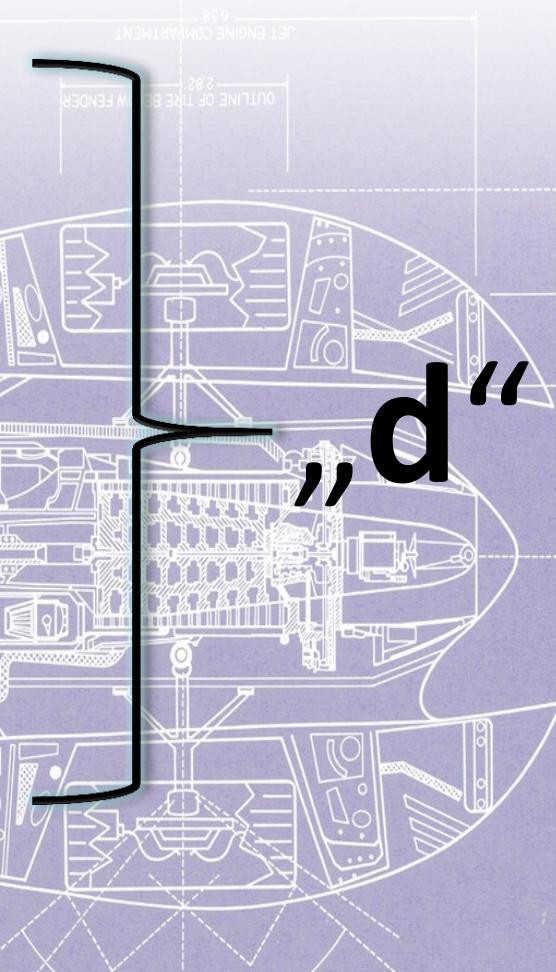
Optimal
design

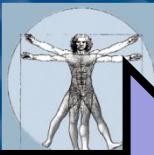


Experimental design

...is blueprint of experiment/campaign:

- Apparatus/system
- Conditions
 - System forcing (active/passive)
 - Boundary/initial conditions
- Observation type (what data)
- Sampling pattern (where)
- Sampling schedule (when)





Optimal design: challenges

Prior envelope?

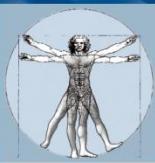
1.) Stochastic/geostatistical model:
realistic envelope to uncertainty $p(\theta)$

2.) Define utility of desired data:
task-driven information needs $U=f(d)$

3.) For a given design:
Quantify utility of future data $U(d)$

4.) Optimize design: $d_{\text{opt}} = \arg \max U(d)$
maximize utility (e.g., cost-benefit)





Prior envelope?

Example: geostatistical model uncertain!

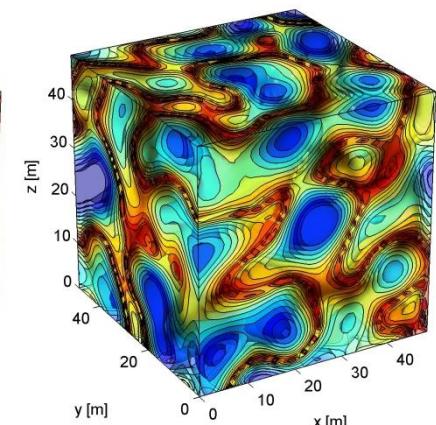
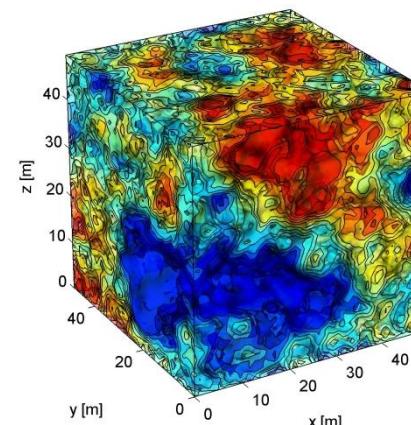
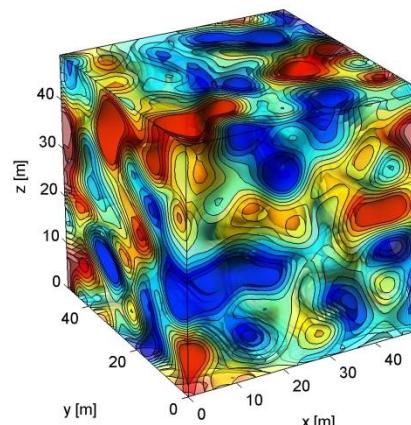
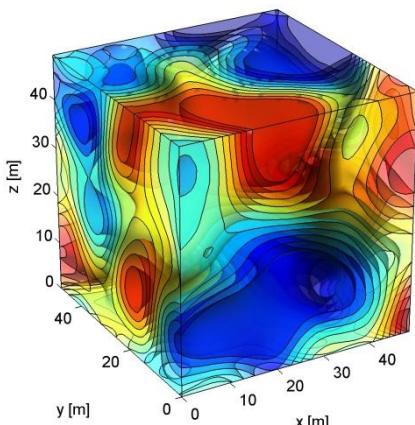
- Bayesian geostatistics

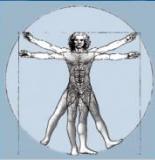
(Kitanidis, WRR 1986)

What could be uncertain?

- Variance, length scales, anisotropy, smoothness
(Matérn covariance)
(BMA)
- Trend/zonation models

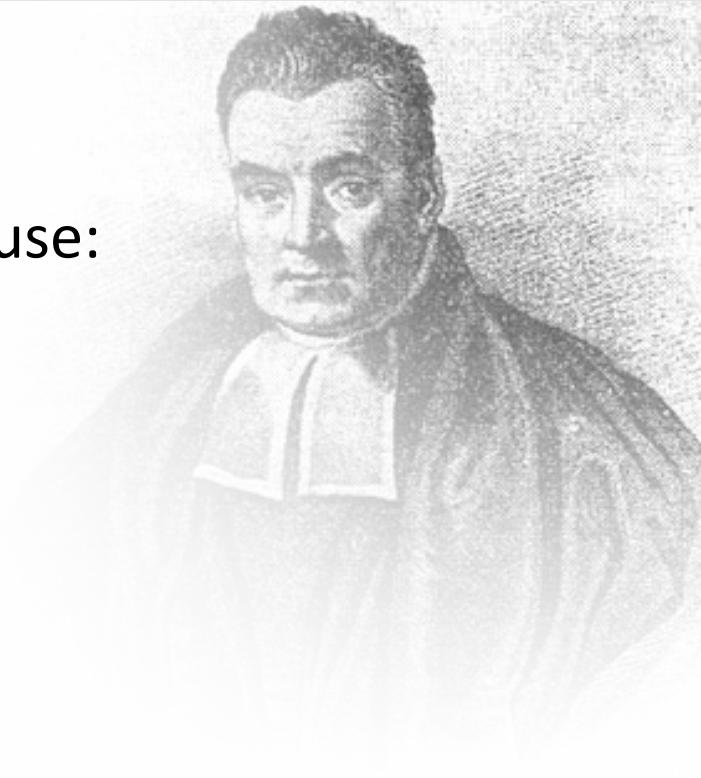
(Nowak & al, WRR 2010,
S. Neumann & al, AWR 2012)
(M. Fienen & al, WRR 2008)

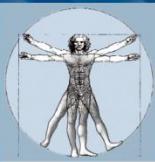




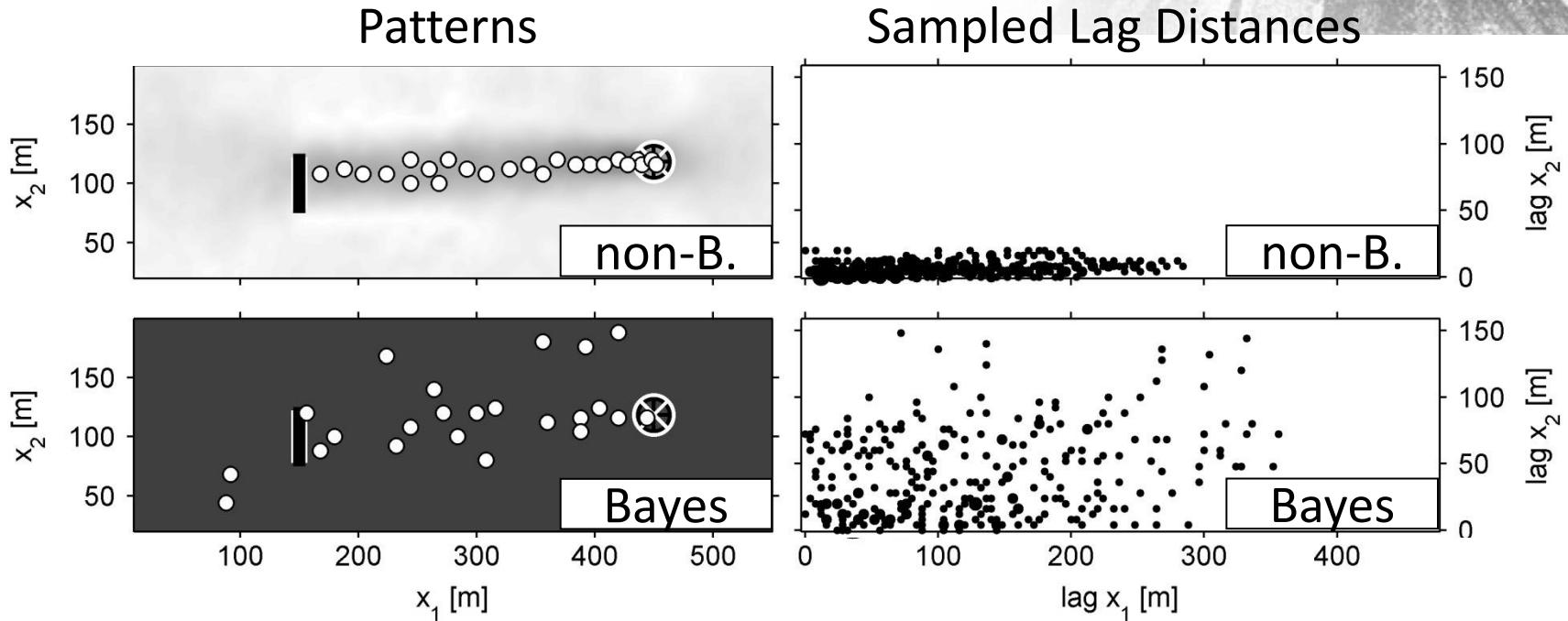
What to do?

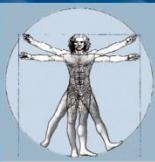
- Accept structural uncertainty, because:
 - Uncertain even after sampling
 - High impact on prediction goal
 - You will learn nothing about what you claim to know already
 - Include & tackle this uncertainty in optimal design!
 - Method: “Bayesian geostatistical design”:
 - Model identification as (implicit/secondary) objective / MOO
 - Robustness against too narrow priors
- (W. Nowak, F.P.J. de Barros and Y. Rubin, WRR 2010)*





Bayesian geostat. Design





Optimal design: challenges

Information
needs?

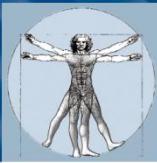


1.) Stochastic/geostatistical model:
realistic envelope to uncertainty

2.) Define utility of desired data:
task-driven information needs

3.) For a given design:
Quantify utility of future data

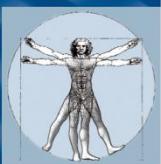
4.) Optimize design:
maximize utility (e.g., cost-benefit)



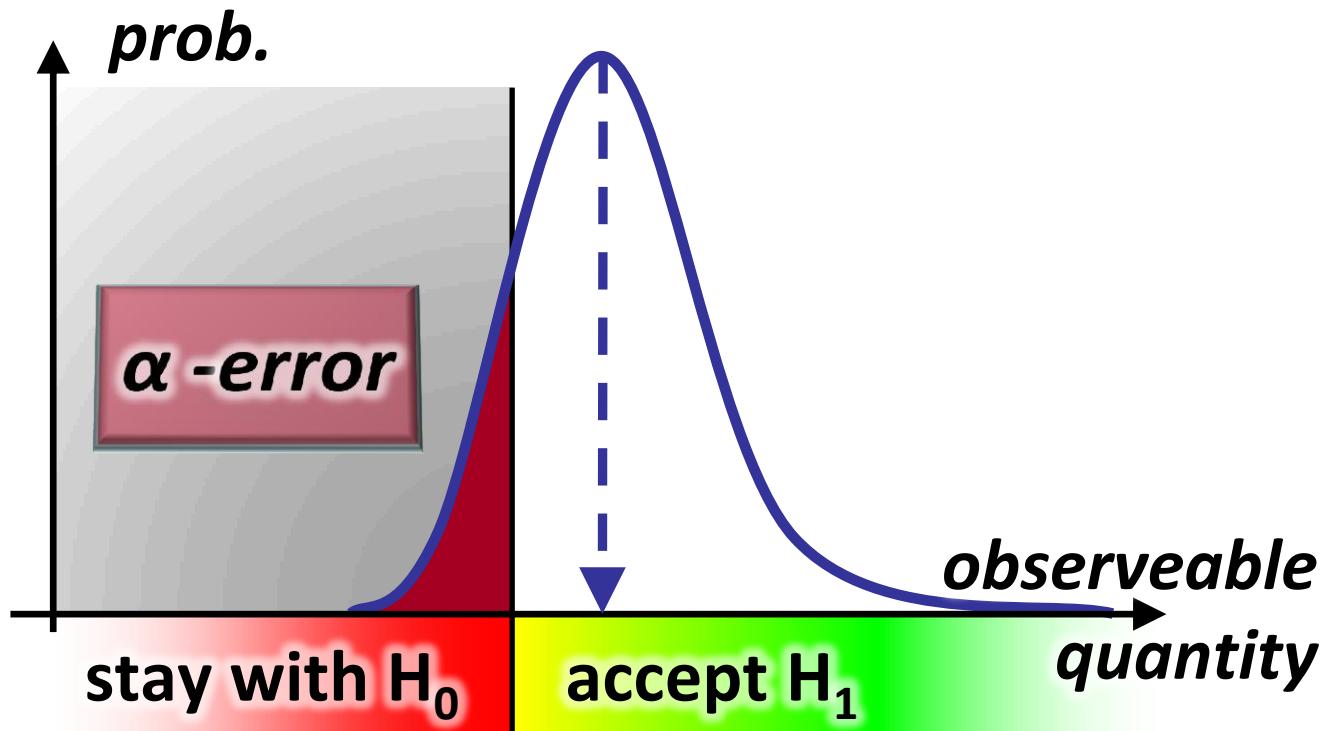
Information needs?

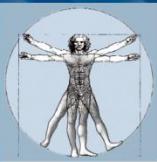
- Shut down well after contaminant spill?
(e.g., Frind et al., 2006; Enzenhöfer et al., 2010)
- Is a contaminant release rate critical?
(e.g., Troldborg et al., 2010)
- Is natural attenuation occurring?
(e.g., Schwede und Cirpka, 2010)
- Is a proposed remediation design safe?
(e.g., Cirpka et al., 2004)
- Is a radioactive waste site safe?
(e.g., Andricevic und Cvetkovic, 1996)
- Is human health risk above critical level?
(e.g., de Barros und Rubin, 2008; de Barros et al., 2009)
- Is a model adequate to describe a site?
(e.g., Neuman, 2003; Refsgaard et al., 2006)



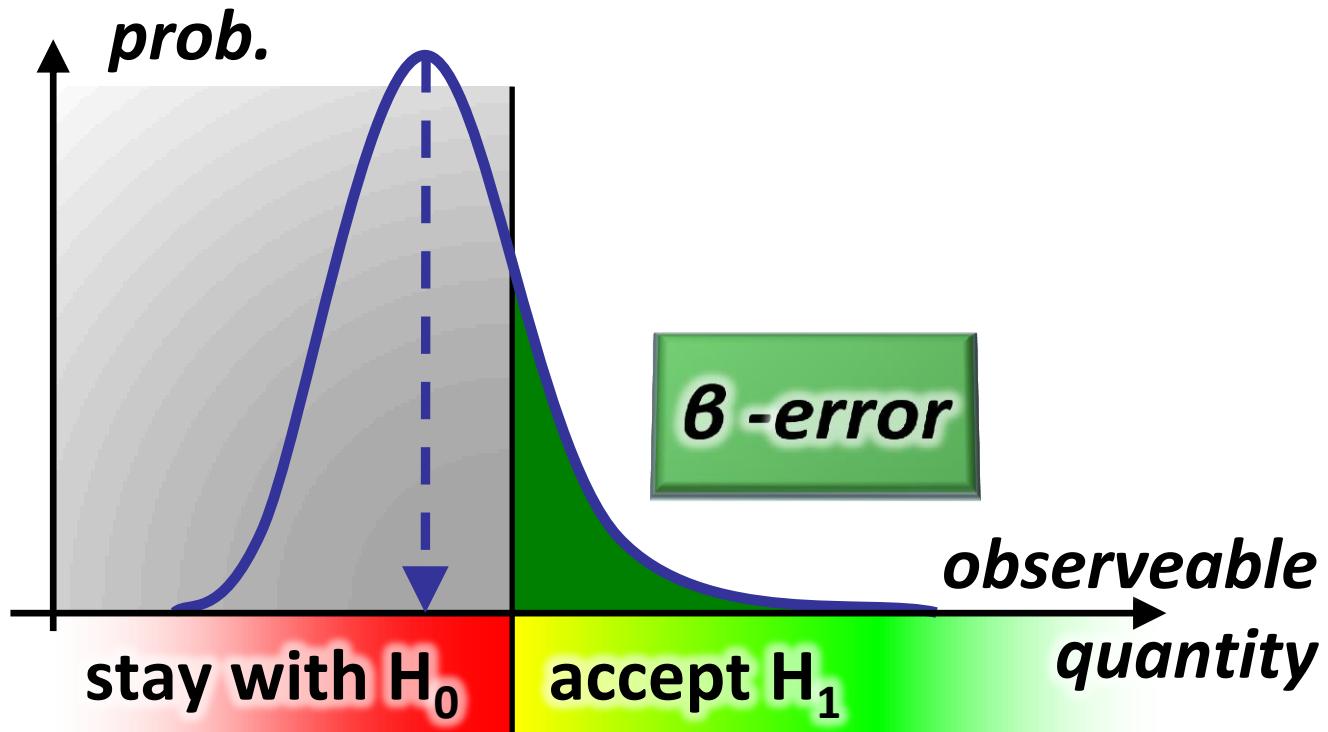


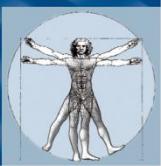
Failure of decisions



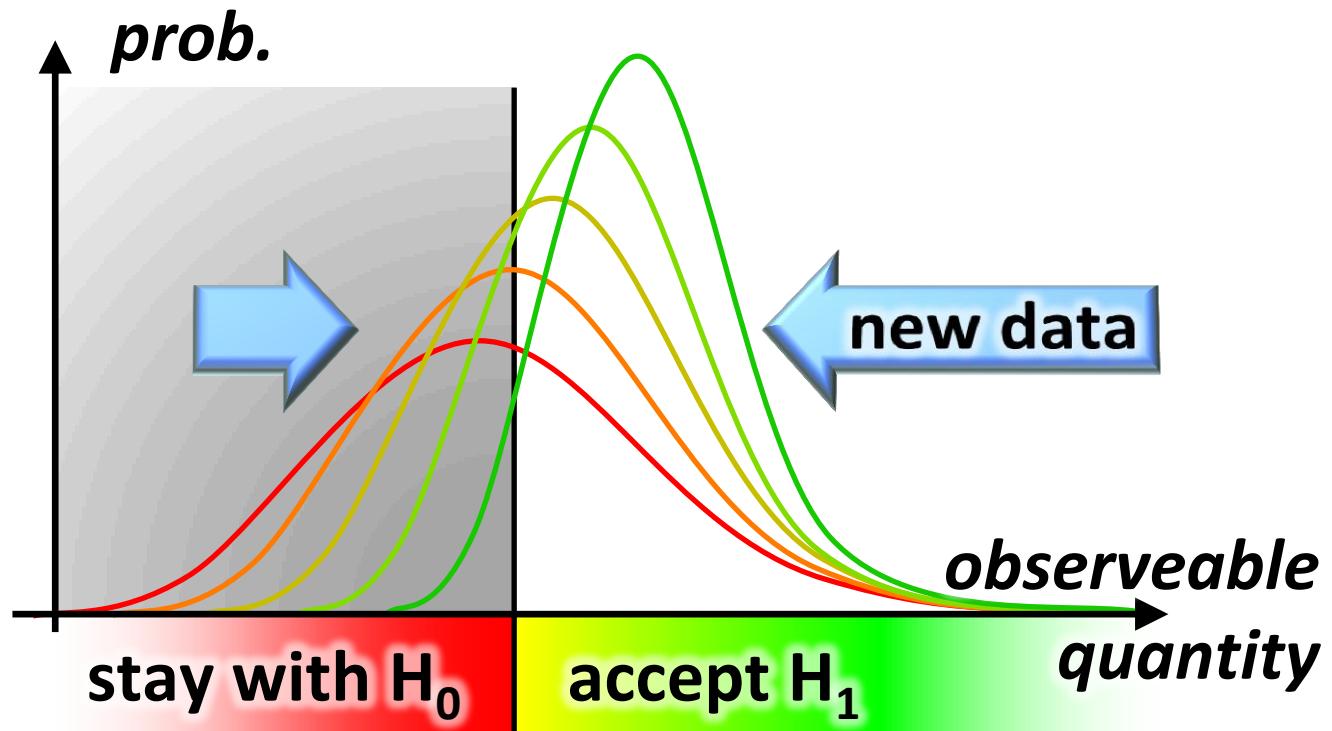


Failure of decisions



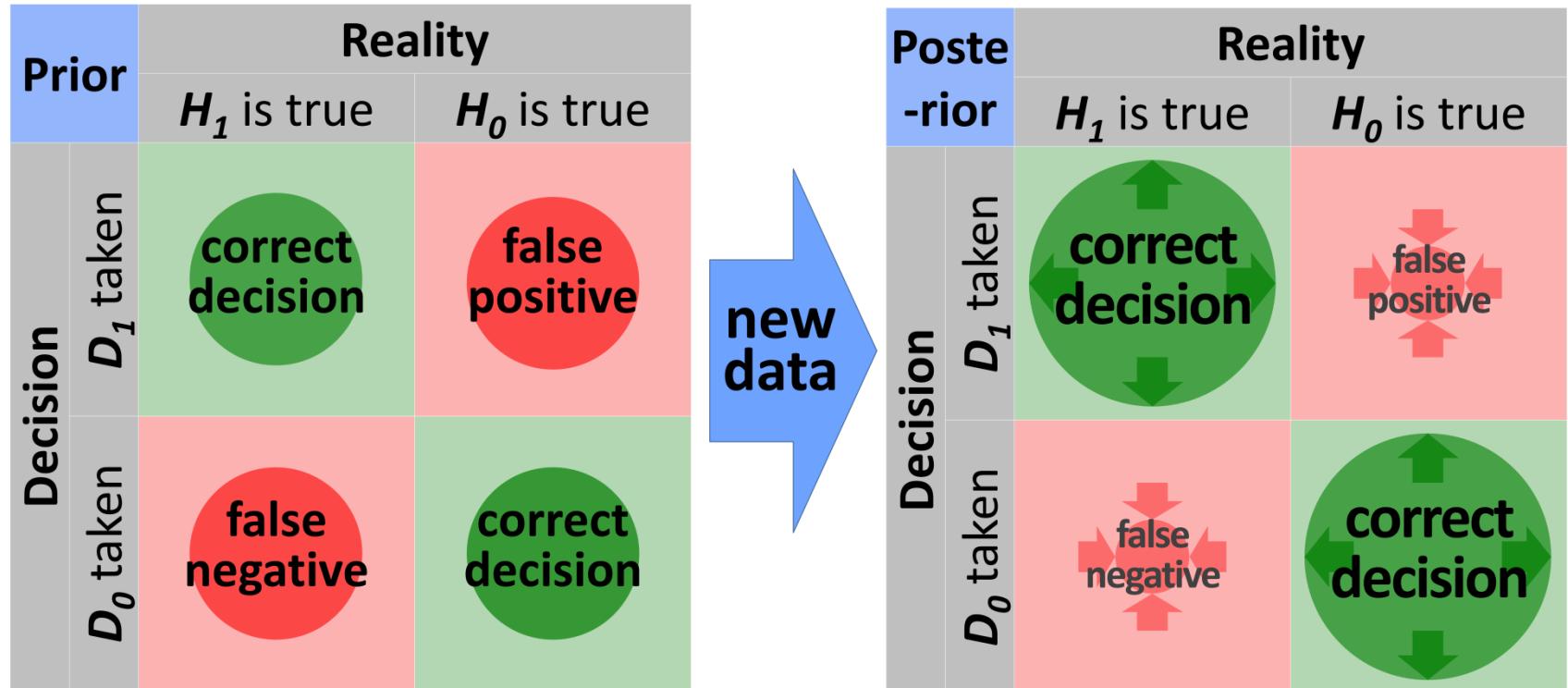


Failure of decisions

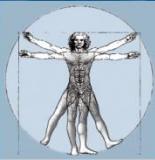




Hypothesis-driven design



- Uses **actual** goals (no surrogates) as objective function
- Searching “scientific truth” avoids “monetization” etc.
- Model assumptions / identification, decision support...



Optimal design: challenges

1.) Stochastic/geostatistical model:
realistic envelope to uncertainty

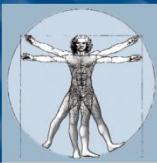
2.) Define utility of desired data:
task-driven information needs

3.) For a given design:
Quantify *expected* utility

3b.) Generate random data sets,
condition & assess utility for all

4.) Optimize design:
maximize utility (e.g., cost-benefit)

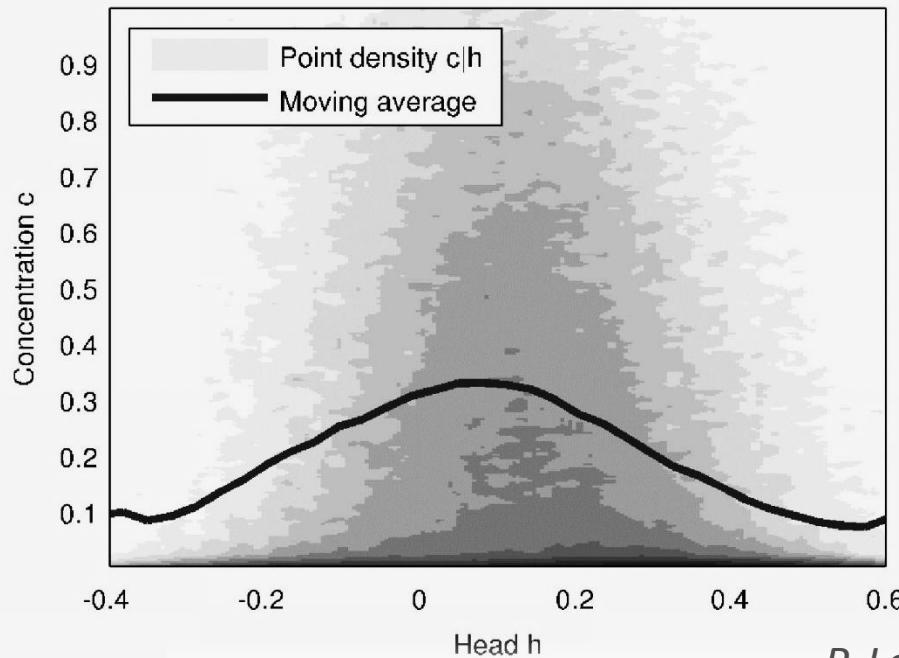
pre-posterior
analysis



Preposterior Analysis

Preposterior Data Impact Assessment (PreDIA):

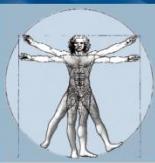
- Any task-driven criteria possible
- Fully non-linear method
(non-lin. info hidden for linear tools)



- Bootstrap filter
- Average over data
- Marginalized errors
- Cross-breeding

Non-Multi-Gaussian

- Multi-Gaussian description is insufficient!
- No 2nd order geostatistics
(e.g., J.J. Gómez-Hernández & al, AWR 1998)



Outlook: Model Choice

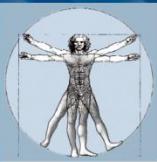
- What will a good “model choice” design do?

Prior		Point towards...		
		Model 1	Model 2	Model 3
Data from Model #...	Model 1	Green	Red	Red
	Model 2	Red	Green	Red
	Model 3	Red	Red	Green



Poste -rior		Point towards...		
		Model 1	Model 2	Model 3
Data from Model #...	Model 1	Dark Green	Light Red	Light Red
	Model 2	Light Red	Dark Green	Light Red
	Model 3	Light Red	Light Red	Dark Green

- Hardly any analytical solutions
- Brute-Force (PreDIA), CPU-intensive



Summary & Conclusions

- OD: Quest for perfect information
 - Envelope for prior uncertainty (stay robust w.r.t. priors)
 - Align OD with task at hand (e.g., hypothesis-driven)
 - Fast tools becoming available (e.g., PreDIA)
- Major challenges:
 - 1.) Multivariate structure
 - 2.) CPU time / real time





Funding Acknowledgments

- EXC 310/1 SimTech
- IRTG 1398 (NUPUS)
- VW foundation
- State of BW