

On the Error Sources in Absolute Individual Antenna Calibrations

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Outline

Antenna Calibration

Anechoic Chamber Calibration

Robot Calibration

Side by Side Comparison

Conclusion



Antenna Calibration

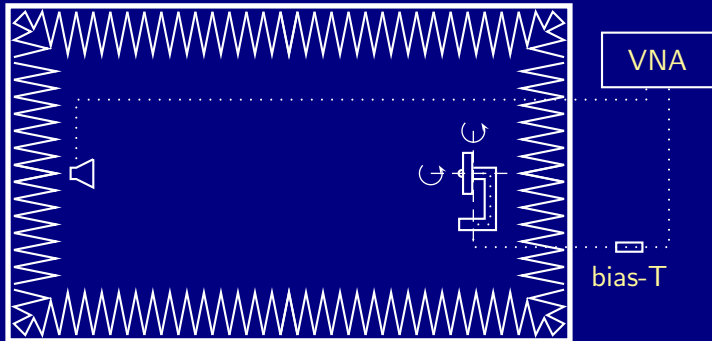
- ▶ Antenna \neq point source, rather current carrying surface
Wheeler limit:

$$\frac{\Delta f}{f} \eta = \frac{4\pi^2}{3} \frac{V}{\lambda^3}$$

- ▶ phase at connector depends on incidence angle \Rightarrow calibration
- ▶ Absolute versus Relative
- ▶ From Antex 1.4 Syntax: METHOD
 - ▶ 'CHAMBER', 'FIELD', 'ROBOT',
 - ▶ 'COPIED' from other antenna,
 - ▶ 'CONVERTED' from igs_01.pcv or blank



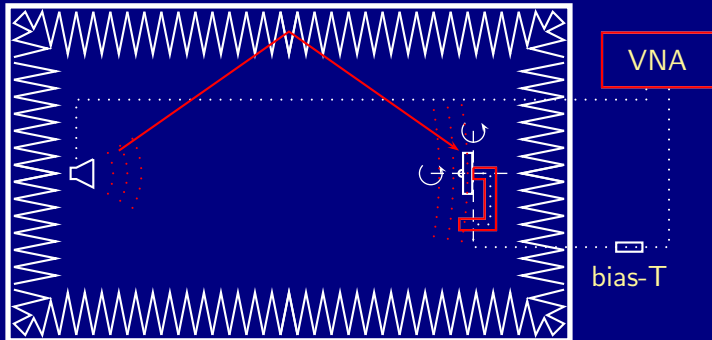
Working Principle



- ▶ cable flexing \Rightarrow rotary joints
- ▶ temperature changes \Rightarrow phase stable cable



Error Sources



- ▶ reflections on walls
- ▶ VNA measurement errors
- ▶ no plane wave at AUT
- ▶ near field of positioner



Error Sources

Reflection on walls:

- ▶ worst case combination of direct and reflected signal
- ▶ depends on (effective) attenuation of wall absorbers
- ▶ error on G02 (GPS L2) in good chamber is ≈ 0.1 mm (calculated with -25 dB effective attenuation)

Vector Network Analyzer (VNA) measurement error:

- ▶ for calibrated VNA
- ▶ depends on received power level (worst for low elevation)
- ▶ error on G02 (GPS L2) with good VNA is $\ll 0.3$ mm (based on 0.4° S_{21} phase uncertainty; e.g. Anritsu MS4642A)
- ▶ [Zeimetz,2008] indicates $\approx 0.1^\circ$ after temperature correction
- ▶ resolution rather than accuracy is expected to matter

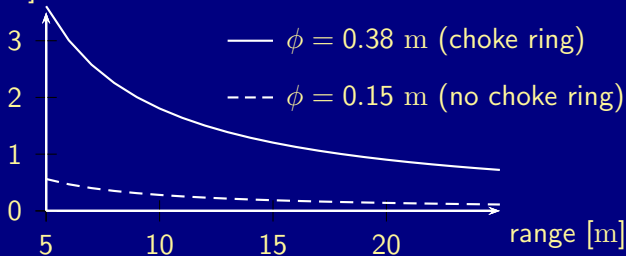


Error Sources

No plane wave at Antenna Under Test (AUT)

- ▶ relation between phase variation over antenna and phase error on connector unclear

Δ range [mm]



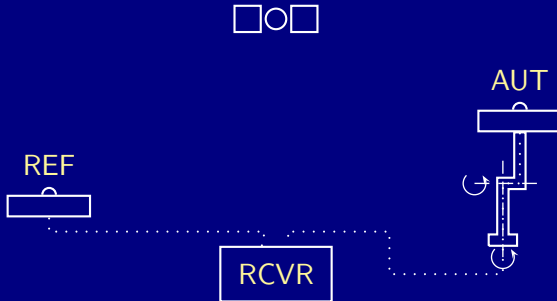
Error Sources

Near field effect of the positioner:

- ▶ any material in (reactive) near field causes change in current profile and (output) phase
- ▶ effect strongly depends on antenna type
- ▶ [Zeimetz,2008] reports difference of 1.2 mm on G02 (GPS L2) at low elevation for a change of antenna cabling geometry (for LEI AX1202GG)



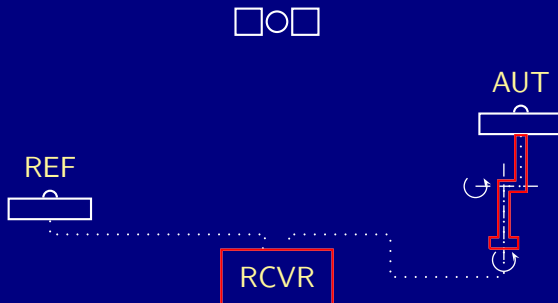
Working Principle



- ▶ cable flexing \Rightarrow rotary joints
- ▶ temperature changes \Rightarrow identical cables of identical length



Error Sources



- ▶ GNSS receiver measurement errors
- ▶ near field of the robot



Error Sources

GNSS receiver measurement error:

- ▶ depends on received C/N_0
- ▶ resolution rather than accuracy is expected to matter
- ▶ error on G02 for contemporary receivers is ≈ 0.25 mm (based on 1 mm accuracy and 0.001 cycle resolution on G02 from SEPT POLARX4PRO data sheet)

Near field effect of the positioner:

- ▶ see also: chamber calibration
- ▶ typically robot geometry differs from positioner geometry



Order of Magnitude of Errors

Errors on G02 in order of magnitude for both calibration methods:

	CHAMBER	ROBOT
reflections	≈ 0.1 mm	$\rightarrow 0$
measurement device	$\ll 0.3$ mm	≈ 0.25 mm
repeatability <small>same setup</small>	0.3 mm [Zeimetz,2008]	??
no plane wave	??	NA
near field	≥ 1.2 mm	??
repeatability <small>different setup</small>	1.5 mm [Zeimetz,2008]	1 mm [Wübbena,2006]

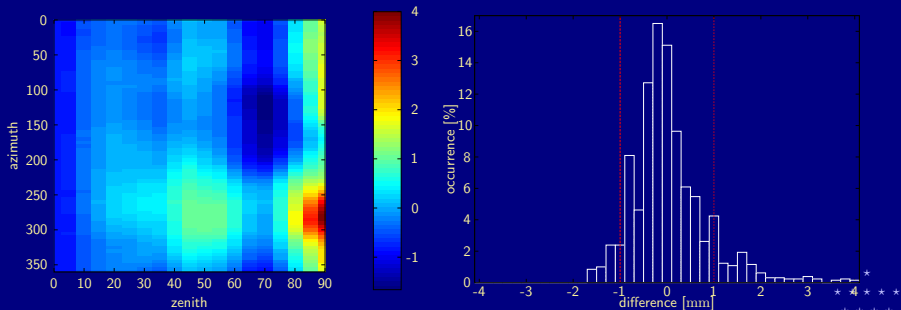
Robot measurements in [Wübbena,2003] reveal up to 5 mm change in PCC for different antenna mounts.

Robot and chamber in [Zeimetz,2009] differ by at most 4 mm.



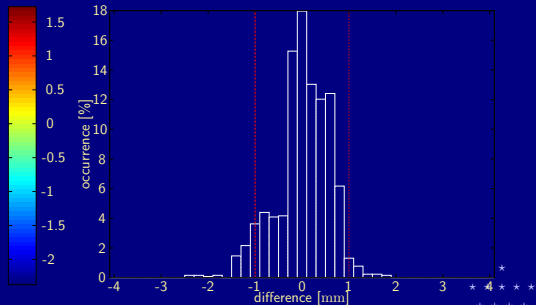
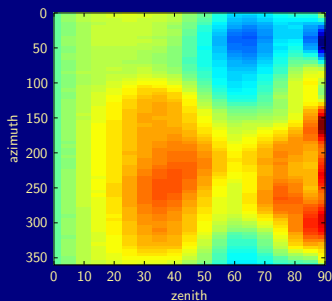
LEIAR25.R3 09300021

Difference between Geo++ and UniBonn PCC (PCO and PCV) calibration on G02 for LEIAR25.R3 antenna 09300021:



TRM59800.00 5115354099

Difference between Geo++ and UniBonn PCC (PCO and PCV) calibration on G02 for TRM59800.00 antenna 5115354099:



Conclusion

- ▶ the dominant error for chamber and robot calibration is near field multipath
- ▶ repeatability (different setup, same method) is better than inter-method difference
- ▶ difference between calibration setup and station setup has same order of magnitude as inter-method difference
- ▶ (sub-)millimeter absolute positioning with GNSS will only be possible after solving this near field issue (in calibration and site installation)



Acknowledgments

- ▶ Solar Terrestrial Center of Excellence (STCE)
- ▶ Holger Milz, Martin Schmitz, Philipp Zeimetz, . . .



References

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- [Wübbena,2006] “Absolute GNSS Antenna Calibration with a Robot: Repeatability of Phase Variations, Calibration of GLONASS and Determination of Carrier-to-Noise Pattern”, G. Wübbena, M. Schmitz, G. Boettcher and C. Schumann, IGS Workshop 2006, Germany.
- [Zeimetz,2008] “On the Accuracy of Absolute GNSS Antenna Calibration and the Conception of a New Anechoic Chamber”, P. Zeimetz and H. Kuhlmann, FIG Working Week 2008, Sweden.
- [Zeimetz,2009] “Ringversuch 2009”, P. Zeimetz, H. Kuhlmann, L. Wanninger, V. Frevert, S. Schön and K. Strauch, 7 GNSS-Antennen-Workshop 2009, Germany

