Abstract and Motivation

This contribution summarizes the gravity field models derived with Since the launch of ESA's GOCE satellite in 2009 and its end in the time-wise approach. The progress along the five releases is 2013, a sequence of official GOCE gravity field models was rehighlighted. Special focus is put on the final release 5. This model, leased. One of the series of models follows the so called time-wise parameterized as 78957 spherical harmonic coefficients (spatial approach (EGM_TIM). They are purely based on GOCE observaresolution of 71 km), was determined from 4×109799264 gravity tions such that they are independent of other gravity information gradient measurements and 108754709 three dimensional posiand describe the Earth's gravity field as seen by GOCE. The modtions within a joint least squares adjustment procedure. As this els of the time-wise series were computed within the ESA funded gravity field models only depend on GOCE observations, the gain High-level Processing Facility (HPF) and are part of the official of GOCE compared to other missions and other gravity field prod-ESA GOCE products. Gravity gradients in the gradiometer refucts can be clearly demonstrated. With release 5 of the time-wise erence frame and the satellite positions as derived by GPS meamodel, a pure GOCE based model with a mean global accuracy surements entered the solutions as observations. Together with of 2.4 cm at a spatial resolution of 100 km for the geoid (0.7 mGal the spherical harmonic coefficients, a realistic and full covariance for gravity anomalies) is available. matrix is provided reflecting the model quality.





igg IG APG G

University of Bonn

GOCE gravity field models following the time-wise approach

SST processing:

short arc integral equation approach

▶ stochastic model: position covariance + empirical cov. function least squares normal equations

SGG processing:

gravity gradients in GRF as time series

- \blacktriangleright components used V_{xx} , V_{xz} , V_{yy} and V_{zz}
- stochastic model: individually adjusted ARMA filters
- iterative outlier detection
- least squares normal equations

Constraints:

Kaula for (near) zonal coefficients (polar gap) Kaula for high degree coefficients

Combined solution:

solution of weighted combined normal equations weights derived by variance component estimation

$\left(\frac{1}{\sigma_{sst}^2}\mathbf{N}_{sst} + \sum_r \frac{1}{\sigma_r^2}\mathbf{N}_r + \sum_g \sum_{s=0}^{S-1} \frac{1}{\sigma_{g,s}^2}\mathbf{A}_{g,s}^T \mathbf{Q}_{\ell_{g,s}\ell_{g,s}}^{-1}\mathbf{A}_{g,s}\right)$	x
$= \frac{1}{\sigma_{sst}^2} \mathbf{n}_{sst} + \sum_{r} \frac{1}{\sigma_r^2} \mathbf{n}_r + \sum_{\sigma} \sum_{s=0}^{S-1} \frac{1}{\sigma_{g,s}^2} \mathbf{A}_{g,s}^T \mathbf{Q}_{\ell_{g,s}\ell_{g,s}}^{-1} \mathbf{A}_{g,s}^T $) ^g,s

input/info	time series	(d/o)	# obs
T, SGG, REG	11/2009-01/2010	2–224	24 524 268
ergy balance, in-flight velocity	pointwise	2–100	6 013 954
X , V_{YY} , V_{ZZ}	1 gapless segment	2–224	3 imes 6161834
nal coefficients	-	$m < \theta_0 I$	5 490
h degree coefficients	-	170–224	19 322
T, SGG, REG	11/2009–07/2010	2–250	82 696 288
ergy balance, in-flight velocity	pointwise	2–100	24 228 376
X_X, V_{YY}, V_{ZZ}	9 gapless segments	2–250	3 imes19477946
nal coefficients	—	$m < \theta_0 I$	6 866
h degree coefficients	-	180–250	27 208
T, SGG, REG	11/2009–04/2011	2–250	pprox 215000000
ergy balance, in-flight velocity	pointwise	2–100	pprox 3 $ imes$ 30 000 000
$X_X, V_{YY}, V_{ZZ}, V_{XZ}$	16 gapless segments	2–250	4×31289605
nal coefficients	-	$m < \theta_0 I$	6866
h degree coefficients	_	180–250	27 208
T, SGG, REG	11/2009–06/2012	2–250	480 719 445
ort arcs, 3-D positions	35 min arcs	2–130	3×69692004
$X_X, V_{YY}, V_{ZZ}, V_{XZ}$	41 gapless segments	2–250	4 imes 67305785
nal coefficients	_	$m < \theta_0 I$	6 866
h degree coefficients	—	180–250	27 208
T, SGG, REG	11/2009–10/2013	2–280	765 504 101
ort arcs, 3-D positions	35 min arcs	2–150	3×108754709
X , V_{YY} , V_{ZZ} , V_{XZ}	87 gapless segments	2–280	4×109799264
nal coefficients	—	$m < \theta_0 I$	8 644
h degree coefficients	_	201–280	34 274

Contact: Jan Martin Brockmann brockmann@geod.uni-bonn.de www.igg.uni-bonn.de/tg/

