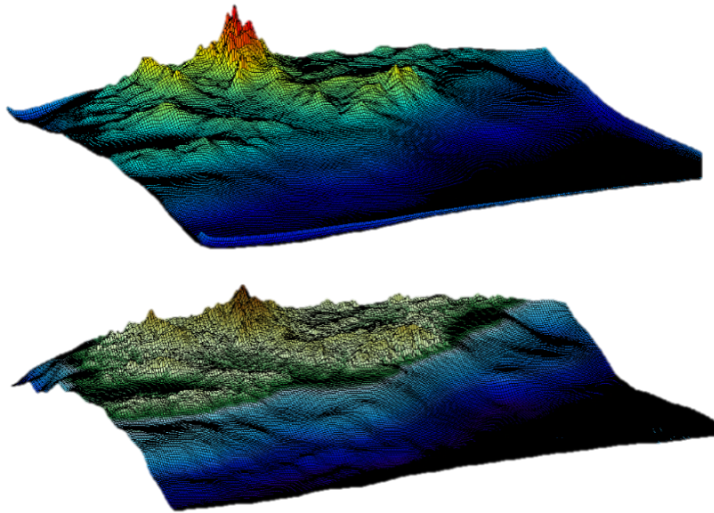


# GTE: a new FFT based software to compute terrain correction on airborne gravity surveys in spherical approximation



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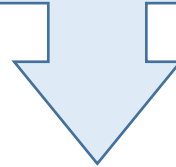
Wien, April 20<sup>th</sup> 2016

# Introduction

The computation of the vertical attraction due to topographic masses is still a matter of study both in geodetic as well as in geophysical applications

## Major issues for the terrain correction computation

- The **huge number of observation points** → e.g. from airborne/shipborne gravimetry measurements (~ 1 milion points)
- The **high resolution of Digital Terrain Models** → e.g. SRTM globally available at 90m (regionally DTM up to 5m are available)
- The **high accuracy of gravity data** → better than 1mGal also for airborne data



**ONE HAS TO QUICKLY COMPUTE THE TC WITH HIGH ACCURACY FOR LARGE GEOGRAPHIC REGIONS AND ON MANY POINTS**

# Gravity Terrain Effect (GTE) software

The GTE software is based on a **new combined algorithm** thought with the aim to **maximize the result accuracy minimizing the computational time**

- quickly compute the **terrain correction at airborne level**
- a new algorithm which **combines the classical prisms and FFT methods**
- work in **spherical approximation**
- **multiresolution approach**
- thought for **geophysical applications** it allows to compute the **effects of the oceanic and topographic masses but also those due to sediments and Moho undulation**

# GTE theoretical aspects

$$\delta g_t(P) = -\frac{\partial}{\partial r} \mu \int dr \int r_Q^2 \frac{dh_Q}{l_{PQ}} d\sigma \quad \text{disregarding terms below 0.1 mGal (*)} \quad \Rightarrow \quad \delta g_t(P) \cong \delta g_t^P(P) + \delta g_t^{sc}(P)$$

So to compute the gravity effect, the calculation can be split between planar and spherical correction terms

## Planar correction

$$\begin{aligned} \delta g_t^P(P) &= -\frac{\partial}{\partial h_p} \mu \int d_2x \int_0^{H_Q} \frac{dh_Q}{L_{PQ}} = \\ &= \mu \int d_2x \left\{ \frac{1}{L_{PQ}} - \frac{1}{L_{PQO}} \right\} \end{aligned}$$

## Spherical correction

$$\begin{aligned} \delta g_t^{sc}(P) &= 2\mu \int d_2x \int_0^{H_Q} dh_Q \varepsilon_Q \frac{\partial}{\partial h_Q} \frac{1}{L_{PQ}} + \mu \int d_2x \frac{s_Q^2}{2R^2} \int_0^{H_Q} dh_Q \frac{\partial}{\partial h_Q} \frac{1}{L_{PQ}} \\ &\quad - \frac{\mu}{2R} \int d_2x \int_0^{H_Q} \frac{s_Q^2}{L_{PQ}^3} dh_Q - \frac{\mu}{2} \int d_2x \int_0^{H_Q} s_{PQ}^2 \varepsilon_{PQ} \frac{\partial}{\partial h_Q} \frac{1}{L_{PQ}^3} dh_Q \end{aligned}$$

**COMBINED ALGORITHM PRISMS+FOURIER**

**NUMERICALLY COMPUTED**

(\*) see Sampietro, D., et al. "GTE: a new software for gravitational terrain effect computation: theory and performances." *Pure and Applied Geophysics* (2016):1-19

# GTE algorithms

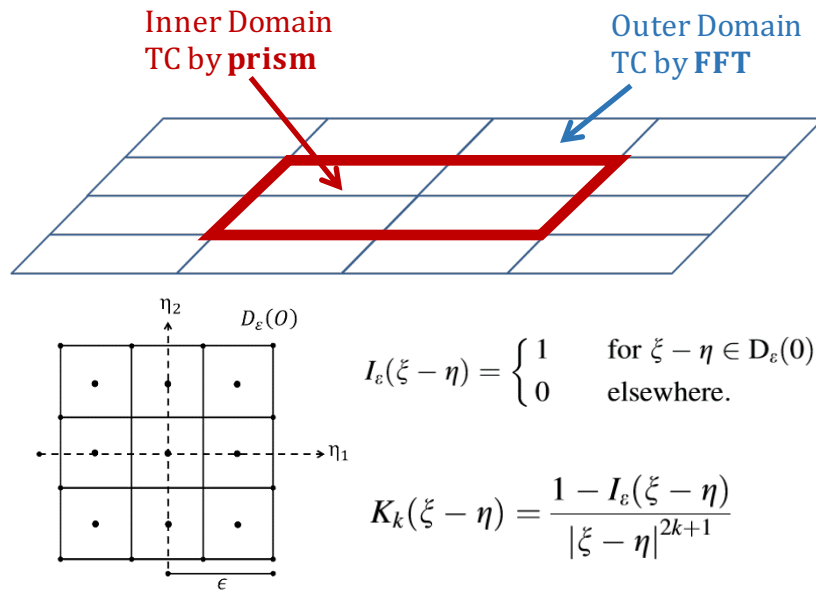
When the number of grid points and of computation points goes **up to  $10^6$**  (i.e. an airborne dataset) the classical prism approach can become **very time consuming and not efficient**

**PROBLEMS** with Fourier approaches:

observation points **close** to the DTM

- reduced accuracy
- non convergence of convolution integrals

Inner and Outer domain



$$\delta g_t^+(P) = \delta g_{ou}^+(P) + \delta g_{in}^+(P)$$

computed by the **Fourier formula**

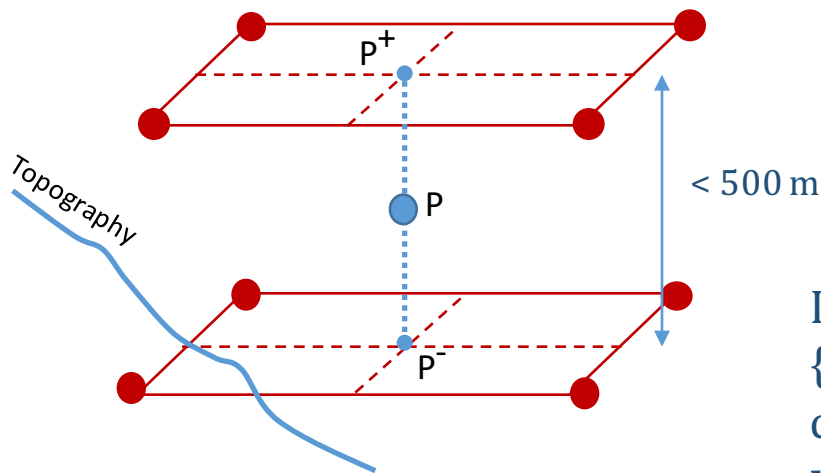
$$\delta g_{ou}^+(P) = \mu \int_D \frac{[1 - I_\epsilon(\xi - \eta)]}{L_{PQ}} d_2 \eta$$

$$\delta g_{ou}^+(P) = \sum_{k=0}^N \sum_{j=0}^{2k} C_{kj} H_\xi^{2k-1} \{K_k * H_\eta^j\}$$

$$K_k * H_\eta^j = F^{-1} \{F\{K_k\} \cdot F\{H_\eta^j\}\}$$

easily computed  
by discretization  
in **prisms**

# GTE for sparse points



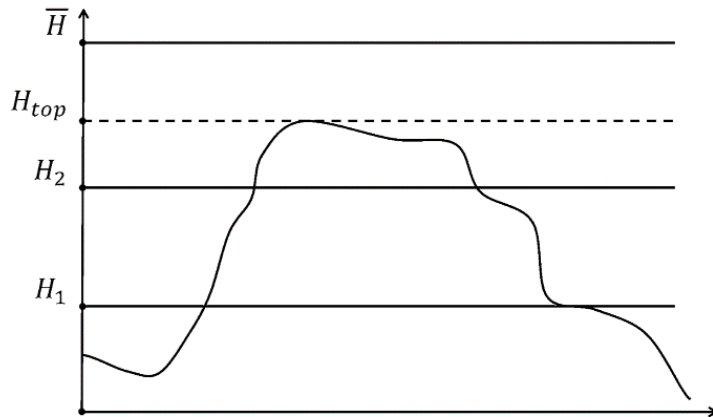
To exploit the advantages of the FFT method the main algorithm of GTE is computing **terrain corrections on grids**

In case of an airborne dataset of sparse points  $\{P_k\}$  above the topography, the software computes **two grids** in correspondence of the **minimum and the maximum heights of  $\{P_k\}$**

Two horizontal interpolations are performed by bilinear functions on the two grids and finally a linear interpolation is performed from  $P^-$ ,  $P^+$  to  $P$

# Slicing

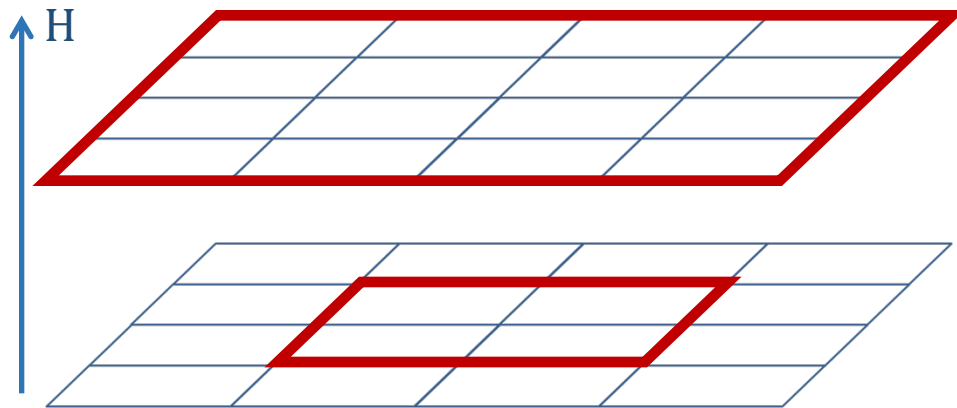
The **slicing** is a particular algorithm implemented in GTE



The **TC** of the topographic body is computed at height  $\bar{H}$  slice by slice and then all the terms are summed up

The reference plane is brought up at the base of the slice in such a way that

$$\frac{H_i - H_{i-1}}{H - H_{i-1}} < 1$$



The slicing allow to increase the size of the inner domain with the height

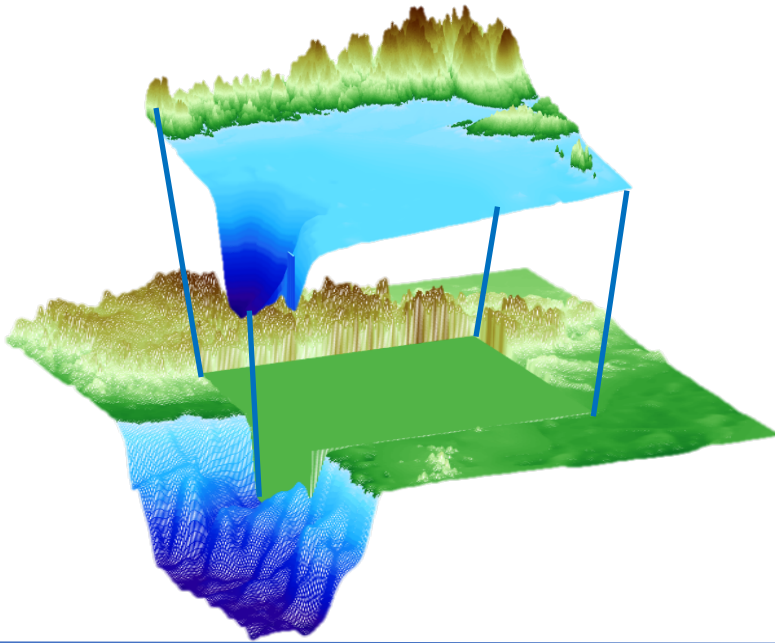
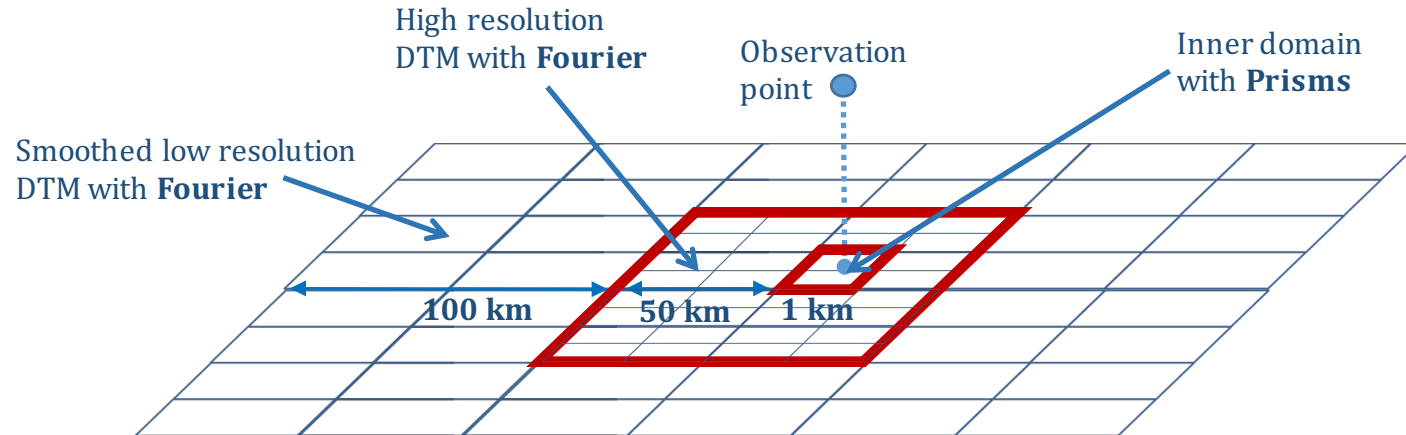


**IMPROVEMENT OF THE CONVERGENCE OF CONVOLUTION INTEGRALS**

**OPTIMIZATION OF COMPUTATIONAL TIMES**



# Multiresolution

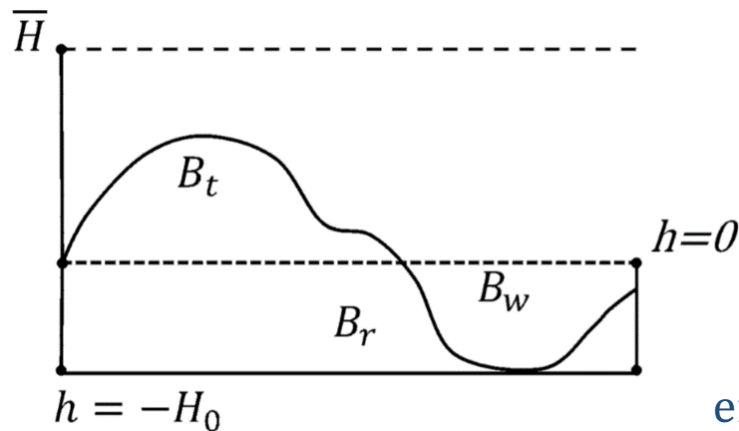


With the multiresolution approach the TC is first computed for the high resolution DTM and then for the smoothed DTM with a lower resolution and finally summed up



# GTE for bathymetry, sediments and Moho

## Bathymetry



$$B_0 = B_r \cup B_w$$

GTE is capable of computing the gravity effect of  $B_t$

How to use the same software to compute the gravity effect of  $B_w$ ?

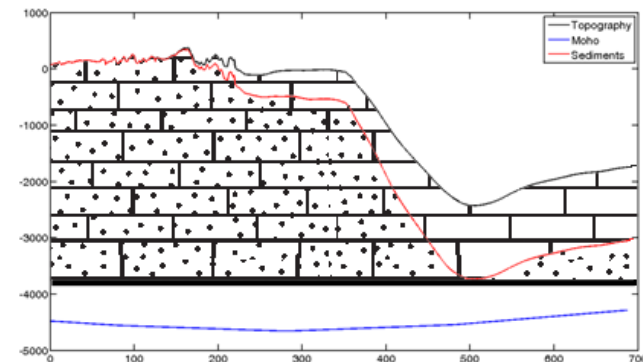
$$\delta g(\rho_w | B_w) = \delta g(\rho_w | B_0) - \delta g(\rho_w | B_r)$$

effect of the big prism  $B_0$

effect of the body  $B_r$  computed at a grid on a plane at height  $H = H_0 + \bar{H}$

## Sediments and Moho

To handle the **Moho effects** can be used the same reordering, by suitably changing the density constant. For **sediments** the algorithm will have to be applied once for the lower surface and once for the upper surface of the sediments

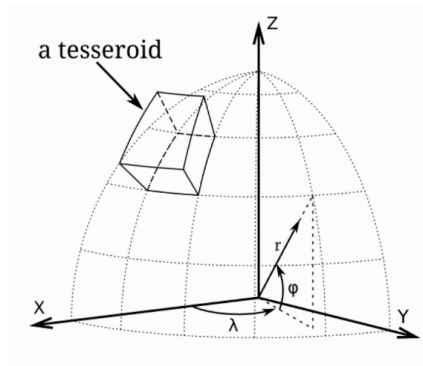


# Numerical tests

Some numerical **tests** have been performed mainly **focused on the computation of terrain correction for airborne gravimetry**

## AIM

To compare the **accuracy** and the **computational times** of GTE algorithms and software with respect to those implemented in **Tesseroids**<sup>(\*)</sup> which is one of the standard scientific software



**Tesseroids** is a collection of command-line C programs to model the gravitational potential, acceleration and gradient tensor of topographic masses.

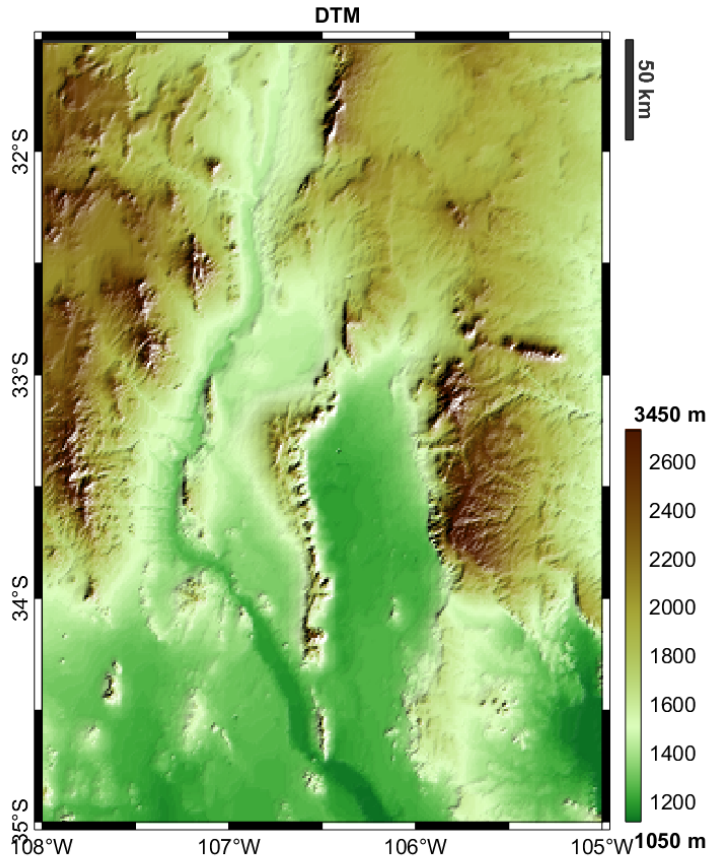
The software computes the gravitational effect of each tesseroid by summing up the effect of a number of point masses optimally distributed and weighted inside the tesseroid

**All the tests have been performed on a single node of a HPC equipped with two 8-cores Intel Haswell 2.40 GHz processors (for a total of 16 cores) with 128 GB RAM**

<sup>(\*)</sup> see Uieda, L., Ussami, N., & Braitenberg, C. F. (2010). Computation of the gravity gradient tensor due to topographic masses using tesseroids. EOS, Trans Am geophys Un, 91, 26.

# Test 1: Dataset

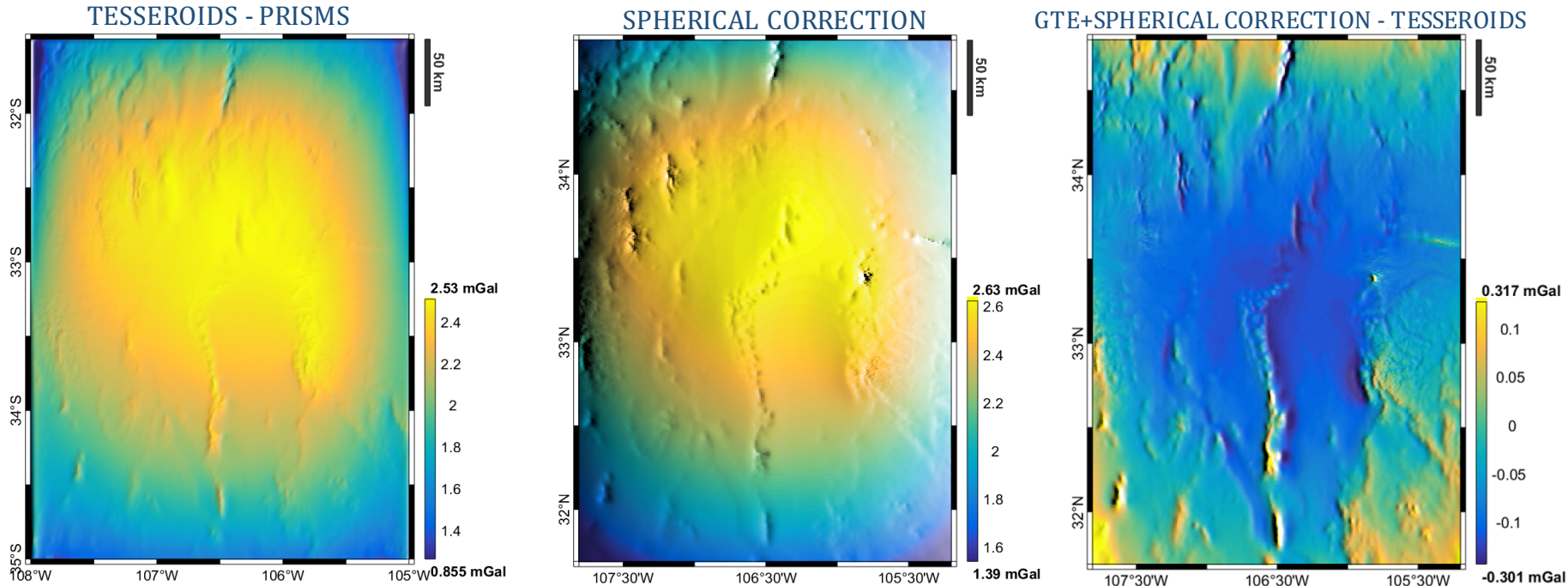
The first test performed consists in comparing, in terms of accuracy and computational time, the results computed on a regular grid



This dataset is located in the south part of New Mexico

- DTM spatial resolution 36 arcsecond
- Region between 31.5° and 35° S and 105° and 108° W (351x301 grid cells)
- DTM height range between 1050 m and 3445 m
- Computation grid height 3500 m

# Test 1: GTE performances



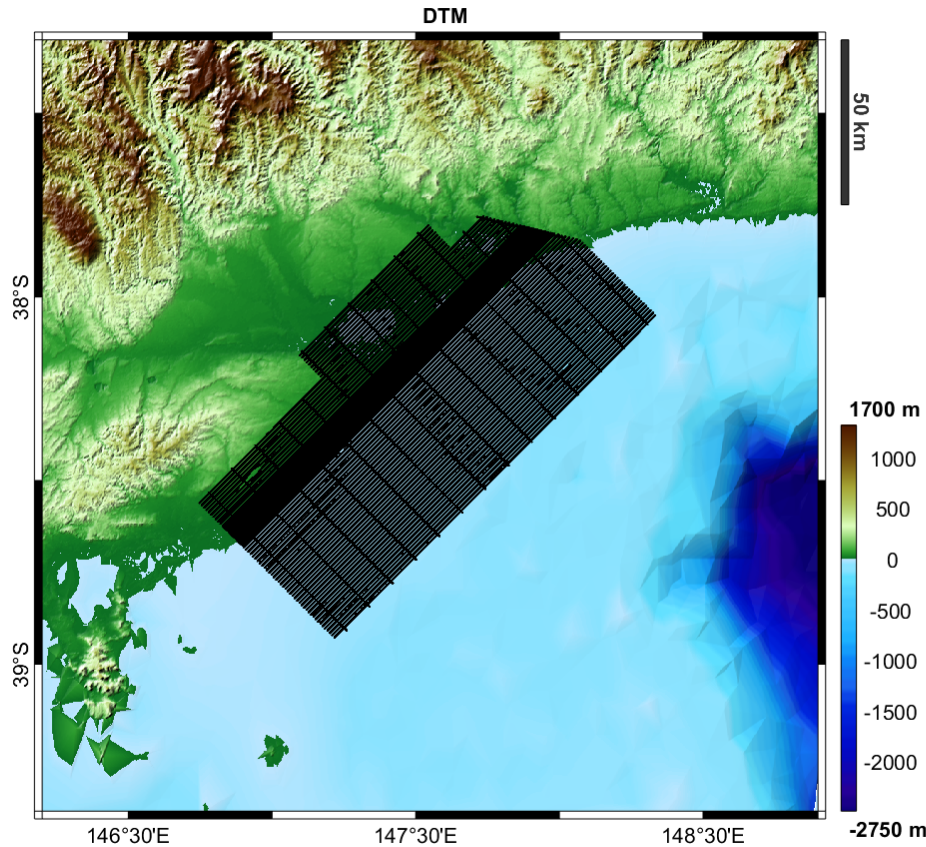
SW	Time [s]	Mean [mGal]	Std [mGal]	Min[mGal]	Max[mGal]
Tesseroids	1937(*)	178.53	40.4	32	349
GTE (no slicing)	11.9	-0.32	0.1	-0.6	-0.07
GTE 3 slices	29.4	-0.09	0.05	-0.3	0.3

(\*)Time has been divided by a factor 16 to account for parallel computing in GTE



# Test 2: Dataset

Tests have been performed on a **real airborne dataset** acquired in the framework of the CarbonNet project (DOPI 2012)

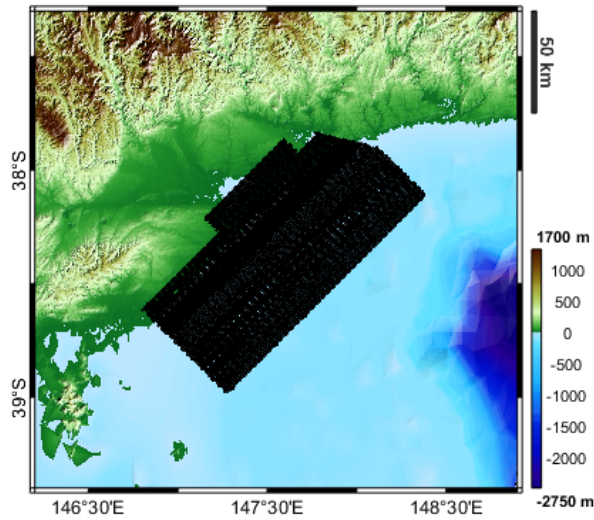


**404.384 real airborne observations** acquired in 2011 by Sanders Geophysics Ltd to provide a better understanding of the onshore and immediate offshore geology of the Gippsland Basin (200 km east of Melbourne)

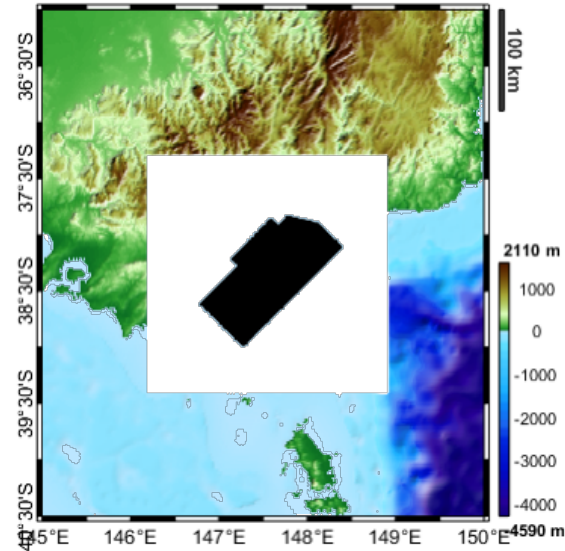
- DTM **spatial resolution 250 m**
- Region between **37.3° and 39.4° S** and **146.2° and 148.9° E** (819x1093 grid cells)
- DTM height range between **1700 m** and **-2754 m**
- The aeroplane is flying **165 m above the ocean** and follows the topography on shore (**max altitude 369 m**)

# Test 2: GTE performances

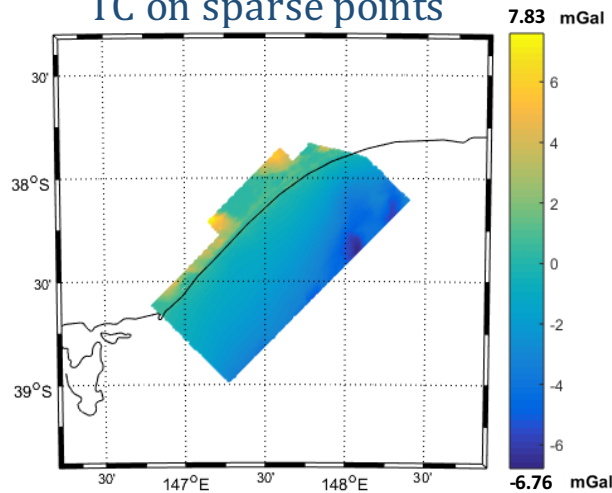
High resolution DTM (250m)



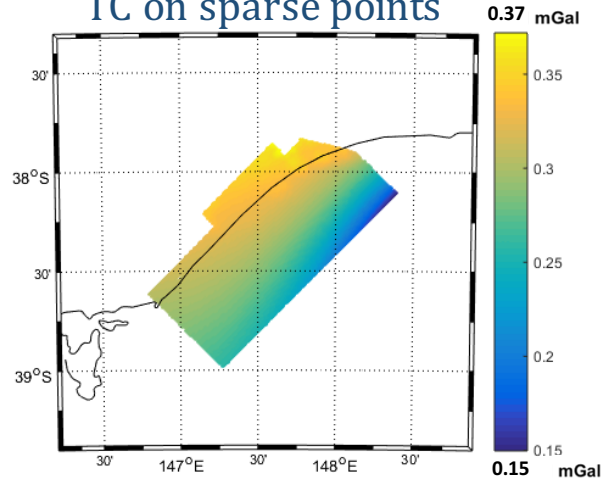
Low resolution DTM (2km)



TC on sparse points



TC on sparse points



Tesseroids	GTE (no slicing)	GTE (3 slice)
Time [s]		
3.8e4 <sup>(*)</sup>	388	1000
Mean [mGal]		
-0.97	-0.019	-2e-3
Std [mGal]		
1.87	0.11	0.016
Min [mGal]		
-6.59	-0.95	-0.082
Max [mGal]		
7.96	0.26	1e-3

(\*)Time has been divided by a factor 16 to account for parallel computing in GTE



# Conclusions

GTE is a new software for the computation of the gravitational terrain effect

- The GTE solution is a **combination of FFT techniques and classical prism modelling** aiming to keep **errors lower than 0.1 mGal**
- It has been developed addressing two major issues required by modern geodetic and geophysical applications, **high accuracy and high computational performances**
- the **prism-FFT mixed algorithm** and the **slicing** provide a solution to the problem of convergence of the series and of its singularity
- It works in **spherical approximation**
- The **multiresolution approach** allows to enlarge the region in which the TC is computed without heavily influences computational times
- the comparison performed have shown that GTE gives **results very close to those obtained by Tesseroids** (differences smaller than 0.1 mGal) but reducing the computational time (few hours vs. few minutes)

# Future developments

Looking forward the future developments, the next activities will be concerned with

- Implementation of **gravitational potential** and **gravity gradients computation** (second radial derivative of the gravitational field)
- Implementation of the computation of **TC on the DTM surface** (this requires to apply different FFT algorithms, a prototypal SW have been already developed and tested in Matlab)
- for observation points close to the topography the actual slope of the terrain should be considered. A solution for this problem (e.g implementation of **triangulated polyhedrons**<sup>(\*)</sup>) should be studied and implemented

<sup>(\*)</sup> see Götze H-J., and Lahmeyer B., Application of three-dimensional interactive modeling in gravity and magnetics, Geophysics, 53, 1096–1108 (1988).

# Thanks for your kind attention



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# Backup slides



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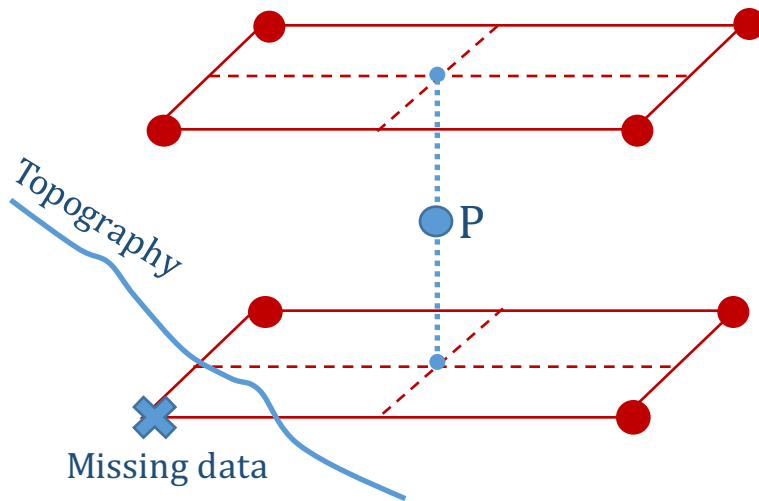


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# GTE for sparse points

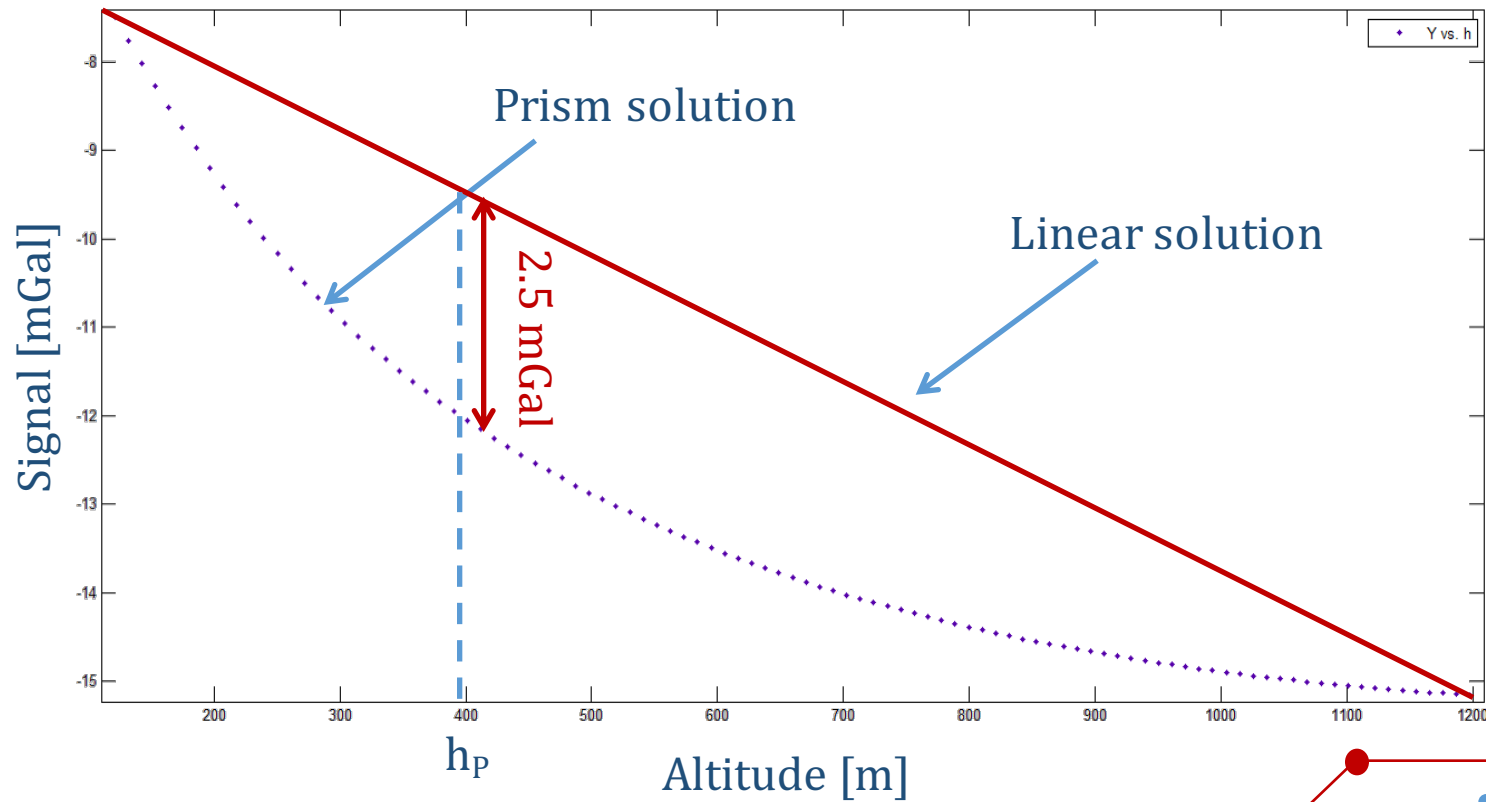
## Problem



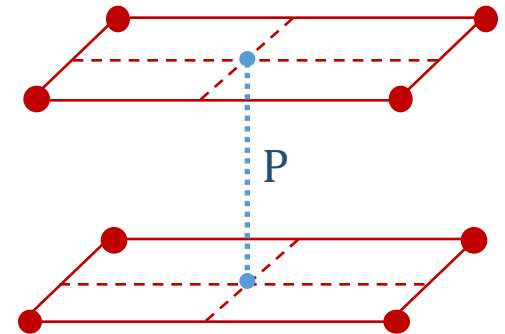
When we are close to the topography it can happen that a knot of the grid is not computed because it is below the topography.



# “Problematic” Points



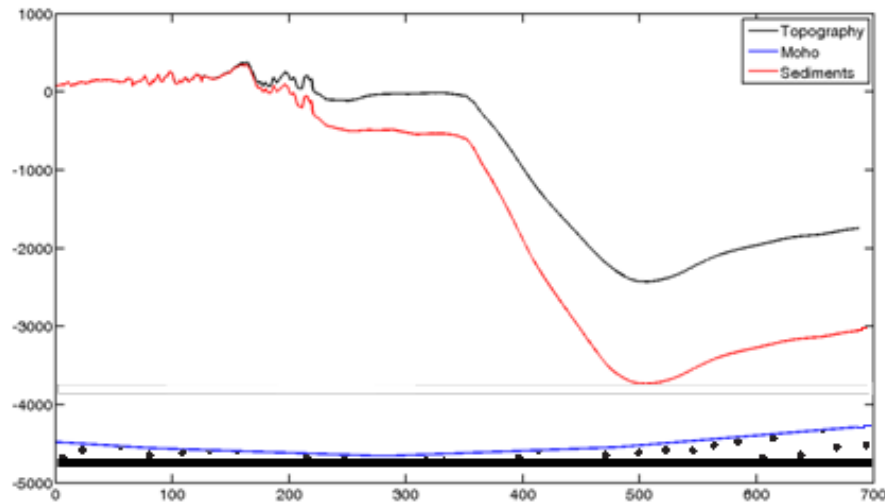
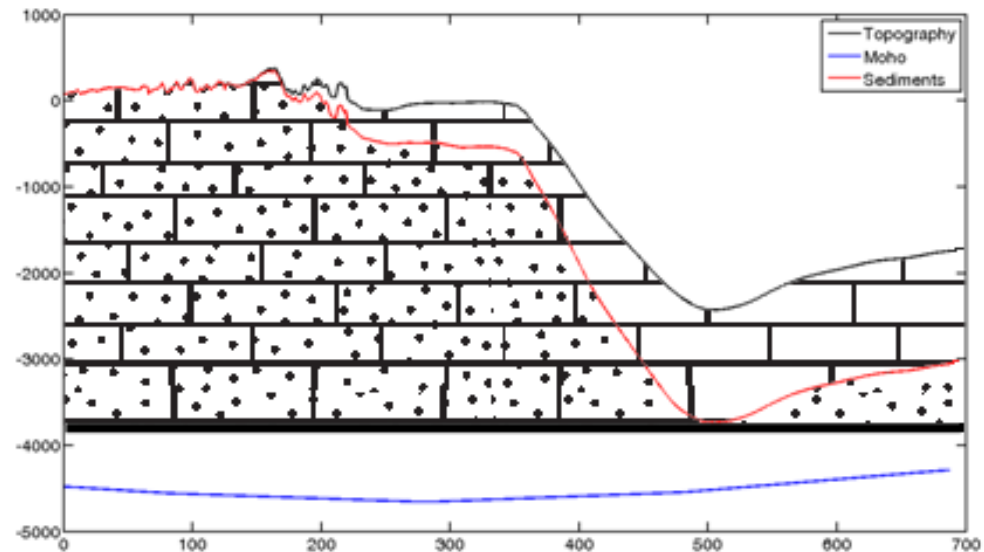
We compute the TC on a column in correspondence of P every 10 meters by prism and with the linear interpolation.



# Terrain Correction

The gravitational effect of sediments is brought back to the computation of two terrain corrections: one for the top and one for the bottom.

(The two grids defining sediments should be properly shifted)



The gravitational effect of the crust-mantle discontinuity is brought back to the computation of one terrain correction

