# Variational Model Reduction for Geophysical Flows with full Coriolis Force

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#### Introduction

#### L1 Balance Model

- It gives a simple relationship of velocity field with mass field i.e density.
- This model supplies a simple solution solving dynamical part of it because it filters out inertia gravity waves.
- It is obtained as an expansion of the Lagrangian and transformation for the system which has the balance in the leading order in  $\varepsilon = Ro$ .
- It keeps the regularity of potential vorticity inversion.
- The velocity field is determined by up to a constant of integration. It is separated as  $u = \hat{u} + \bar{u}$ .

with

$$\mathsf{P}\hat{\boldsymbol{v}} = -\frac{1}{2}\mathsf{J}^{\mathsf{T}}\hat{\boldsymbol{U}} + \lambda\,\mathsf{J}^{\mathsf{T}}\hat{\boldsymbol{U}}_{g}$$

In this expression,  $\lambda$  is a free parameter, J is the rotation matrix and

$$oldsymbol{U}_g = oldsymbol{u}_g + oldsymbol{A}[oldsymbol{u}_g]$$
 .

We note that  $oldsymbol{U}_g$  takes the same form as  $oldsymbol{U}$ , with  $oldsymbol{u}$  replaced by  $oldsymbol{u}_g$ 

 $L_1 = \int_{\mathcal{D}} \nu \, \hat{u} \cdot \hat{u}_g + \frac{1}{2} \, |\bar{u}|^2 - \frac{\lambda}{\hat{\Omega}_z} \, |\hat{u}_g|^2 \, d\boldsymbol{x} \,,$ 

**TRR181** 

O.

(10)

(11)

(12)

- $\hat{u}$  causes degeneracy on L1 and fixed via transformation vector.
- $ullet ar{u}$  is the mean velocity and found by the evolution of potential vorticity.

#### Aim

- To obtain the balance model using the full Coriolis force
- To show the non-hydrostatic effect on the 3D model

## **Axis of Rotation**



The unit vector in the direction of the axis of rotation is

(1)

(3)

(4)

 $\mathbf{\Omega} = \left[ \cos \phi / \sin \phi \right]$ 

**Figure 1:** local *f* plane model positioned at latitude  $\phi$ , [2].

Projectors along the rotation axis

$$\mathbf{Q} = \sin^2 \phi \, \mathbf{\Omega} \mathbf{\Omega}^{\mathsf{T}} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & \cos^2 \phi & \cos \phi \sin \phi \\ 0 & \cos \phi \sin \phi & \sin^2 \phi \end{pmatrix} \text{ and } \mathbf{P} = \mathsf{I} - \mathsf{Q} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \sin^2 \phi & -\cos \phi \sin \phi \\ 0 & -\cos \phi \sin \phi & \cos^2 \phi \end{pmatrix}$$
(2)

#### $J_{\mathcal{D}}$ , $\mathcal{I}$

where  $\nu = \lambda + 1/(2\hat{\Omega}_z)$ .

## **Results**

#### L1 Model and Potential vorticity

$\tilde{\boldsymbol{\Omega}} \times \boldsymbol{u} + \rho \boldsymbol{k} + \varepsilon \left( \partial_t \boldsymbol{p} + (\boldsymbol{\nabla} \times \boldsymbol{p}) \times \boldsymbol{u} - \boldsymbol{\nabla} \rho  \nabla^{\perp} \cdot B \right) = -\boldsymbol{\nabla} \phi .$	(13)
with incompressibility property	
$\boldsymbol{\nabla}\cdot\boldsymbol{u}=0,$	(14)
where $\boldsymbol{p} = (\bar{\boldsymbol{u}} + \nu \hat{\boldsymbol{u}}_g, \boldsymbol{0}),  \boldsymbol{b} = \nu \hat{\boldsymbol{u}} - \frac{2}{\Omega_z} \hat{\boldsymbol{u}}_g$ and potential $\Phi = -\pi - \frac{1}{2}  \boldsymbol{u} ^2$ with the pres $\pi$ . <i>B</i> is the vertical anti-derivative of $\boldsymbol{b}$ . The evolution equation for potential vorticit	sure y
$\partial_t \omega + \bar{\boldsymbol{u}} \cdot \boldsymbol{\nabla} \omega = \boldsymbol{\zeta} \cdot \boldsymbol{\nabla} \bar{u}_3 - \overline{\boldsymbol{\nabla} \rho \cdot \boldsymbol{\nabla}^{\perp} \boldsymbol{\nabla}^{\perp} \cdot B} - \nu \overline{(\partial_z \boldsymbol{\nabla} \Theta \cdot \boldsymbol{\nabla} u_3 - \Delta \Theta \partial_z u_3 + \boldsymbol{u} \cdot \boldsymbol{\nabla} \Delta \Theta)},$	(15)
where $\boldsymbol{\zeta} = (\partial_z \bar{u}^{\perp}, \nabla^{\perp} \cdot \bar{u})$ . The balance relation for $\hat{\boldsymbol{U}}$	
$L\hat{U} = F\hat{U} + G(\bar{U},\Theta),$	(16)

where *L* is the elliptic operator, *F* is the linear operator. *L* is elliptic as long as the fluid is stably stratified and  $\nabla \rho$  is not too large.

The potential vorticity is

 $q = \begin{vmatrix} -\varepsilon\nu\Delta\Theta - (1+\varepsilon\omega) & \nabla(\tilde{\mathbf{\Omega}}\cdot\mathbf{\nabla})\Theta \\ (\tilde{\mathbf{\Omega}}+\varepsilon\partial_z\bar{u}^{\perp}) - \varepsilon\nu\partial_z\nabla\Theta & \partial_z(\tilde{\mathbf{\Omega}}\cdot\mathbf{\nabla})\Theta \end{vmatrix},$ 

(17)

which has the same ellipticity conditions with balance relation (16).

The family of characteristics is parameterized by x. We can read as

 $oldsymbol{\chi}(oldsymbol{x}) = {\sf A}oldsymbol{x} + oldsymbol{b}\,,$ 

where

$$\mathsf{A} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & \Omega_y \\ 0 & 0 & 1 \end{pmatrix} \quad \text{and} \quad \boldsymbol{b} = H\boldsymbol{\Omega} \,.$$

## **Thermal Wind Relation**

The fluid domain  $\mathcal{D} = \mathbb{R}^2 \times [-H, 0]$ . The thermal wind relation as

$$\boldsymbol{\Omega} \cdot \boldsymbol{\nabla} \hat{\boldsymbol{u}}_g = -\nabla^{\perp} \boldsymbol{\rho} \,, \tag{5}$$

where  $\rho$  is the density and the geostrophic velocity at any point along the characteristics is

$$\hat{\mu}_{g} \circ \boldsymbol{\chi} = -\int_{-H}^{0} \frac{z}{H} \nabla^{\perp} \rho \circ \boldsymbol{\chi}' - \int_{-H}^{z} \nabla^{\perp} \rho \circ \boldsymbol{\chi}' = \nabla^{\perp} \Theta \circ \boldsymbol{\chi}.$$
(6)

## L1 model for mid-latitude

Euler-Poincaré theorem for continua: u and  $\rho$  satisfy

$$\int_{t_1}^{t_2} l(\boldsymbol{u}, \rho) \, dt = 0 \,.$$
 (7)

 $L_1$ -type model which is the Lagrangian in the order of Rossby number is derived for mid-latitude,

f f 1

## **General Solution**



#### Ideas for future work

• The numerical solution is expected.

• Validity of variational principle for anisotrophic scaling for the equatorial long wave scaling is under progress.

## References

$$L = \int_{\mathcal{D}} \boldsymbol{u} \cdot J\boldsymbol{x} - \rho \, z \, d\boldsymbol{x} + \varepsilon \int_{\mathcal{D}} \boldsymbol{u} \cdot J\boldsymbol{v} + \frac{1}{2} \, |\boldsymbol{u}|^2 - \rho \, \boldsymbol{v} \cdot \boldsymbol{k} \, d\boldsymbol{x}$$
$$= L_0 + \epsilon L_1 \, .$$

We seek v in the form

$$oldsymbol{v} = \mathsf{P}\hat{oldsymbol{v}} + \mathsf{Q}\hat{oldsymbol{v}} + oldsymbol{ar{v}}$$

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