



Verification of flood wave arrival time predictions using remote sensing-derived water levels

Stefania Grimaldi*, Ashley Wright, Jeffrey Walker, and Valentijn Pauwels.

*Stefania.Grimaldi@monash.edu







ent Australian Government

Geoscience Australia





Rationale, study aims, and hypothesis

- 2-Dimensional hydraulic models are essential tools for floodplain inundation modelling.
- Remote sensing-derived flood extent and level (at the wet/dry interface) have been increasingly used for the calibration and validation of hydraulic flood forecasting models.
- Due to their uncertainty and discrete temporal coverage, remote sensing-derived data have been so far seen as a complement to field data.

This study presents a novel remote sensing (RS)-based methodology for the calibration of 2-Dimensional hydraulic flood forecasting models.

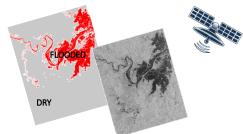
The methodology was designed to meet the following criteria:

- 1) only RS data are employed for model calibration;
- 2) discrimination between underprediction and overprediction of flood wave arrival time;
- 3) limited computational time;
- 4) the selected parameter configuration has to be **robust** for different events.

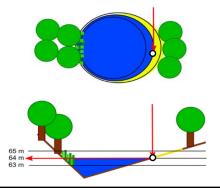
Hypothesis for the application of the methodology:

• <u>roughness</u> is the main parameter affecting flood dynamics.





(b) WET/DRY BOUNDARY POINTS









RS-based calibration: workflow

1 Initial set of model realizations with uniform river roughness (n) values.

E.g.: $n=0.015-0.035 \text{ m}^{1/3} \text{ s}^1 (\Delta n=0.0025 \text{ m}^{1/3} \text{ s}^1)$

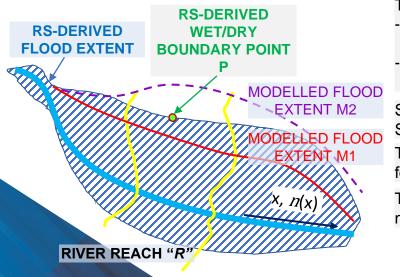
2 Computation of the performance metrics.

2a) RS-DERIVED WET/DRY BOUNDARY POINTS: **Space-Time-Score (new).**

2b) RS-DERIVED FLOOD EXTENT: binary performance metrics (literature).

Steps 2 and 3 are repeated until there is no significant change in the computed river roughness values.

3 Computation of novel set of river roughness values.



The Space-Time-Score (STS) quantifies:

- how far is the observed point P from the modelled flood extent (how far outside in M1/inside in M2);
- how long it takes for model M1 to reach P/for how long P was wet in model M2 → VERIFICATION OF THE FLOOD WAVE ARRIVAL TIME

STS<0 overestimation & early arrival time (STS_o , n_o) STS>0 underestimation & late arrival time (STS_u , n_u)

The STS allows comparing the performances of different model realizations for each river reach "R".

The novel roughness values aims to minimise the discrepancies between

model and observations:

$$n_{new,"R"} = \frac{STS_u * n_o - STS_o * n_u}{STS_u - STS_o}$$

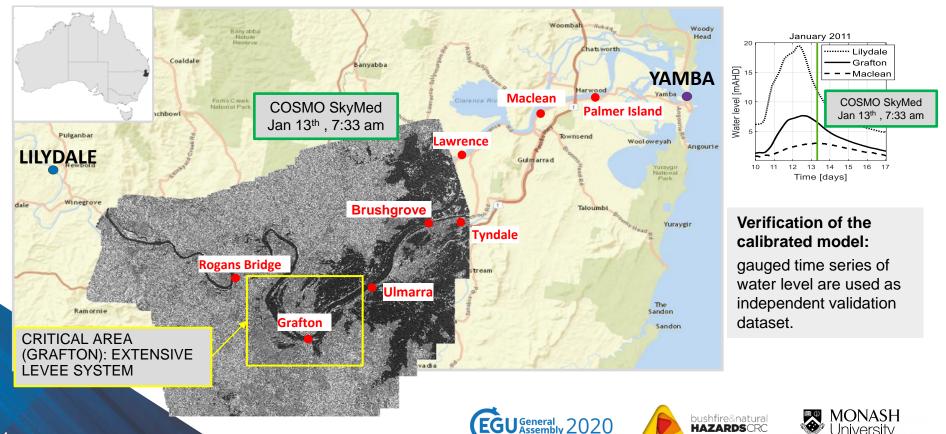






Test case 1: Clarence River (Australia), January 2011

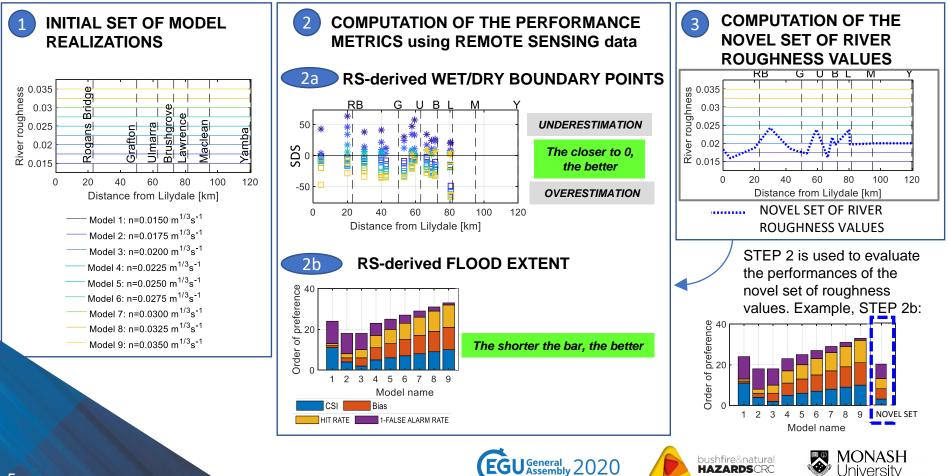
Remote Sensing observation: 1 high resolution image, good spatial coverage (63% of the modelled river length); which includes the critical area (Grafton); acquisition time: immediately after the flood peak.



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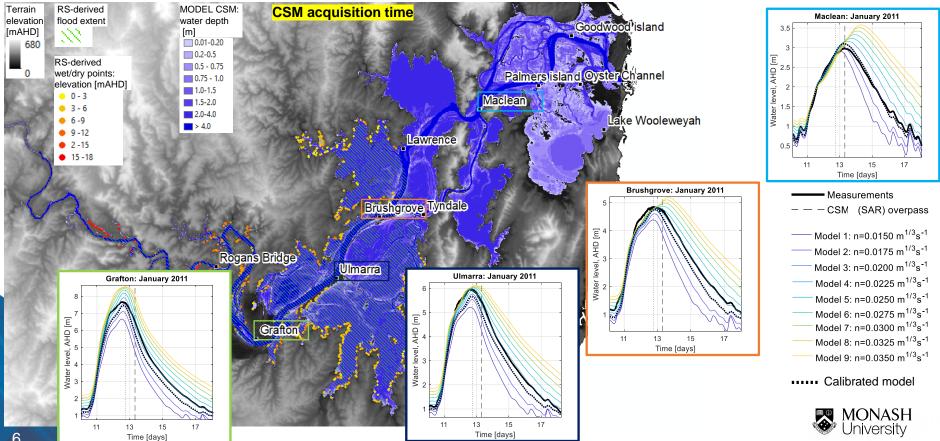
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RESULTS: 2011 flood – schematic of the application of the calibration algorithm



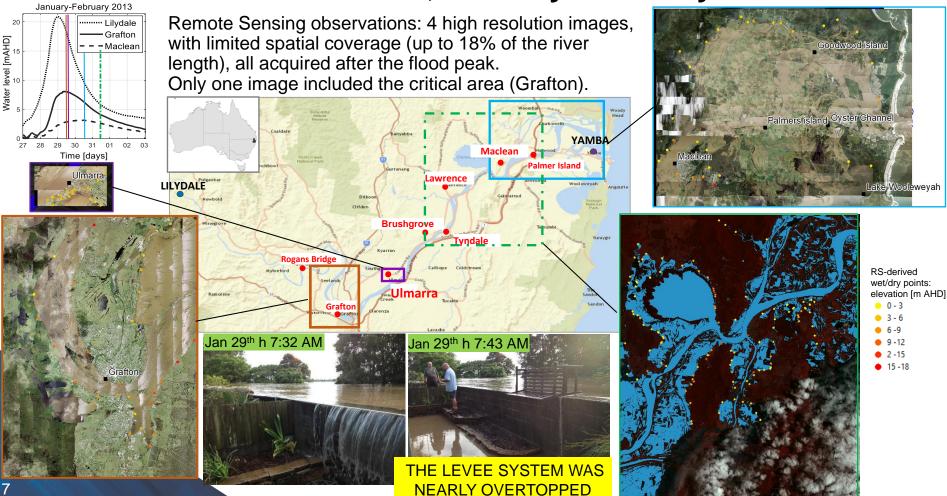
RESULTS: 2011 flood – one "large" image including the critical area

Calibrated model: - comparison between modelled and RS-derived flood extent and wet/dry boundary points; - comparison between modelled and gauged water level (independent validation dataset).



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Test case 2: Clarence River, January-February 2013



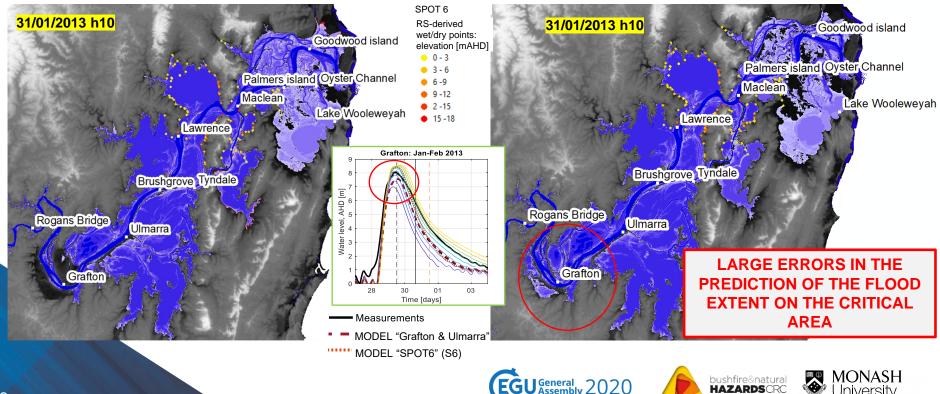
RESULTS: 2013 flood – analysis of the importance of the acquisition footprint

Calibration using two small images (7.5% of river length) including the critical area (Grafton, levees): MODEL "Grafton & Ulmarra"

Calibration using a larger image (18%) acquired downstream of the critical area: MODEL "SPOT6" [figures: wet/dry points from SPOT6, 31/01/2013 h10]

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Summary and future work

- This study proposed a calibration methodology that makes exclusive use of RS-derived observations and consequently enables model calibration in ungauged catchments.
- RS observations are used in a two-fold manner: 1) flood extent; 2) wet/dry boundary points.
- A novel performance metric (named Space Time Score) was introduce to discriminate between underprediction and overprediction of flood dynamics (in space and time).
- Differently from a Monte-Carlo approach, this methodology requires a limited number of simulations. Nevertheless there is a potential caveat: the iterations stop when all the available information has been used (but the model could still have poor accuracy).
- The analysis of a number of scenarios demonstrated the importance of the footprint of RS acquisitions.
- The accuracy of RS-derived observation and terrain data clearly affects the effectiveness of the calibration exercise.
- Future research include:
 - the analysis of the impact of remote sensing uncertainty on the effectiveness of the calibration methodology.
 - the testing of a large number of case studies to investigate the impacts of different catchment morphologies, flood dynamics, image resolution and accuracy on the results of the calibration methodology.





