

# Explicit nonlinear waves of fluid models on extended domains and unbounded growth with backscatter

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# Rotating shallow water equations with backscatter

We consider here the rotating shallow water equations with backscatter (red terms) on the unbounded domain  $\mathbb{R}^2$

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = -f \mathbf{v}^\perp - g \nabla \eta - \begin{pmatrix} d_1 \Delta^2 + b_1 \Delta & 0 \\ 0 & d_2 \Delta^2 + b_2 \Delta \end{pmatrix} \mathbf{v}$$

$$\frac{\partial \eta}{\partial t} + (\mathbf{v} \cdot \nabla) \eta = -(H_0 + \eta) \operatorname{div}(\mathbf{v}).$$

- Velocity field  $\mathbf{v} = \mathbf{v}(t, \mathbf{x}) \in \mathbb{R}^2$  and deviation  $\eta = \eta(t, \mathbf{x}) \in \mathbb{R}$  with characteristic fluid depth  $H_0 > 0$  and fluid thickness  $H_0 + \eta$ .
- Here simplified backscatter, which comes from the subgrid parametrisation and is intended to provide energy consistency in the simulations (e.g. [Jansen & Held, 2014]).
- We are looking for solutions of the full nonlinear equations, which we call explicit solutions here.

# Explicit solutions

We consider solutions of the form

$$\mathbf{v}(t, \mathbf{x}) = \psi(t, \mathbf{k} \cdot \mathbf{x})\mathbf{k}^\perp, \quad \eta(t, \mathbf{x}) = \phi(t, \mathbf{k} \cdot \mathbf{x}),$$

with wave-vector  $\mathbf{k} \in \mathbb{R}^2$  and sufficiently smooth wave-shapes  $\psi$  and  $\phi$ .

- With this approach the nonlinear terms of the material derivative vanish, since the gradient of  $\psi$  and  $\phi$  are orthogonal to the velocity  $\mathbf{v}$  (for more details also in other models see [Prugger & Rademacher]).
- A linear problem remains, which implies a linear behavior of the explicit solutions, as long as the orthogonality condition is satisfied.
- The usual shallow water equations (choosing  $b_i, d_i = 0$ ) for example, have the large set of explicit stationary geostrophic solutions

$$\mathbf{v}(\mathbf{x}) = \psi'(\mathbf{k} \cdot \mathbf{x})\mathbf{k}^\perp, \quad \eta(\mathbf{x}) = \frac{f}{g}\psi(\mathbf{k} \cdot \mathbf{x}),$$

for any wave-vector  $\mathbf{k} \in \mathbb{R}^2$  and wave-shape  $\psi \in C^2(\mathbb{R})$ .

# Explicit solutions

The whole equations with backscatter have explicit solutions

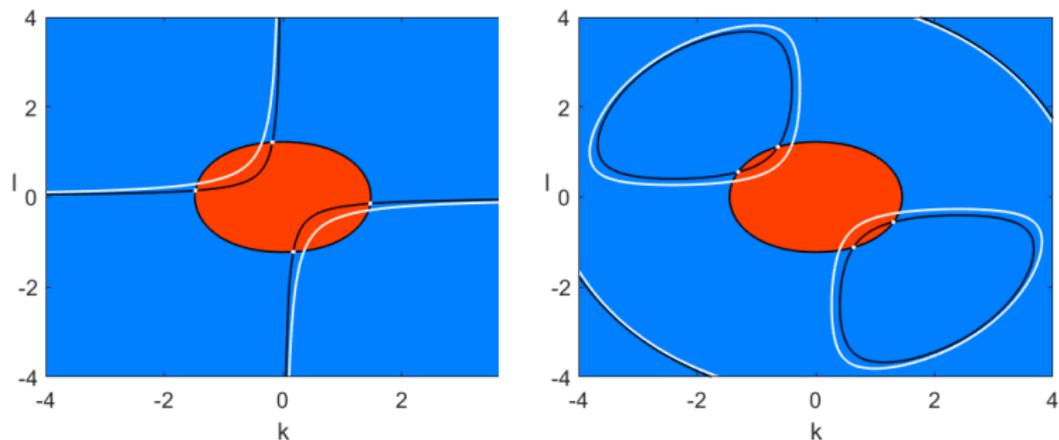
$$\mathbf{v}(t, \mathbf{x}) = \alpha_1 e^{\beta t} \cos(\mathbf{k} \cdot \mathbf{x} + \delta) \mathbf{k}^\perp, \quad \eta(\mathbf{x}) = \alpha_2 \frac{f}{g} \sin(\mathbf{k} \cdot \mathbf{x} + \delta)$$

with  $\beta = 0$  or  $\alpha_2 = 0$ , and satisfying the conditions

$$\beta = (b_1 - d_1 \|\mathbf{k}\|^2) k_2^2 + (b_2 - d_2 \|\mathbf{k}\|^2) k_1^2,$$
$$\frac{\alpha_2 - \alpha_1}{\alpha_1} f = ((d_1 - d_2) \|\mathbf{k}\|^2 + b_2 - b_1) k_1 k_2.$$

- There are stationary and exponentially growing/decaying flow.
- These explicit solutions have arbitrary amplitudes.
- Superposition of these solutions with vector  $s\mathbf{k}$  and arbitrary factor  $s \in \mathbb{R}$  are also explicit solutions.

## Example of the existence of explicit solutions

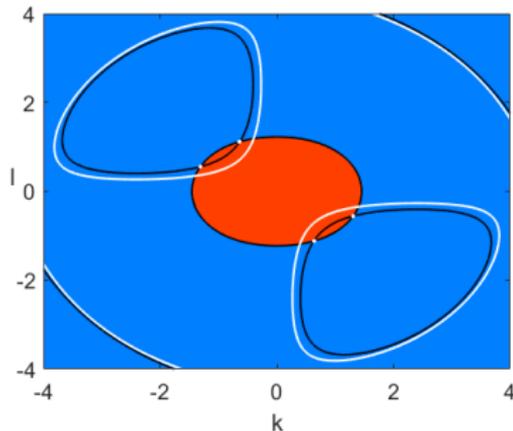


**Figure:** Left:  $d_2 = 1, \alpha_2 = 0.5$ , right:  $d_2 = 1.04, \alpha_2 = -0.5$ . Red:  $\beta > 0$ , blue  $\beta < 0$ . White solid: existence of the solutions for  $\alpha_2 = 0$ , white dots  $\alpha_2 \neq 0$ . Black curves:  $\beta$  for  $\alpha_2 \neq 0$ . Fixed parameters:  $d_1 = 1, b_1 = 1.5, b_2 = 2.2, f = 0.3, g = 9.8, H_0 = 0.1, \alpha_1 = 1$ .

# Instability of some explicit solutions

An important question is the stability of stationary flow. For some of them we can show that they are unstable:

- We consider the explicit stationary solution, which is described by one of the white dots on the black ellipse.
- Superpose with an exp. increasing solution (white curve on the red region) with wave-vector in the same direction.
- This yields an explicit solution, which is a perturbation of the stationary flow and is exp. increasing in time.



# Summary and conclusion

- The orthogonality between wave-vectors and velocity-directions can remove the nonlinear terms caused by the material derivative.
- The remaining linear problem implies a certain linear behavior of the explicit solutions.
- With this property we can show the instability of certain explicit stationary flow.
- This approach of finding explicit solutions of the full nonlinear problem can be used in different fluid models, but we focused on the backscatter model here.
- Here: energy accumulates in selected scales, causing exponentially and unboundedly growing ageostrophic nonlinear flow.

Thank you for your attention!



Artur Prugger & Jens D. M. Rademacher:

*Explicit internal wave solutions in nonlinear fluid models on the whole space.*

2020, in preparation, arXiv link: <https://arxiv.org/abs/2003.07824>



Malte F. Jansen & Isaac M. Held:

*Parameterizing subgrid-scale eddy effects using energetically consistent backscatter.*

Ocean Modelling, Vol. 80, 2014, pp. 36-48