Soil erosion monitoring at small scales: Using close range photogrammetry and laser scanning to evaluate initial sediment delivery

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Introduction

Soil erosion represents one of the most significant environmental problems of the 21st century with severe impacts on terrestrial ecosystems. Traditionally, soil losses by water are determined by runoff plots in situ. Micro-scale devices (<1 m length) are commonly used to monitor soil erosion rates in comparative field studies. This is especially the case in ecological-pedological experiments, investigating e.g. the effect of plant characteristics on erosion processes. The small plot size allows to focus precisely on interrill processes with the smallest possible set of confounding factors and a high replication. However, the runoff plot method is labor- and time-intensive, sediment handling can be challenging and the measurement accuracy varies importantly with set-up maintenance and control. To optimize the acquisition of erosion data from splash and interrill processes, digital methods become more and more of interest. Thus, the objective of this study was to transfer those approaches to smaller scale and

I. to compare different methods to create repeatable 3D point clouds of soil surfaces with sub-millimeter resolution

II. to evaluate their accuracy and the reliability of measurements.

Material & Methods

Runoff Plots: micro-scale (0.4 m x 0.4 m) with hortic anthrosol or sand (0.1-0.45 mm) substrate

Reference frame with 24 ground control points and 4 laser scan targets

Discharged sediment weighed for ground-truth

Treatments: a) terrestrial (TC) and b) airborne camera (AC) and c) terrestrial laser scanner (TLS)

Image Creation:

Digital camera: Panasonic Lumix DC, 24 MP mounted on rack or UAV, respectively

Terrestrial laser scanner: Leica ScanStation P40

Image Processing:

Referencing, image matching, processing of digital elevation models (DEM) and photogrammetry (Structure from Motion) with Agisoft PhotoScan 1.5.1 (a, b) and calculation of 3D point clouds with Leica Cyclone (c)

DEM refinement, calculation of volumes, Cut&Fill, evaluation with ESRI ArcGIS 10.5 and CloudCompare 2.8.1

Rainfall Simulation: Tübingen Rainfall simulator intensity 80 mm h⁻¹, drop fall height 3.8 m

15 replications for every treatment and substrate

Results

Erosion Rates and Surface Changes:

Mean discharge weighed (mean surface change):

<table>
<thead>
<tr>
<th>Sterilization</th>
<th>Sand</th>
<th>Anthrosol</th>
</tr>
</thead>
<tbody>
<tr>
<td>TC</td>
<td>118.5 g</td>
<td>36.2 g</td>
</tr>
<tr>
<td>TLS</td>
<td>161.6 g</td>
<td>70.5 g</td>
</tr>
</tbody>
</table>

Mean discharge calculated:

<table>
<thead>
<tr>
<th>Sterilization</th>
<th>Sand</th>
<th>Anthrosol</th>
</tr>
</thead>
<tbody>
<tr>
<td>TC</td>
<td>137.8 g</td>
<td>48.6 g</td>
</tr>
<tr>
<td>TLS</td>
<td>0.542 mm</td>
<td>0.167 mm</td>
</tr>
</tbody>
</table>

Treatment b (AC) strongly overestimated erosion rates and results could not be used

TC underestimated, whereas TLS over-estimated sediment discharge

Calculated erosion rates differed from weighed sediment discharge (TC and TLS) up to 45%

Accuracy was higher for uniform sand than for the hortic anthrosol treatment

Increasing accuracy of volume calculations with increasing sediment losses

Sources of Error:

- Resolution of images to capture sub-millimeter surface changes
- Precision of measurements in the field (e.g. accurate positioning of the camera)
- Precision of software processing (e.g. linking of ground control points)
- Conditions of (artificial) illumination
- Compaction of investigated substrates by raindrop impacts

Conclusion & Outlook

The presented methods appear to be promising tools for process studies on small-scale soil erosion. Suitable small-scale 3D point clouds to map topography differences from initial soil erosion could be derived. Nevertheless, the precise quantification of sediment loss still needs further refinement. In particular, an exact application of techniques in the field, higher resolution of images as well as improved and more reliable software processing is needed. In particular, further experiments with light-weight and high resolution laser scanners are regarded as promising.

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