

# ON THE NECESSITY OF ENERGY BALANCED NON-HYDROSTATIC PRESSURE MODELS FOR FREE SURFACE FLOWS OVER COMPLEX TOPOGRAPHY

I. Echeverribar<sup>1</sup> / P. Brufau<sup>1</sup> / P. García-Navarro<sup>1</sup>  
<sup>1</sup> University of Zaragoza, email: echeverribar@unizar.es

## MOTIVATION

SWE widely used for numerical geophysical applications. Limitations arise when dealing with dispersive effects



Dispersive effects can be found when dealing with complex topographies and a non-hydrostatic profile appears.



A SW model is compared with a non-hydrostatic pressure (NHP) model to analyse their behaviour in different test cases

## NON-HYDROSTATIC PRESSURE MODEL EQUATIONS

The depth-averaged system is based on conservation laws as in [1]:

- Mass and x momentum equations:

$$\begin{cases} \frac{\partial h}{\partial t} + \frac{\partial(hu)}{\partial x} = 0 \\ \frac{\partial(hu)}{\partial t} + \frac{\partial}{\partial x} \left( hu^2 + \frac{1}{2}gh^2 \right) + gh \frac{\partial z_b}{\partial x} = -\frac{1}{2} \left( h \frac{\partial p}{\partial x} + p \frac{\partial(h+2z_b)}{\partial x} \right) \end{cases}$$

Non-hydrostatic terms

- Development of the continuity equation [1] that must be fulfilled and is used to solve  $p$ :

$$h \frac{\partial(hu)}{\partial x} + 2hw + (hu) \frac{\partial}{\partial x} (h + 2z_b) = 0$$

- And the z momentum equation neglecting convective terms [1]

$$\frac{\partial w}{\partial t} = \frac{p}{h}$$

## NUMERICAL SCHEME

The system is solved in two steps:

- First, the hydrostatic part is solved with a FV first-order scheme [2] as a pure SW system, updating each cell with a ARoe solver [2]:

$$\begin{aligned} (h)_i^* &= (h)_i^{n+1} = (h)_i^n - \Delta t / \Delta x \left[ \delta \mathbf{f}_{i-1/2}^+ + \delta \mathbf{f}_{i+1/2}^- \right] \\ (hu)_i^* &= (hu)_i^n - \Delta t / \Delta x \left[ \delta \mathbf{f}_{i-1/2}^+ + \delta \mathbf{f}_{i+1/2}^- \right] \end{aligned}$$

- Secondly, the Pressure Correction Method is solved implicitly so the  $p$  can be computed at cell edges from continuity eq.
- Once  $p$  is obtained, the velocity field in  $x$  and  $z$  is updated up to  $n+1$

$$\begin{aligned} (hu)_i^{n+1} &= (hu)_i^* - \Delta t / 2 \left[ h_i \frac{p_{i+1/2} - p_{i-1/2}}{\Delta x} + p_i \frac{(h+2z)_{i+1} - (h+2z)_{i-1}}{2\Delta x} \right] \\ w_{i+1/2}^{n+1} &= w_{i+1/2}^n + \Delta t \frac{p_{i+1/2}^{n+1}}{h_{i+1/2}^{n+1}} \end{aligned}$$

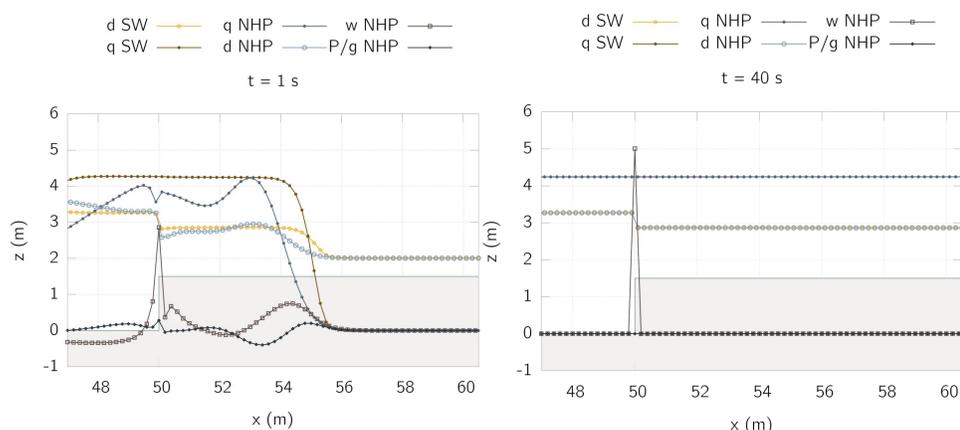
- Note the index of the variables. Since a staggered grid is used,  $p$  and  $w$  are edge values, whereas  $h$  and  $hu$  are cell centered.

## RESULTS

### IDEALIZED DAMBREAK (AUGMENTED RIEMANN PROBLEM, RP)

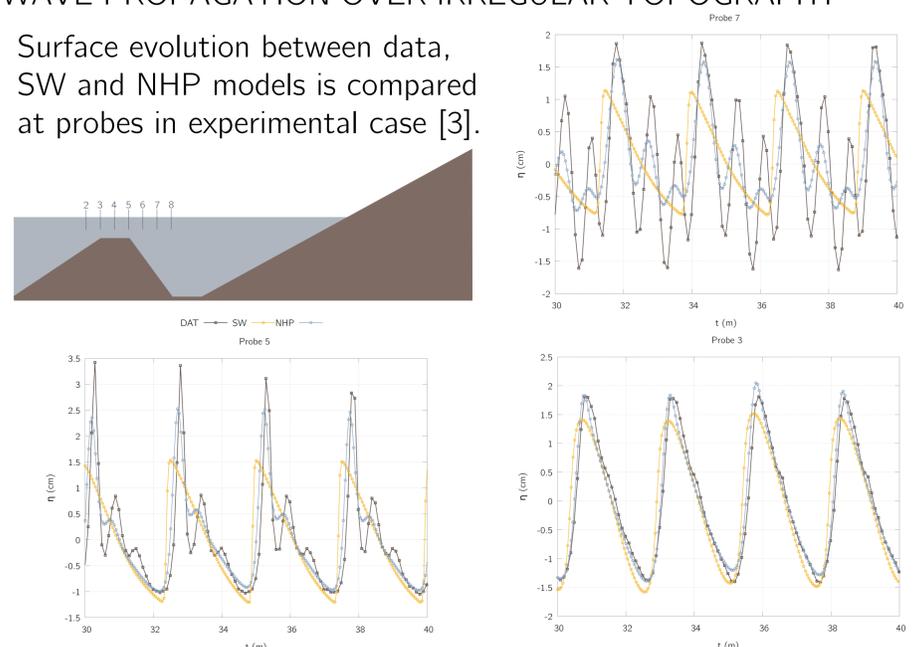
- Aug. RP converges to same steady state w/ different unsteady.

Ini. Cond	h (m)	z (m)	u (m/s)
Left	4,0	0	0,1
Right	0,505	1,5	0



### WAVE PROPAGATION OVER IRREGULAR TOPOGRAPHY

- Surface evolution between data, SW and NHP models is compared at probes in experimental case [3].



## CONCLUDING REMARKS AND FUTURE WORK

- The NHP model shows a good agreement with experimental data in [3]. However, some discrepancies are observed in high frequency waves due to an energy transfer [3] that is not reproduced.
- Augmented RP are properly solved with NHP models. However, they do not preserve energy balance in steady states if the approach in [2] is used.
- An adaptation of numerical energy balance approach must be found for NHP models

