

AIM

Assimilate Paleomagnetic data to reconstruct the motion of continents over the last **hundreds of Myr**, while preserving basic **geodynamical principles**.

MOTIVATION

- Using **plate tectonic theory**, we can integrate a wide range of geological and geophysical observations to produce **kinematic plate tectonic reconstructions**. These reconstructions are built via a **largely manual process** of integrating many individual time-dependent regional tectonic histories into a **geometrically self-consistent global model**, making the **quantitative estimation of uncertainties** very complex.
- The **particle filter** provides a statistically consistent framework within which one can assimilate **data of variable nature and source** within a **dynamical model**, providing quantitative uncertainties on the estimated trajectory of the system.

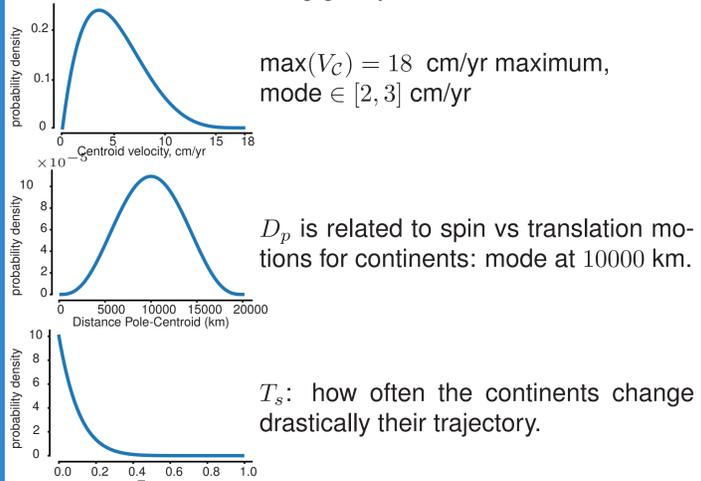
Here, we demonstrate a first step to building a data assimilation framework for plate tectonics reconstructions: we apply a particle filter to reconstruct time-dependent continental configurations and motions.

THE FORWARD MODEL

Continents motions are **solid body rotations**: At Each timestep, we compute the rotation of each continent during the time δt (here 1 Myrs). This rotation is determined by 3 parameters:

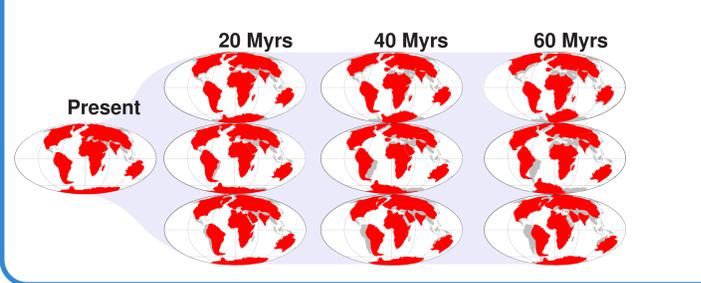
- D_p , the distance from continent centroid to the Euler pole (pole of rotation)
- V_C , the velocity of the continent's centroid
- T_s , the fraction of the current rotation to be kept for the next rotation

Computation of the Random drift for each continent: D_p , V_C and T_s are **random variables**. Each of them follows a beta function. We choose the parameters (a, b) of those beta functions to fit the following geodynamical constraints:

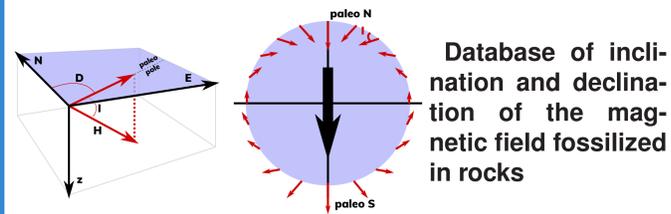


Collision rules: If during a timestep, two continents overlap each other, then they form a cohesive block and are rotated together.

EXAMPLE RANDOM DRIFT SCENARIO



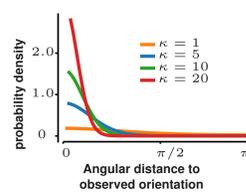
OBSERVATIONS



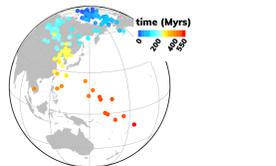
Uncertainties modelled with Fisher statistics:

$$p(\mathbf{h}^p | \mathbf{h}^o, \kappa) = C(\kappa) \exp(\kappa [\mathbf{h}^o]^T \mathbf{h}^p)$$

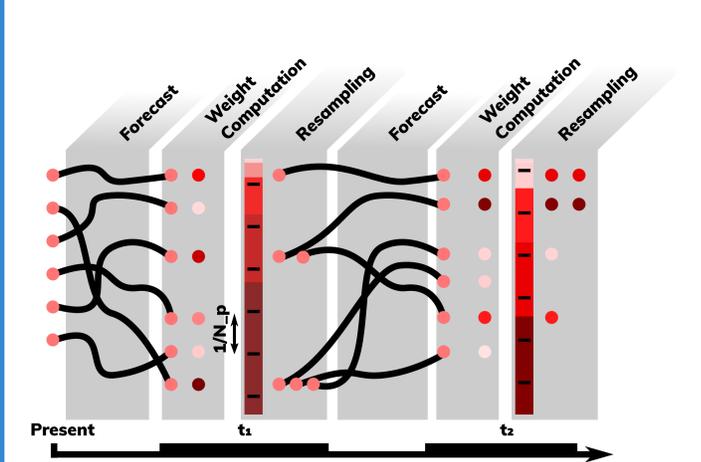
$$\text{with } C(\kappa) = \frac{\kappa}{2\pi(e^\kappa - e^{-\kappa})}$$



North America paleopoles computed from the inclination declination database used in Tetley [2018], dated from 0.5 to 550 Ma



DATA ASSIMILATION METHOD



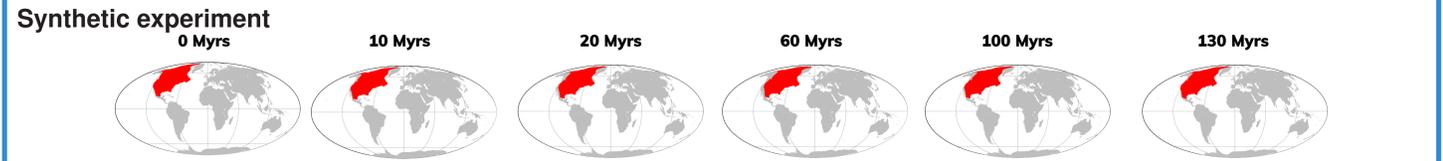
We use a particle filter [van Leeuwen et al., 2018]:

Initial setup
 N_p particles $\{\mathbf{x}_0^{n_p}\}_{n_p \in [1, N_p]}$ with identical continental blocks, but different random rotations.
 weight: $\{\omega_0^{n_p} = 1/N_p\}_{n_p \in [1, N_p]}$
 pdf: $p(\mathbf{x}_0) = \prod_{n_p=1}^{N_p} \omega_0^{n_p} \delta(\mathbf{x}_0 - \mathbf{x}_0^{n_p})$, with δ the dirac function.

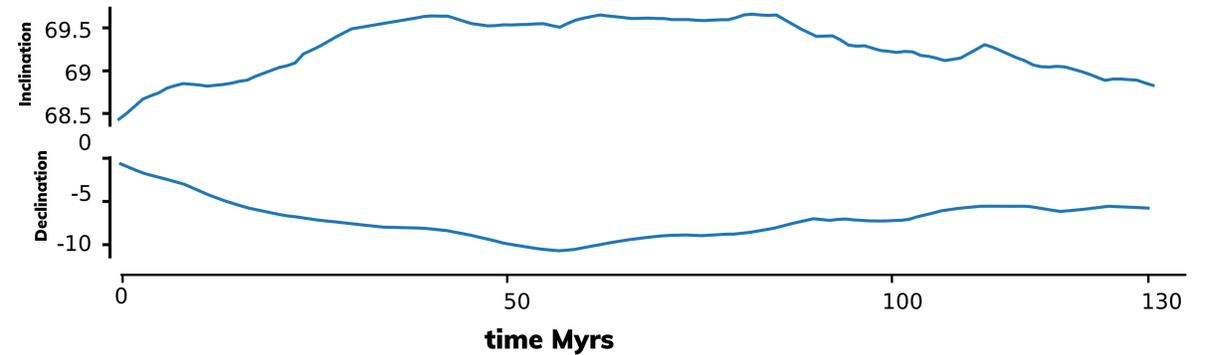
loop over observations:

- Forecast:** see forward model.
- weight computing:** $\forall n_p \in [1, N_p]$, $\omega_k^{n_p} = \frac{p(\mathbf{y} | \mathbf{x}_k^{n_p})}{\sum_{j=1}^{N_p} p(\mathbf{y} | \mathbf{x}_k^j)}$ with $p(\mathbf{y} | \mathbf{x}_k)$ a multivariate Fisher distribution with each component independant of the other.
- Stochastic universal resampling.**

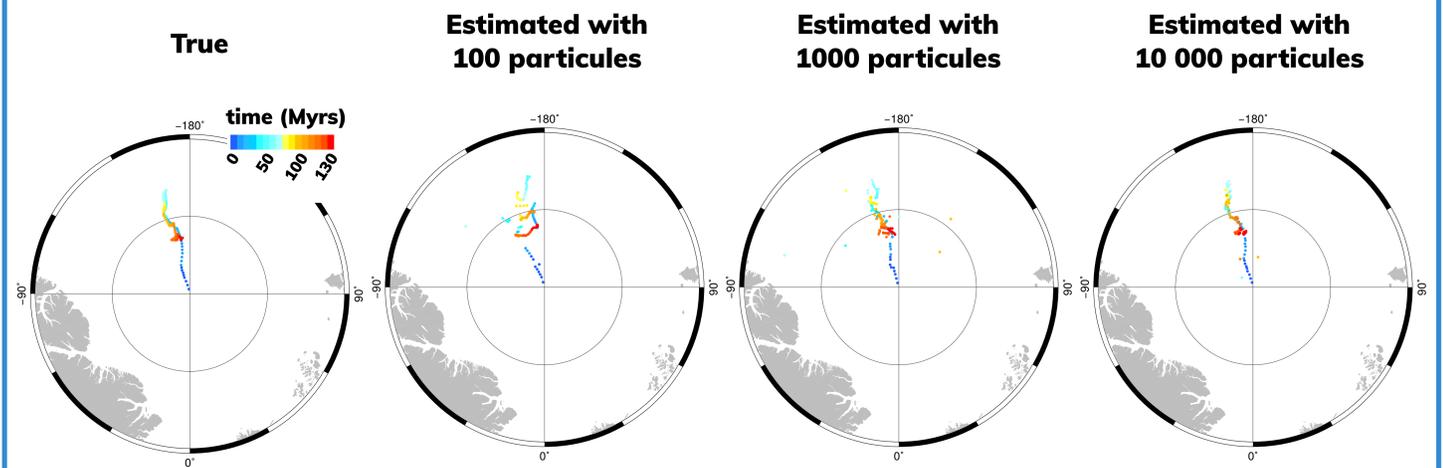
PRELIMINARY TESTS



Observations



Apparent polar Wander



CONCLUSIONS

- We have developed a data assimilation framework for paleomagnetic data:
 - based on the **Particle Filter**,
 - with a continental drift model **consistent with basic geodynamics rules**,
 - where the uncertainties on observations are taken into account.
- For single continents synthetic experiments, a number of particles of ca. 10000 allows us to estimate the trajectory of continents for at least 130 Myrs.

THE WAY FORWARD

- Perform synthetic tests with data at multiple sites and on different continents
- Optimize forward code to allow for more particles
- test different resampling techniques, while conserving geodynamical constraints.

REFERENCES

Michael G. Tetley. *Constraining Earth's plate tectonic evolution through data mining and knowledge discovery*. University of Sydney, 2018.
 Peter Jan van Leeuwen, Hans R Künsch, Lars Nerger, Roland Potthast, and Sebastian Reich. Particle filters for applications in geosciences. *arXiv preprint arXiv:1807.10434*, 2018.