

On associating significance levels with temporal changes
in empirical orthogonal function analysis:
a case study for ENSO

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Outline

Introduction

Time dependence of λ

Time dependence of EOF

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Temporal changes of what?

- ▶ The variability in a field $T(\mathbf{x}; t)$ is described correctly by an ensemble of different realizations $T_r(\mathbf{x}; t)$ at any given **fixed** time instant t .
- ▶ This variability can be decomposed to EOFs:
$$T_r(\mathbf{x}) = \sum_k \text{PC}_r^{(k)} \text{EOF}^{(k)}(\mathbf{x}).$$
- ▶ An amplitude can be associated with each EOF: $\lambda^{(k)}$.
- ▶ The EOFs and the amplitudes can be different in different “instants of time” (years): e.g., we have $\lambda^{(k)}(t)$ (cf. EGU2020-2894; EGU2020-7527; EGU2020-12061; Maher et al., Geophys. Res. Lett. 45, 11,390, 2018; Haszpra et al., J. Climate 33, 3107, 2020; Haszpra et al., Earth System Dynam. 11, 267, 2020).
- ▶ How do we detect this time dependence if we can only **estimate** these quantities from a finite number of ensemble members?
- ▶ The methodology is the same for any k , we thus omit the index k .

Outline

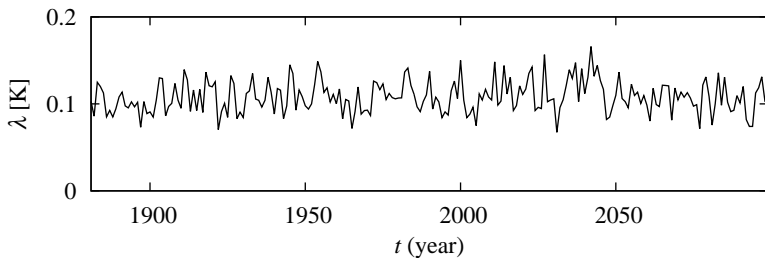
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Example: $\lambda^{(1)}$ of the Pacific SST field

MPI-GE historical+RCP8.5



Do we have a trend here?

Linear fit:

$$(2.08 \pm 2.06)^{-5} \text{ [K/yr]}$$

\implies Yes, we have?

Concept for testing

- ▶ A linear fit provides with an upper bound on the significance level for a temporal change, since
 - ▶ either the dependence is really linear (unlikely),
 - ▶ or not, so that the numerical result is meaningless, but then λ cannot be constant: there **is** a temporal change!
(Thanks to T. Bodai.)
- ▶ However: the errors $\Delta\lambda$ are heteroskedastic and autocorrelated
 - ⇒ the traditional significance level is incorrect
 - ⇒ generalized least squares fit must be used based on the variance-covariance matrix $\sigma_{ij}^2 = \langle \Delta\lambda(t_i)\Delta\lambda(t_j) \rangle$.

Methodology

- ▶ Estimating the variance-covariance matrix of the errors: between years t_i and t_j :

$$\sigma_{ij}^2 = \langle \Delta\lambda(t_i)\Delta\lambda(t_j) \rangle = \frac{1}{N} \langle \text{PC}(t_i)\text{PC}(t_j) \rangle,$$

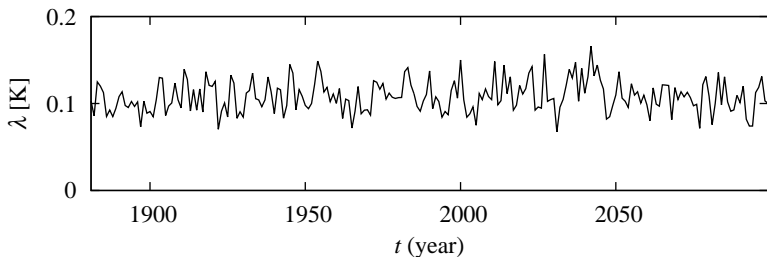
and the latter can be estimated just by using the ensemble!

- ▶ Improving the estimation: fitting a Markovian form to the corresponding correlation matrix:

$$\begin{pmatrix} 1 & \rho_1 & \rho_1\rho_2 \\ \rho_1 & 1 & \rho_2 \\ \rho_1\rho_2 & \rho_2 & 1 \end{pmatrix}$$

(The fit is performed in a sliding window that is long enough to ensure independence on the window size.)

Example revisited



Do we have a trend here?

Linear fit:

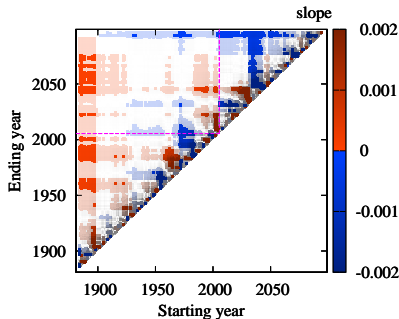
$$(2.08 \pm 2.06) \times 10^{-5} \text{ [K/yr]}$$

$$(0.11 \pm 2.39) \times 10^{-5} \text{ [K/yr]}$$

\implies Not significant.

Subintervals in the example

Grayscale: insignificant, saturated: 5% significant slope.



Yes, there **are** significant trends! (Warning: multiple testing, see [Wilks, BAMS 97, 2263, 2016.](#))

- ▶ Strengthening ENSO before 1900,
- ▶ forced fluctuations until 2050
- ▶ weakening in the late 21st century.

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Future work...