

On the Multi-Technique Combination with Atmospheric Ties

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EGU General Assembly, G2.4: New Strategies for Consistent Geodetic Products and Improved Earth System Parameters

Vienna, May 6th, 2020

Motivation

- ❑ Regardless of space geodetic observing system (GNSS, VLBI, SLR, and DORIS) estimates of
 - ❑ plate tectonics,
 - ❑ satellite orbits,
 - ❑ Earth's rotation, and
 - ❑ atmospheric state
- should –in principle- differ only within measurement error bounds, e.g., Krügel et al. (2007), Thaller et al. (2007), Thaller (2008), Nilsson et al. (2015)
- ❑ Multi-technique combination facilitates distinction of ***genuine geophysical signals*** from ***technique-specific artefacts***, e.g., Rothacher (2002)
- ❑ Improvements in ground co-location (more sites with more systems)

In this presentation

- ❑ Atmospheric ties from a *modeller's* perspective
- ❑ Atmospheric ties from a *geodesist's* perspective

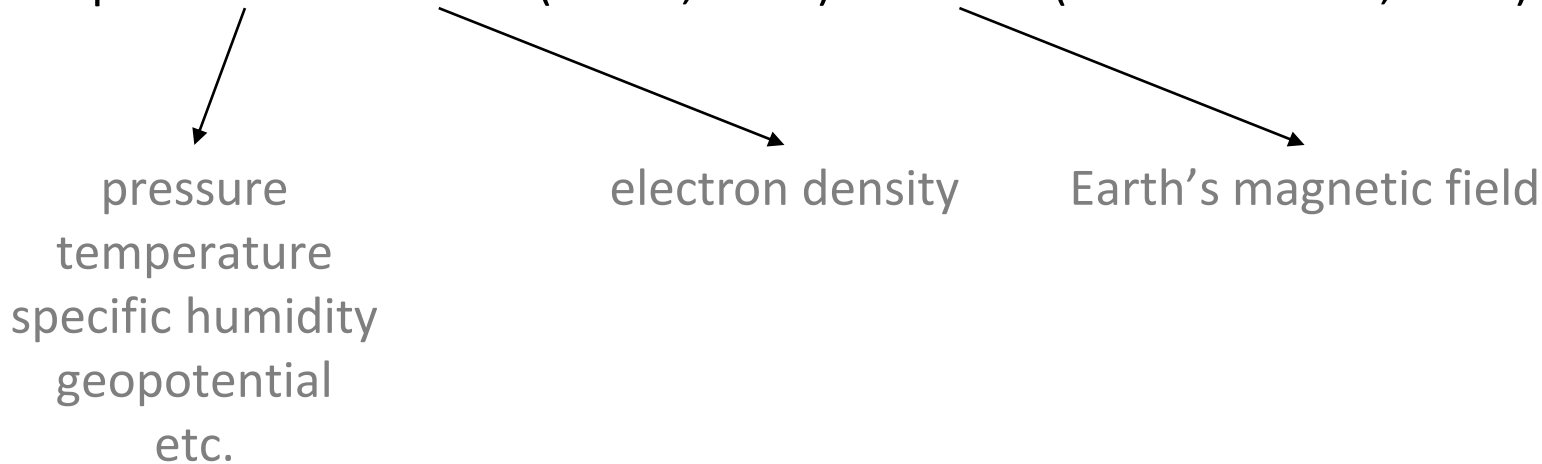
Chapter 0

Ray-Tracing

How Are the Atmospheric Delays Calculated?

- ❑ In-house GFZ's **ray-tracing software**: Direct Numerical Simulation (DNS) Tool by Zus et al. (2014)

- ❑ Input: **ERA5** + **IRI2016** (Bilitza, 2018) + **IGRF12** (Thébault et al., 2015)



Chapter I

Definition of Atmospheric Ties

What Are Atmospheric Ties?

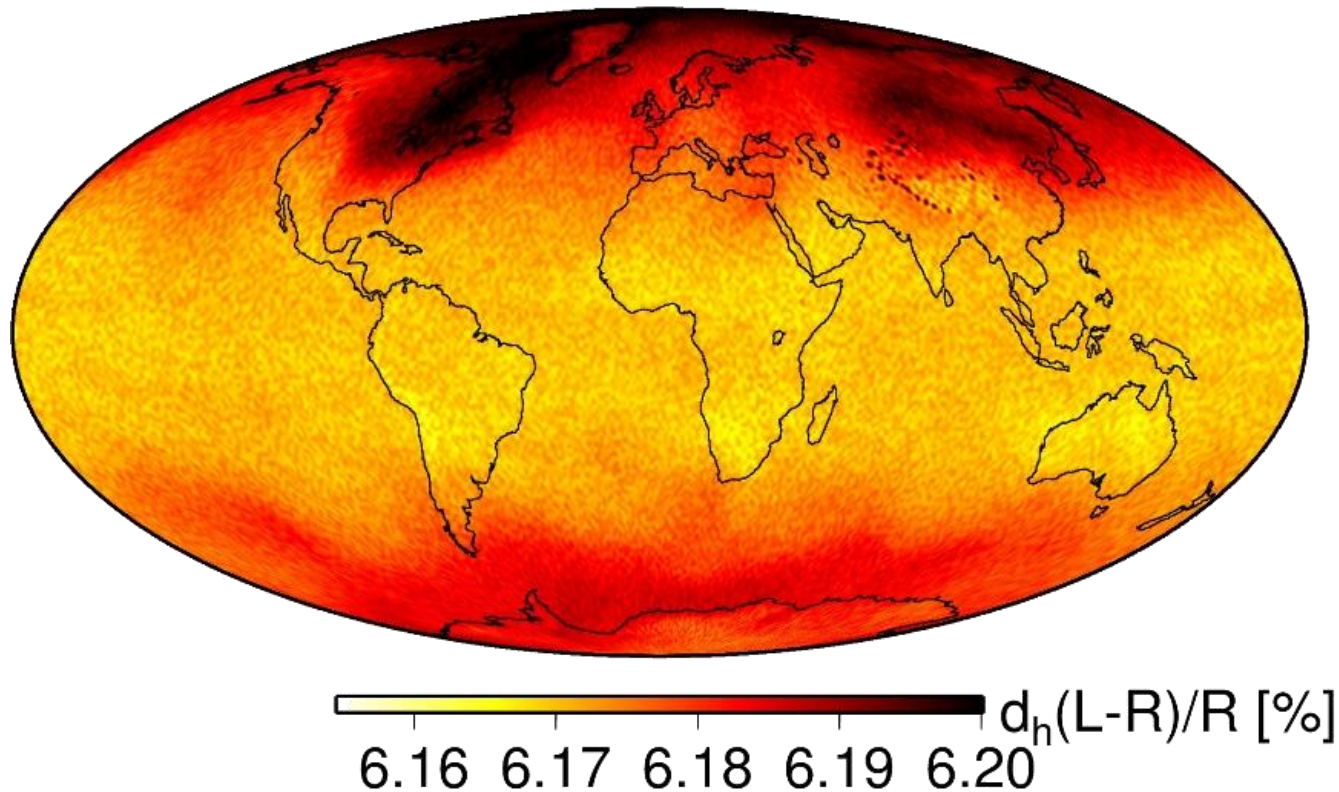
- ❑ Expected differences between atmospheric parameters at co-locations obtained ***independently*** of space geodetic methods
- ❑ Useful for intra- and inter-technique combination (e.g., Krügel et al., 2007; Thaller, 2008)
- ❑ Systematic discrepancies due to:
 - ❑ **frequency** difference (microwave, optical);
 - ❑ **position** difference (mainly height); and
 - ❑ **observing system** differences (technique, geometry, hardware)
- ❑ IAG JWG Tropospheric Ties (Heinkelmann et al., 2016)
... continued for a second term by Kyriakos Balidakis & Daniela Thaller

Chapter II

Frequency-Induced Differences

Zenith Hydrostatic Delays

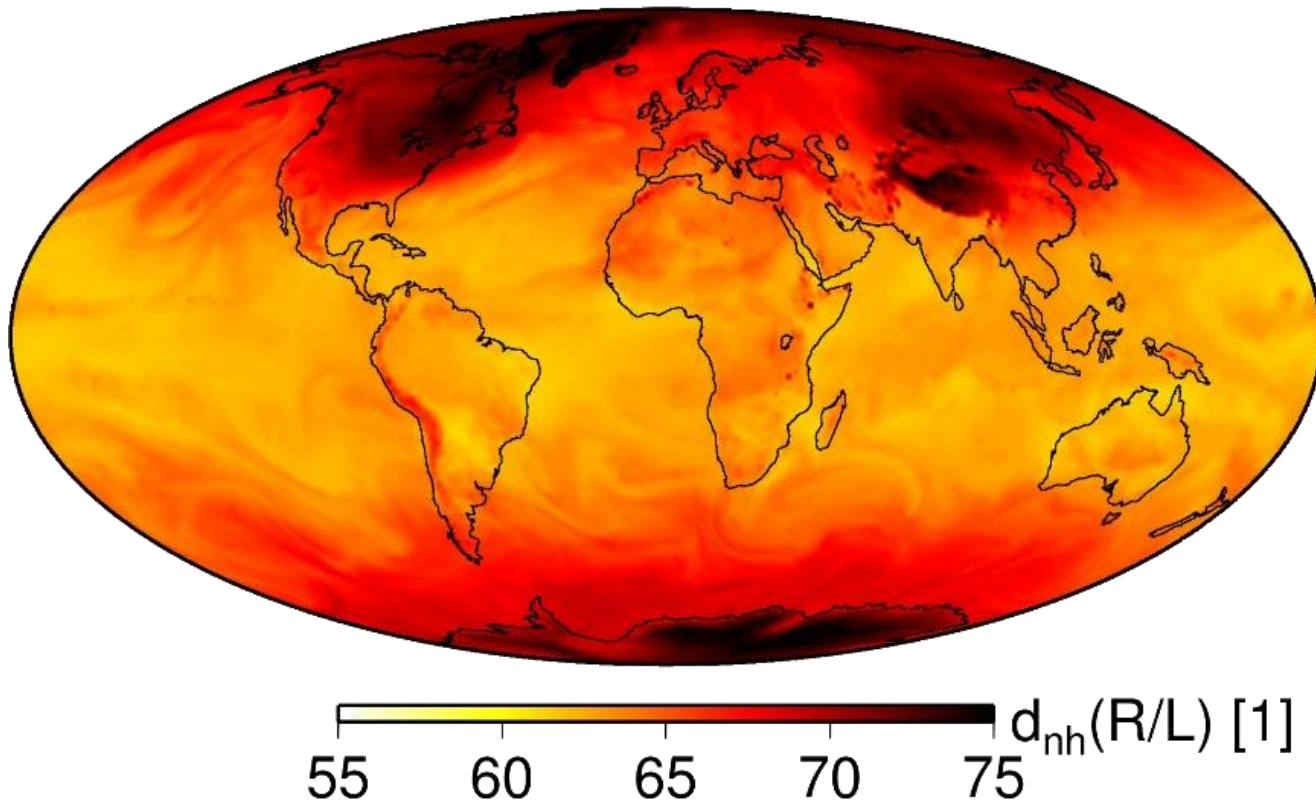
- ❑ SLR@532nm **6% larger** than VLBI/GNSS/DORIS



Balidakis (2019)

Zenith Non-Hydrostatic Delays

- ❑ SLR@532nm **66 times smaller** than VLBI/GNSS/DORIS



Balidakis (2019)

Asymmetric Delays I

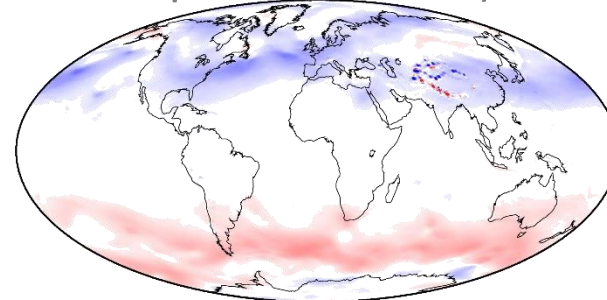
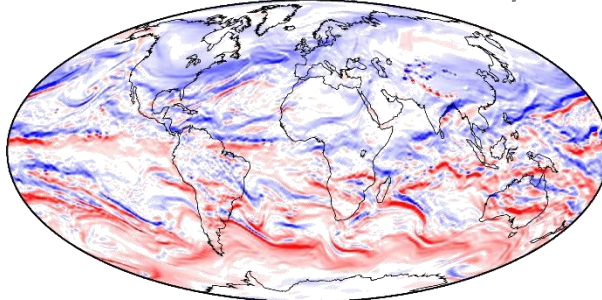
- Linear gradient components

1mm gradient $\approx$
3cm@10 degrees

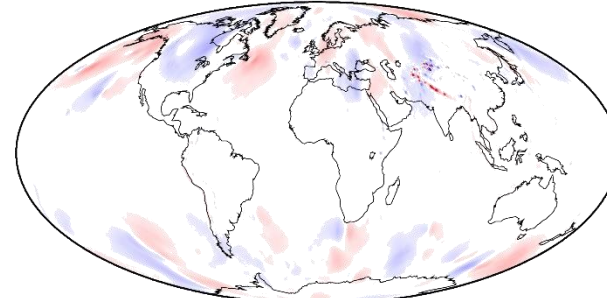
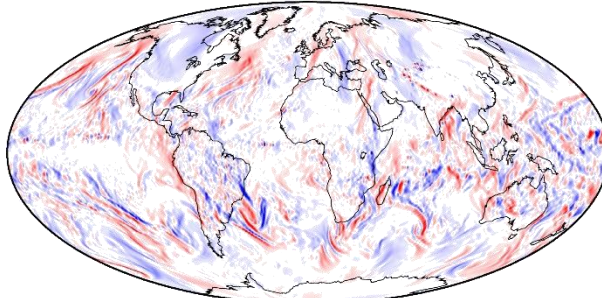
microwave (L-Band)

optical (532 nm)

North-South



East-West



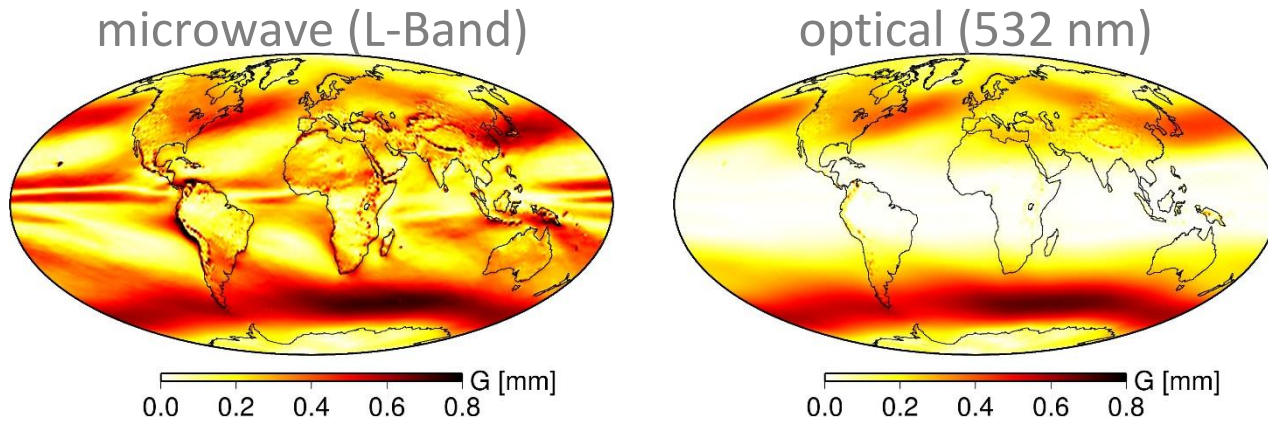
- Spatio-temporally noisy for microwave, smooth for optical

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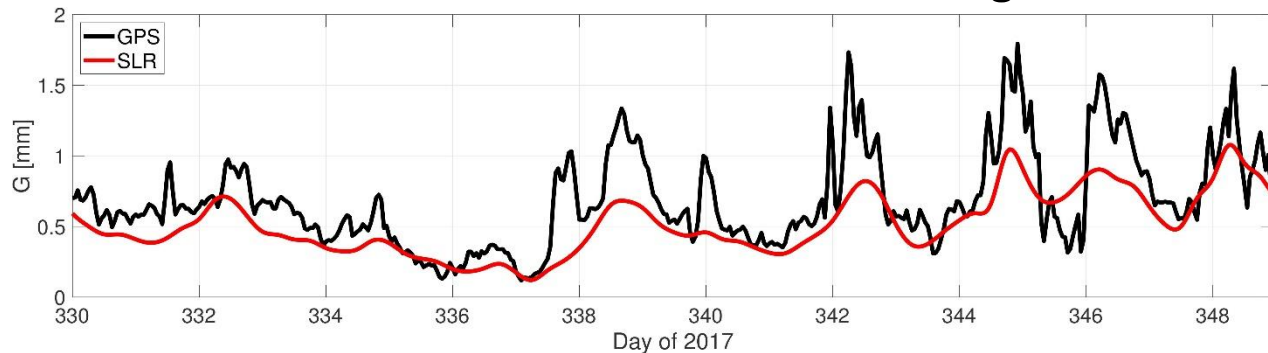
Asymmetric Delays II

- 40-year average asymmetric delay amplitude

$$G = \sqrt{G_{NS}^2 + G_{EW}^2}$$



- Hourly gradient estimates from ERA5 at Wettzell during CONT17



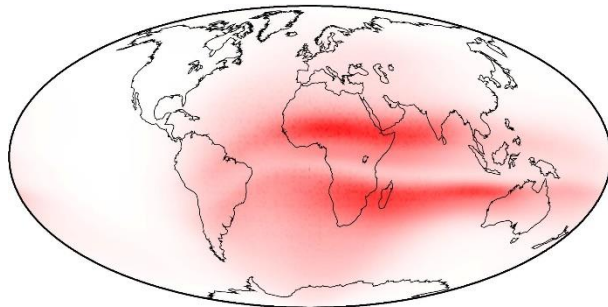
Ray-Bending due to Ionospheric Refraction

Based on ERA5, IRI2016, IGRF2014, $\varepsilon = 3^\circ$, $\alpha = 0^\circ$

$$\int (1 + 10^{-6}N) ds_i - \int (1 + 10^{-6}N) ds_\infty$$

N : refractivity, s_i : arc length, s_∞ : arc length in the hypothetical absence of ionosphere

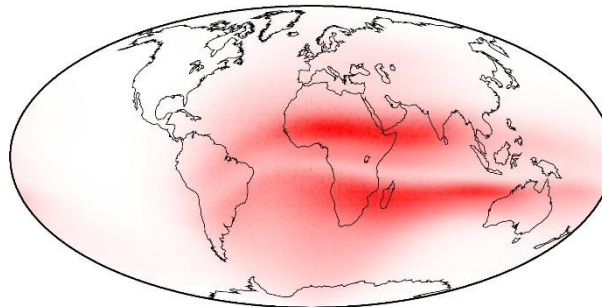
VLBI X-band



-4 -2 0 2 4 d [0.001 mm]

expected $\delta H \approx 0.4 \mu\text{m}$

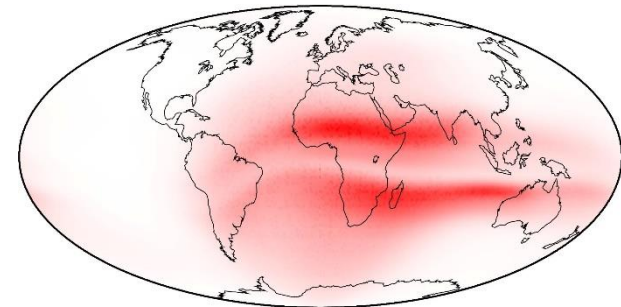
GPS L-band



-3.0 -1.5 0.0 1.5 3.0 d [mm]

expected $\delta H \approx 0.4 \text{ mm}$

DORIS UHF-band



-800 -400 0 400 800 d [mm]

expected $\delta H \approx 100 \text{ mm}$

Note the different colour scales!

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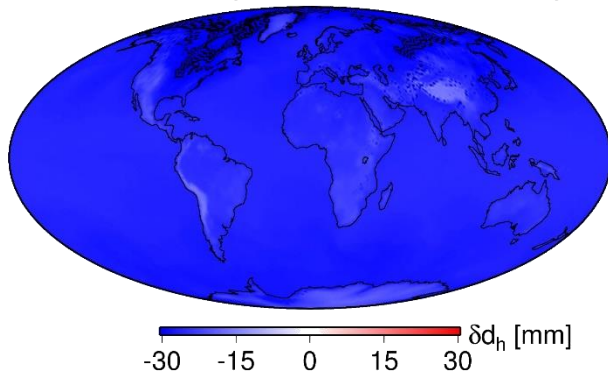
Chapter III

Position-Induced Differences

Height-Related Differences

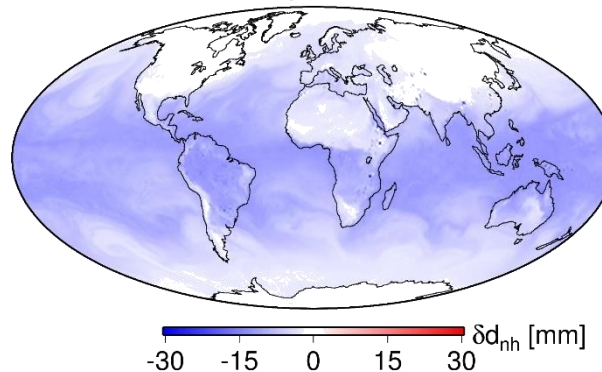
- 100 m height difference (Galileo)

Zenith hydrostatic delay



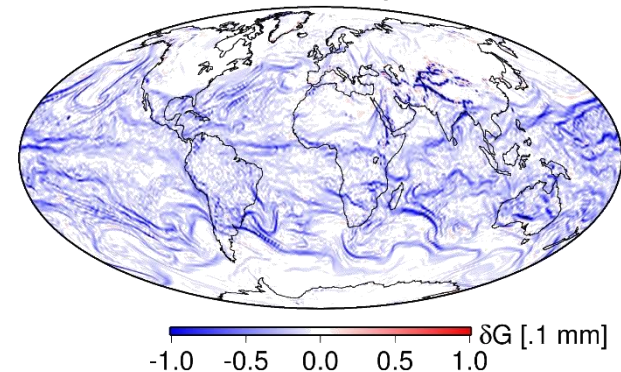
−27 mm on average

Zenith non-hydrostatic delay



−3 mm on average

Gradient amplitude



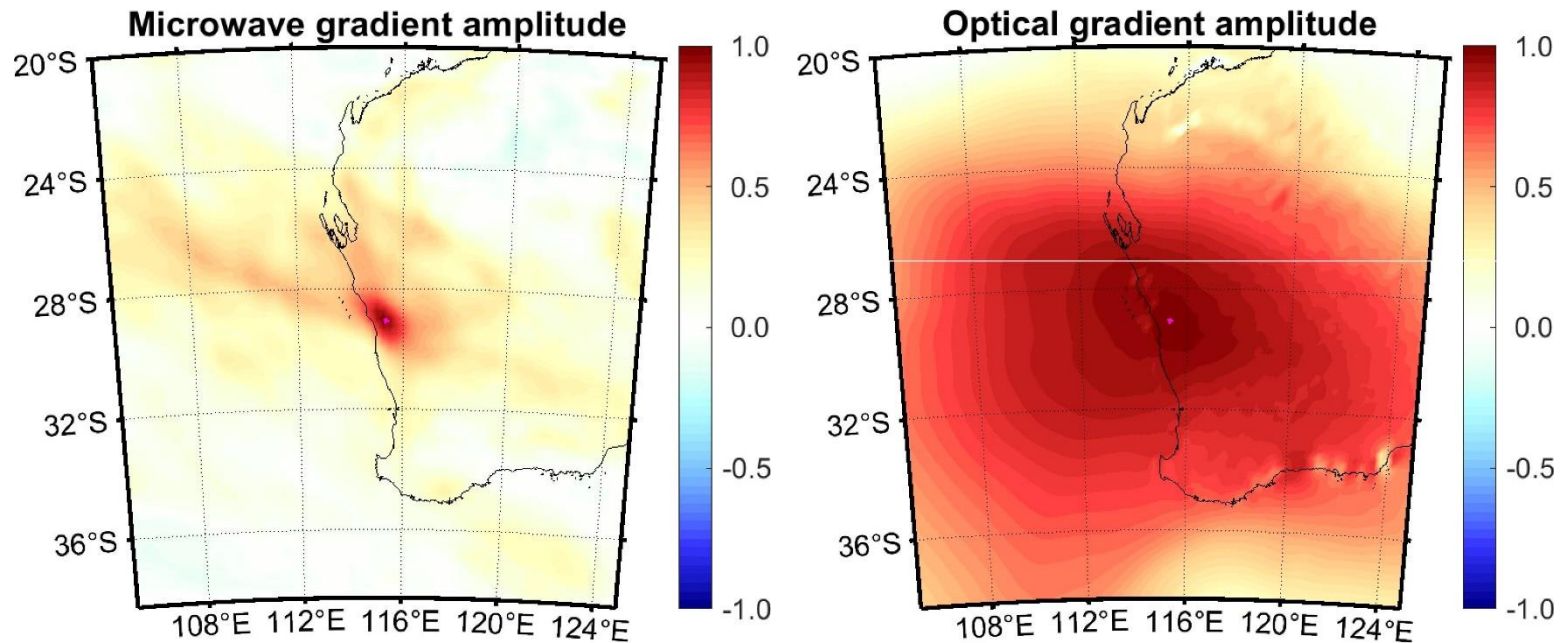
$$G = \sqrt{G_{NS}^2 + G_{EW}^2}$$

−0.06 mm on average
or −3 mm@7°

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- Symmetric/asymmetric delay decreases upwards

Spatial Correlation



Yarragadee, Australia

❑ Microwave gradients decorrelate very fast → difficult to predict

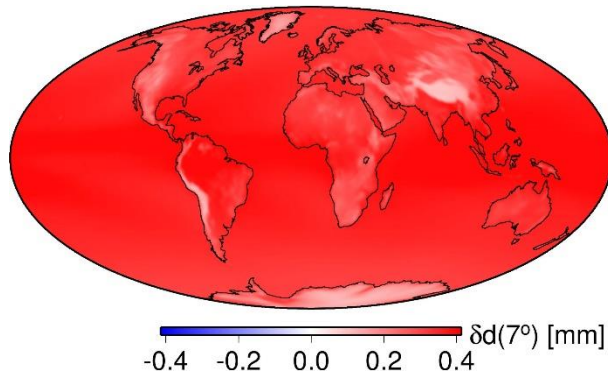
Balidakis (2019)

Chapter IV

Observing System-Induced Differences

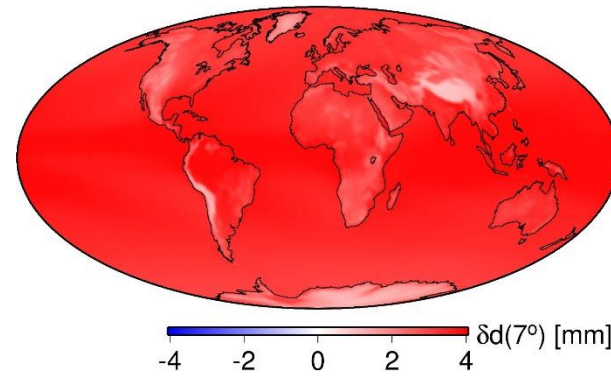
Mapping Functions Depend on the Orbital Altitude

GNSS minus VLBI



expected $\delta H \approx 0.2$ mm

DORIS minus VLBI



expected $\delta H \approx 2$ mm

□ Mapping factor magnitude ranking

$$mf^L < mf_{h,nh}^R < mf_{h,nh}^P < mf_{h,nh}^D$$

L: SLR, R: VLBI, P: GNSS, D: DORIS

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Chapter V

Simulation of Space Geodetic Observations

Space Geodetic Adjustment

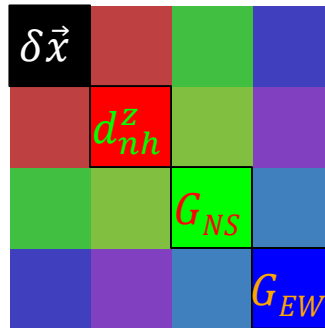
- ❑ Assumption: everything perfectly understood except for non-tidal station motion, atmospheric refraction, and frequency standards' stability
- ❑ Weighted least-squares, statistical tests for outliers, loose relative constrains, no absolute constrains, etc.

$$o - c = mf_{nh}d_{nh}^z + mf_g[G_{NS} \cos(\alpha) + G_{EW} \sin(\alpha)] + clk + \delta\vec{x}$$

estimated parameters

o : observed, c : computed, mf_{nh} : non-hydrostatic mapping factor, mf_g : gradient mapping factor, α : azimuth

- ❑ NEQs for combination



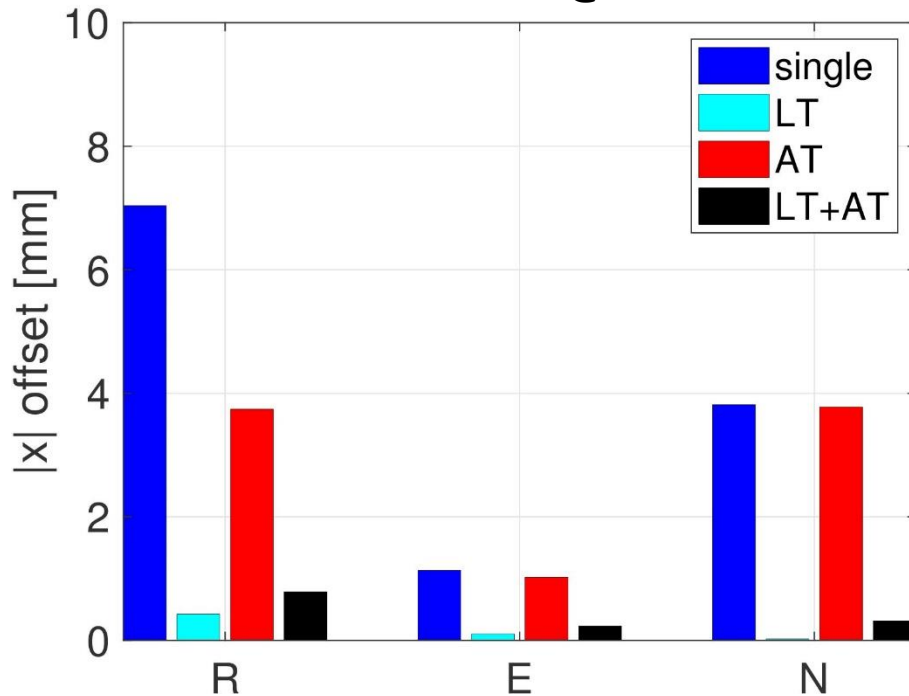
Chapter VI

Multi-Technique Combination

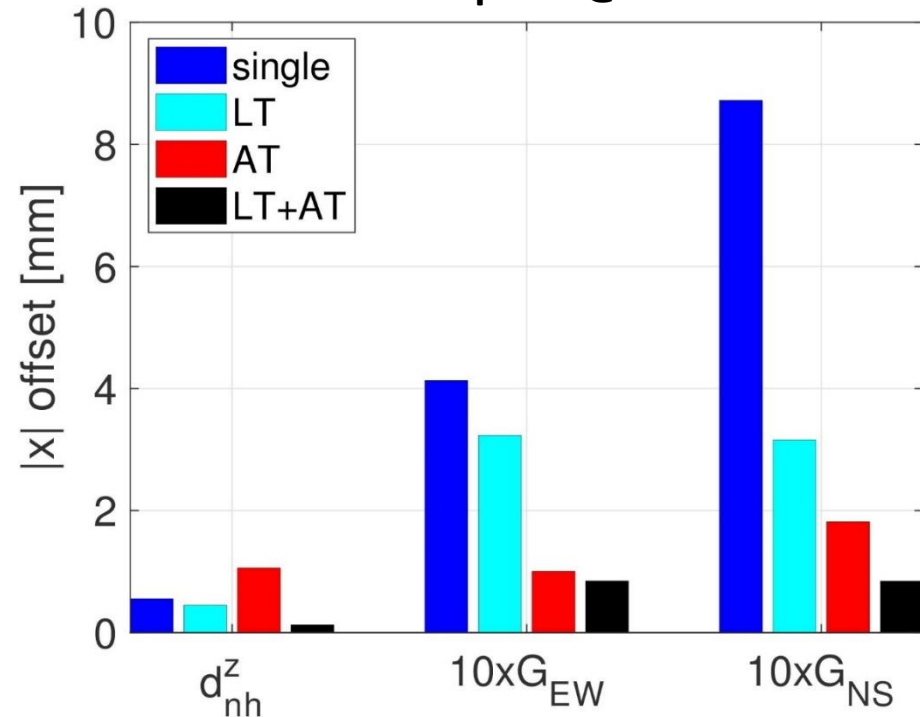
... Introducing Local + Atmospheric Ties

- Imp. for coordinates/troposphere → offset/scatter reduction

Coordinates@VLBI



Atmosphere@VLBI

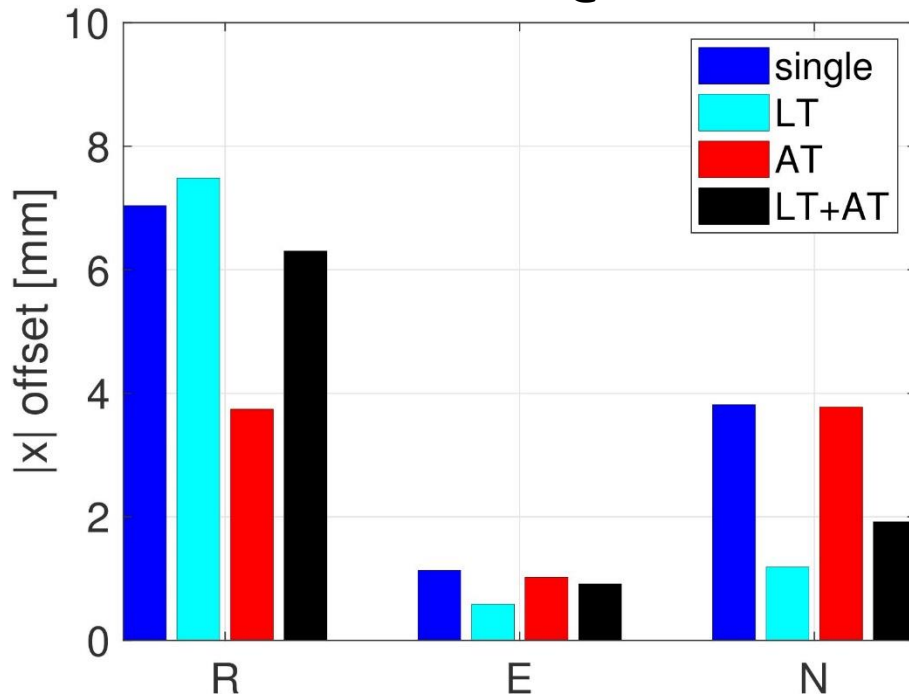


47% and 66% reduction in zenith delay and gradient scatter resp.

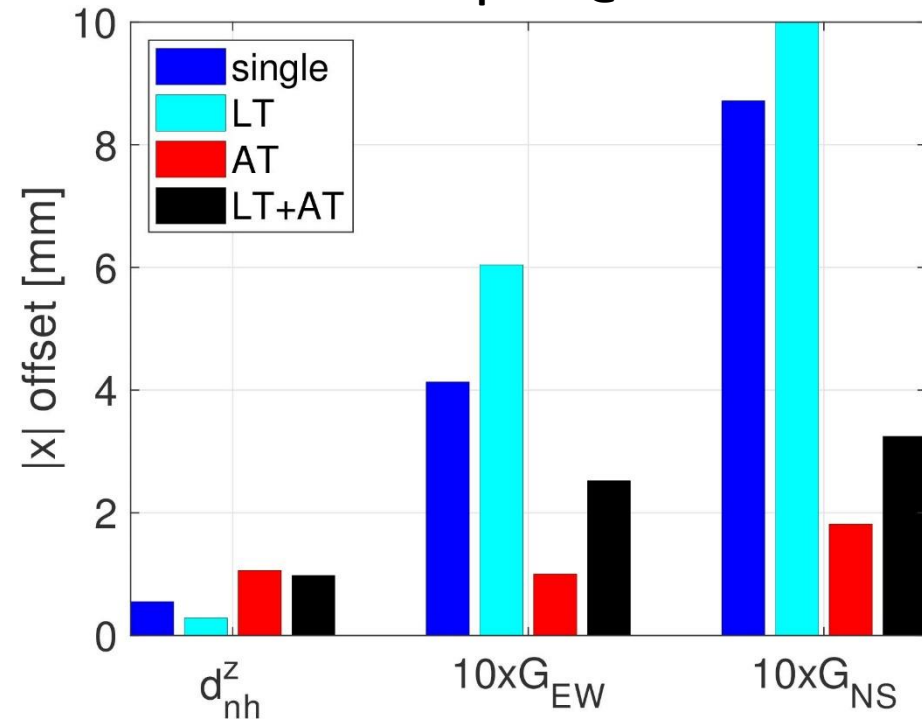
... Introducing 1cm Bias in VLBI Height

❑ Detr. for coordinates/troposphere → offset increase

Coordinates@VLBI

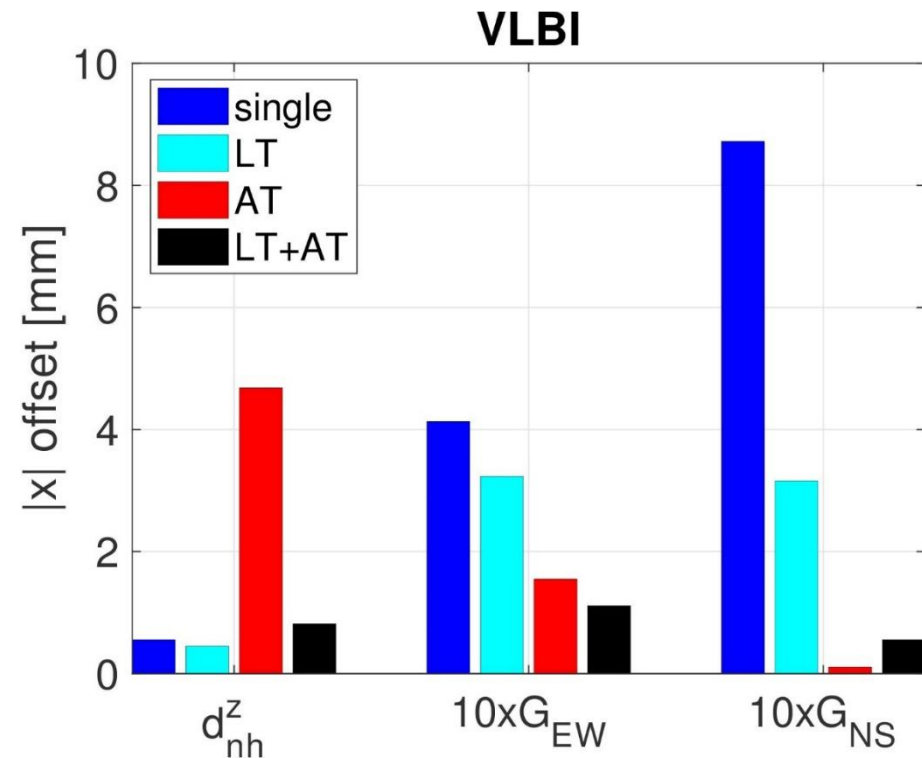
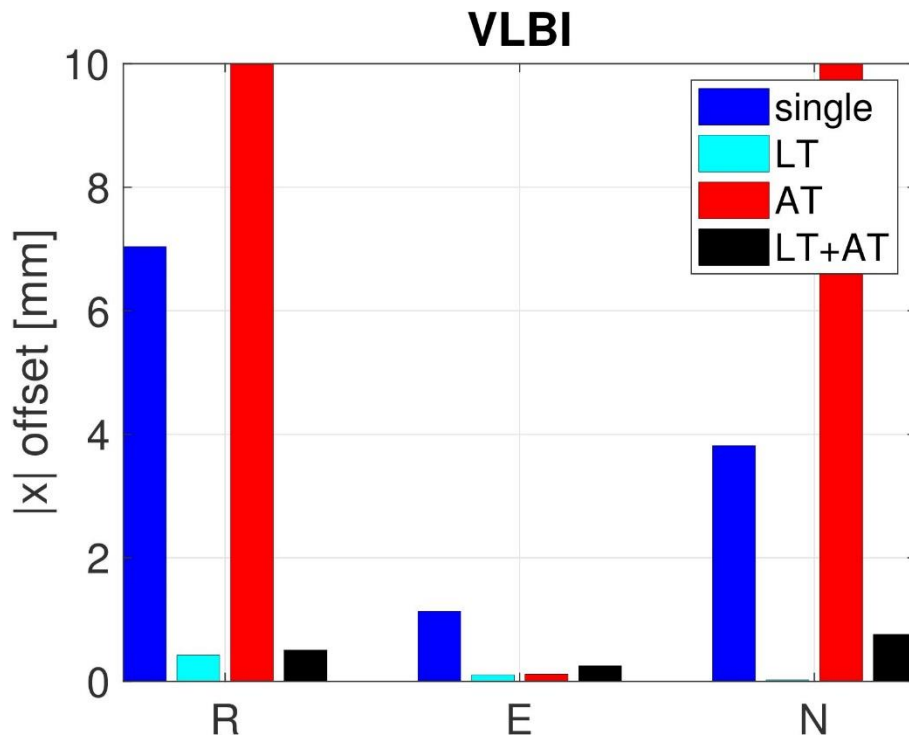


Atmosphere@VLBI



... Introducing 1cm Bias in VLBI d_{nh}^z

❑ Detr. for coordinates/troposphere → offset increase



Recapitulation

- ❑ Frequency: optical gradients smoother spatially and temporally than microwave
- ❑ Position: symmetric/asymmetric delays decrease with increasing altitude
- ❑ System: $mf^L < mf_{h,nh}^R < mf_{h,nh}^P < mf_{h,nh}^D$
- ❑ Based on simulations (PRLD combination with atmospheric and local ties):
 - ❑ ATs improve coordinate and troposphere estimation
 - ❑ ATs slightly mitigate the “damage” induced by biased LTs
 - ❑ ATs useful to detect biased LTs

Thank you!

contact

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Acknowledgements

ECMWF for making available the ERA5 reanalysis datasets
IVS, IGS, ILRS, and IDS for the VLBI, GNSS, SLR, and DORIS data resp.



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Some references

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