

The potential of detecting flaws in an experimental dam at Älvkarleby, Sweden, using P-wave traveltimes tomography

Silvia Salas-Romero, Christopher
Juhlin & Christian Bernstone

Outline

- Background and project goals
- Survey layout: hydrophones and boreholes
- What is P-wave travelttime tomography?
- Synthetic models:
 - Cavity
 - Horizontal permeable layer
- Summary & Outlook
- References

Background

- A large number of earth embankment dams were built in the second half of 20th century in Sweden
- Defects (e.g., seepages and internal erosion) inside the dams can be detected but not located with precision using indirect methods
- Vattenfall initiated a research project for detecting damages in this type of dams, using blind testing through continuous seismic, resistivity, and temperature measurements

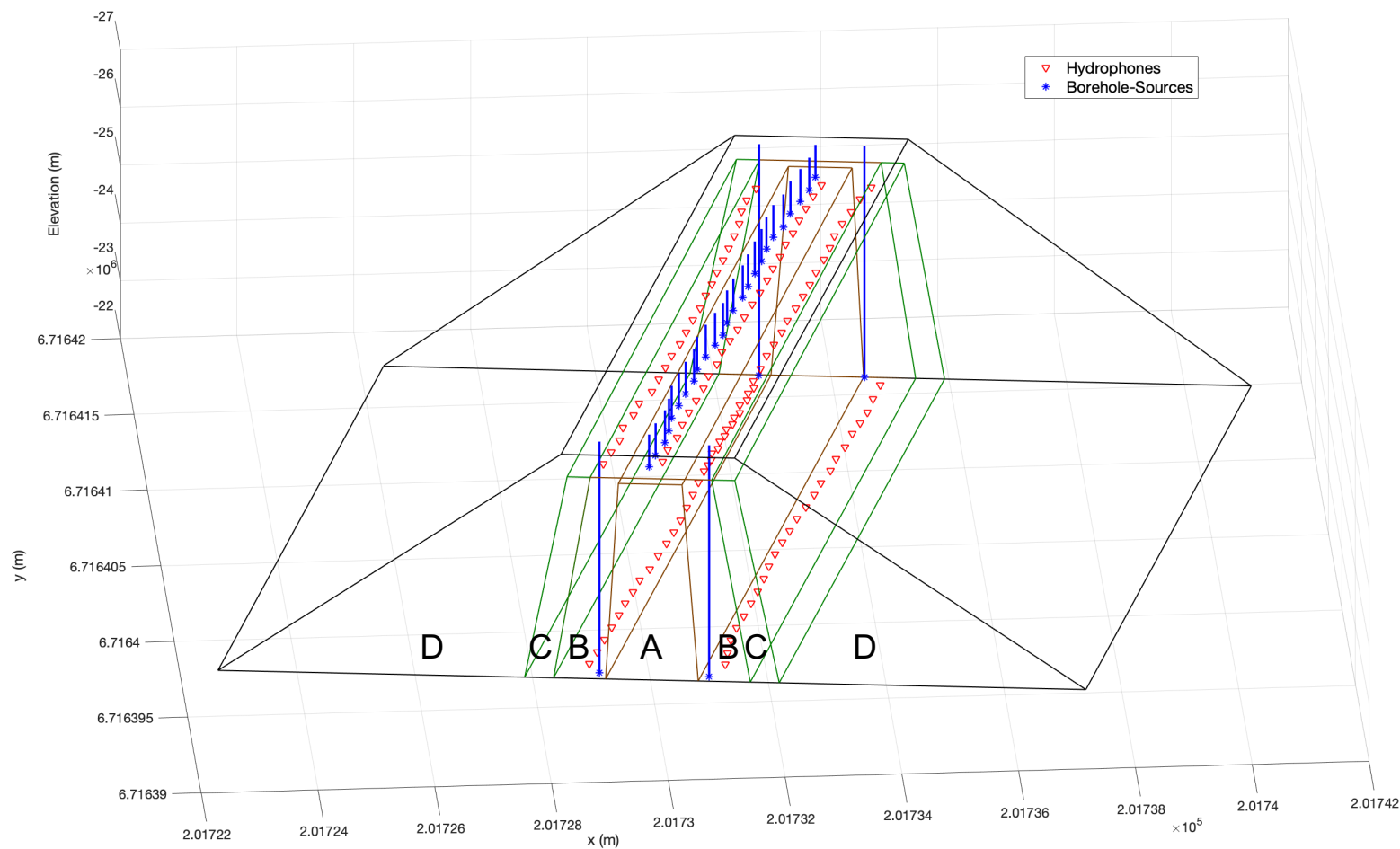
Goals of this work

- Test and, if possible, detect built-in flaws of unknown position and size within the core of an experimental dam using synthetic and real P-wave traveltimes tomographic data
- Support the interpretation of P-wave reflection seismic data

Experimental dam design

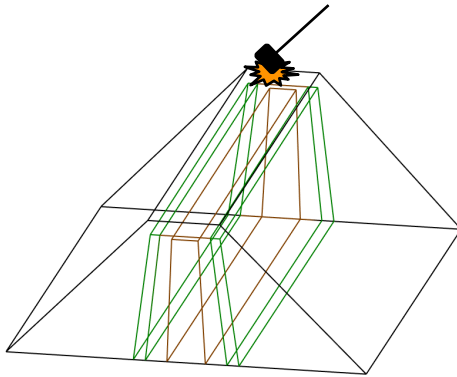
- 20 m long and 4 m high, composed of four parts: A (impermeable core), B (fine filter), C (coarse filter), and D (support filling)
- Seismic data recorded with 5 lines of hydrophones and one 3C-geophone in the deep boreholes, using a P-wave sparker as seismic source in every borehole

Survey layout

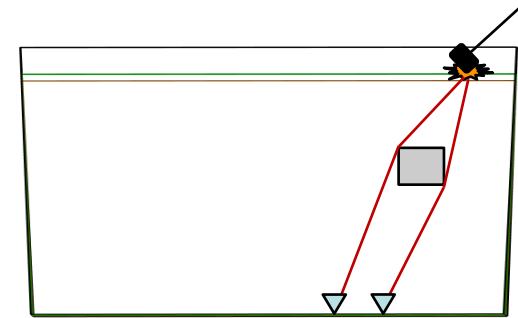


P-wave traveltimes tomography

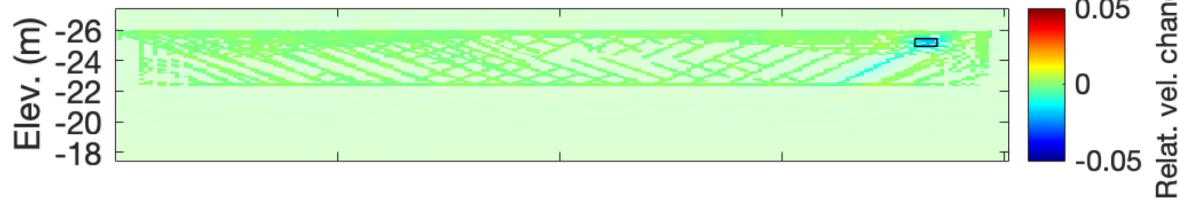
1. Shooting seismic source



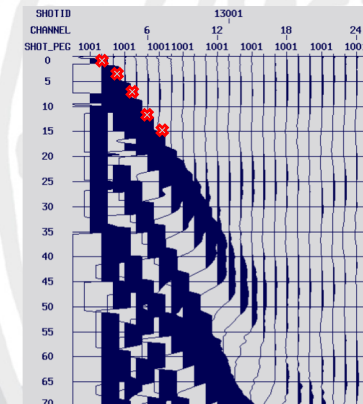
2. Raypath affected by cavity



4. Traveltimes inversion for P-wave velocities (V_p)



3. Picking traveltimes (first arrivals) from shot records



Inversion parameters

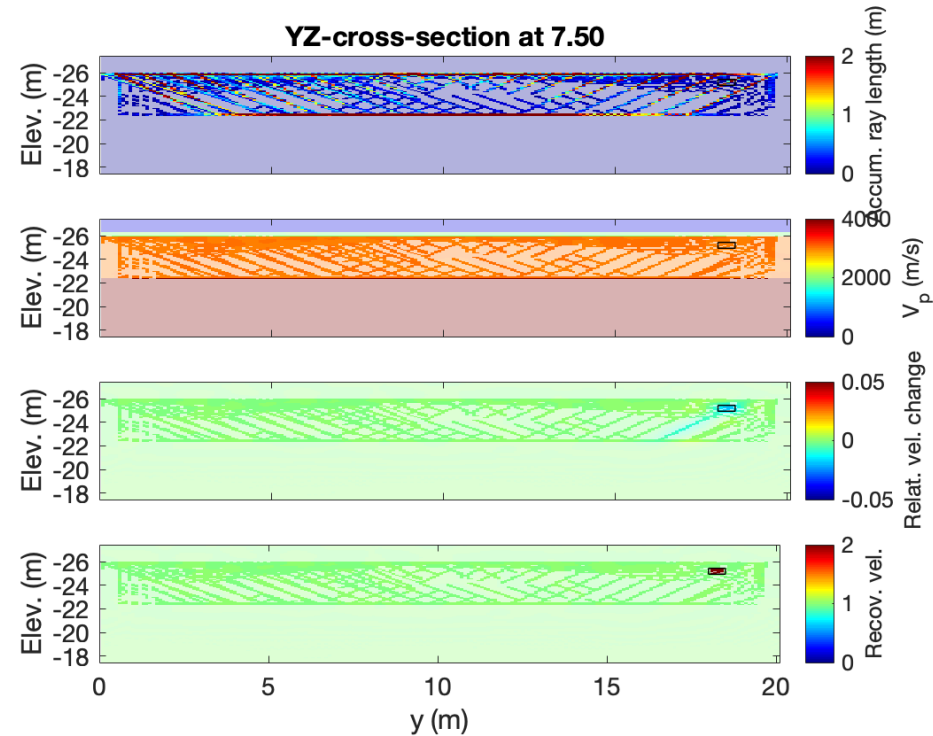
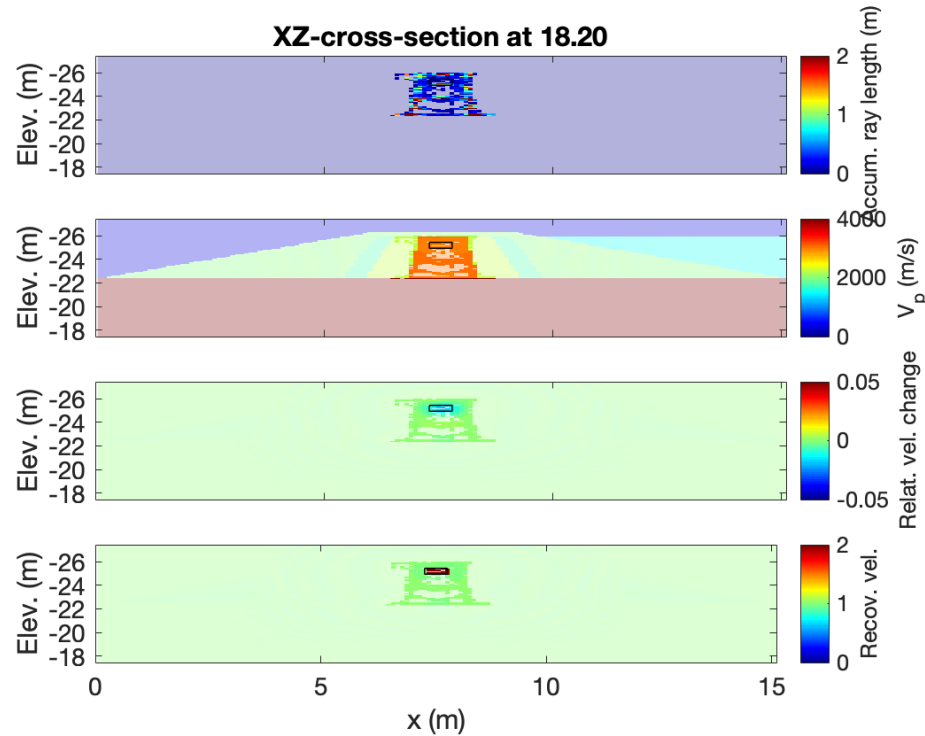
- Program: PStomo_eq (Tryggvason et al., 2002)
- Cell size (x,y,z): 0.1 x 0.1 x 0.1 m
- Number of iterations: 9

Starting
model for
inversion

V_p

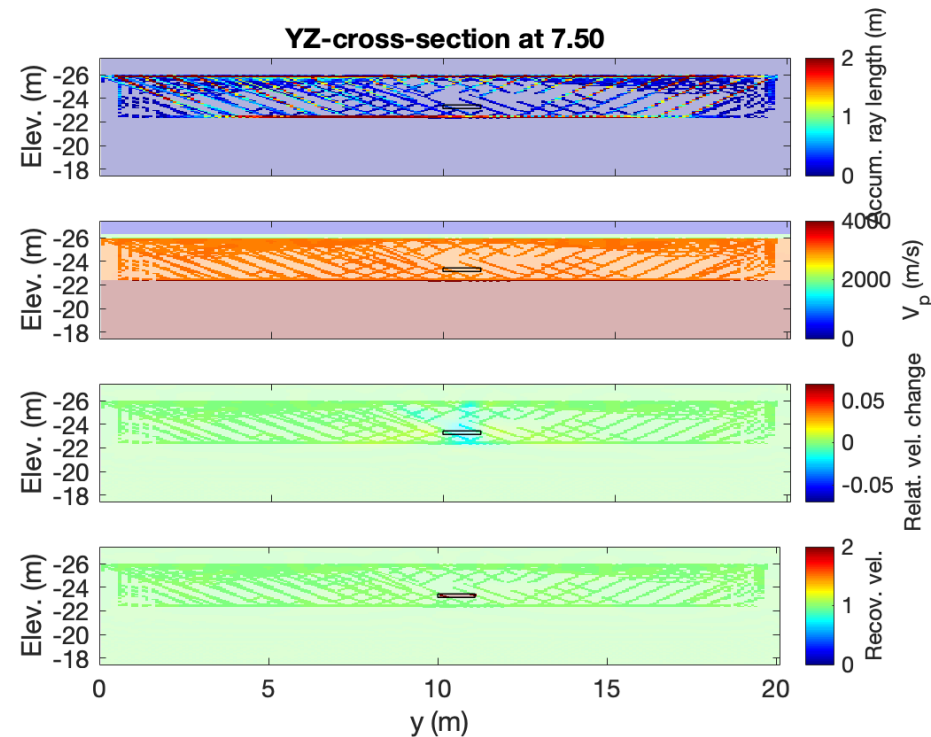
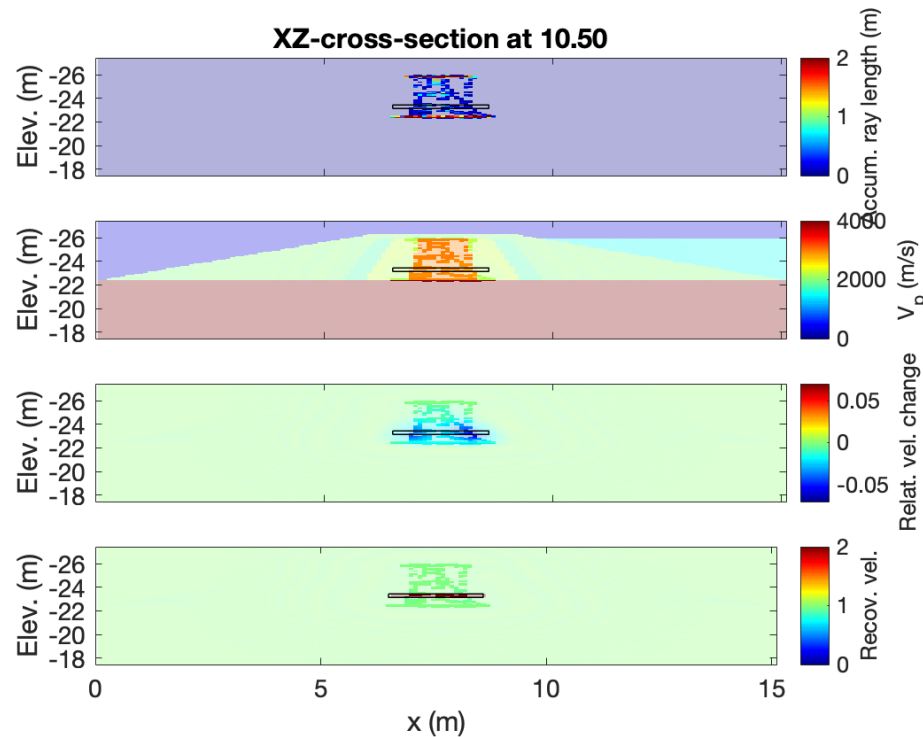
A: 3000 m/s
B: 2200 m/s
C: 1800 m/s
D: 2000 m/s
Bedrock: 5000 m/s
Water: 1500 m/s
Air: 340 m/s

Synthetic model: cavity



Cavity { Size: 0.4 x 0.4 x 0.4 m
 $V_p = 1000$ m/s

Synthetic model: horizontal permeable layer



Horizontal permeable layer — { Size: 2 x 1 x 0.2 m
 $V_p = 1000$ m/s

Summary

- Synthetic modelling results show, in general, that the defect position can be identified by tomography
- Velocity and size of the defects are not well recovered by the method (seismic ray coverage is limited in some areas)

Outlook

- Continue modelling synthetic and real traveltimes data
- Reflection seismic surveys every 2 months (the reservoir will be operated at its max. water level for about 18 months)
- Interpretation of reflection seismic data together with P-wave traveltimes tomography

References

- Tryggvason A, Rögnvaldsson S ður T, Flóvenz ÓG (2002) Three-dimensional imaging of the P- and S-wave velocity structure and earthquake locations beneath southwest Iceland. *Geophys J Int* 151: 848–866. doi:10.1046/j.1365-246X.2002.01812.x