

# Spatially-distributed Deep Learning for rainfall-runoff modelling and system understanding

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EGU HS 3.4: Deep Learning in Hydrological Science  
05.05.2020

```
for (k in 1:length(file.names)){  
  basin <- read.delim(file.names[k],sep=" ",na.strings="-9999.000")  
  names(basin) <- c("JJ", "DD", "MM", "YYYY", "Qm3", "P", "T", "PET", "SM", "AET", "Peff")  
  # basin <- basin[which(is.na(basin$Q)==FALSE),] #leave out data gaps  
  basin$Date <- as.Date(paste(basin$DD, basin$MM, basin$YYYY, sep="."),format="%d.%m.%Y")  
  basin$Q <- basin$Qm3*3.6*24/area$Area[k]  
  thresh <- quantile(basin$Q, pVal, na.rm=TRUE)  
  basin$Station <- as.numeric(gsub("sub_1.txt", "", file.names[k]))  
  
  index <- 1  
  basin$Event <- NA #prepare output vectors/dataframe  
  basin$EventID <- NA  
  for(m in (max(lag)+1):length(basin[,1])){#assign flood event numbers to each day  
    #start from max-lag+1 to allow for calculation of preconditions below
```



# The Elbe catchment

- 4th largest river catchment of EU
  - Strong flood events in 2002, 2006, 2013
  - Low-flow period 2003, 2005
- Need for accurate prediction of streamflow



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<https://commons.wikimedia.org/wiki/File:Elbe-niedrig.jpg>



[https://commons.wikimedia.org/wiki/File:Elbe\\_Einzugsgebiet.png](https://commons.wikimedia.org/wiki/File:Elbe_Einzugsgebiet.png)

# Methods

- Streamflow prediction from E-OBS gridded dataset of precipitation + temperature
- Transfer Convolutional-LSTM Architecture to Hydrology
- Aim: Exploit spatio-temporal patterns in gridded climate data
- Baseline models:
  - Spatially-distributed Physical model (mHM: Samaniego L., R. Kumar, S. Attinger (2010))
  - Non-spatially distributed LSTM on catchment means



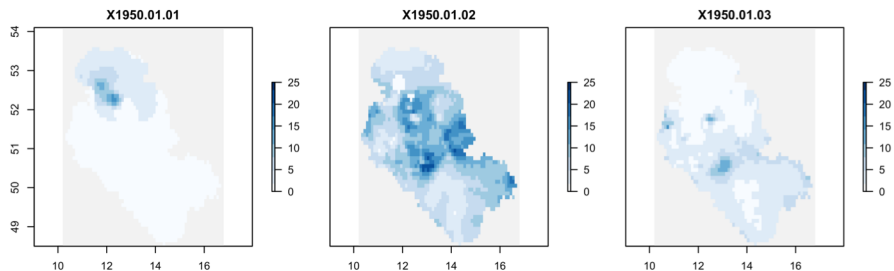
Creative Commons



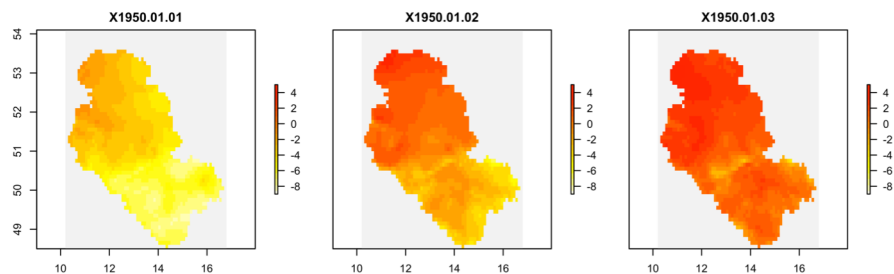
<https://commons.wikimedia.org/wiki/File:Elbe-niedrig.jpg>

# Data

Precipitation [mm/d]



Air temperature [°C]



Input

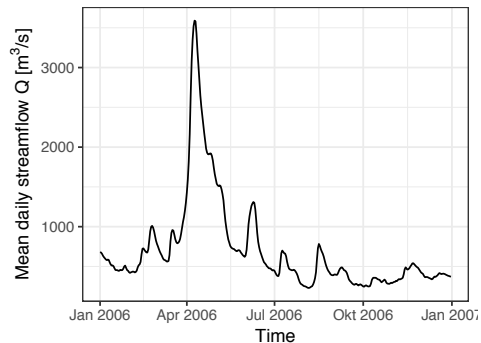
- 1950 – 2013
- Daily mean values
- Spatial Resolution 0.1°



ConvLSTM

Patterns:

- Spatial
- Temporal



Target



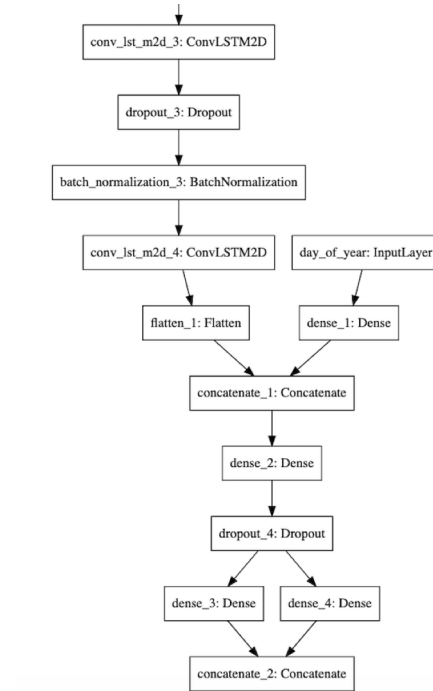
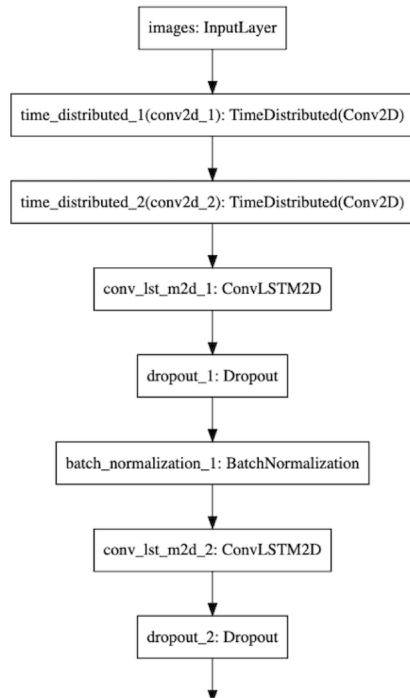
# ConvLSTM

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## Uncertainty Quantification:

- Aleatoric uncertainty by estimating standard deviation in gaussian loss function (Kendall & Gal, 2017)
- Epistemic uncertainty: Drop-out in inference

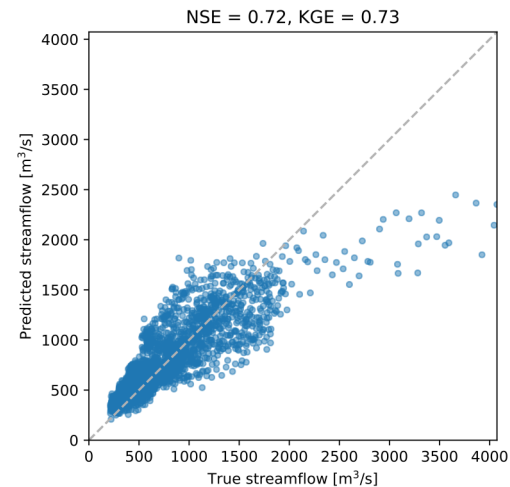
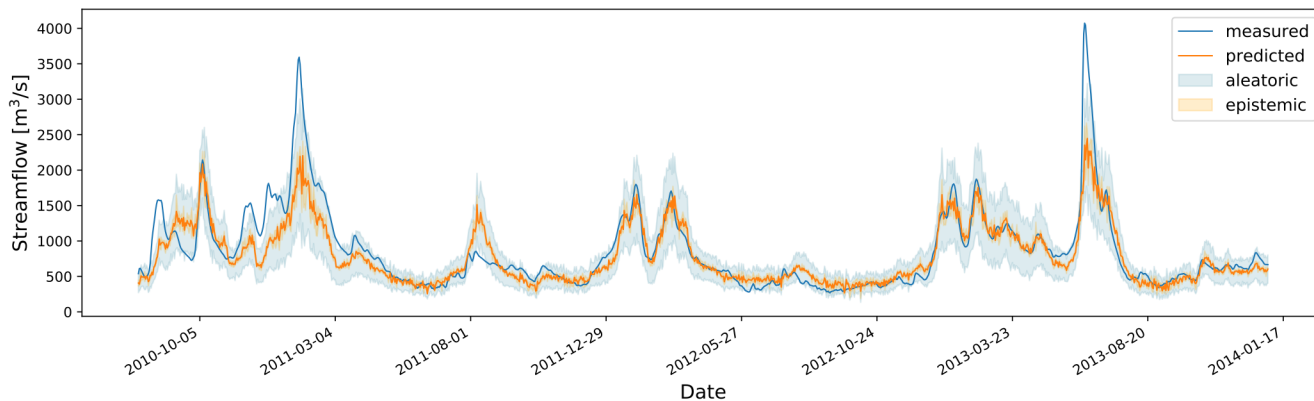
# ConvLSTM



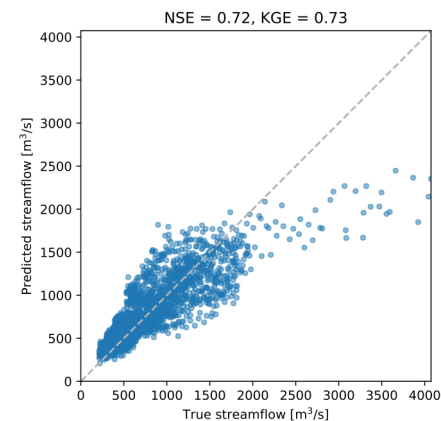
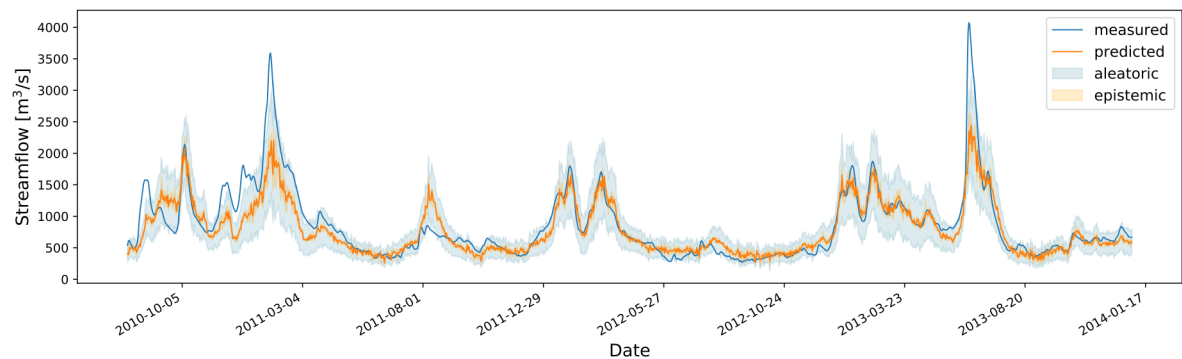
Strided convolution operations (instead of pooling)

# Results: ConvLSTM

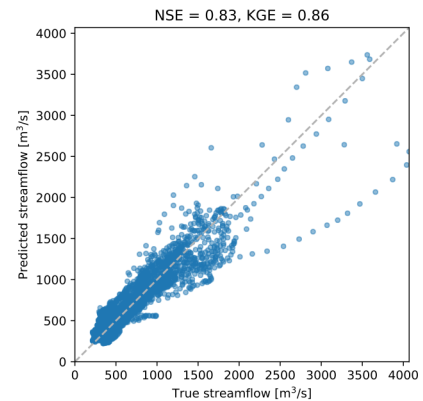
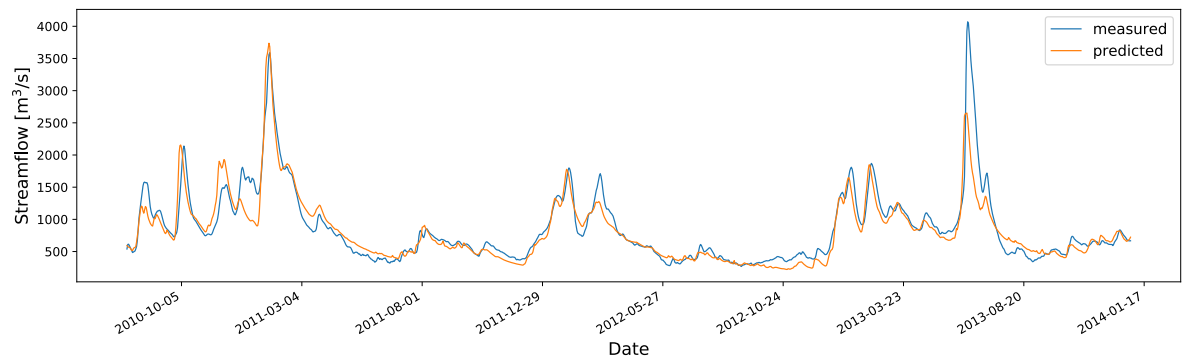
- Accurate modelling of dynamics
- Meaningful uncertainty bands
- Oscillations
- Underestimation of peak flows



# Results: ConvLSTM vs. Physical Model



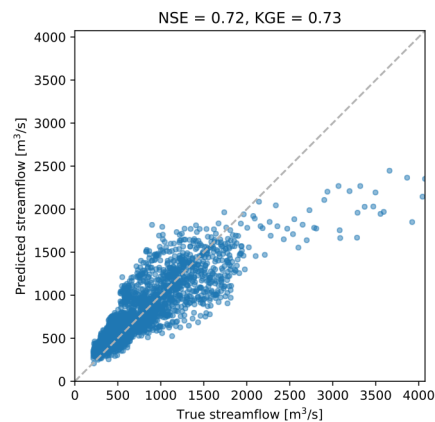
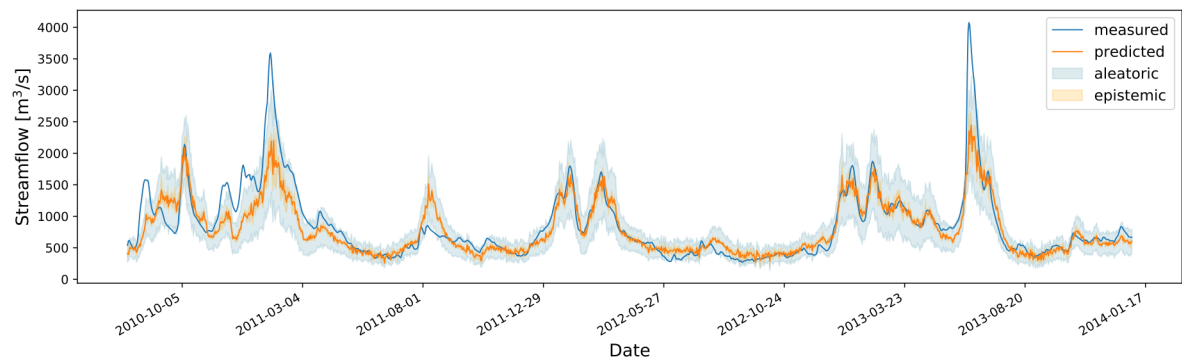
ConvLSTM



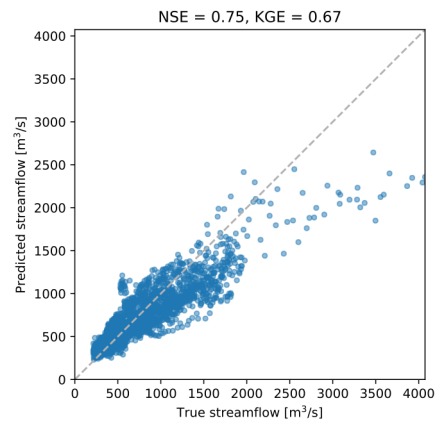
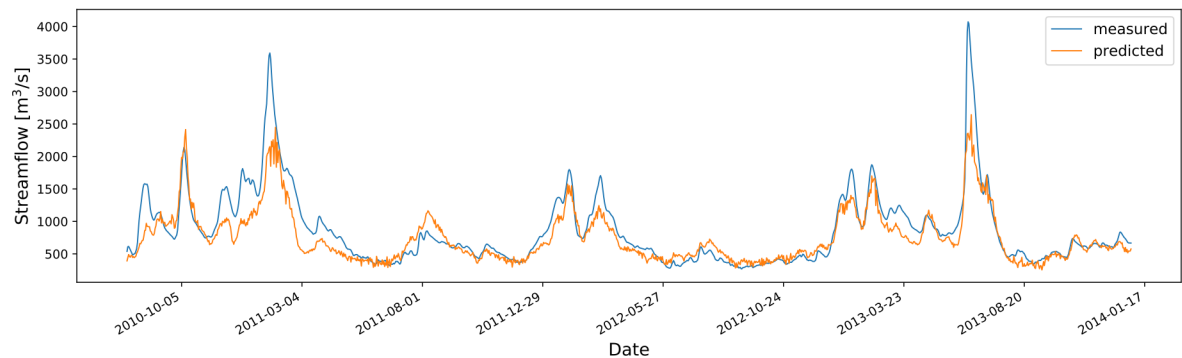
Physical



# Results: ConvLSTM vs. LSTM



ConvLSTM



LSTM

# Results: Summary

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- Deep Learning allows for accurate prediction incl. uncertainty from 2 inputs
- Similar predictions to physical model but oscillations
- Non-spatially distributed LSTM achieves similar accuracy as spatially-distributed ConvLSTM

→ Flexibility of DL does not guarantee more accurate predictions

→ Spatial patterns not exploited / not relevant

# Results: Discussion

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→ Spatial patterns not exploited / not relevant

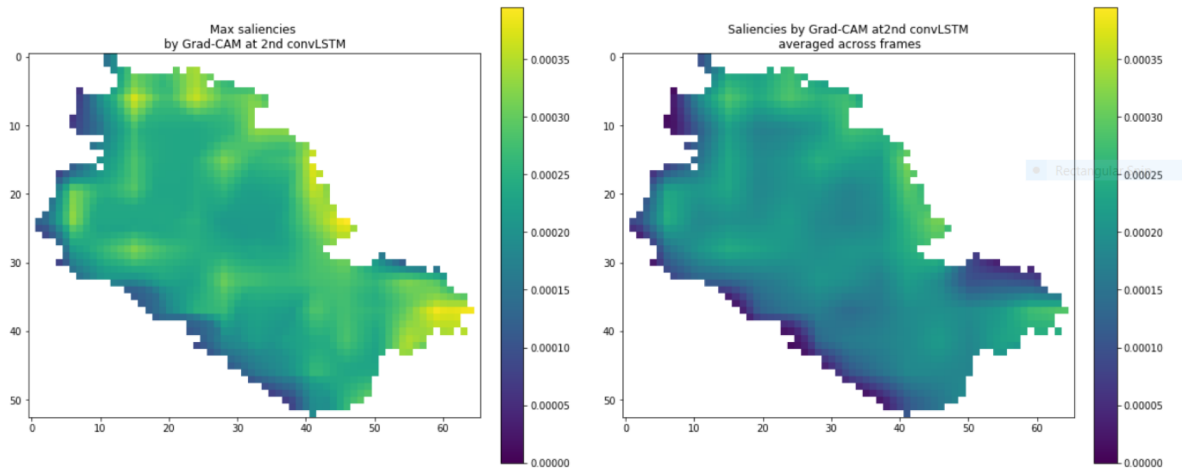
Possible explanations:

- Uncertainty in E-OBS gridded dataset
- Short-comings in model training / architecture
- Similar to known issue in process-based modelling:

Lumped models might be more accurate than distributed models

# Outlook

- Systematic Hyperparameter tuning
- Analyze: Reasons for limited use of spatial information
- Interpretation: Saliency Maps
  - Runoff-relevant subregions in catchment
  - Relevant time-lags
- Apply on real-time Remote-Sensing Data





# References

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- Cornes, R., G. van der Schrier, E.J.M. van den Besselaar, and P.D. Jones. 2018: An Ensemble Version of the E-OBS Temperature and Precipitation Datasets, *J. Geophys. Res. Atmos.*, **123**. doi:10.1029/2017JD028200
- Samaniego L., R. Kumar, S. Attinger (2010): Multiscale parameter regionalization of a grid-based hydrologic model at the mesoscale. *Water Resour. Res.*, 46,W05523, doi:10.1029/2008WR007327.