

Estimating IDF-Relations consistently using a duration-dependent GEV with spatial covariates

Jana Ulrich, Madlen Peter, Oscar E. Jurado and Henning W. Rust



Topic

Intensity-Duration-Frequency (IDF) curves are a popular tool in Hydrology for estimating the properties of extreme precipitation events. They describe the relationship between rainfall intensity and duration for a given non-exceedance probability (or frequency).

Method

We use a **duration dependent GEV with spatial covariates**, to model the distribution of **annual precipitation maxima** simultaneously for a range of durations and locations.

Why?

This way, we can obtain **return level maps for various durations**, as well as **IDF curves at all locations**. Further advantages are parameter reduction and more efficient use of the available data.

Does it work?

We use the **Quantile Skill Score** to investigate under which conditions this method leads to an improved estimate compared to using the GEV separately for each duration at every station.

Precipitation Data

- Case study in **Wupper-Catchment**:

- 92 gauge stations in 75 locations (see figure 1)
- different measuring periods (see figure 2)
- varying length of time series

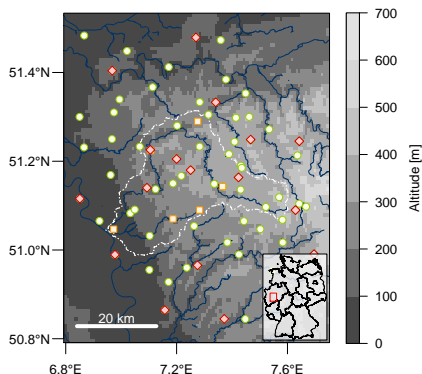


Figure 1: Study area: dashed line shows catchment area.
Altitude data: [1], River data: [2]

- Provided by the German Weather Service (DWD) and the Wuppverband (WV)

- **Annual precipitation maxima**

- for durations 1, 4, 8, 16, 32 minutes, 1, 2, 3, 8, 16 hours and 1, 2, 3, 4, 5 days

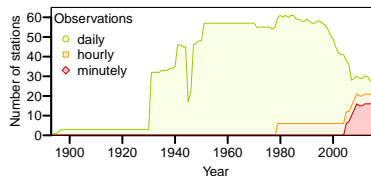


Figure 2: Number of active gauge stations in the study area per year for the different measuring periods.

Provider	Number of stations	Measuring period	Length of time series
DWD	69	1 day	9-121 years
DWD	17	1 min	5-14 years
WV	6	1 hour	38 years

- Modeling precipitation block maxima z with the GEV [3]:

$$G(z; \mu, \sigma, \xi) = \exp \left\{ - \left[1 + \xi \left(\frac{z - \mu}{\sigma} \right) \right]^{-1/\xi} \right\}$$

- Simultaneously model maxima over different **durations** and **locations** using

Duration dependent GEV (d-GEV)

- Assumptions for the dependency of the **GEV-parameters** on duration d following [4]:

scale: $\sigma(d) = \sigma_0 \cdot (d + \theta)^{-\eta}$

location: $\mu(d) = \tilde{\mu} \cdot \sigma(d)$

shape: $\xi(d) = \xi = \text{const.}$

- Resulting in d-GEV:

$$G(\mu(d), \sigma(d), \xi) = G(\tilde{\mu}, \sigma_0, \xi, \theta, \eta)$$

$\uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow$
5 parameters

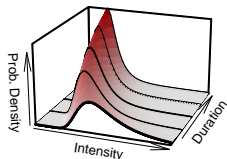


Figure 3:
Probability density surface of the d-GEV

with spatial covariates

- Allow **d-GEV parameters** to vary in space:

$$G(\tilde{\mu}(\vec{r}), \sigma_0(\vec{r}), \xi(\vec{r}), \theta(\vec{r}), \eta(\vec{r}))$$

- Using orthogonal polynomials of longitude and latitude [5]
for all parameters $\Phi \in \{\tilde{\mu}, \sigma_0, \xi, \theta, \eta\}$, with maximum orders $J = K = 6$:

$$\begin{aligned} \phi &= \phi_0 + \sum_{j=1}^J \beta_j^\phi P_j(\text{lon}) + \sum_{k=1}^K \gamma_k^\phi P_k(\text{lat}) \\ &+ \sum_{j=1}^J \sum_{k=1}^K \delta_{j,k}^\phi P_j(\text{lon}) P_k(\text{lat}) \end{aligned}$$

- Model selection: avoid overfitting, by allowing certain **coefficients** to remain zero

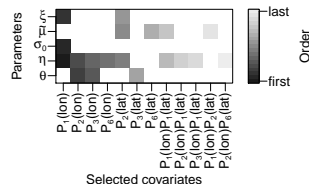


Figure 4:

Model selection result: added covariates colored according to order of their selection. White means parameter remains zero.

Quantile estimation

Using the d-GEV with spatial covariates, we can obtain **return level maps for various durations** (figure 5) and **IDF-curves at all locations** (figure 6).

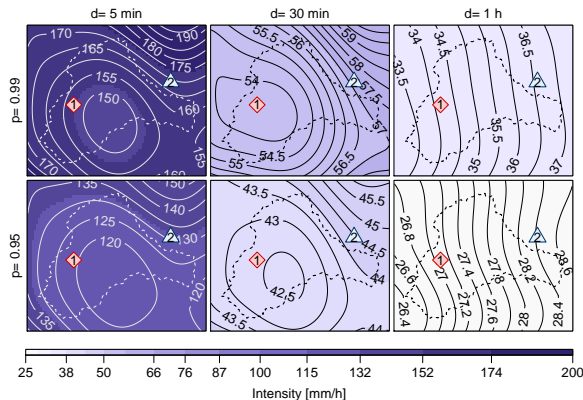


Figure 5: 100-year (upper panel) and 20-year (lower panel) return level maps for durations: 5 minutes, 30 minutes and 1 hour. Diamond and Triangle mark the locations for the IDF-curves in figure 6

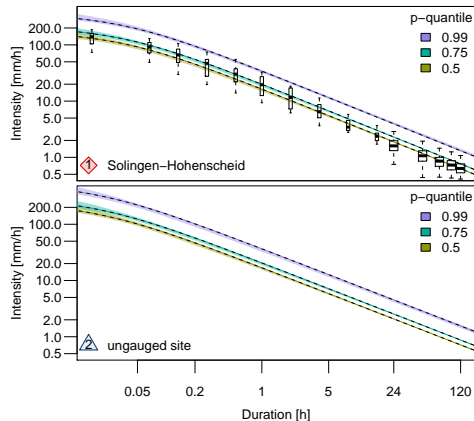


Figure 6: IDF-curves for a station with minutely precipitation measurements and an ungauged location. 95% confidence Intervals were obtained by the bootstrap percentile method.

- How does the d-GEV perform in the study area?

1. When using an individual model at each station
2. When using one spatial model

- Investigation of model performance using the Quantile Score QS [6] corresponding to weighted mean difference between observations $o_{s,d}$ at certain station s , for certain duration d and modeled p -quantile $q_{s,d}(p)$
- Mean Quantile Score for probability p and duration d , averaged over stations:

$$\overline{QS}_d(p) = \frac{1}{S_d} \sum_{s=1}^{S_d} \frac{1}{N_{s,d}} \sum_{n=1}^{N_{s,d}} \rho_p(o_{s,d,n} - q_{s,d}(p)), \quad \rho_p(u) = \begin{cases} pu & , u \geq 0 \\ (p-1)u & , u < 0. \end{cases}$$

- Compare **model score** with **reference** using the Quantile Skill Score QSS
- Reference** = individual GEV model for each duration at every station

$$\overline{QSS}(p)_d = 1 - \frac{\overline{QS}_d^{\text{d-GEV}}(p)}{\overline{QS}_d^{\text{GEV}}(p)}$$

- Results** (see figure 7):

- Both approaches: **improved modeling of rare events**
- $d \geq 24$ h (right of dashed line): more data availability, pooling information over durations is less important
 - **Improvement for stations with short observation time series**
- Short durations $d \leq 0.5$ h: loss in skill for both approaches (dashed circle)
 - d-GEV might not be flexible enough to model durations $d \leq 0.5$ h properly

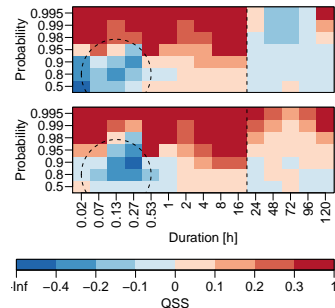


Figure 7: Mean Quantile Skill Score $\overline{QSS}_d(p)$ for station-wise d-GEV (upper panel) and spatial d-GEV (lower panel). Positive values (red) indicate improvement compared to the reference.

References

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We would like to acknowledge the Wupperverband as well as the Climate Data Center of the DWD, for providing the precipitation time series.