

Presenting the **GeForse** approach to create synthetic laser scanning data (LS) from simulated forest stands to optimize LS-based forest inventories

Fabian Ewald Fassnacht, **Jannika Schäfer**, **Hannah Weiser**, **Lukas Winiwarter**, **Nina Krašovec**, **Hooman Latifi**, **Bernhard Höfle**

Karlsruhe Institute of Technology, Germany

Heidelberg University, Germany

K. N. Toosi University of Technology, Iran



K. N. Toosi University of Technology



UNIVERSITÄT
HEIDELBERG
ZUKUNFT
SEIT 1386

GeForse - Generating Synthetic Forest Remote Sensing Data

- **Objective**
- **Approach**
- **Motivation**
- **Application Example**

GeForse - Generating Synthetic Forest Remote Sensing Data

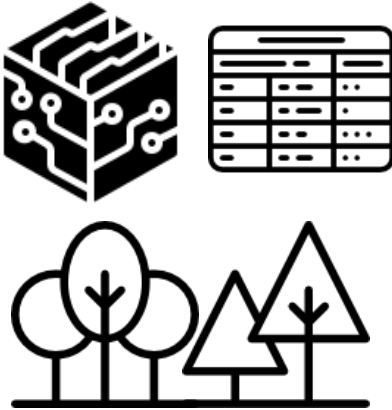
- **Objective**

Simulate realistic laser scanning data of forests where tree properties (species, DBH, height, crown diameter) of each tree are known

- **The elements**

The GeForse approach bases on three elements:

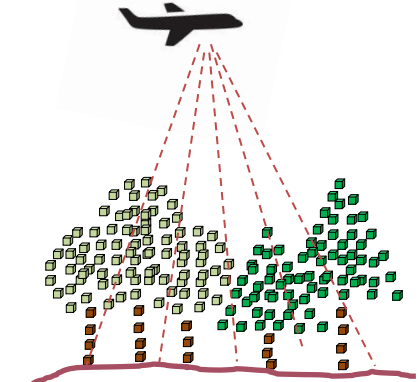
Forest Growth Simulator



Model Trees



Laser scanning simulation



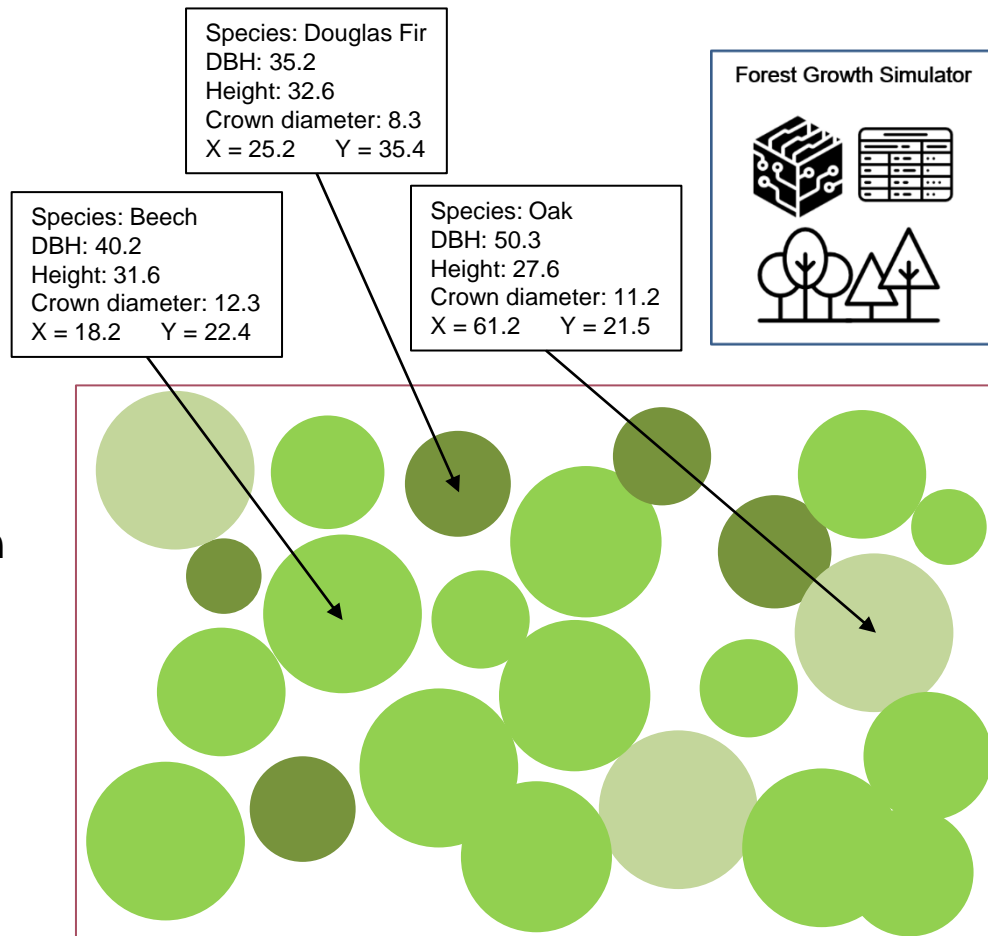
Forest Growth Simulator

Why is it needed?

- Create realistic and complete forest inventory data
- Alternatively, full inventory data could be used (but is rarely available)

Which forest growth simulators can be used?

- Individual tree-based simulators
- Spatially explicit
- Matching the study region's species
- For central Europe for example SILVA



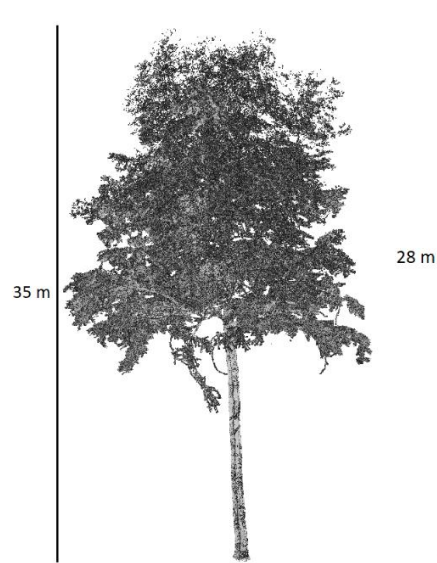
- **Why are they needed?**

- Provide realistic species-specific 3-D structure

- **How are they created?**

- Sampled from real LiDAR point clouds
- From ALS, TLS, ULS data
- Available in a **single-tree-database** (publicly available soon)

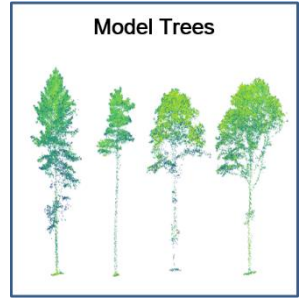
- **How are they used?**



(a) *Fagus sylvatica*



(d) *Picea abies*



■ Why are they needed?

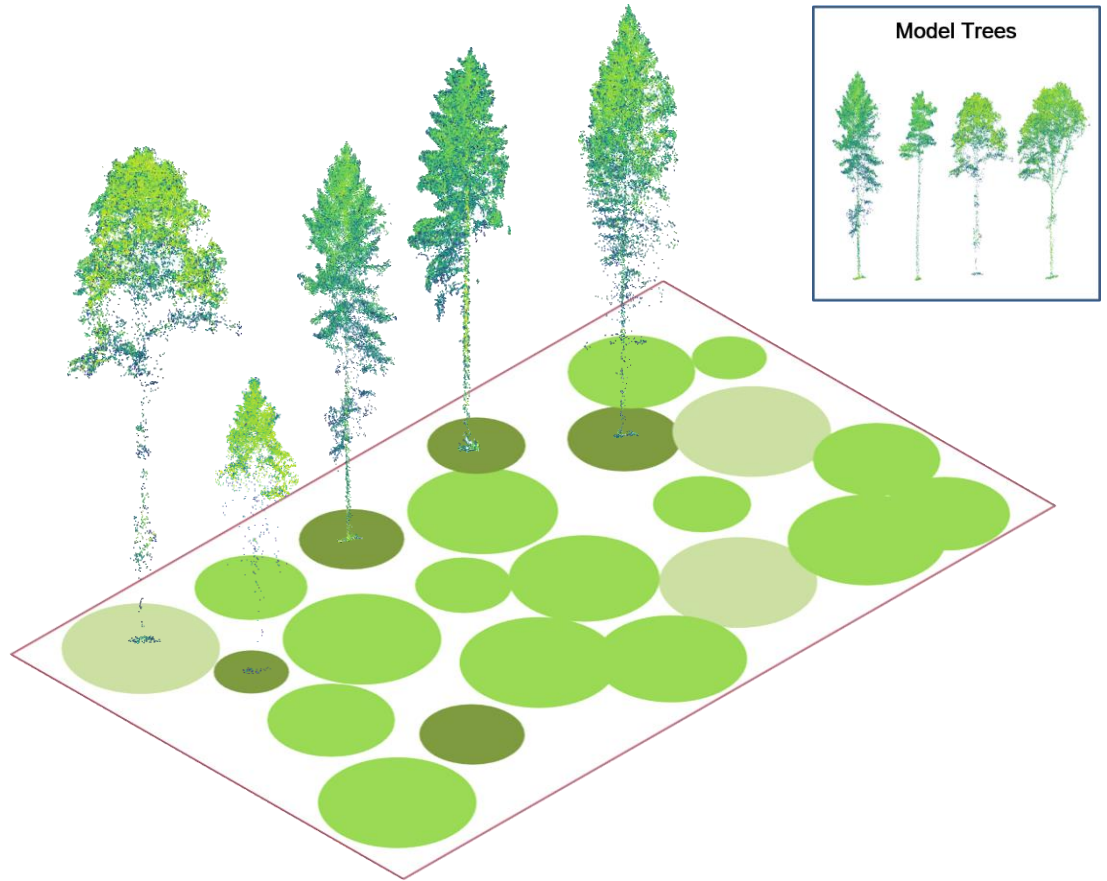
- Provide realistic species-specific 3-D structure

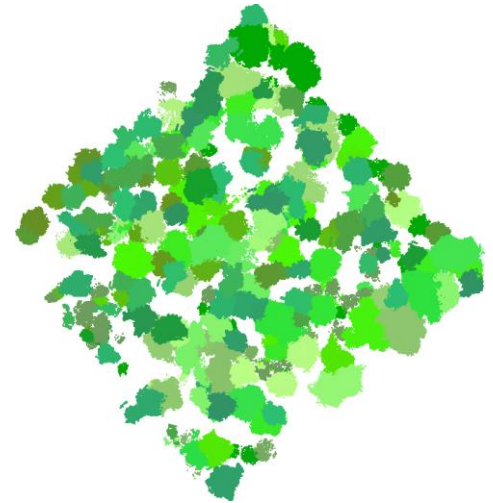
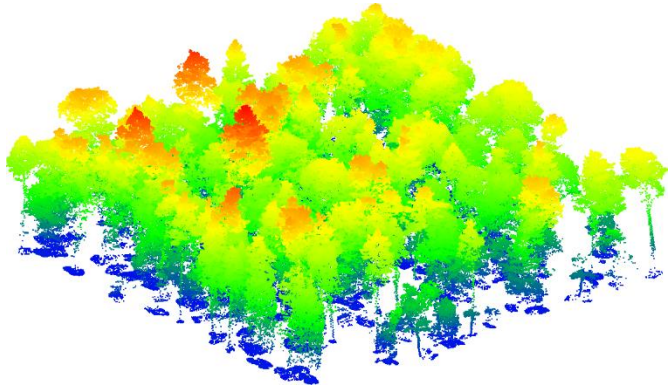
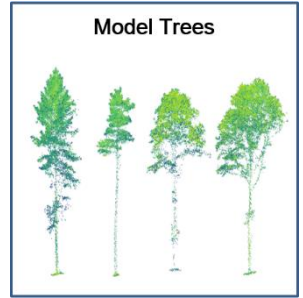
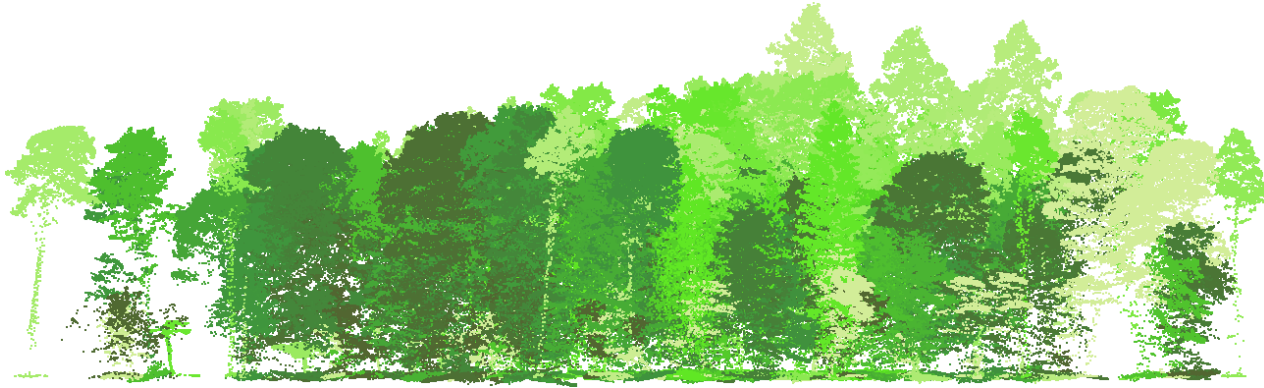
■ How are they created?

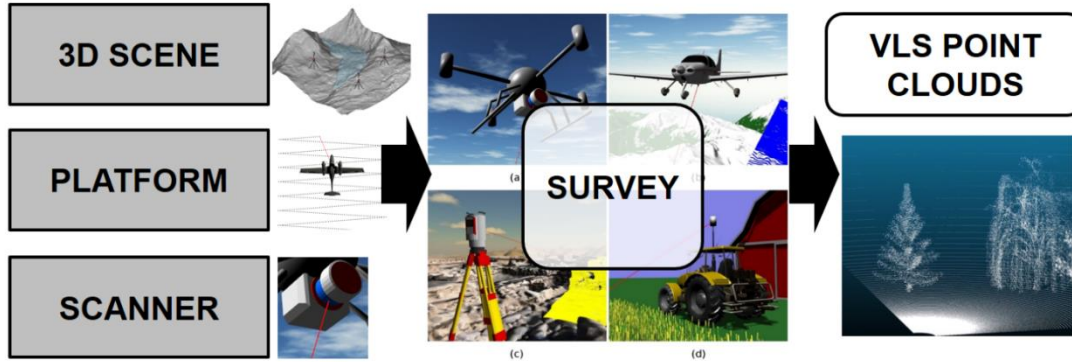
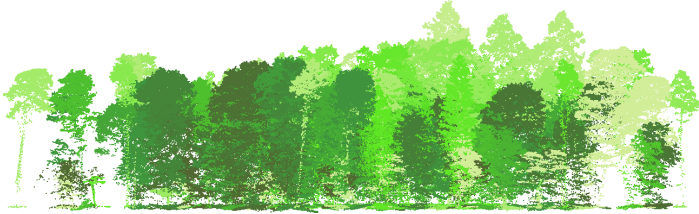
- Sampled from real LiDAR point clouds
- From ALS, TLS, ULS data
- Available in a **single-tree-database** (publicly available soon)

■ How are they used?

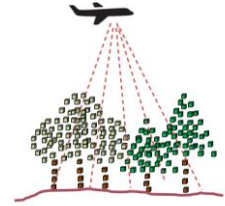
- Modell trees are inserted at each position where the forest growth simulator grew a tree
- Trees are **matched based on species, height and crown-diameter**



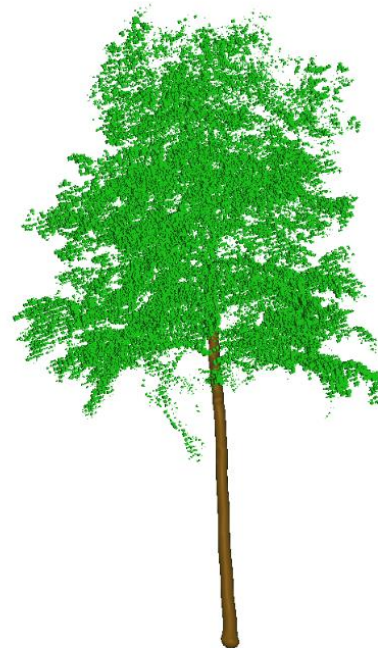
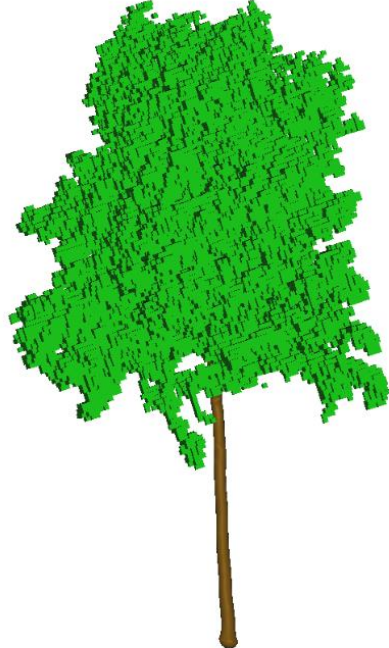
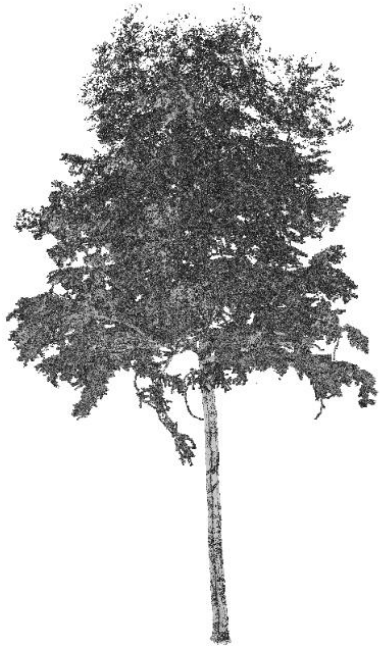




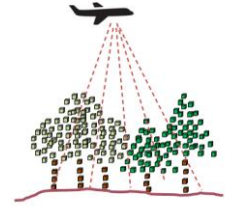
Laserscanning simulation



HELIOS++
3DGEO HEIDELBERG



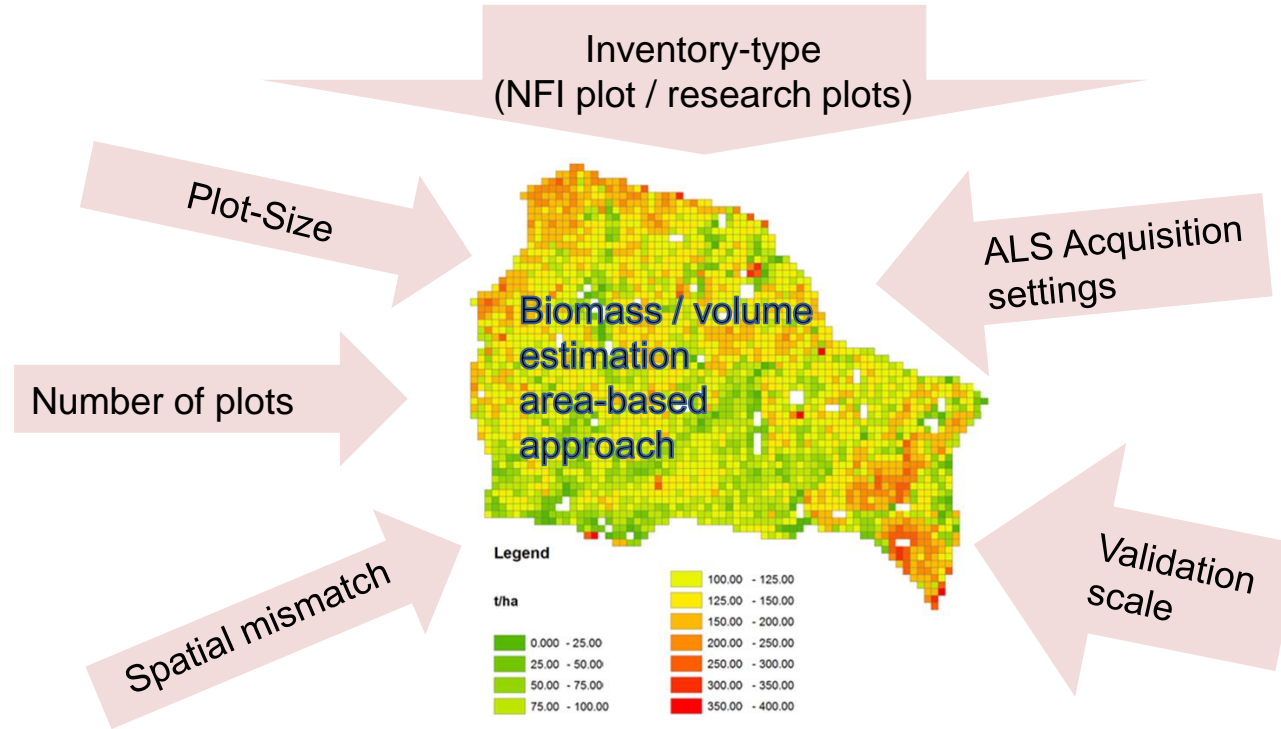
Laserscanning simulation



Virtual laser scanning (VLS) in forestry – Investigating appropriate 3D forest representations for LiDAR simulations with HELIOS++ - Hannah Weiser et al.

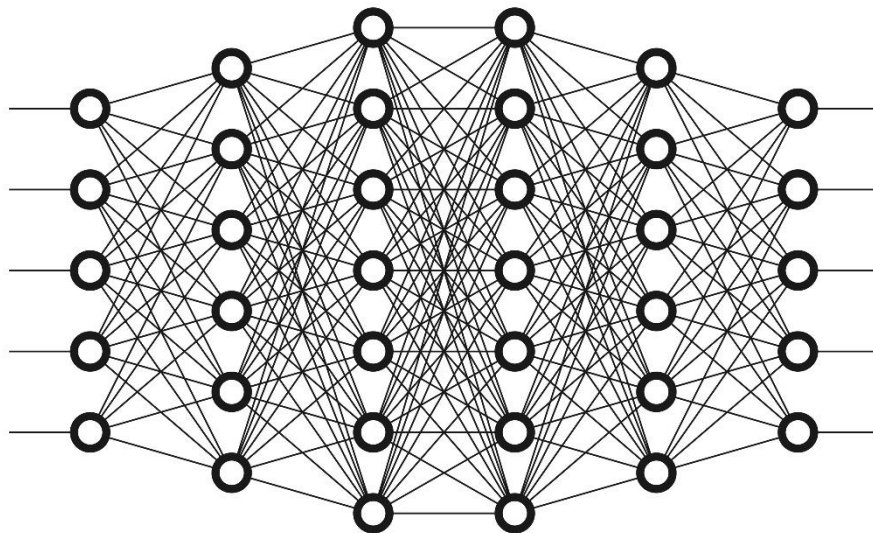
▪ Sensitivity analyses

- Operational
- But optimization potential
- High data demands and costs for sensitivity analyses
- Synthetic data provides quasi-unlimited data for free



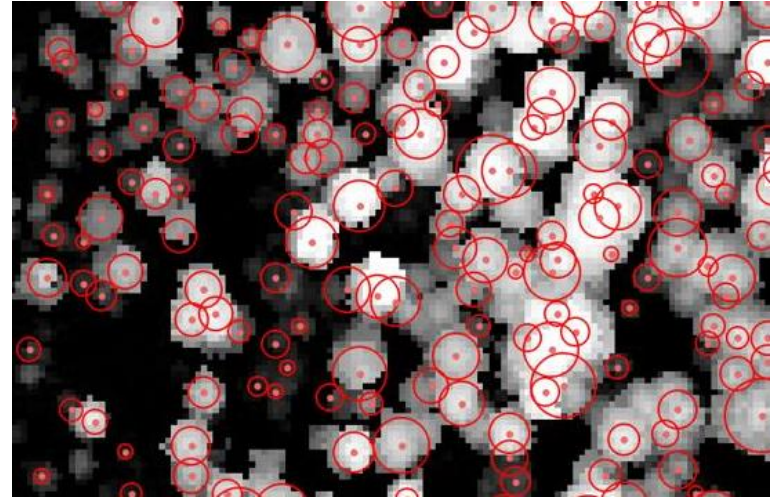
▪ Replace field data (?)

- Create lots of synthetic data
- Train “empirical” model with synthetic data
- Apply to real ALS data
- Particularly interesting for Deep learning
→ high training data demands (?)



▪ Algorithm development

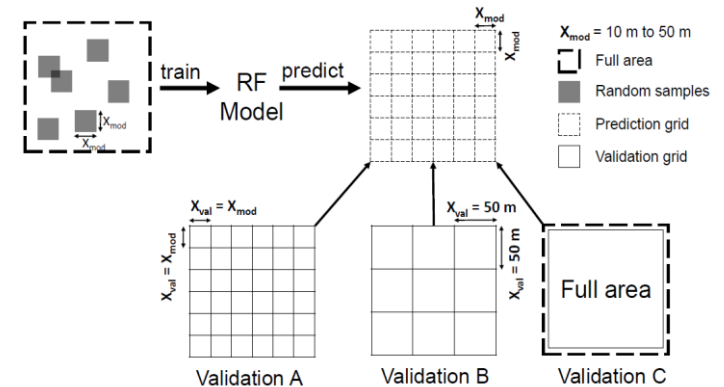
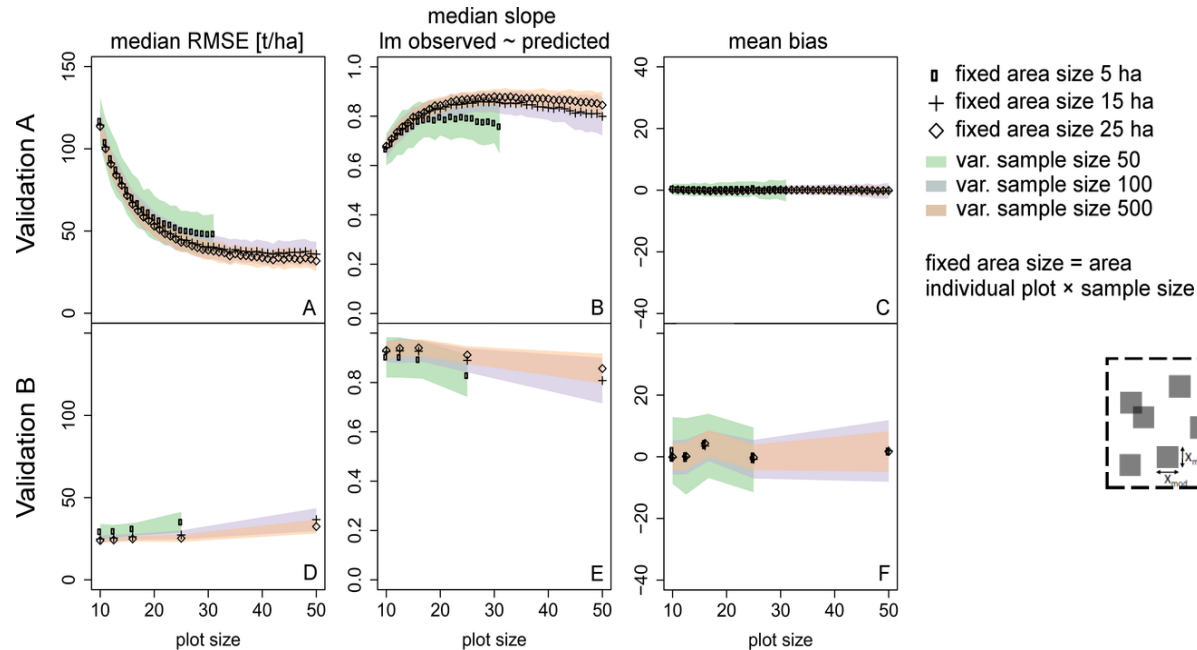
- Realistic benchmark datasets can be created
- All trees are “known”
- Can be used for example to evaluate workflows for:
 - Single tree delineation
 - Tree Species classification
 - ...



Adapted from <https://i.stack.imgur.com/A8xNy.jpg>

Example

Influence of plot size and sample size on ALS-based biomass estimations



Thank you for your attention
Thanks for support!

We acknowledge all the participants of the Single-tree Mapathon back in pre-pandemic times.

We acknowledge DFG for support of this research in the framework of the SYSSIFOSS project (project id: 411263134).

Contact: fabian.fassnacht@kit.edu

<https://www.youtube.com/watch?v=B9yStyUBaa0&t=23s>

<http://www.uni-heidelberg.de/syssifoss>

https://www.ifgg.kit.edu/vegetation/projekte_1776.php



Deutsche
Forschungsgemeinschaft

