

Effect of spatially distributed radar-gauge rainfall products on simulated urban flows

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- Urban hydrological studies require a **fine temporal and spatial resolution**.
- Dense rainfall gauge (RG) networks** are **rarely available**.

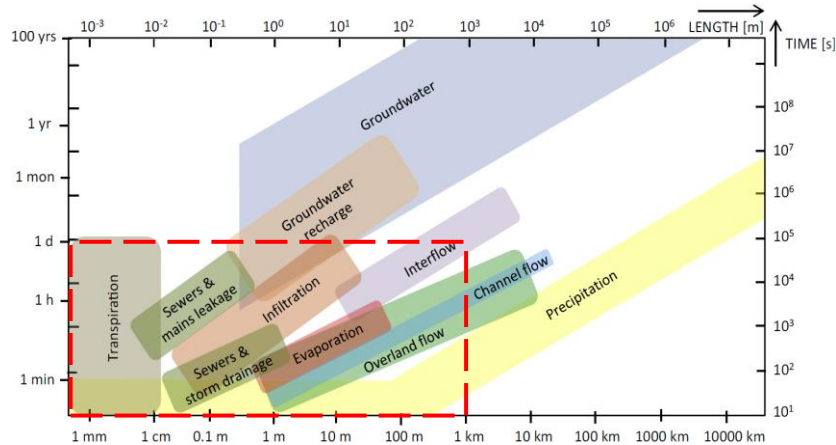


Fig. 1: Spatial and temporal scales of hydrological processes in urban areas

Source: from (Salvadore et al., 2015)

- Weather radars** provide **high spatial and temporal resolution**, **RG high accuracy** for a (small) area.
- Several merging radar-gauge methods** in the literature, **mainly validated with rain gauges** few with flow simulation (Ochoa-Rodriguez et al., 2019).

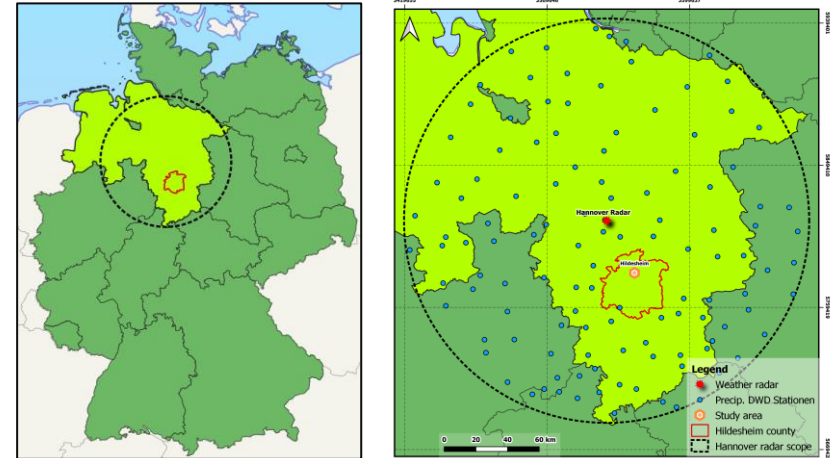


Fig. 2: Low rain gauge density in Hildesheim, Lower Saxony, Germany

- Area of 133 ha **without operational structures**
- Two monitoring sites for the period **February 2021 until October 2021** (each 1-5 min).
- Twenty-two (**22**) **events** with duration ranging 2-14-hours
- **Calibration/Validation** -> **7/22 events**

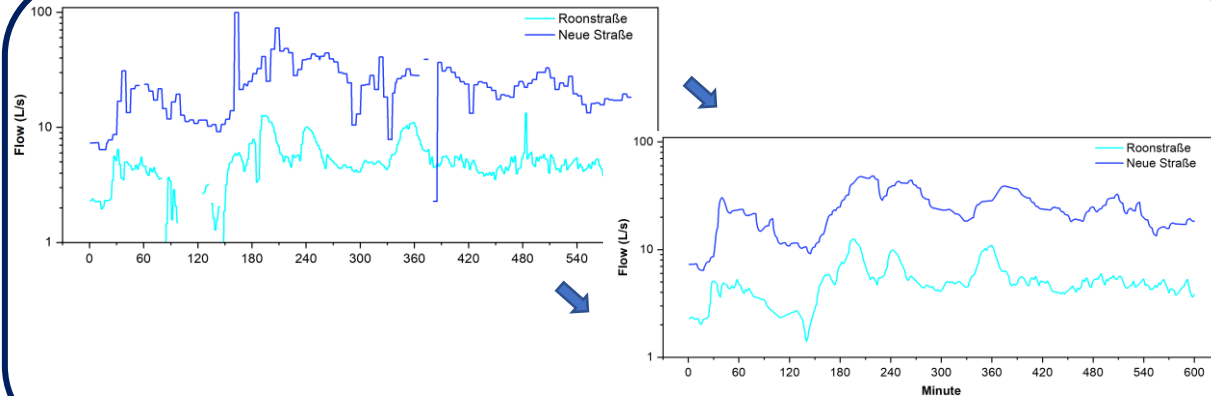


Fig. 4: Measurement corrections

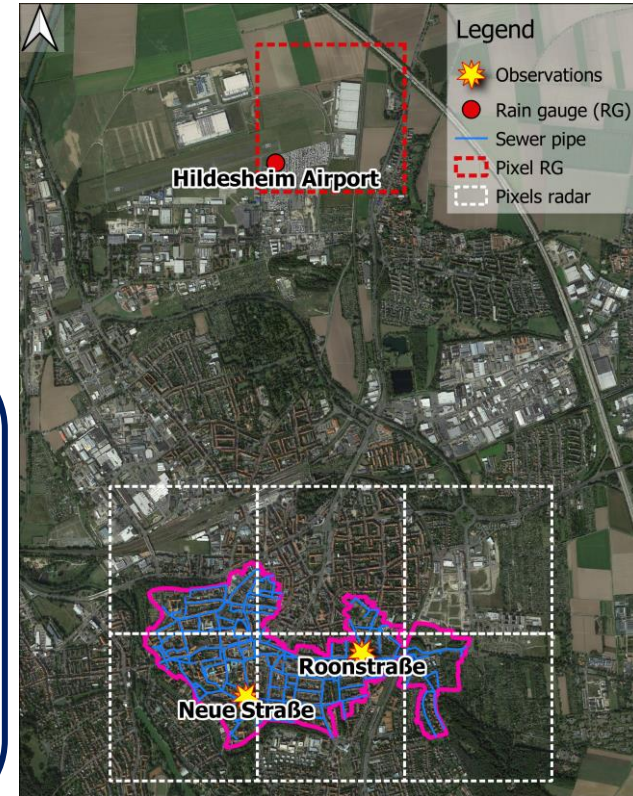


Fig. 3: Monitoring sites in the Study area

Radar processing

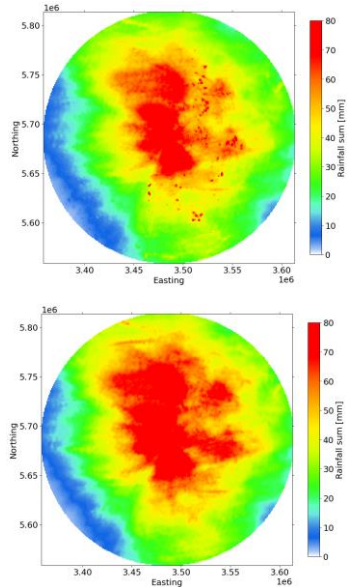


Fig. 5: Radar processing FLD Radar (2021-03)

Temporal and Spatial Smoothing (TSS)

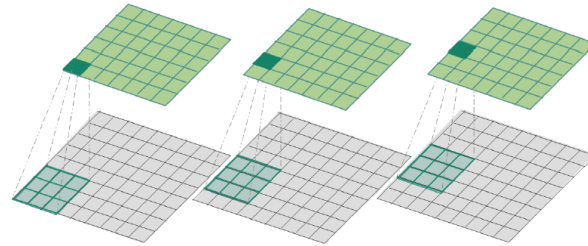


Figure 6. Spatial smoothing with a 3x3 kernel size
Source: (Shehu, 2021)

1

Conditional Merging (CM)

(Ehret, 2003)

2

Kriging with external drift (KED)

3

QM Bias Correction

(Rabiei and Haberlandt, 2015)

(FB)

4

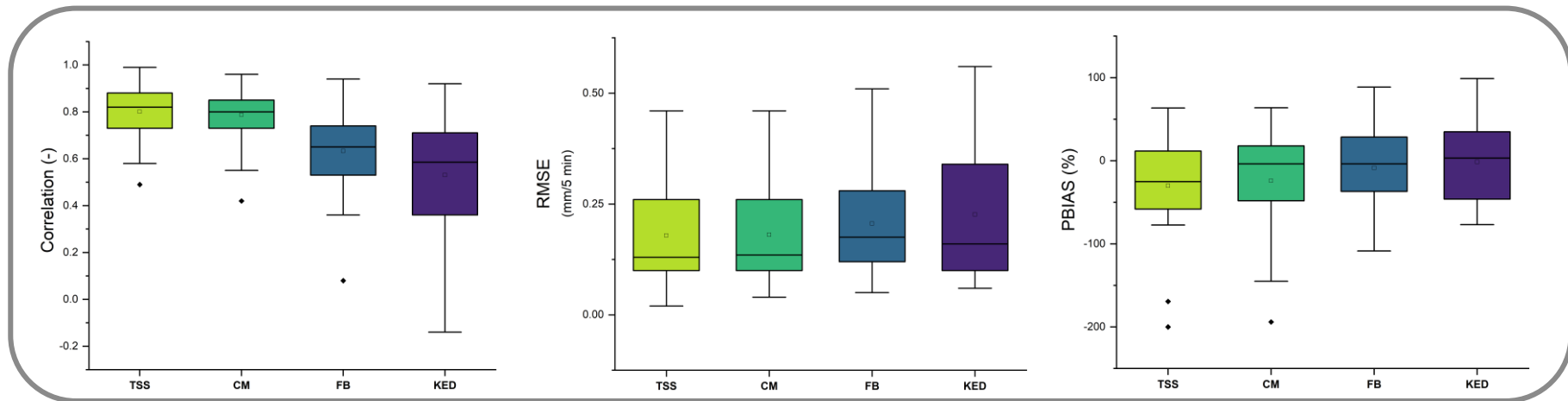
KED hourly basis

Disaggregation to 5'

(Rabiei and Haberlandt, 2015)

Rainfall performance

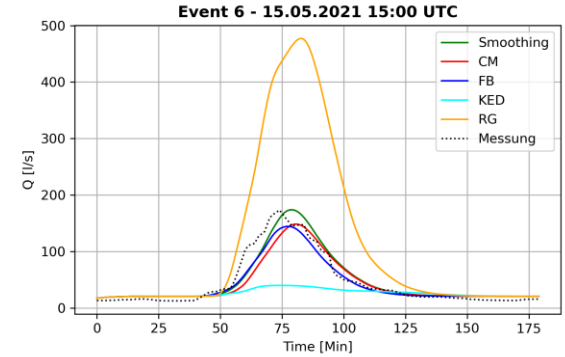
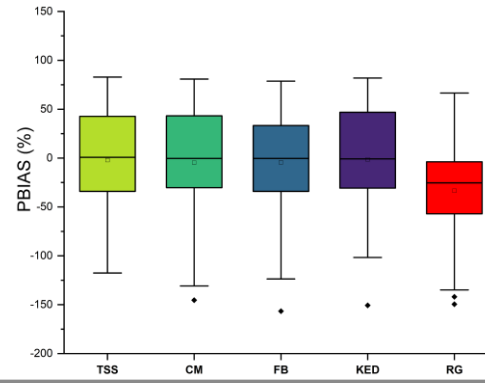
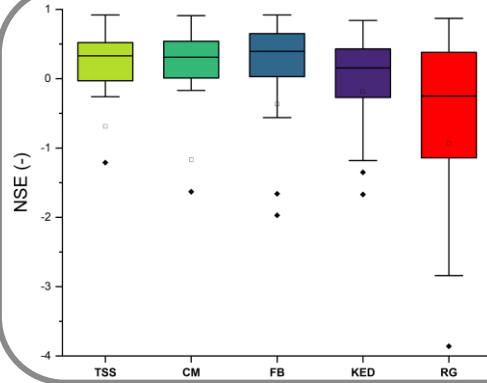
- **TSS** is the best for capturing the **event occurrence** but not their **magnitude**
- **Merging methods** performance could be **limited** due to the **low density** of rain gauges



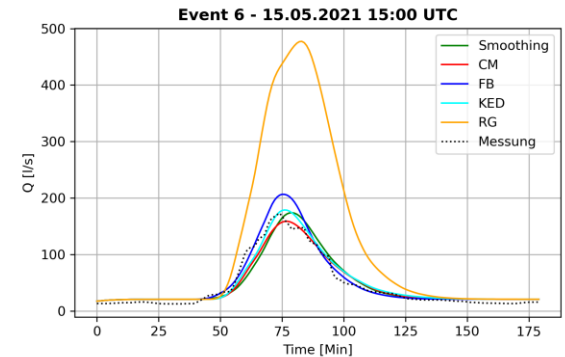
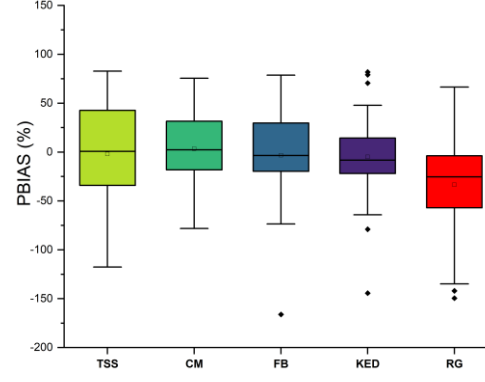
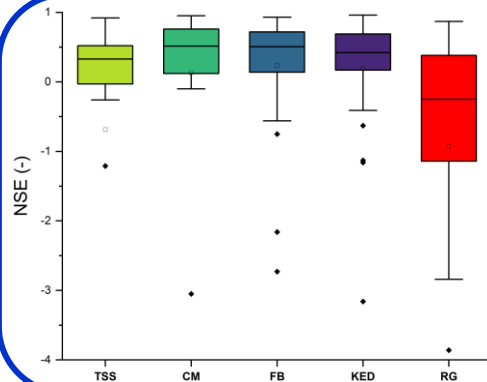
TSS: Temporal and spatial smoothing, **CM:** Cond. Merging, **FB:** Field Bias, **KED:** Kriging with External Drift

Flow performance

Without RG



With RG



- **Merging methods and flow simulations are strongly affected by the density of rain gauges (KED is the most influenced, CM is more robust).**
- **Only the smoothed radar data delivered better simulation results than one gauge station in the vicinity.**
- **The inclusion of the RG in interpolation improved considerably the merging results, which might require adjustments in the model parameterization (new calibration).**

Thank you for your time and interest!



This work was possible thanks to:

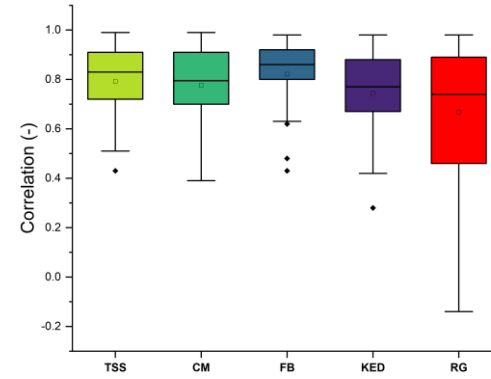
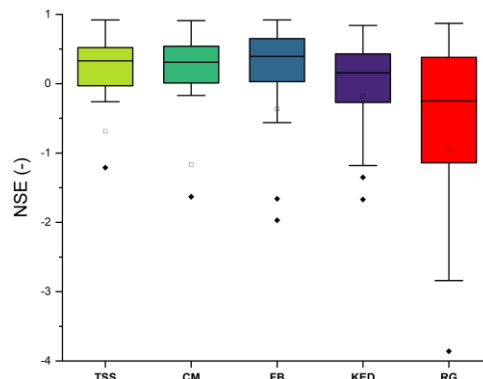
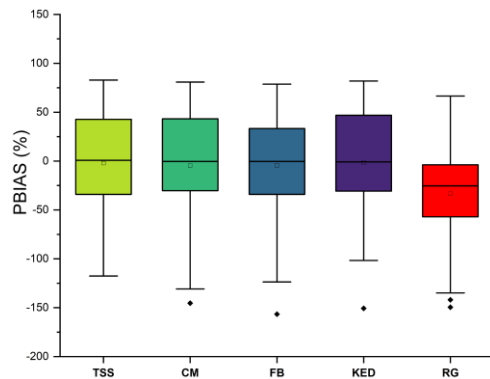
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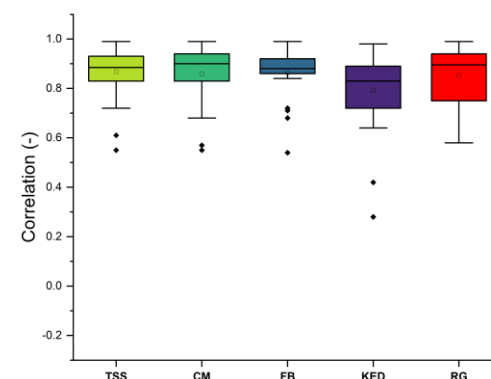
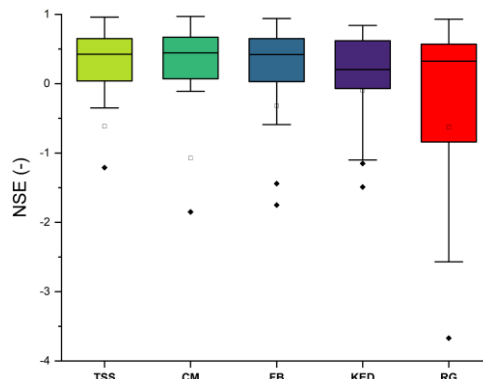
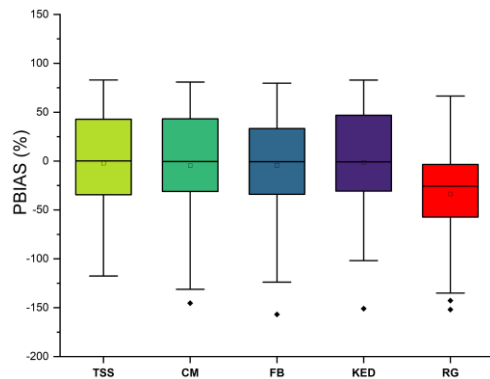
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Not shifted, without
RG at Airport

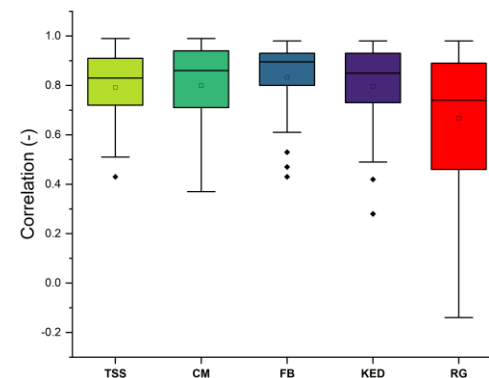
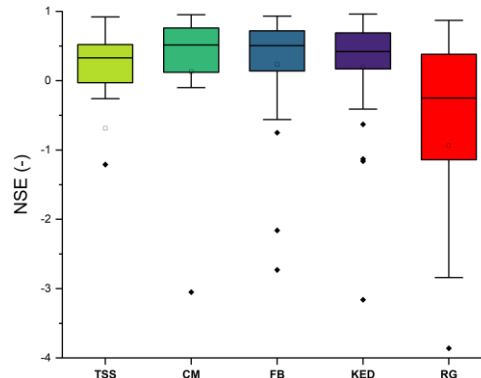
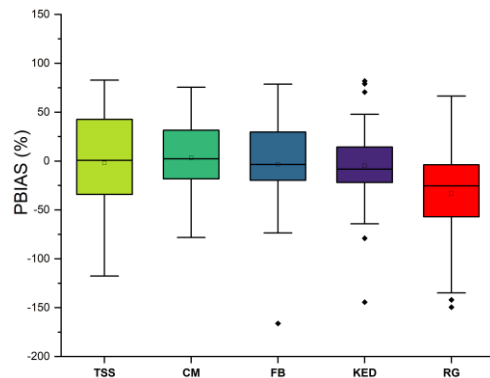


Shifted, without RG
at Airport

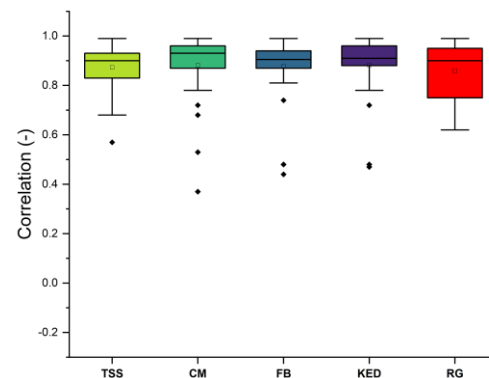
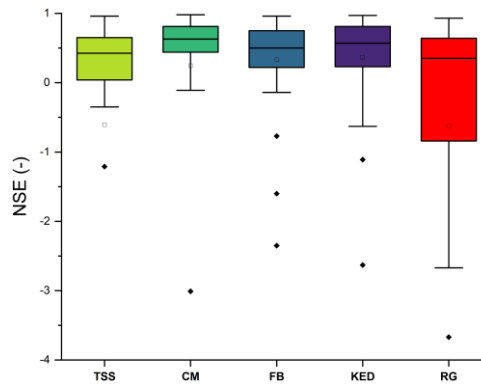
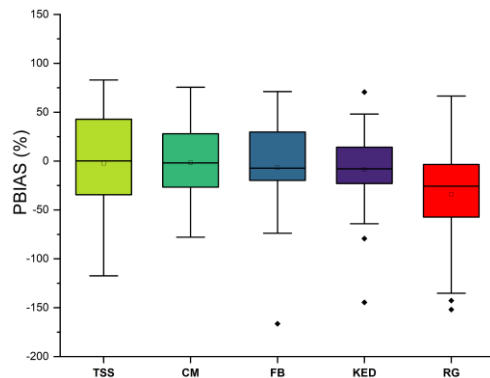


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Not shifted, with RG
at Airport



Shifted, without RG
at Airport



TSS: Temporal and spatial smoothing, CM: Cond. Merging, FB: Field Bias, KED: Kriging with External Drift