



The Framework of Relativistic Geodesy: What do we know? (beyond pN)

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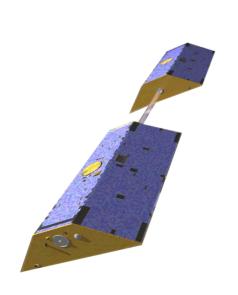


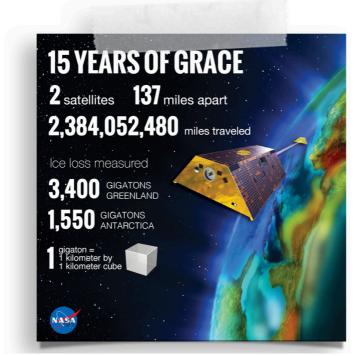


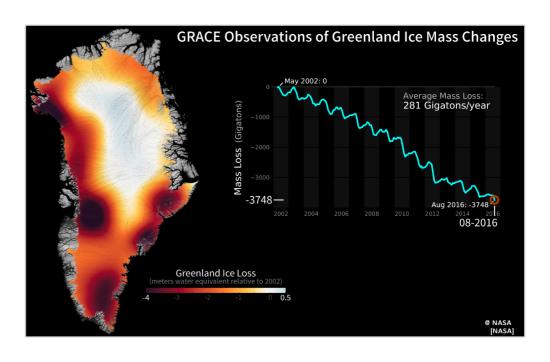
Global challenges



Introduction & Motivation







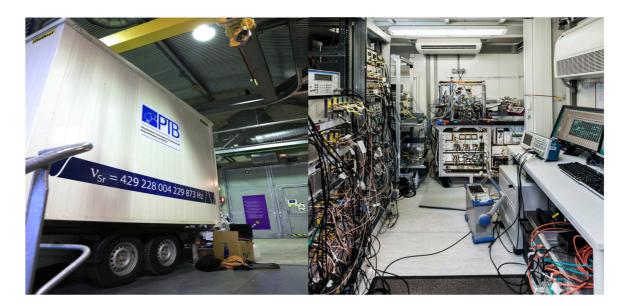
- Geodesy might be described as the science of the properties and gravity field of our Earth; engineering physics
- There are important links to fields such as positioning, environmental and climate research.
- Conventional Geodesy builds upon Newtonian gravity and the gravitational potential is a central notion.





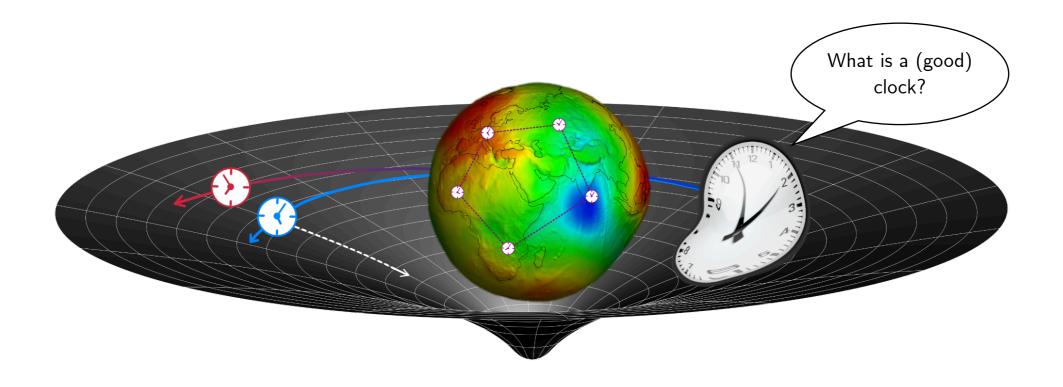
Introduction & Motivation

- For observations, reference systems are needed.
 Height references are of particular interest and intimately related to properties of the gravity field.
- Relativistic gravity: reformulate basic geodetic notions (dof) and develop a consistent theoretical framework relativistic geodesy to yield an undoubtedly correct interpretation of measurement results.
- Chronometric geodesy builds on the comparison of clocks and offers fundamental insight into the spacetime geometry if a solid theoretical formulation of observables is underlying modern high-precision measurements.
- Genuine relativistic def. of potential(s), geoid, ellipsoid, normal gravity, height notions, multipoles and more is possible.









Make sense of geodetic concepts and notions in a relativistic theory of gravity!



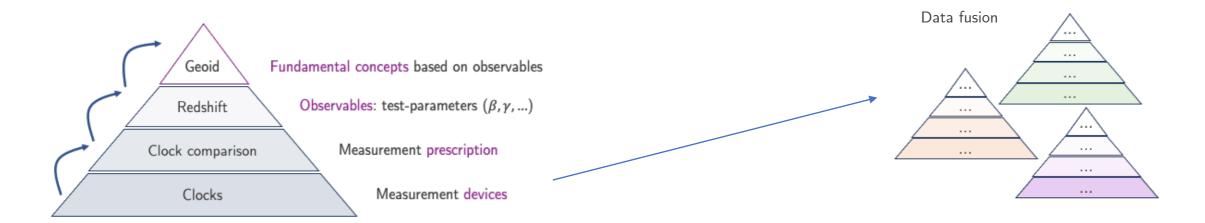








- Set up a theoretical framework following a set of assumptions (e.g. stationarity, asymptotic flatness)
- Employ measurement devices and give a prescription of how to obtain observables —> define basic notions
- Constrain the set of model parameters by a multitude of measurements in data fusion



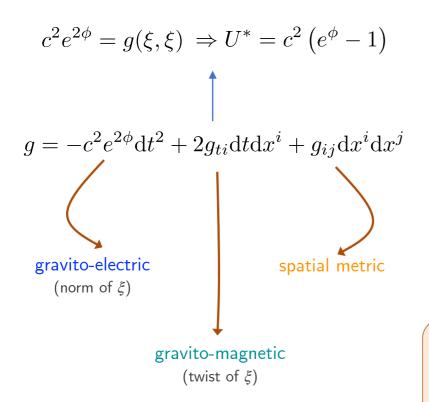
$$(\mathcal{M}, g, \nabla, ...)$$
 Theoretical framework (GR, ppN, ...) + assumptions

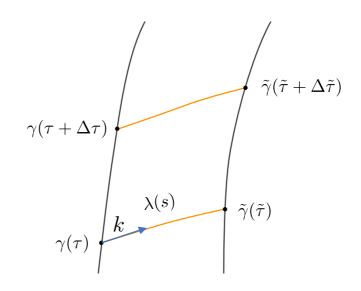
- Geoid, normal gravity, ellipsoid, mass multipole moments, height notions, field equations
- spin moments, twist potential, relativistic effects on orbits & clocks (precession, Lense-Thirring, gravitomagnetism, ...)





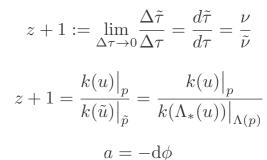
- \exists timelike Killing vector field ξ ; the Earth is modeled by an isometric (Killing) congruence in GR.
- dof are contained in two potentials and the spatial metric.
- Rigidly co-rotating observers agree on a time-independent redshift potential ϕ ; in the congruence: $1+z=\exp(\Delta\phi)$
- We can formulate a relativistic gravity potential —> Relativistic geoid: $U^* = U_0^* = \mathrm{const.}$





The post-Newtonian limit is

$$1 + z = \left(1 + \frac{\Delta W}{c^2} + \frac{v^2 - \tilde{v}^2}{2c^2}\right) \frac{1 + \vec{n}(x) \cdot \vec{v}/c}{1 + \vec{n}(\tilde{x}) \cdot \vec{\tilde{v}}/c}$$



See excellent work of Kopeikin et al. on pN developments,

DSX papers, Blanchet, Poncin-Lafitte, Petit, Wolf, Linet, Teyssandier et al.



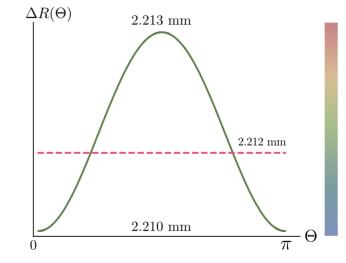


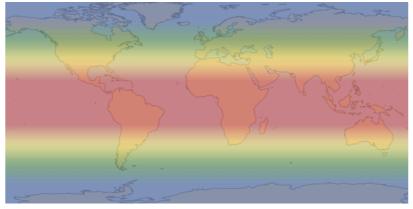
For some exact solutions, we have

$$\frac{U_{\text{Schwarzschild}}^*}{c^2} = \sqrt{1 - \frac{2GM}{c^2r} - \frac{\omega^2}{c^2}r^2\sin^2\theta} - 1,$$

$$\frac{U_{\text{ER}}^*}{c^2} = \sqrt{e^{2\psi_{\text{ER}}(x,y)} - \frac{\omega^2}{c^2} (GM/c)^2 (x^2 - 1)(1 - y^2) e^{-2\psi_{\text{ER}}(x,y)}} - 1$$
with $\psi_{\text{ER}(x,y)} = \frac{1}{2} \log \left(\frac{x - 1}{x + 1} \right) + \underbrace{q_2}_{2} \underbrace{\frac{(3y^2 - 1)}{2} \left(\frac{(3x^2 - 1)}{4} \log \left(\frac{x - 1}{x + 1} \right) + \frac{3}{2}x \right)}_{2},$

$$\frac{U_{\mathrm{Kerr}}^*}{c^2} = \sqrt{1 - \frac{2mr}{\rho(r,\vartheta)^2} + 4\frac{\omega}{c}\frac{(mr\sin^2\vartheta)}{\rho(r,\vartheta)^2} - \frac{\omega^2}{c^2}\sin^2\vartheta\left(r^2 + (a^2) + \frac{2mr(a^2)\sin^2\vartheta}{\rho(r,\vartheta)^2}\right)} - 1.$$









Use the Newtonian relation for normal gravity

$$J_0 = 1$$
, $J_{2l} = f(J_2, E, a, l)$, $\forall l > 1$.

- Model spacetime by a Weyl solution and investigate Newtonian limit [Ehlers, Quevedo]
- Exact expression for normal gravity spacetime,
 which reduces to the Newtonian notion in the limit.
- Should frame-dragging effects be included?
 —> Quevedo-spacetime (degenerate notion)

$$g_{\mu\nu}dx^{\mu}dx^{\nu} = -e^{2\psi}c^{2}dt^{2} + m^{2}e^{-2\psi}(x^{2} - 1)(1 - y^{2})d\varphi^{2}$$

$$+ m^{2}e^{-2\psi}e^{2\gamma}(x^{2} - y^{2})\left(\frac{dx^{2}}{x^{2} - 1} + \frac{dy^{2}}{1 - y^{2}}\right),$$
where $\psi = \sum_{l=0}^{\infty} (-1)^{l+1}q_{l} Q_{l}(x) P_{l}(y)$

$$q_{l} = (-1)^{l} \frac{(2l+1)!!}{l! m^{l}} R_{ref}^{l} J_{l}.$$

$$\psi_{N} = -\sum_{k=0}^{\infty} \frac{(4k+1)!!}{(2k)!} \left(\frac{R_{\text{ref}}}{m}\right)^{2k} J_{2k} Q_{2k}(x) P_{2k}(y)$$

$$= -\sum_{k=0}^{\infty} \left[\frac{(4k+1)!!}{(2k)!} \left(\frac{R_{\text{ref}}}{m}\right)^{2k} J_{2k} P_{2k}(y) \times \left(\log\left(\frac{x+1}{x-1}\right) P_{2k}(x) - 2\sum_{i=0}^{k-1} \frac{4k-4i-1}{(2k-i)(2i+1)} P_{2k-2i-1}(x)\right) \right],$$

$$= -Q_{0}(x) - \frac{15}{2} \left(\frac{R_{\text{ref}}}{m}\right)^{2} J_{2} Q_{2}(x) P_{2}(y) - \sum_{k=2}^{\infty} \dots$$





- Multipole moment definitions [Simoin+Beig 1982; Geroch+Hansen 1970,74, Thorne 1980]
- Moments related to STF parts of

$$\Phi_M = \sum_{l=0}^{m-1} \frac{E_{a_1 \cdots a_i} x^{a_1} \cdots x^{a_l}}{l! r^{2l+1}} + O^{\infty} \left(r^{-(m+1)} \right)$$

$$\Phi_S = \sum_{l=0}^{m-1} \frac{F_{a_1 \cdots a_i} x^{a_1 \cdots x^{a_l}}}{l! r^{2l+1}} + O^{\infty} \left(r^{-(m+1)} \right)$$

Field equation [Geroch+Hansen; Simon+Beig; Bäckdahl 2006]

Moments related to STF parts of
$$\mathcal{M} = \mathbb{R} \times \mathcal{N} \qquad \gamma_{ij} = e^{2\phi}g_{ij} - \xi_i\xi_j \qquad \text{space}$$

$$\Phi_M = \sum_{l=0}^{m-1} \frac{E_{a_1 \cdots a_i} x^{a_1} \cdots x^{a_l}}{l! r^{2l+1}} + O^{\infty} \left(r^{-(m+1)} \right) \qquad \text{gravito-electric} \qquad ds^2 = e^{2\phi} \left(dt + \sigma_i dx^i \right)^2 - e^{-2\phi} \gamma_{ij} dx^i dx^j \qquad \text{spacetime}$$

$$R_{ij}(\gamma) = \frac{1}{2} e^{-4\phi} \left(\partial_i e^{2\phi} \partial_j e^{2\phi} + \partial_i \varpi \partial_j \varpi \right) \longrightarrow \text{curvature}$$

$$R_{ij}(\gamma) = \frac{1}{2} e^{-4\phi} \left(\partial_i e^{2\phi} \partial_j e^{2\phi} + \partial_i \varpi \partial_j \varpi \right) \longrightarrow \text{curvature}$$

$$\gamma^{ij} D_i D_j e^{2\phi} = e^{-2\phi} \gamma^{ij} \left(\partial_i e^{2\phi} \partial_j e^{2\phi} - \partial_i \varpi \partial_j \varphi \right)$$

$$\gamma^{ij} D_i D_j \varpi = 2e^{-2\phi} \gamma^{ij} \partial_i e^{2\phi} \partial_j \varpi$$

$$\varpi_i = e^{\phi} \epsilon_i^{jk} D_j \sigma_k$$

Thorne's definition in an ACMC coord. system

$$g_{00} = -1 + \frac{2g}{r} - \frac{2g^2}{r^2} + \sum_{i=2}^{\infty} \frac{1}{r^{l+1}} \left[\frac{2(2l-1)!!}{l!} g_{A_l} N_{A_l} + [(l-1) \text{ pole }] + \dots + [\text{ monopole }]] \right]$$

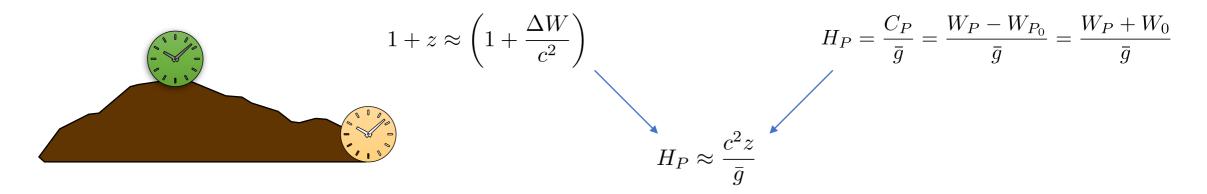
$$g_{0j} = \sum_{l=1}^{\infty} \frac{1}{r^{l+1}} \left\{ -\frac{4l(2l-1)!!}{(l+1)!} \epsilon_{jka_l} S_{kA_{l-1}} N_{A_l} + [(l-1) \text{ pole }] + \dots + [\text{ monopole }] \right\}$$

$$g_{ij} = \delta_{ij} \left[1 + \frac{2g}{r} \right] + \frac{g^2}{r^i} \left(\delta_{ij} + n_i n_j \right) + \sum_{l=2}^{\infty} \frac{1}{r^{l+1}} \left[\frac{2(2l-1)!!}{l!} g_{A_l} N_{A_l} \delta_{ij} + [(l-1) \text{ pole }] + \dots + [\text{ monopole }] \right]$$





Chronometric geodesy allows to measure heights by clock comparison



- This is a mixed concept! We can do better.
- We use the relativistic gravity potential U^* to define the notion of chronometric height.
- The average acceleration \bar{a} is computed from the acceleration potential, which coincides with the redshift potential!
- Alternatively, GR introduces a unique acceleration: surface gravity κ at, e.g., the gravitational radius (of the monopole part)

$$C_P^* := U_P^* - U_0^* = z(c^2 + U_0^*)$$
 alternative
$$H_P^* := \frac{C_P^*}{\bar{a}} = \frac{z(c^2 + U_0^*)}{\bar{a}}, \quad a = c^2 \mathrm{d}\phi$$

$$H_P^* = \frac{C_P^*}{\kappa} = \frac{z(c^2 + U_0^*)}{\kappa}$$



