A tool for accelerometer modeling

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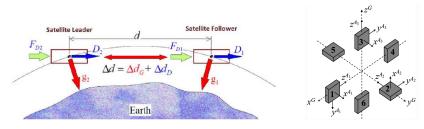






Accelerometers in gravimetry

Accelerometers (ACCs) are part of science payload in gravimetry missions. Can be used to measure forces impacting spacecraft (SC), or as test mass (TM) following a geodesic. Also gradiometers to measure local Δg .



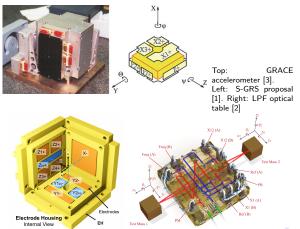
Left: scheme of GRACE-type gravimetry mission [9]. Right: accelerometer placement in GOCE (gradiometry mission) [8].

Accelerometer design challenges

Different geometries depending on application and constraints; Sensors can be capacitive, optical, cold atom (in future).

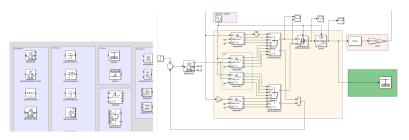
Actuation of TM is electrostatic repulsion;

TM may have charge build up and needs UV light or gold wire to discharge;



Accelerometer modeling

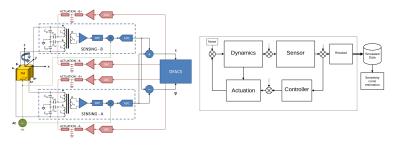
Need a tool to estimate the performance of the instruments and indicates scenarios w/ best science return. A mission can have one or more ACCs (of the same or different designs) per SC. ACME - Accelerometer Modeling Extended. Programmed in Matlab/Simulink environment. Designed to be modular, parametrizable, instantiable, integration with XHPS [7];



Simulink block library and example application model

Accelerometer modeling

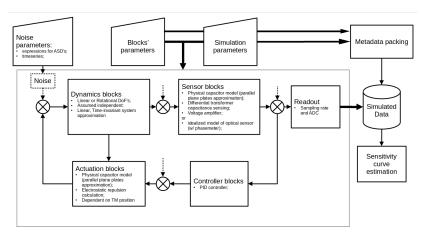
The simulator is independent of geometry, sensor technique, noise model, control loop, etc. To simplify, assume independent DoFs, linearized terms and a generalized ACC.



Left: Block diagram of LPF actuation circuit [5]. Right: generic block diagram representing an ACC

Accelerometer modeling

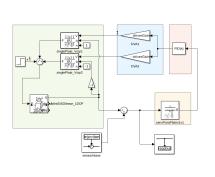
Each module can contain a variety of implementation options and parameters, as we try to cover most ACC designs.

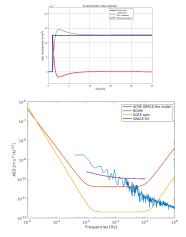


Block diagram with options and parameters

Standalone simulation

Able to simulate a instrument with a model for dynamics, sensors, actuation and noises. Produces both time and frequency domain results.





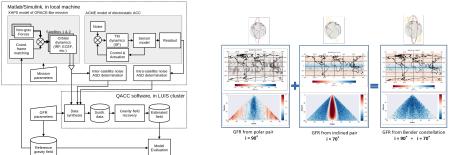
 $\ \, \mathsf{Left:} \,\, \mathsf{Screenshot} \,\, \mathsf{of} \,\, \mathsf{a} \,\, \mathsf{GRACE}\text{-}\mathsf{FO}\text{-like} \,\, \mathsf{ACC} \,\, \mathsf{model}. \,\, \mathsf{Top:} \,\, \mathsf{time-domain} \,\, \mathsf{response} \,\, \mathsf{of} \,\, \mathsf{an} \,\, \mathsf{ACC} \,\, \mathsf{to} \,\, \mathsf{a} \,\, \mathsf{step} \,\, \mathsf{input}. \,\, \mathsf{Bottom:} \,\, \mathsf{and} \,\, \mathsf{a$

GFR simulation

Simulate a Gravity Field Recovery mission scenario using tools developed within the TerraQ collaborations ACME + XHPS + QACC:

XHPS = multibody orbital dyn. on hi-fi gravitational field [7];

 $\mathsf{QACC} = \mathsf{GFR}$ data synth. from orbital and ACCs simulation [10].



Left: ACME+XHPS+QACC workflow. Right: map of EWH produced in 3 mission scenarios

Thank you!

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