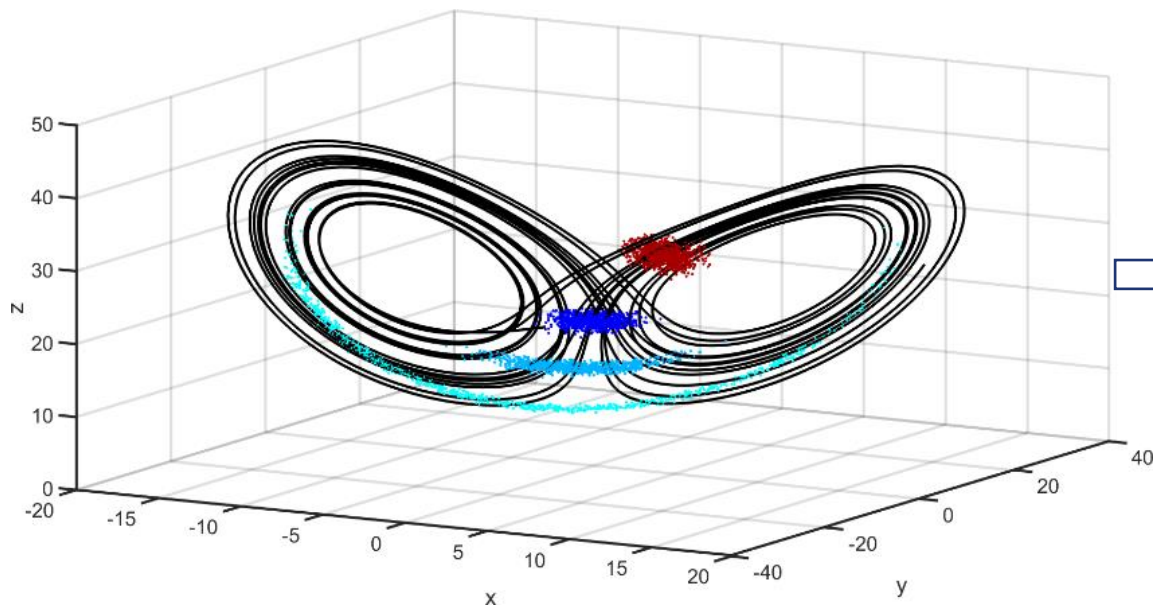


A 4D-Localized Particle Filter Method for Regional Data Assimilation at DWD

Nora Schenk, Anne Walter, Roland Potthast, ...



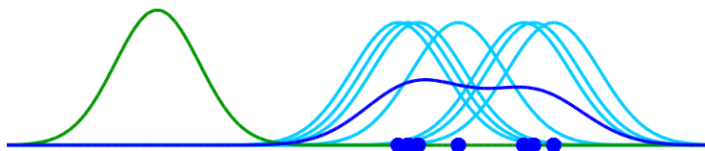


In general background ensemble does not represent a Gaussian distribution

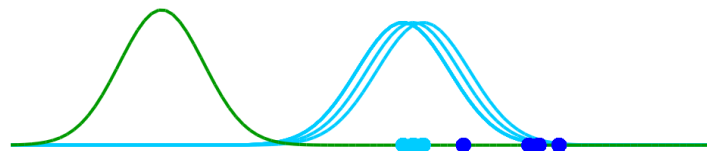
Development over time of a Gaussian distributed sample following the Lorenz 1963 model

Localized Mixture Coefficients PF (LMCPF)

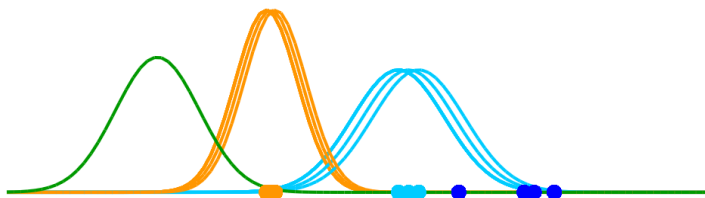
1 Background



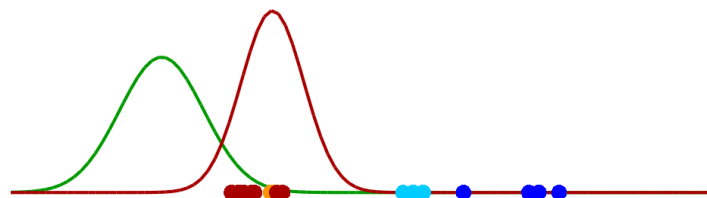
2 Resampling



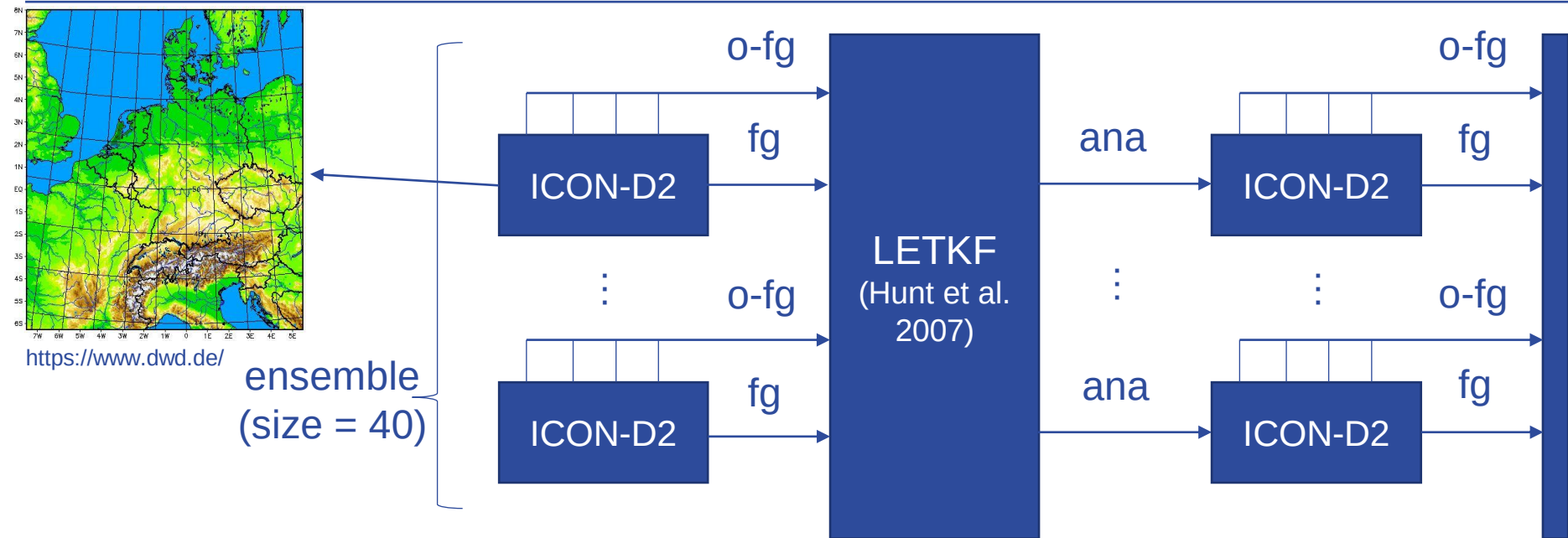
3 Shift of Particles



4 Gaussian Rejuvenation



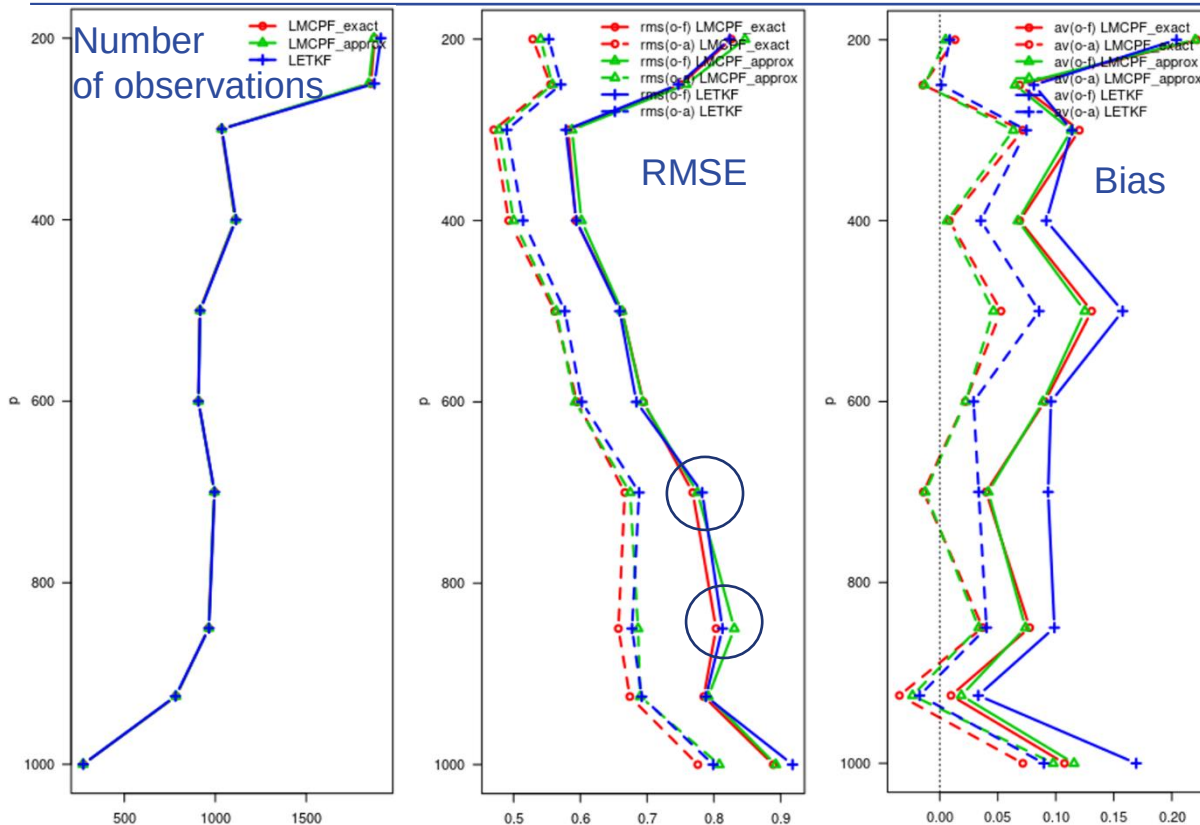
KENDA – Kilometre-scale Ensemble DA



Schraff et al. (2016)

- ➔ Period: June 01, 2021 – June 02, 2021
- ➔ Model: ICON-D2
- ➔ 40 ensemble member
- ➔ Observation systems
 - ➔ Conventional data (AIREPs, TEMP, ...)
 - ➔ Radar data
 - ➔ SYNOP data (T2M and RH2M)
- ➔ LMCPF method: shift parameter $\kappa = 2.5$
- ➔ Comparison of ensemble means

RMSE for AIREPs (Temperature)



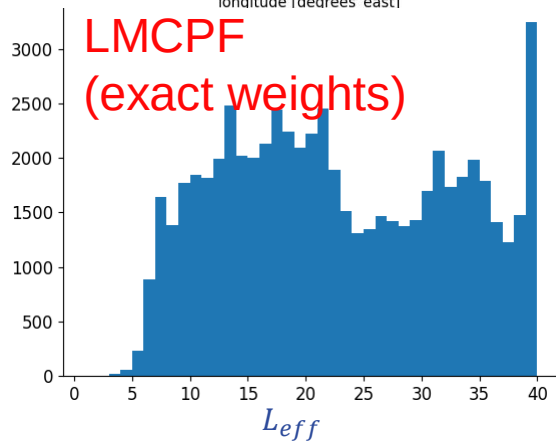
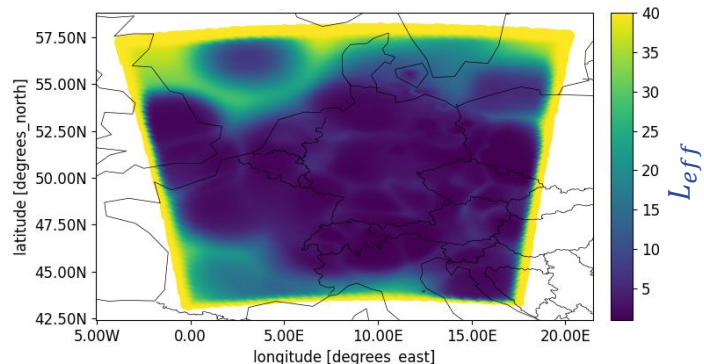
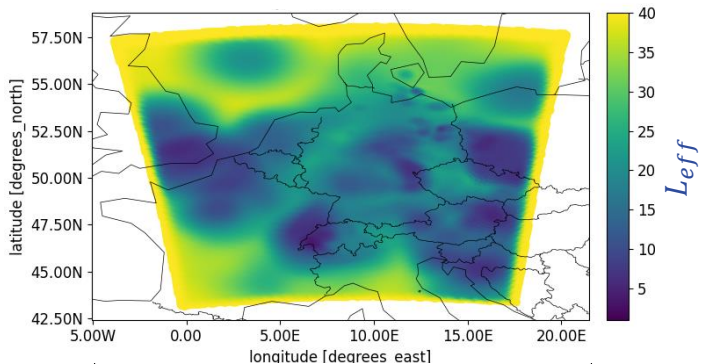
Period:
June 01, 2021 12 UTC –
June 02, 2021 00 UTC

LMC PF (exact weights)
LMC PF (approx. weights)
LETKF

obs-first guess —
obs-analysis - - -

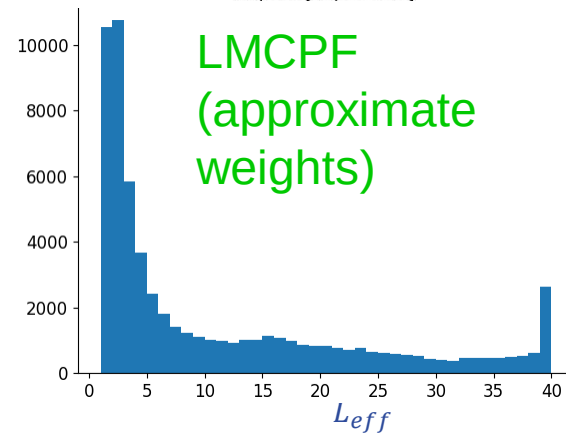
Effective Ensemble Size L_{eff} – 850hPa

2021/06/02
00 UTC



$L_{eff} \rightarrow 1$
filter degeneracy

$L_{eff} \rightarrow L$
uniform weights



- ➔ Particle filters as the LMCPF aim to improve the numerical weather prediction in a non-Gaussian setting
- ➔ In the KENDA framework for regional NWP, the LMCPF is a 4D-Particle Filter method with 4D background error covariance matrices
- ➔ With the application of exact particle weights, the LMCPF is much improved and the effective ensemble size is increased

Outlook:

- ➔ Further experiments for ICON-D2 with the LMCPF with exact weights and different values for κ
- ➔ Further analysis of background distributions in ICON-D2

Many thanks for your attention! Questions?



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