



Characterizing Alpine peatlands from drones: a case study

Marco Assiri¹, Anna Sartori², Giulio Vignoli³, Matteo Massironi⁴, and Sonia Silvestri²

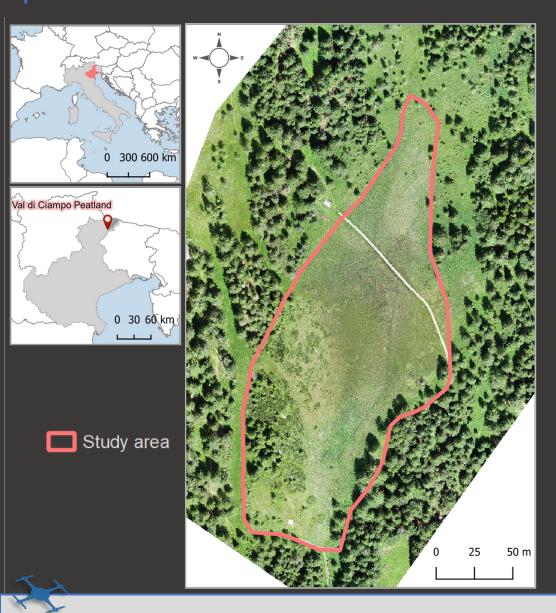
- ¹Department of Land, Environment, Agriculture and Forestry, University of Padova, Agripolis, viale dell'Università 16, 35020 Legnaro, Italy;
- ²Department of Biological Geological and Environmental Sciences, University of Bologna, P.za Porta S. Donato 1, 40126 Bologna, Italy;
- ³Department of Civil and Environmental Engineering and Architecture, University of Cagliari, via Marengo 2, 09124 Cagliari, Italy & Department of Groundwater and Quaternary Geology Mapping, Geological Survey of Denmark and Greenland, C.F. Moellers Allé 8, 8000 Aarhus, Denmark;
- ⁴Department of Geosciences, University of Padova, Italy.

CHANGED Project: "CHAracteriziNG pEatlands from Drones"



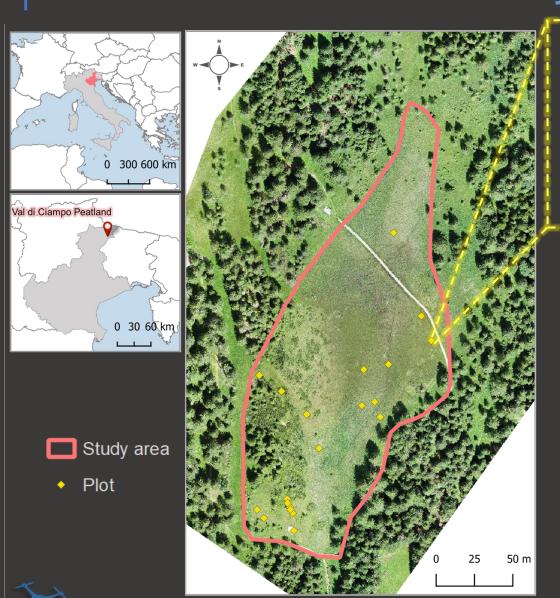












Vegetation attributes ----











0 30 60 km



Vegetation attributes

- Species composition
- Vegetation height

AG biomass

(sites = 20)

- Bulk density
- •BG biomass
- Carbon content

$$(sites = 15)$$

Peat properties

- Bulk density
- Carbon content

(sites = 20; sample units = 46)

Study area

Boreholes

Plot





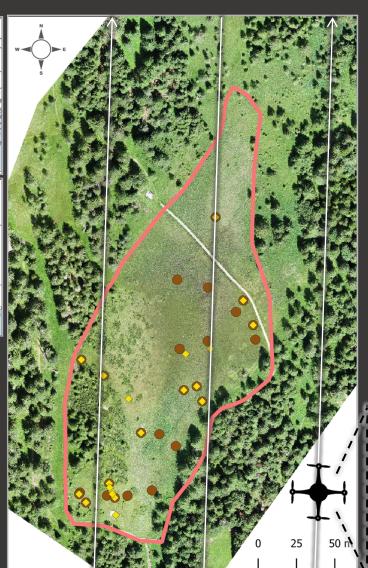


Study area

Boreholes

→ Flightlines

Plot



Vegetation attributes

- Species composition
- AG biomass
- Vegetation height
 - (sites = 20)

- Bulk density
- BG biomass
- Carbon content

(sites = 15)

Peat properties

- Bulk density
- Carbon content

(sites = 20; sample units = 46)

Data from drone -----

DJI Matrice 300 + Camera L1



- LiDAR (3 returns)
- Orthomosaic (20 mpx)

DJI Matrice 600 + Nano Hyperspec

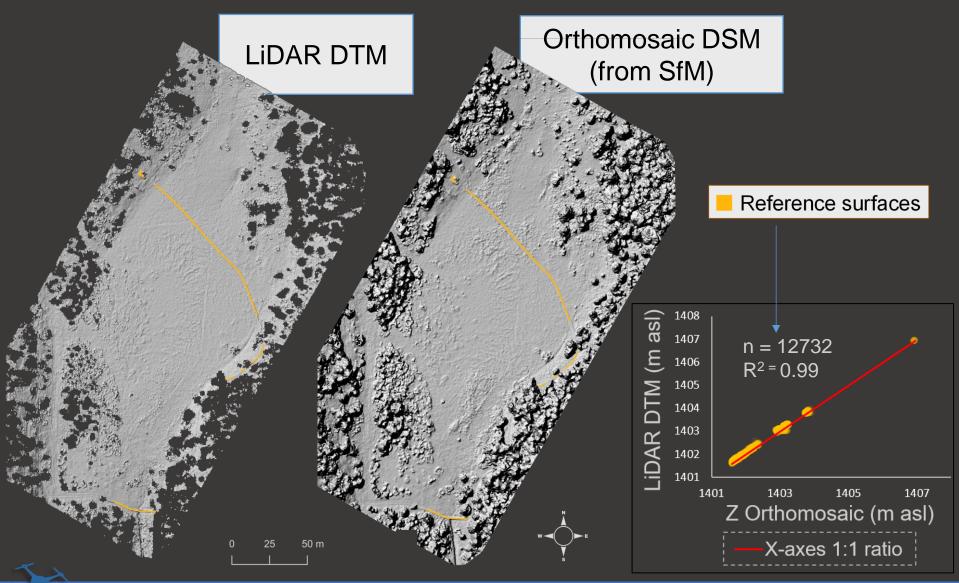


•273 spectral bands (400:1000 nm)





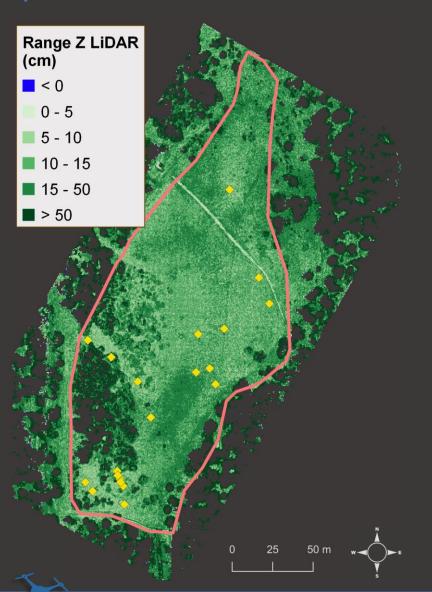
Preliminary results: LiDAR DTM



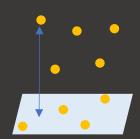


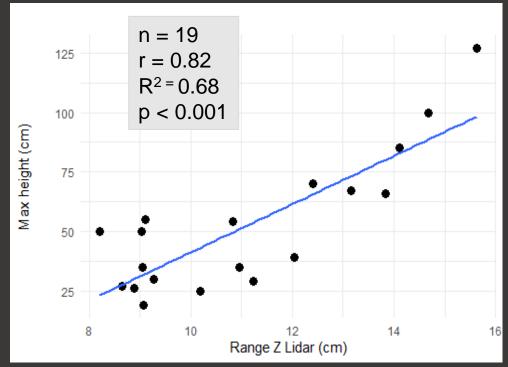


Preliminary results: LiDAR vegetation heights



Range Z LiDAR = Max(Z) - DTM

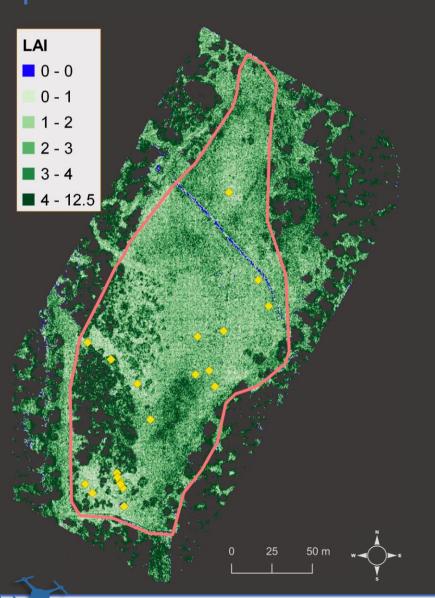








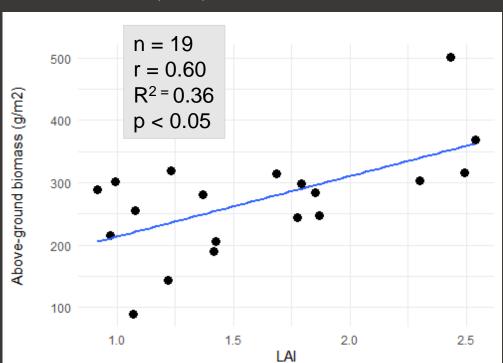
Preliminary results: LiDAR Leaf Area Index



$$LAI = -\frac{\cos(\theta)}{k} * \ln(Rg/Rt)$$

$$\approx -\frac{\cos(0)}{0.5} * \ln(Rg/Rt)$$

Richardson et al. (2009)





Thank you for your attention



