

Spatio-temporal distributed water vapor retrieved from GNSS observations and its usage in monitoring a rainfall process in Hong Kong

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Outline

- ❑ Backgrounds
- ❑ Water vapor retrieved from GNSS observations
 - Precipitable water vapor (PWV)
 - Spatio-temporal distributed water vapor
- ❑ Monitoring a rainfall process in Hong Kong
- ❑ Conclusions

Backgrounds

□ Tropospheric atmosphere

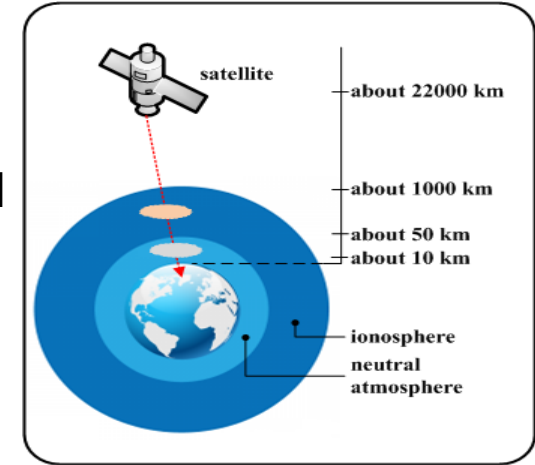
- the lowest layer of Earth's atmosphere
- extends upward to about 10 km above sea level
- **almost all** weather occurs within this layer
- **the wettest** layer of the atmosphere by far

□ GNSS

- tropospheric **refraction**
- line-of-sight delay **error**, i.e., tropospheric delay errors
- calibration of observations

□ Meteorology

- water vapor is a necessary information
- **GNSS Meteorology**
- water vapor **retrieval**



Delay error → Useful information

Calibration → Retrieval

Water vapor retrieval: precipitable water vapor

- ❑ The total amount of water vapor above a particular location is highly variable
- ❑ **PWV**: the depth of liquid water (in mm) that would result if all the water vapor in the atmospheric column is condensed and precipitated
- ❑ Zenith wet delay $\Delta\rho_{r,wet}^Z$ and PWV

$$\Delta\rho_{r,wet}^Z = 10^{-6} \int \left[k_2' \left(\frac{e}{T} \right) + k_3 \left(\frac{e}{T^2} \right) \right] Z_W^{-1} dz$$
$$PWV = \frac{1}{\rho_l} \int \rho_w dz$$



$$PWV = \Pi \cdot \Delta\rho_{r,wet}^Z$$

$$PWV = 10^6 \left[R_w \cdot \rho_w \cdot \left(\frac{k_3}{T_m} + k_2' \right) \right]^{-1} \cdot \Delta\rho_{r,wet}^Z$$

$$T_m = \frac{\int (e/T) Z_W^{-1} dz}{\int (e/T^2) Z_W^{-1} dz}$$

A particular station

→ GNSS observations

→ zenith wet delay $\Delta\rho_{r,wet}^Z$

→ PWV

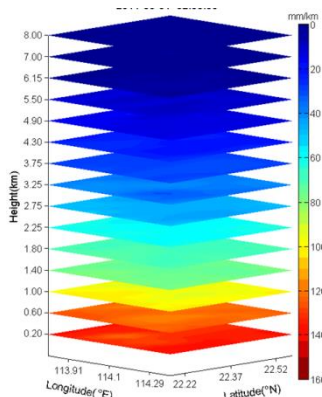
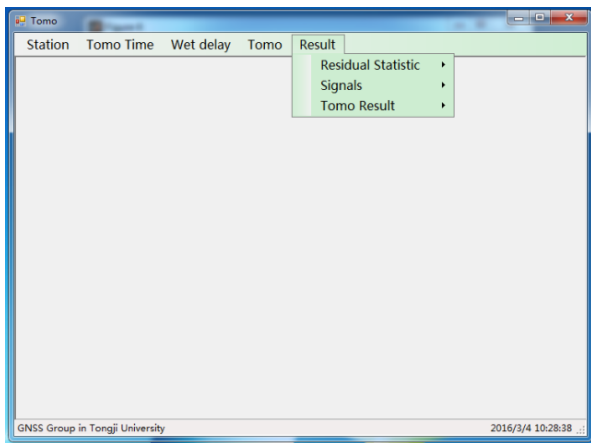
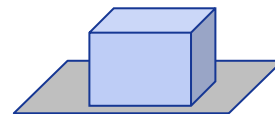
Water vapor retrieval: spatio-temporal water vapor

- ❑ two-dimensional
- ❑ integral water vapor
- ❑ PWV

Tomography



- ❑ three- or four-dimensional
- ❑ spatio-temporal distributed water vapor
- ❑ **TWV**

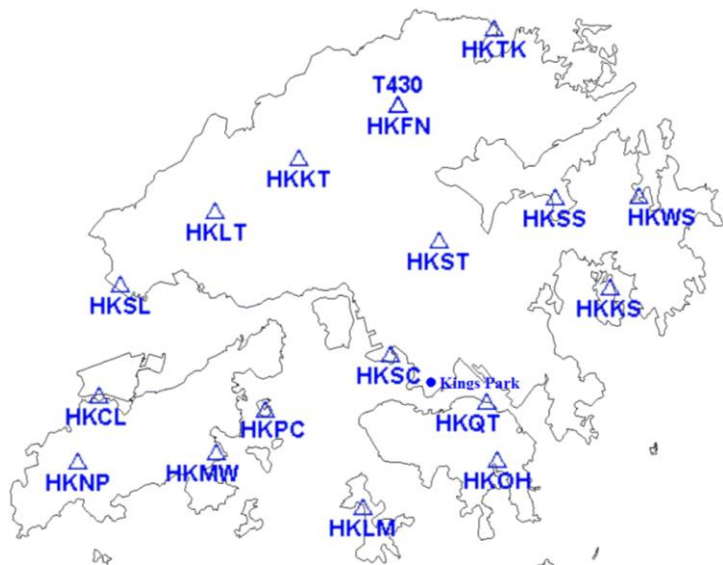


A certain amount of stations

- GNSS observations
- water vapor in line-of-sight (SWV)
- TWV

Software Copyright: Bofeng Li, Miaomiao Wang. GNSS WAter vapor Tomography
Software package (**GWATOS** V1.0). 2017.08.02, 2017SR418615

Monitoring a rainfall process in Hong Kong



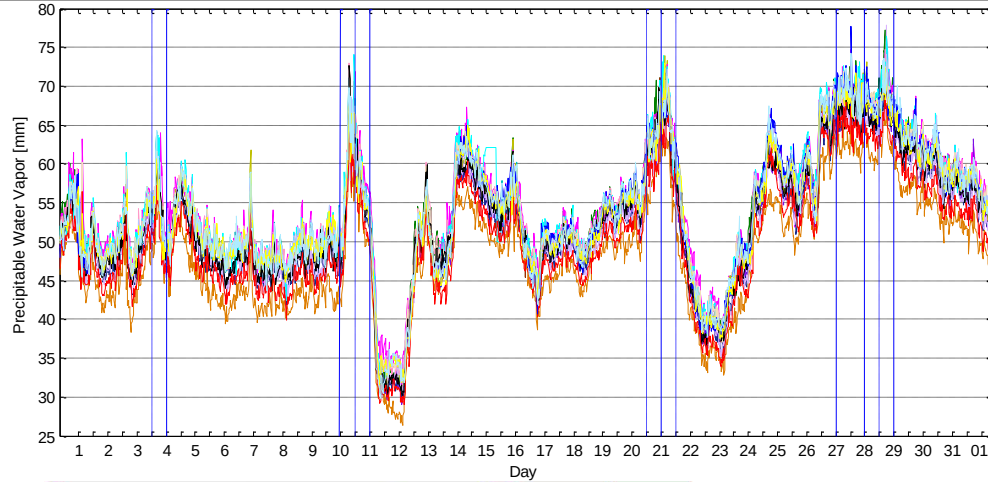
Hong Kong Satellite Positioning
Reference Station Network(SatRef),
and a radiosonde station Kings Park
<https://www.geodetic.gov.hk/sc/index.htm>

Rainstorm Warning Signals in May 2016

Colour	Beginning Time	Ending Time	Duration
	Month/Day Hour:Minute	Month/Day Hour:Minute	Hour:Minute
Amber	05/03 18:10	05/03 20:55	02:45
Amber	05/10 06:00	05/10 07:35	01: 35
Red	05/10 07:35	05/10 09:35	02: 00
Amber	05/10 09:35	05/10 11:20	01: 45
Red	05/10 11:20	05/10 13:45	02: 25
Amber	05/10 13:45	05/10 14:45	01: 00
Amber	05/21 01:55	05/21 06:15	04 :20
Amber	05/28 16:35	05/28 18:40	02: 05

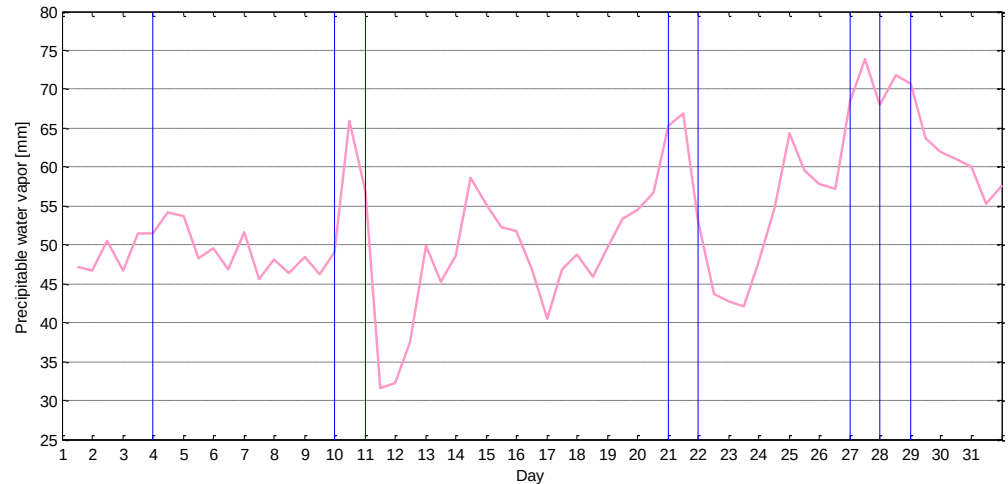
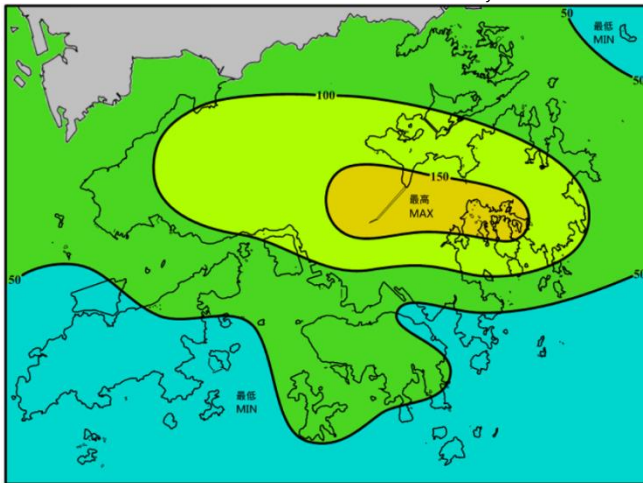
<https://www.hko.gov.hk/sc/wxinfo/pastwx/mws2016/mws201605.htm>

Monitoring a rainfall process in Hong Kong



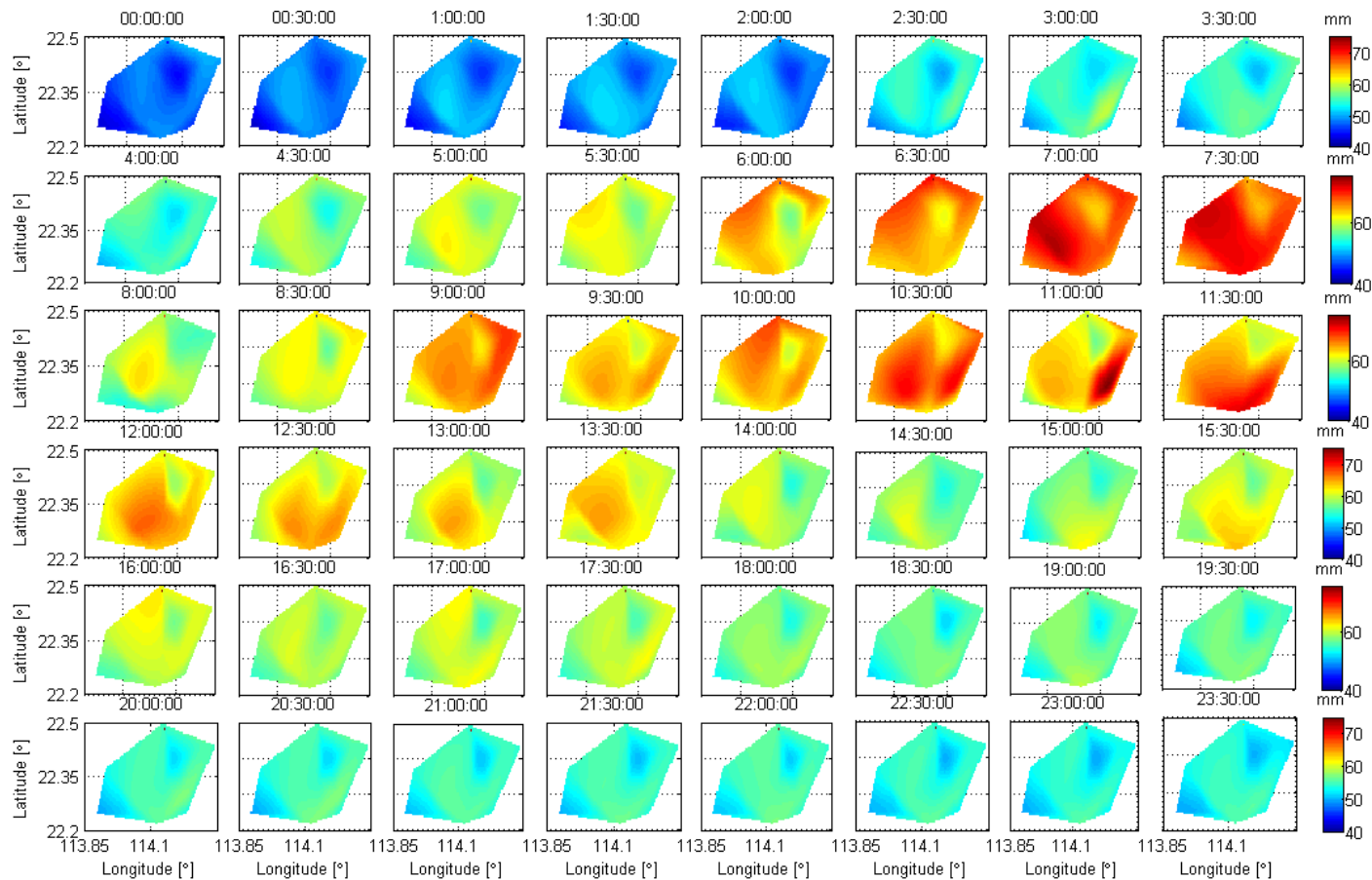
GNSS PWV

Rainfall Map | Radiosonde PWV



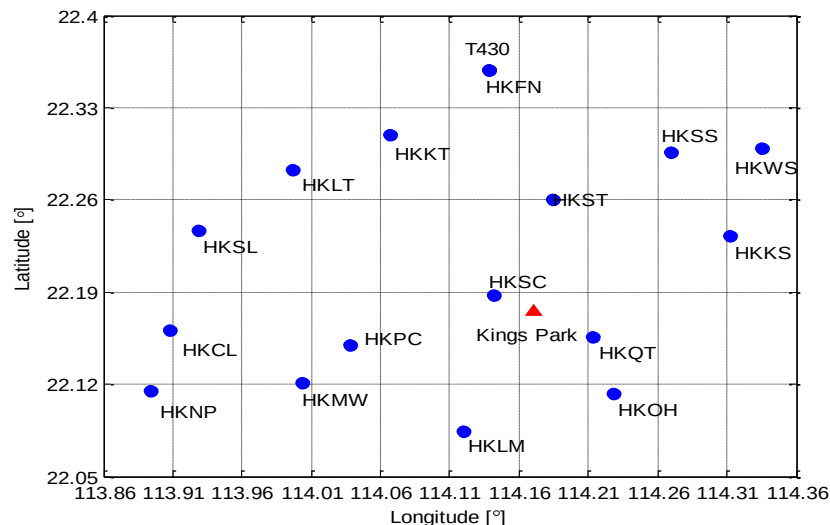
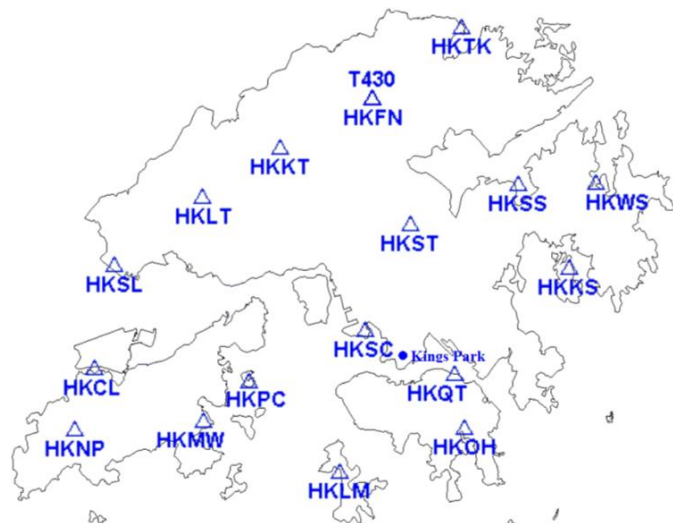
Rainfall Map for 10 May 2016 (isohyets are in millimetres)

Monitoring a rainfall process in Hong Kong



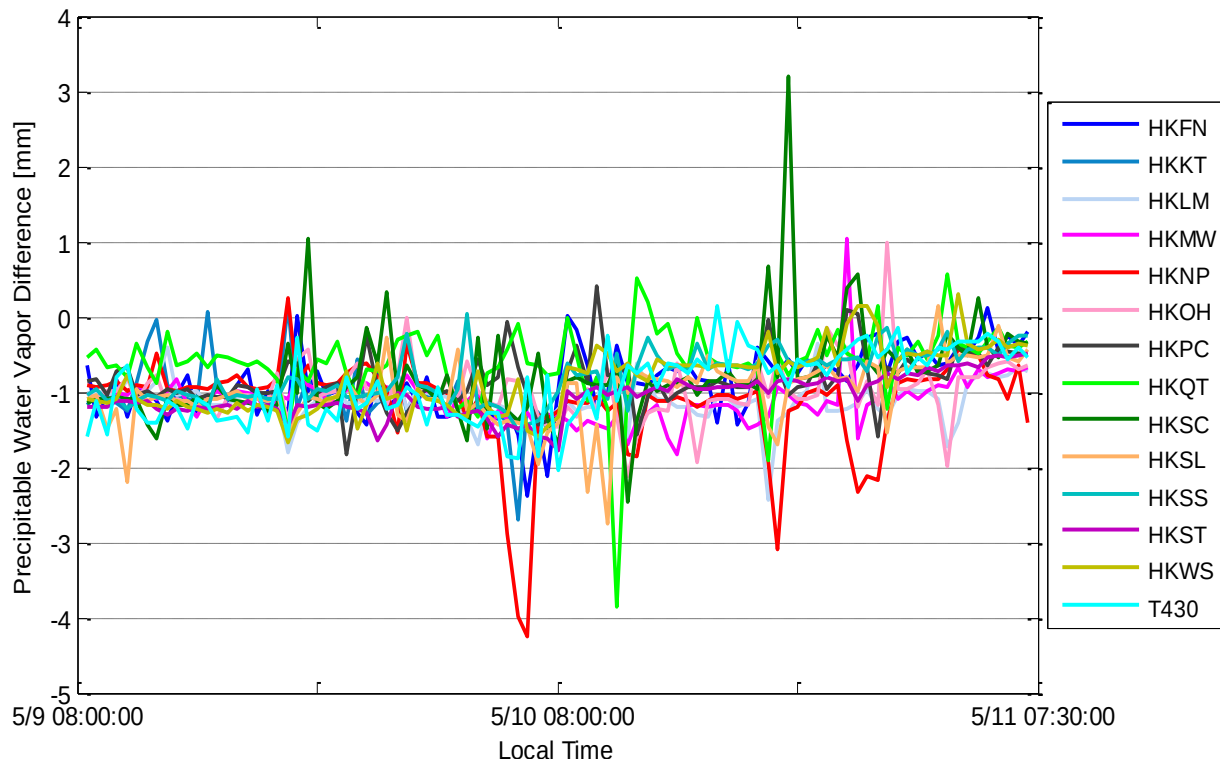
Hong Kong Regional **PWVs** in 10th May, 2016

Monitoring a rainfall process in Hong Kong



- **TWV** : spatio-temporal water vapor with tomography technique
- **Longitude**: 113.86~114.36°E, resolution of 0.05°
- **Latitude** : 22.05~22.40°N, resolution of 0.07°
- **Height** : 400, 800, 1200, 1600, 2000, 2500, 3000, 3500, 4000, 4600, 5200, 5800, 6500, 7500 and 8500 m, in total 15 layers
- **Time** : resolution of 30 min

Monitoring a rainfall process in Hong Kong

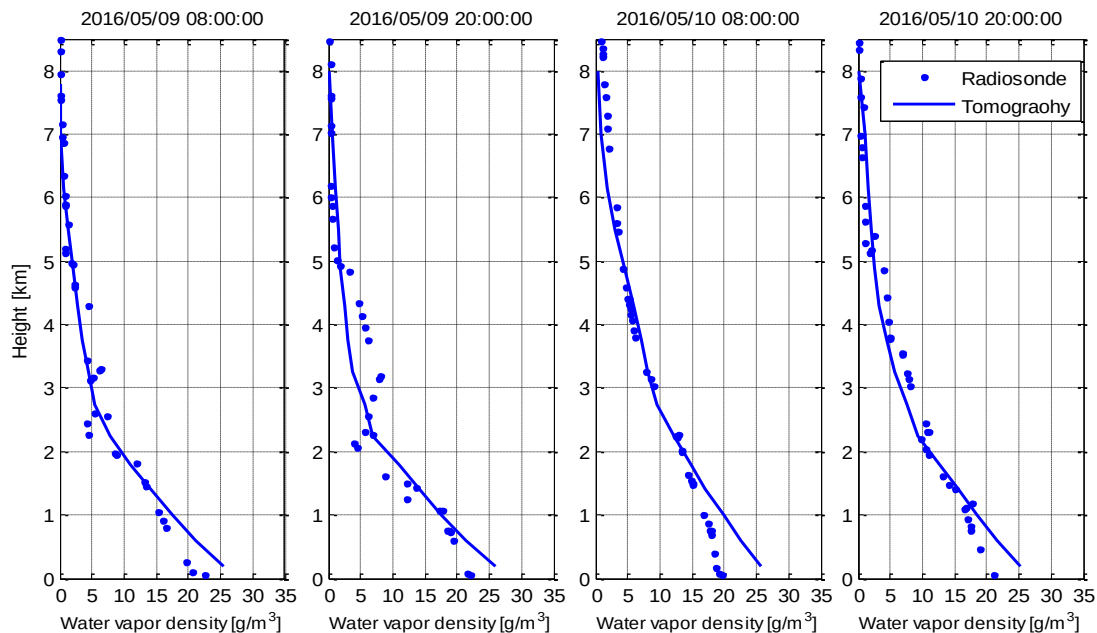


The difference between GNSS **PWVs** and TWRV re-calculated **PWVs**

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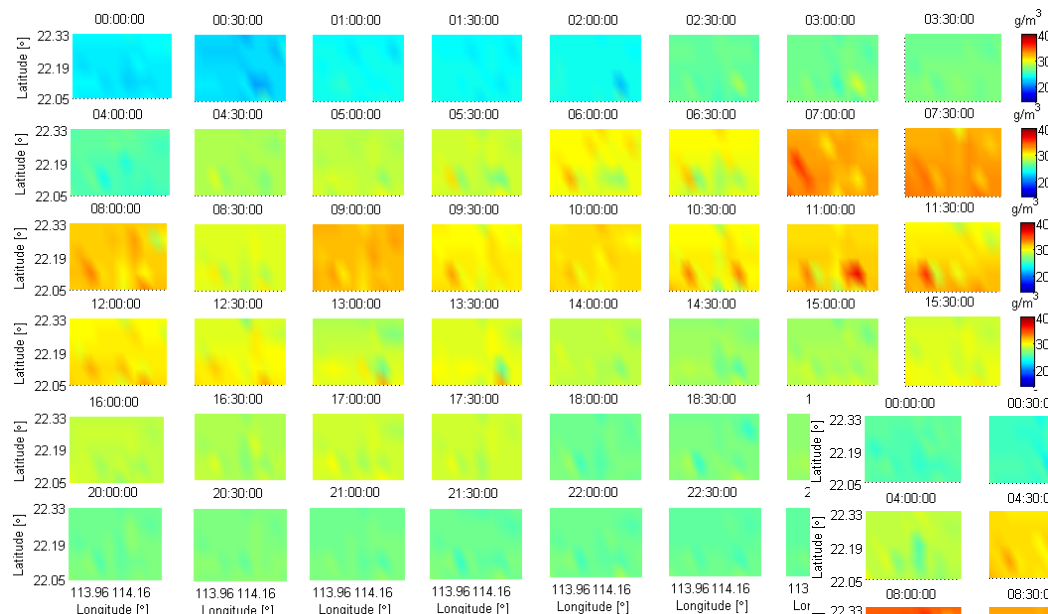
The **PWVs** above the radiosonde station Kings Park [mm]

	05/09 08:00:00	05/09 20:00:00	05/10 08:00:00	05/10 20:00:00
TWV re-calculated	47.95	48.15	66.21	55.30
Radiosonde	46.25	49.16	65.86	56.87



The water vapor profile above Kings Park

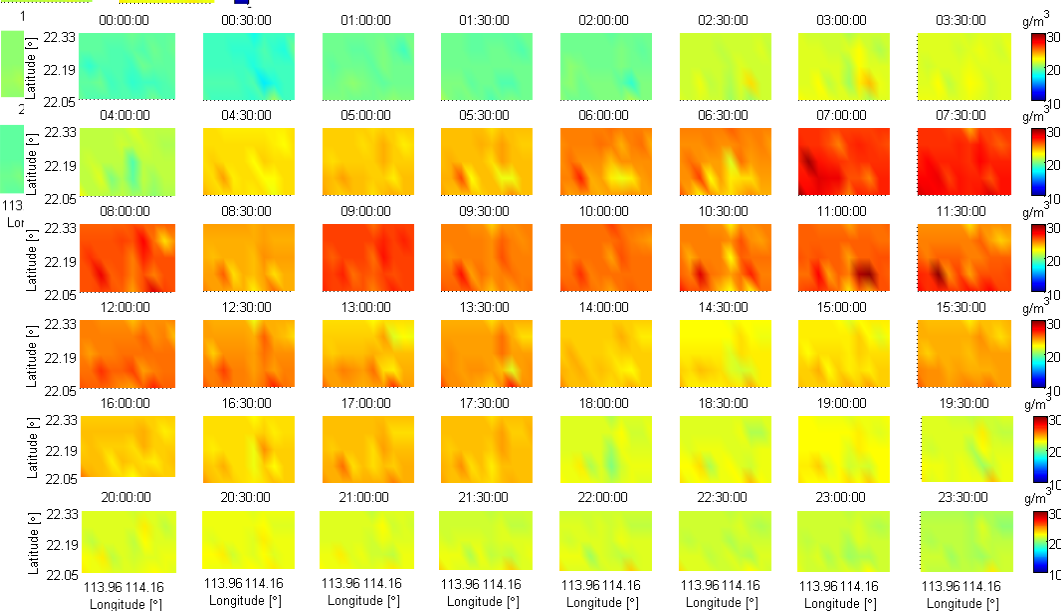
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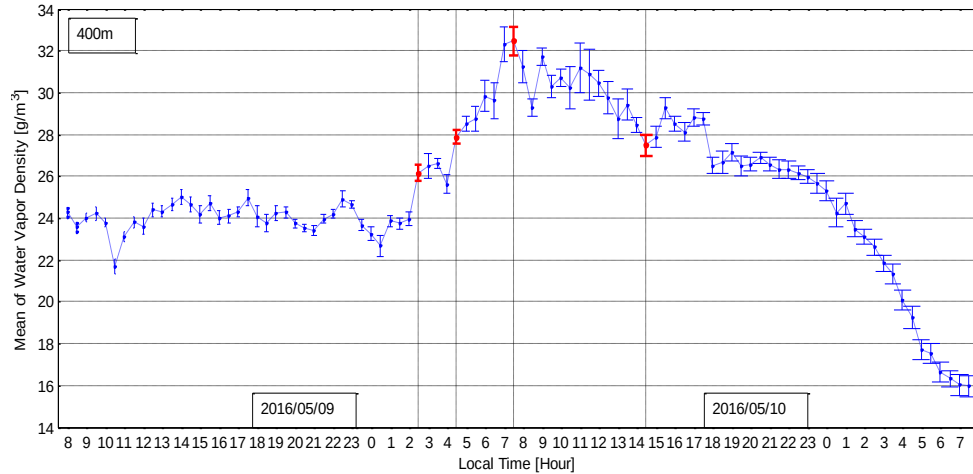
spatio-temporal water vapor
density in 10th May, 2016

below 400 m

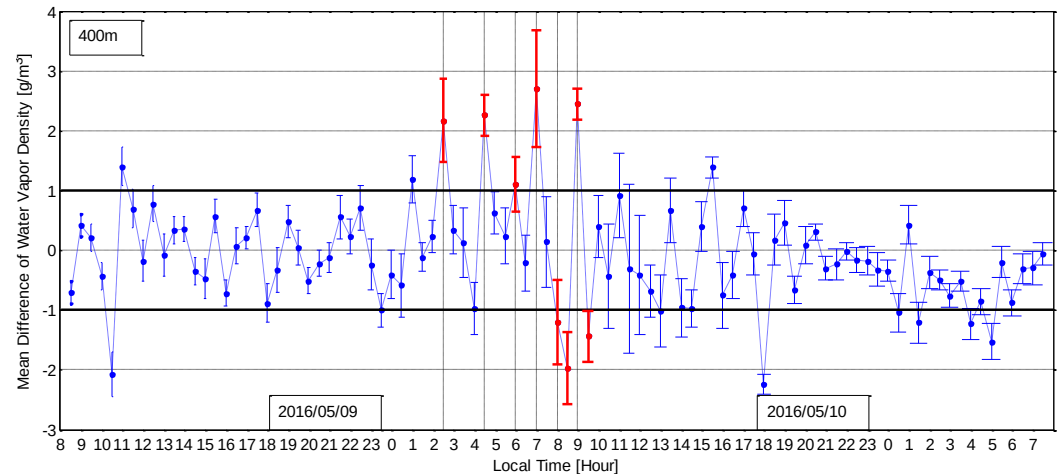
between 400 and 800 m



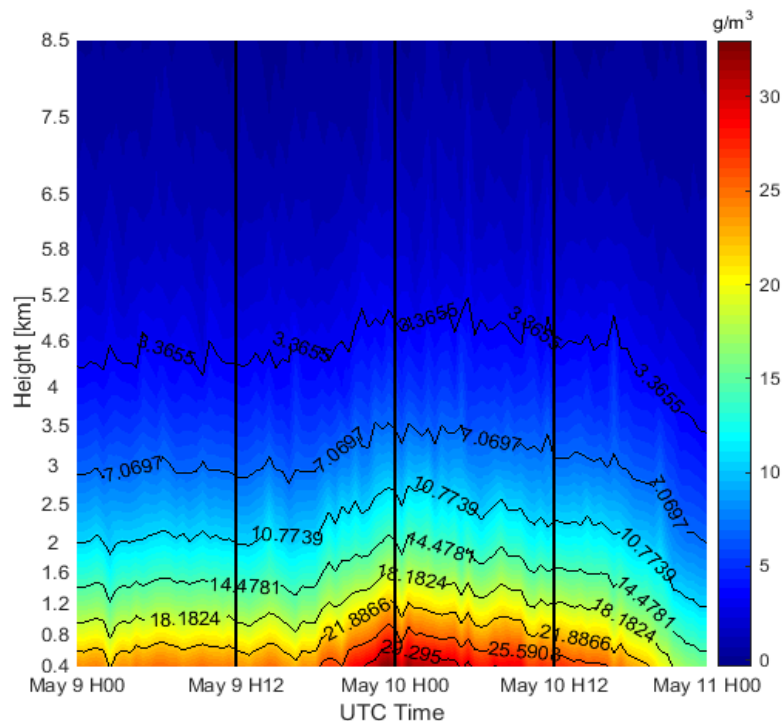
Monitoring a rainfall process in Hong Kong



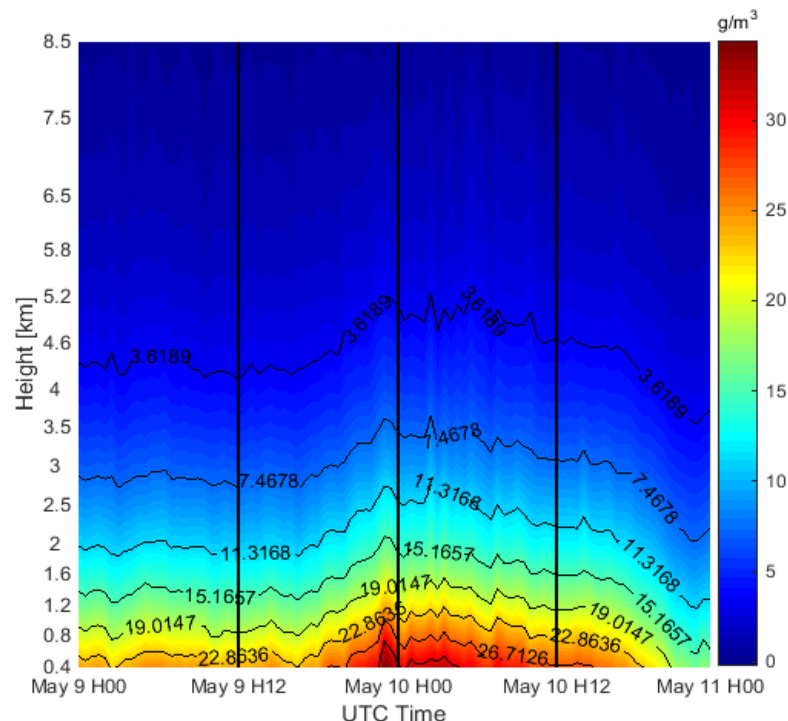
The mean value of water vapor density
below 400 m
the variations



Monitoring a rainfall process in Hong Kong



The time-varying water vapor profile
above HKST



The time-varying water vapor profile
above HKNP

Conclusions

- ❑ Hong Kong Satellite Positioning Reference Station Network (SatRef)
- ❑ GNSS retrieved tropospheric delay ($\Delta\rho_{r,wet}^Z$, etc.)
- ❑ GNSS retrieved spatio-temporal distributed water vapor (PWV, TWV, etc.)
- ❑ Initial results about monitoring a rainfall process with GNSS water vapor
- ❑ GNSS retrieved PWVs and radiosonde PWVs are in good agreement
- ❑ Internal and external (radiosonde) check of TWVs are of good performance
- ❑ Spatio-temporal PWVs and TWVs are useful to monitor a rainfall process
- ❑ There's **still** a lot of work to be done in a lot of places



Thanks for your attention!

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