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Analysis of pan-tropical GNSS-R observations from CYGNSS satellites for floods detection and mapping

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Extraction of flood patterns

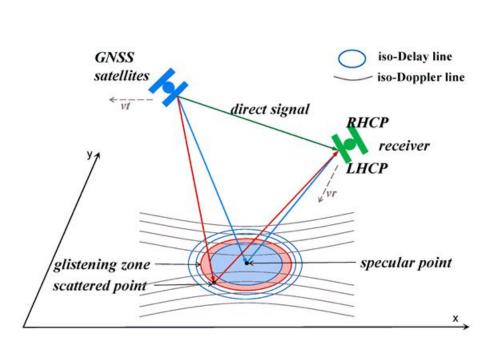
Toward a dynamic product of Surface Water Extent

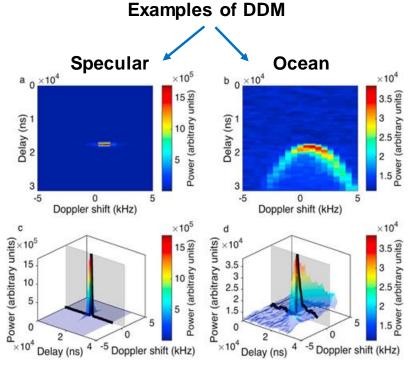
Conclusion

GNSS signals of opportunity

Bistatic Radar → Information about the reflecting surface

- \rightarrow L-band signals ($\lambda_{1.1} = 19.03$ cm)
- → Correlation of the reflected signal with a replica of the direct signal
- → Observable: Delay Doppler Maps (DDMs)

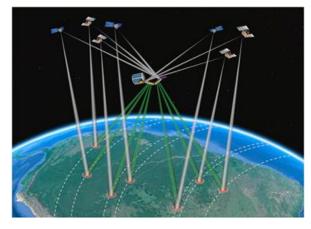




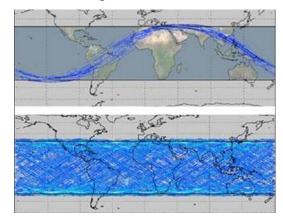
Chew et al. (2016)

The CYGNSS mission

- Spatial resolution
 - → Fresnel area ~ 0.6 to 1 km (coherent scattering)
 - → Incoherent integration of the reflected signals (1s)
 - → Spatial resolution ~ 1 x 7 km (over land) ~ 25 km (over ocean)
 - → Inter-tropical band only (+- 38° lat)
- Multi-incidence measurements
 - → Incidence from 0 to >70°
- 8 instruments able to track 4 GNSS satellites each
 - → 32 observations / second
 - → Satellite overpass ~1.5 hrs
 - → pseudo-random repartition (bistatic configuration)
 - → Temporal resolution ~ 1-2 days over ocean (incoherent scattering)

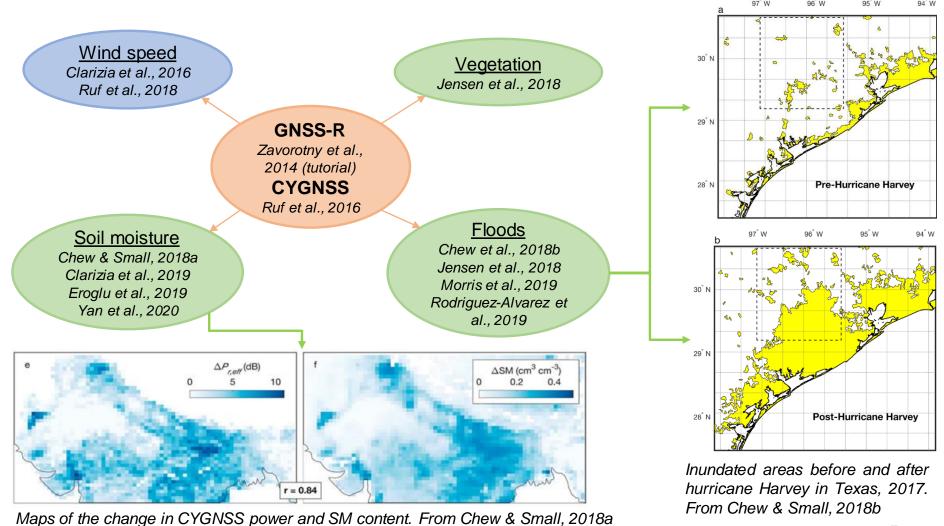


Nghiem et al., 2016



Source: NASA

Applications of spaceborne GNSS-R



Monitoring of flood dynamics

 ➤ At the global scale → Using active and passive microwave instruments, i.e. GIEMS (Prigent et al., 2020), SWAMPS (Jensen et al., 2019) 	Limitations Coarse spatial (0.25°) and temporal (1-month) resolutions
→ Using multispectral imagery like Landsat (<i>Pekel et al., 2016</i>)	No data over vegetated areas, mask with cloud cover
➤ At the regional scale → Using SAR imagery (Kuenzer et al., 2013)	Low temporal sampling, data availability in L-band
→ Using optical and IR imagery like MODIS (Frappart et al., 2018)	Only over regions with few vegetation cover, cloud cover

What about GNSS-Reflectometry?

- → Only studied at the regional scale: Chew et al., 2018; Jensen et al., 2018; Morris et al., 2019; Rodriguez-Alvarez et al., 2019
- → Monitoring of extreme events (hurricanes, typhoons...)
- → Threshold methods that cannot be extended at the global scale

Mapping of CYGNSS reflectivity over land

1. Preprocessing

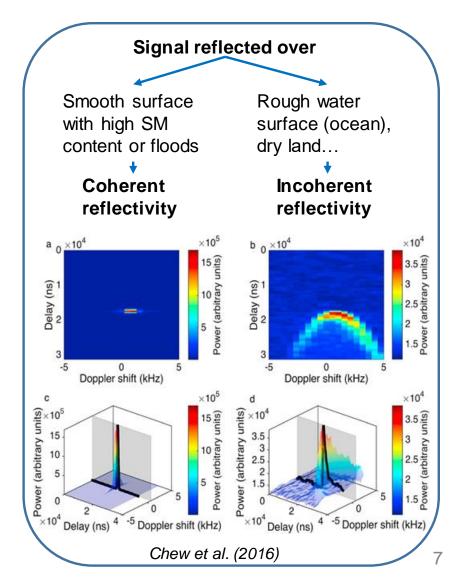
- Extraction of the DDM peak power
- Subsetting
- CYGNSS flags (ocean mask + quality flags)

2. Coherent reflectivity computation

$$\Gamma_{RL}(\theta_i) = \left(\frac{4\pi}{\lambda}\right)^2 \frac{P_{RL}^{coh}(r_{st} + r_{sr})^2}{P_t G_t G_r}$$

With:

- Γ_{RL} : CYGNSS reflectivity
- P_{RL}^{coh} : DDM peak power
- r_{st} : range from surface to transmitter
- r_{sr} : range from surface to receiver
- P_tG_t : GPS EIRP (equivalent isotropically radiated power)
- *Gr*: antenna gain of the receiver



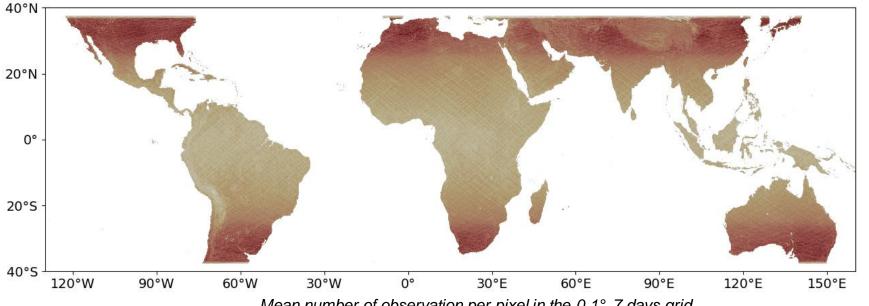
Mapping of CYGNSS reflectivity over land

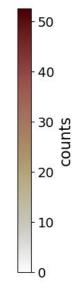
3. Gridding CYGNSS reflectivity

- 0.1°, 7 days grid
- Gaps due to pseudo-random bistatic configuration
- Moving average with Gaussian weighting (1 month)

→ CYGNSS parameters extracted:

- Weighted Γ_{mean} and Γ_{std}
- $\Gamma_{90\%}$ (90th percentile)
- Γ_{median} and Γ_{MAD} (median absolute deviation)
- → **Key point:** less observations around the Equator than at higher latitudes





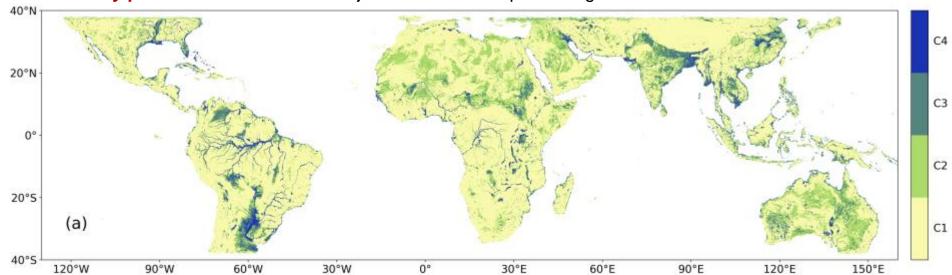
Mean number of observation per pixel in the 0.1°, 7 days grid

Mapping of CYGNSS reflectivity over land

4. Clustering of CYGNSS reflectivity

- K-means clustering with Dynamic Time Warping (DTW) similarity measure for time-series analysis
- Parameter : $\Delta \Gamma_{90-50} = \Gamma_{90\%} \Gamma_{median}$
- Time series padding to avoid boundary effect

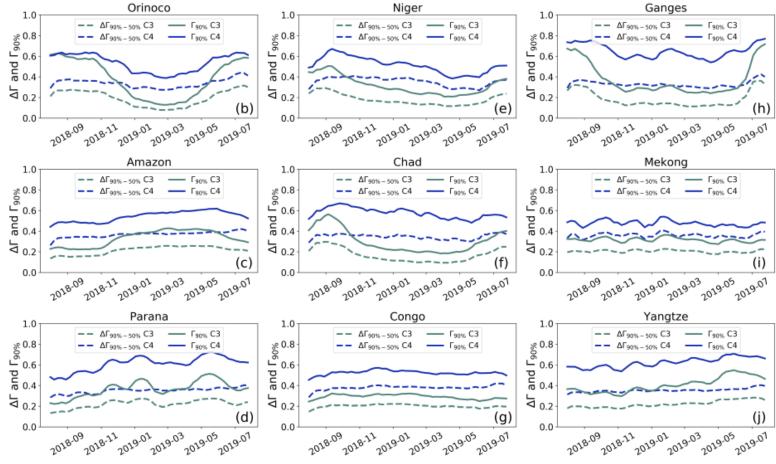




Result of the K-means – DTW clustering of $\Delta\Gamma_{90-50}$. The cluster C1 has the lowest average reflectivity, and the cluster C4 has the highest. From Zeiger et al., 2022, under review.

Extraction of flood patterns

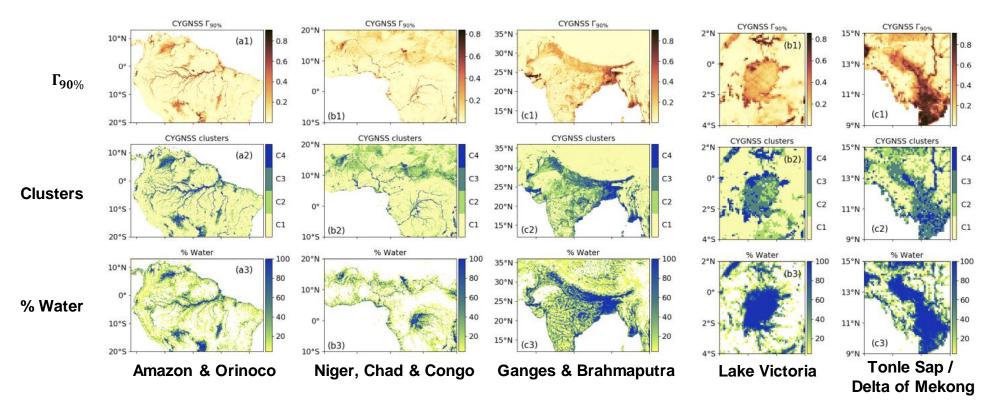
→ **Key point:** very high, ~constant reflectivity for C4. High reflectivity and strong seasonality for C3.



Average time series of reflectivity per basin for cluster C3 and C4. From Zeiger et al., 2022, under review.

Comparison with static inundation maps

→ Key point: very high, ~constant reflectivity for C4. High reflectivity and strong seasonality for C3.

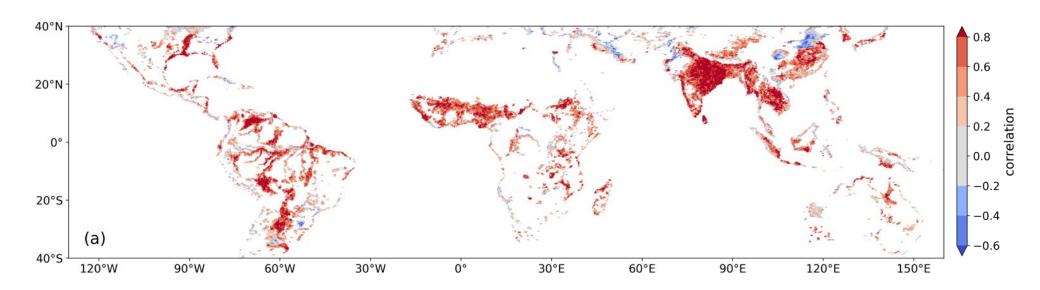


Regional Comparison of CYGNSS reflectivity and clusters with the percentage of Regularly Flooded Areas (Tootchi et al., 2019).

From Zeiger et al., 2022, under review.

Comparison with dynamic inundation maps

- > Comparison of CYGNSS reflectivity with GIEMS Surface Water Extent (SWE)
 - → **Key point:** high correlation (R > 0.8) in most of the major floodplains and irrigated fields.
 - lower correlation on coastal areas (limitation of GIEMS), over densely vegetated areas (Cuvette Centrale of Congo), etc.

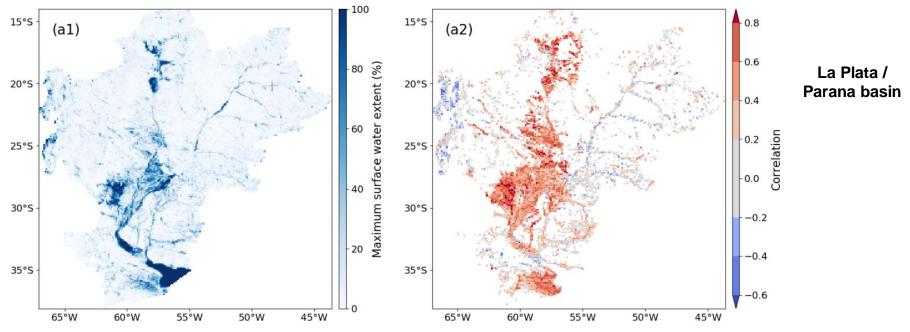


Pixel-by-pixel correlation of CYGNSS reflectivity and GIEMS Surface Water Extent time series.

From Zeiger et al., 2022, under review.

Comparison with dynamic inundation maps

- Regional comparison of CYGNSS reflectivity with SWE from MODIS
- MODIS SWE extracted using a threshold method (Frappart et al., 2018; Normandin et al., 2018)
- → Key point: medium to high correlation over the wetter areas

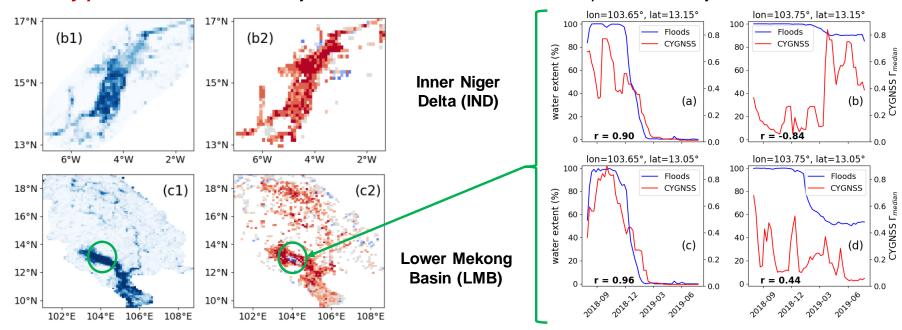


Pixel-by-pixel correlation of CYGNSS reflectivity and MODIS Surface Water Extent time series (Frappart et al., 2018).

From Zeiger et al., 2022, under review.

Comparison with dynamic inundation maps

- Regional comparison of CYGNSS reflectivity with SWE from MODIS
- MODIS SWE extracted using a threshold method (Frappart et al., 2018; Normandin et al., 2018)
 - → Key point: CYGNSS reflectivity correlated to SWE unless the temporal variability of SWE is low



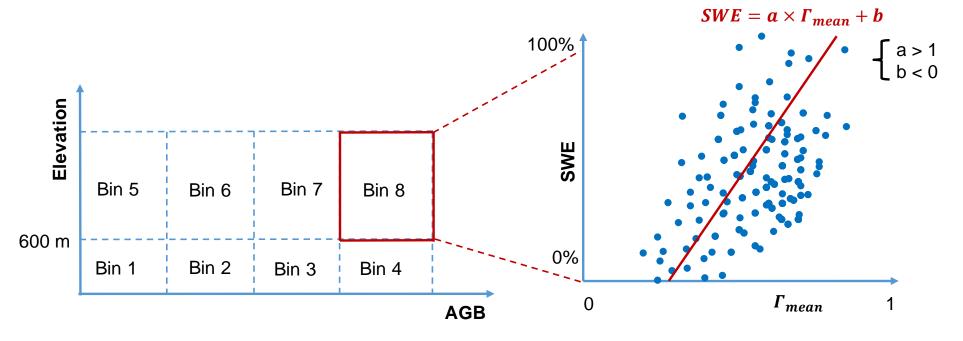
Pixel-by-pixel correlation of CYGNSS reflectivity and MODIS Surface Water Extent time series (Frappart et al., 2018).

Time series of CYGNSS reflectivity and Surface water extent over pixels near the Tonle Sap

Toward a dynamic estimation of SWE

\triangleright Relation between CYGNSS Γ_{mean} and SWE from MODIS

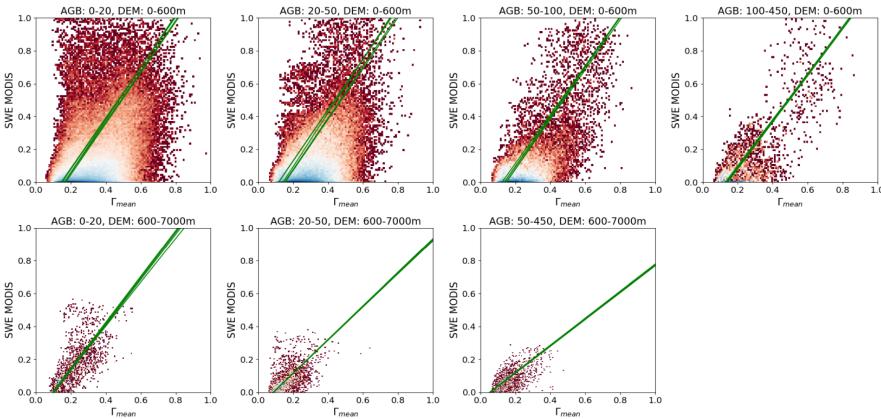
- → Influence of the vegetation and altitude on CYGNSS reflectivity to be removed
- → Binning of CYGNSS, MODIS and GIEMS datasets according to mean values of AGB & DEM in the pixel
- → Linear relationship found in every bin



Toward a dynamic estimation of SWE

\triangleright Relation between CYGNSS Γ_{mean} and SWE from MODIS

→ **Key point:** clear linear relationship that can be used for regression

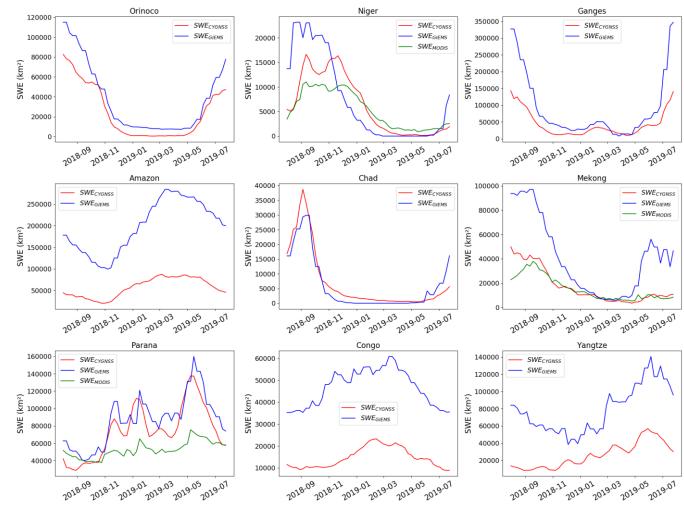


2D histograms of SWE vs. Γ_{mean} for every AGB / DEM bin. The linear curves from a k-fold fit are shown in green.

Toward a dynamic estimation of SWE

CYGNSS SWE vs. GIEMS + MODIS

- → CYGNSS in agreement with MODIS over Niger & Mekong
- → Overestimation of SWE in the Parana → SM ?
- → CYGNSS very lower than GIEMS over equatorial basins (Amazon, Congo) and under high flood regimes (Orinoco, Ganges, Yangtze, Mekong)
- → Underestimation of floods in the Amazon and Congo basins in particular due to vegetation effects

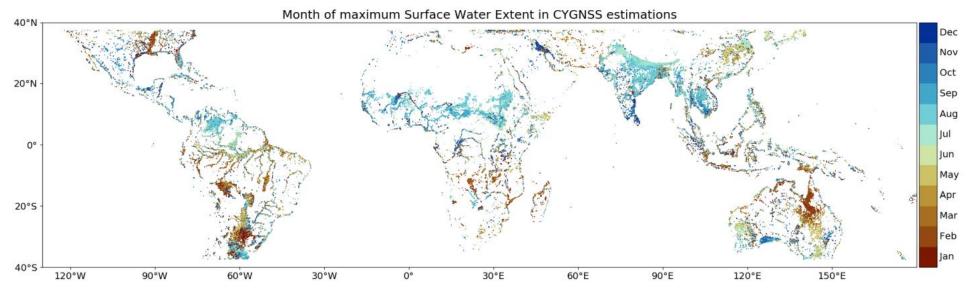


Time series of total SWE from CYGNSS (red), GIEMS (blue) and MODIS (green) per basin

Conclusion

> CYGNSS shows high sensitivity to Surface Water Extent

- → Detection of the main floodplains and open water bodies using a K-means / DTW clustering
- → Separation of constant and seasonal flood patterns
- → Seasonality of CYGNSS reflectivity agrees with the dynamics of floods (SWE from MODIS or GIEMS)
- → Limitations: dense vegetation, altitude

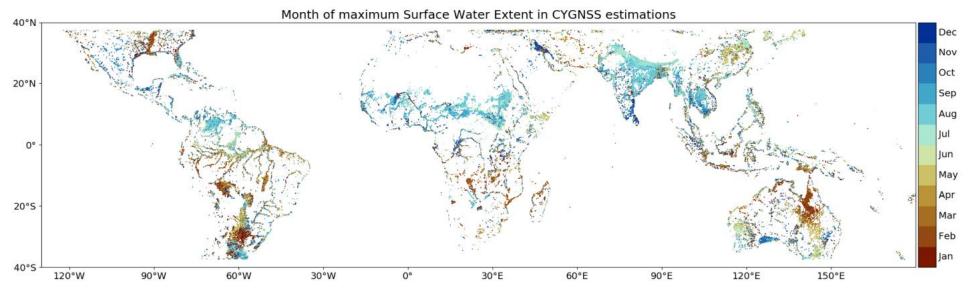


Month of maximum flooded extent in CYGNSS SWE estimation

Conclusion

Toward a CYGNSS SWE product (work in progress)

- → Linear relationship between CYGNSS reflectivity and MODIS SWE when removing the influence of the vegetation and altitude
- → Calculation of a 0.1°, 7-day dynamic product of water fraction using CYGNSS in the pan-tropical area
- → Final product will be available after correction of the vegetation and SM effects













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Thank you for your attention !

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