

EGU - 25.05.2022

Ensemble **data assimilation** of screen-level observations **across the atmosphere-land interface** enhanced by **fingerprint operators**

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In which case can we expect warmer temperature?



In which case can we expect warmer temperature?



25.05.2022



Heat fluxes couple atmospheric boundary layer to the land surface

2-metre-temperature

Heat fluxes

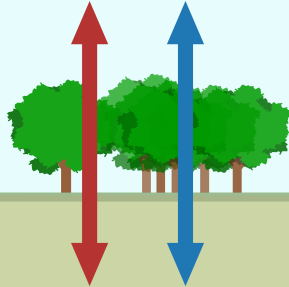
Simplified 1D methods

(ECMWF, 2020; Gómez et al., 2020; Carrera et al., 2015)

+ impact on boundary layer forecast

- impact on soil moisture analysis

(e.g. Hess, 2001; Drusch and Viterbo, 2007; Carrera et al., 2019; Muñoz-Sabater et al., 2019)



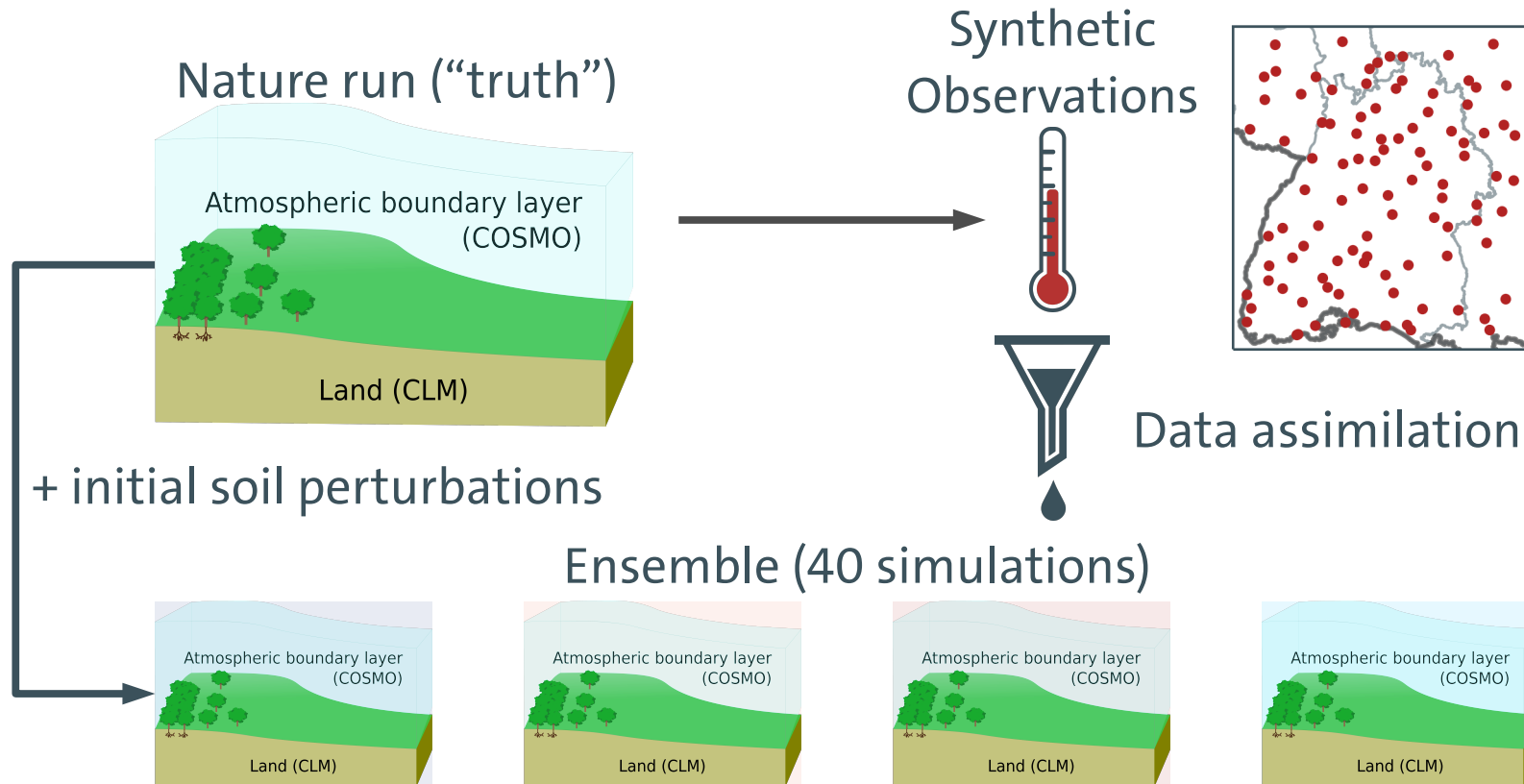
Data assimilation

Soil moisture



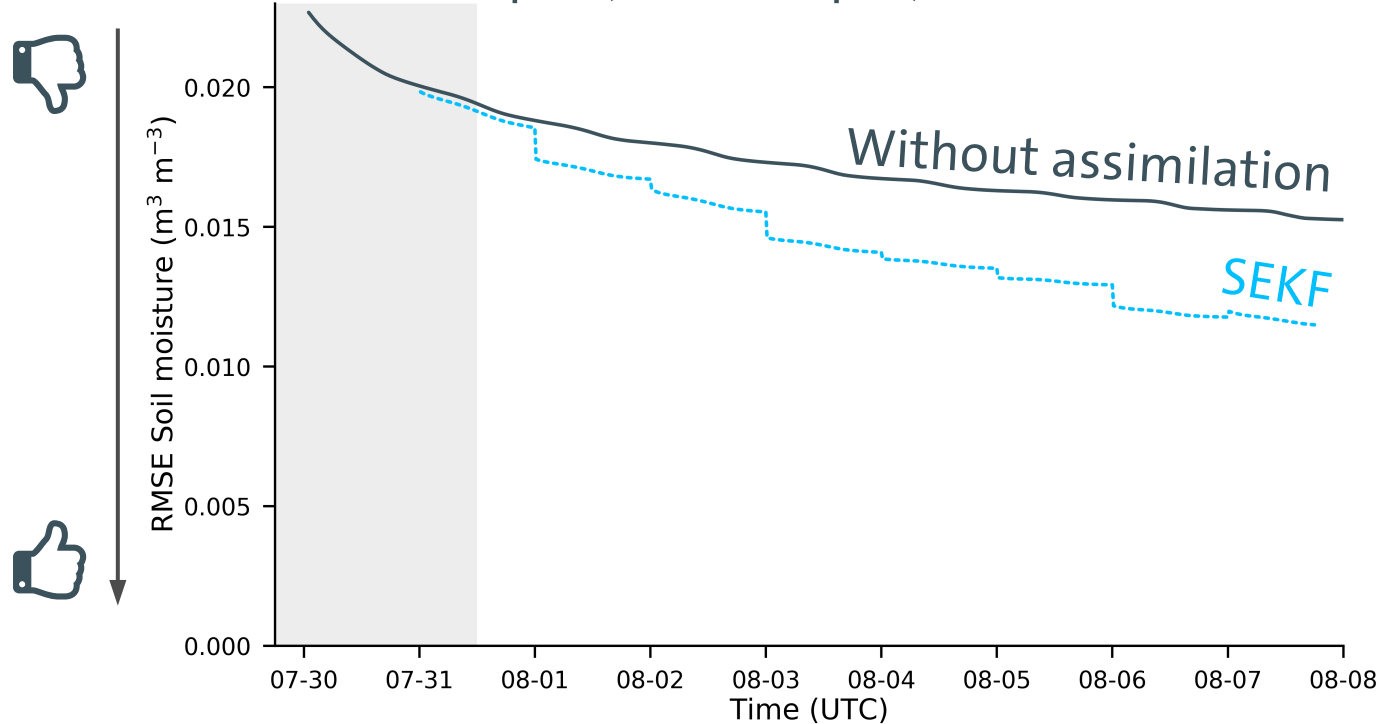
How to efficiently assimilate observations across the interface?

Idealised twin experiments for coupled atmosphere-land data assimilation



Setup works for reference data assimilation

Soil moisture in root-depth (0.21 m depth)



Simplified extended Kalman
filter – 1D method
(de Rosnay et al. 2013)

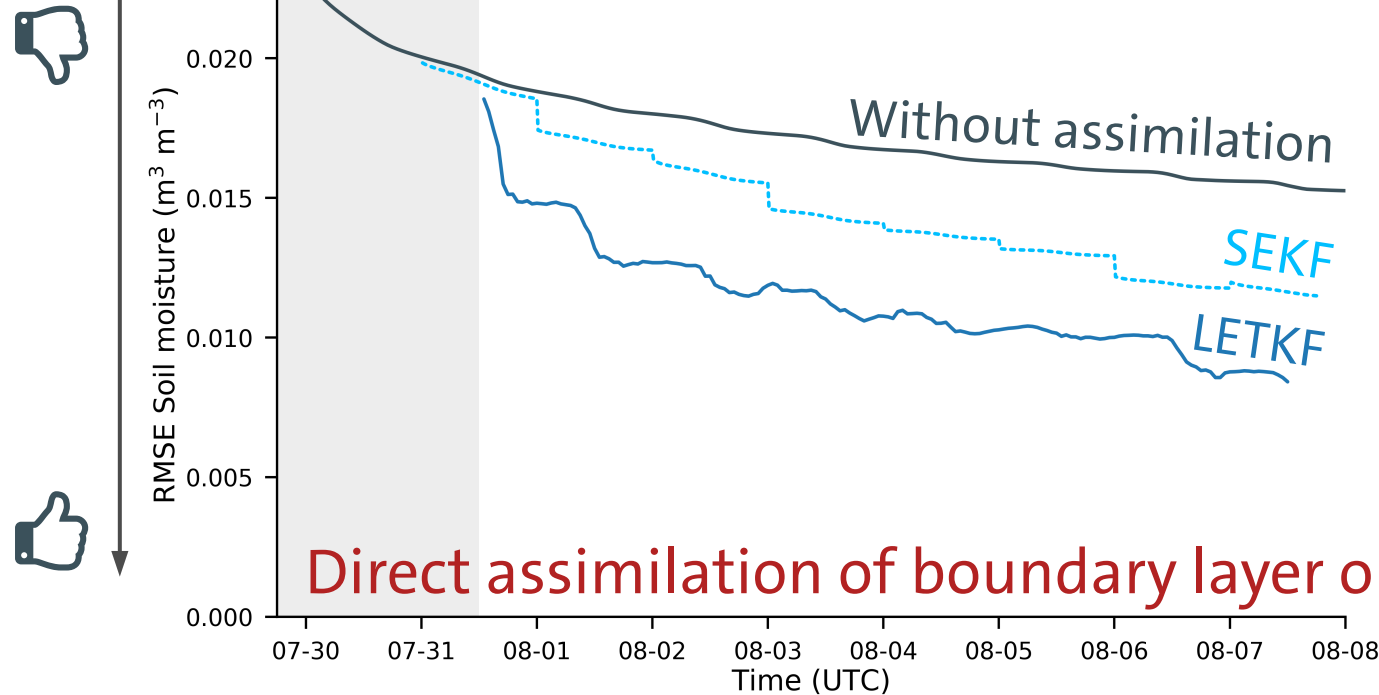
Update at 00:00 UTC

Fully-observed field
at 12:00 UTC

Hourly LETKF assimilation additionally improves analysis

Soil moisture in root-depth (0.21 m depth)

↗ Improvement (SEKF): 20 %



LETKF (Hunt et al. 2007)

Hourly updates with
99 observations

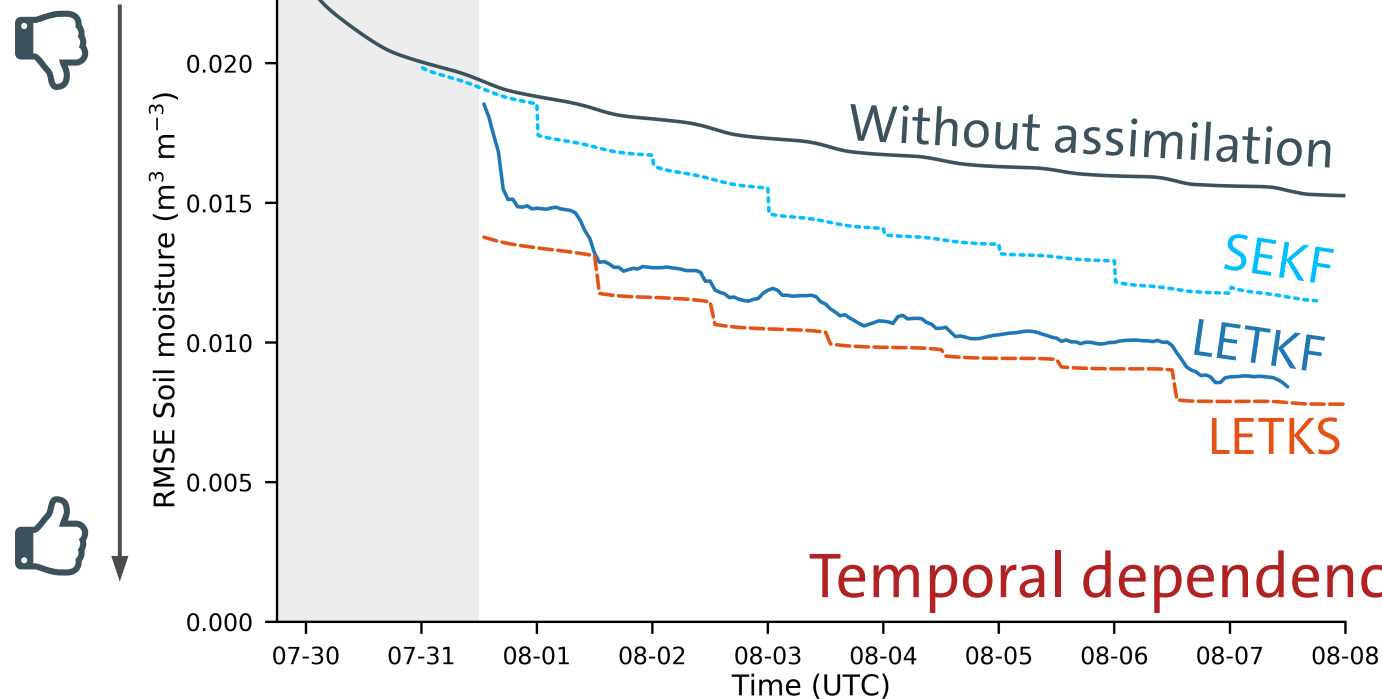
Obs. localisation (15 km)
+ very small inflation

Direct assimilation of boundary layer observations possible

A positive impact with a localised ensemble Kalman smoother

Soil moisture in root-depth (0.21 m depth)

↗ Improvement (LETKF): 10 %



Linearised IEnKS
(Bocquet and Sakov, 2014)

Same localisation
+ much larger inflation

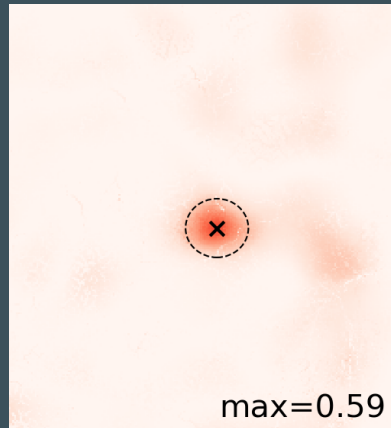
24 hour window

Temporal dependencies improve analysis

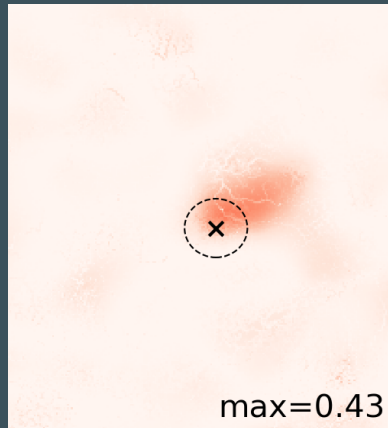
“Overfitting” with the ensemble Kalman smoother

12:00 UTC

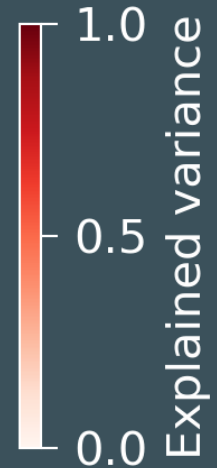
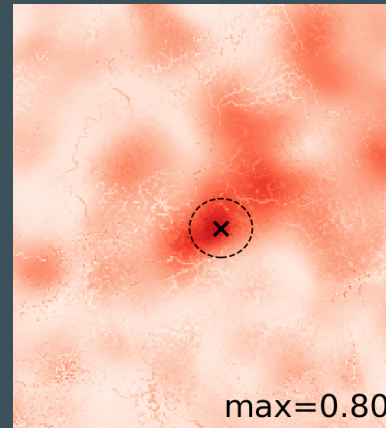
Soil moisture
Filter



Filter



Smoother

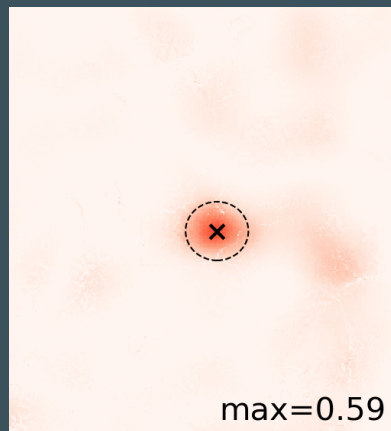


More difficult to tune covariances with inflation and localisation

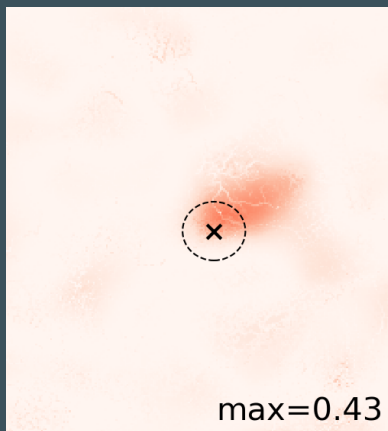
Fingerprint operators reduce this problem

12:00 UTC

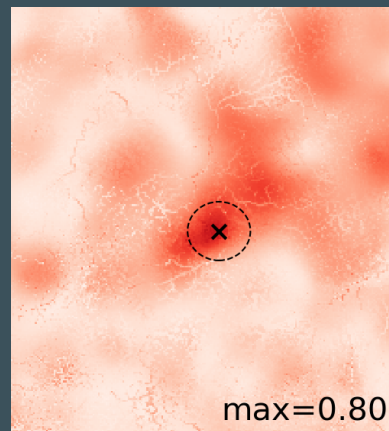
Soil moisture
Filter



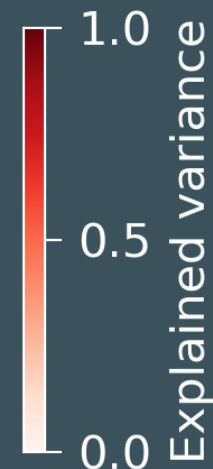
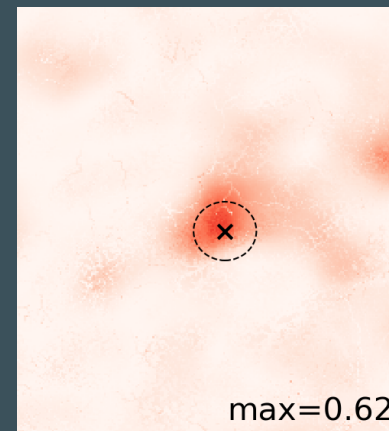
Filter



Smoother



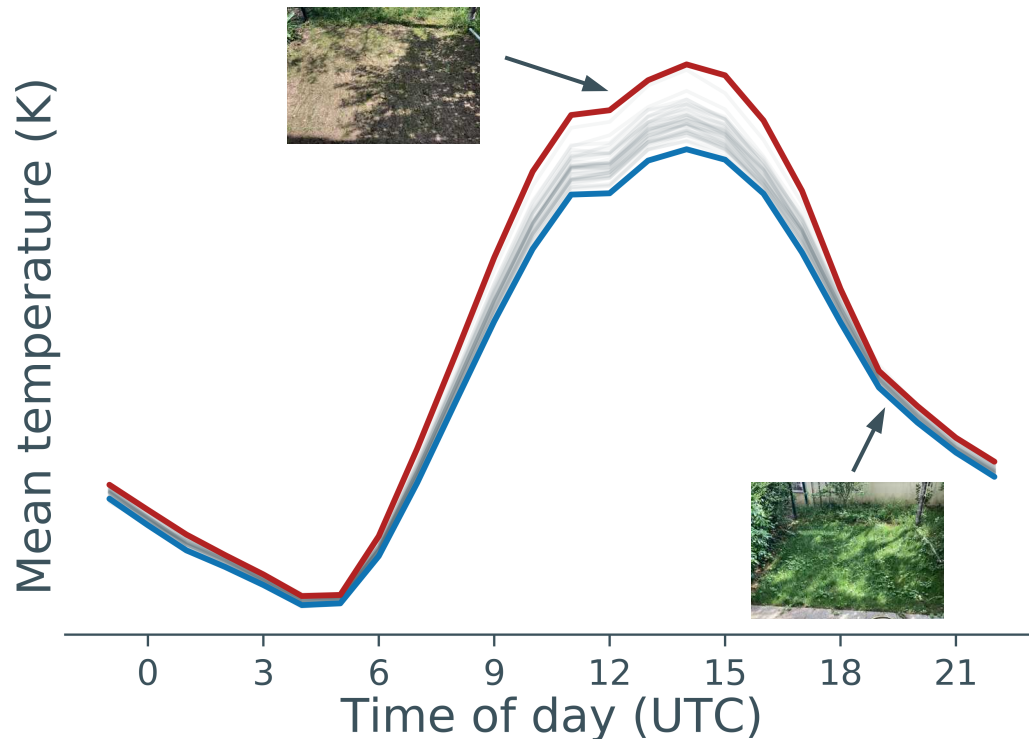
Fingerprint



What are fingerprint operators and how to construct them?

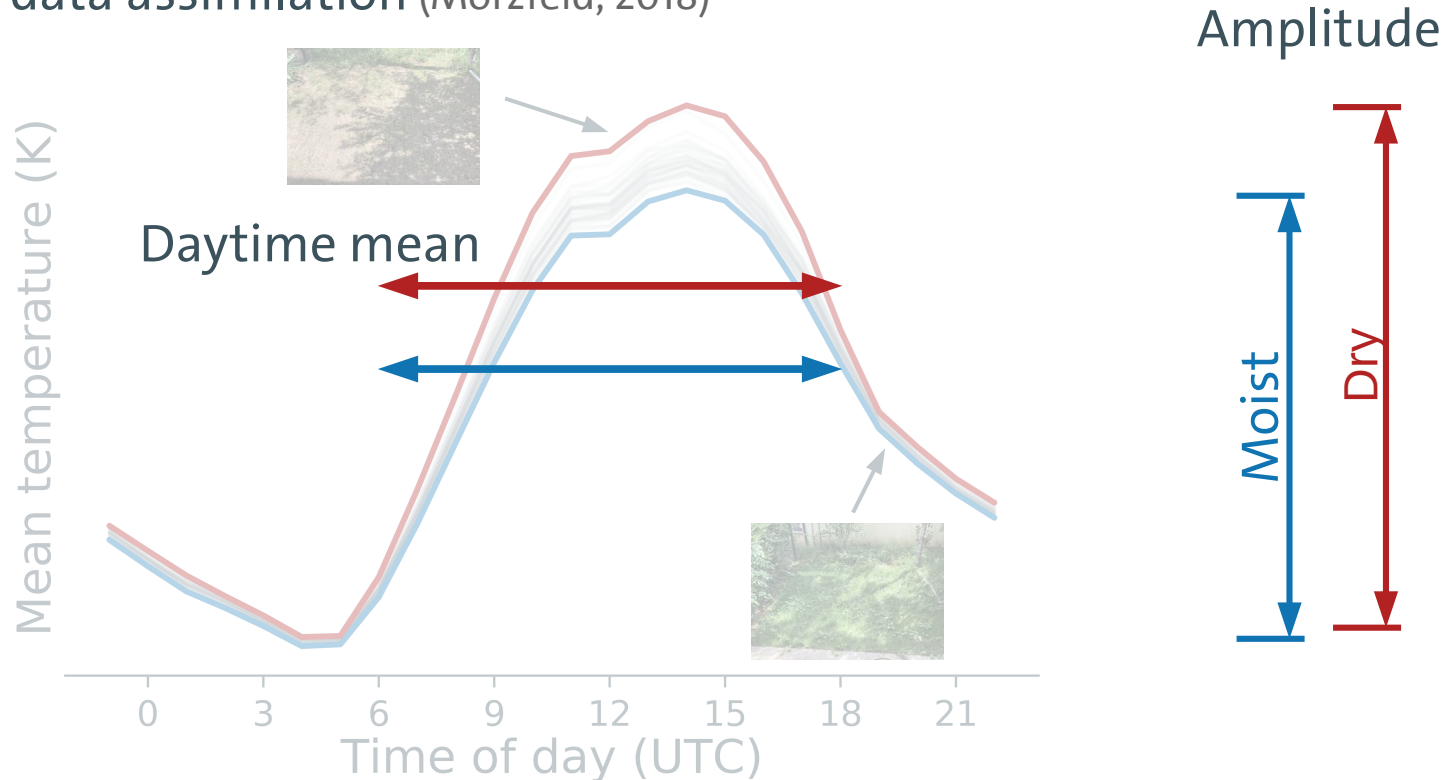
How to construct fingerprint operators for the atmosphere-land interface

Feature-based data assimilation (Morzfeld, 2018)



How to construct fingerprint operators for the atmosphere-land interface

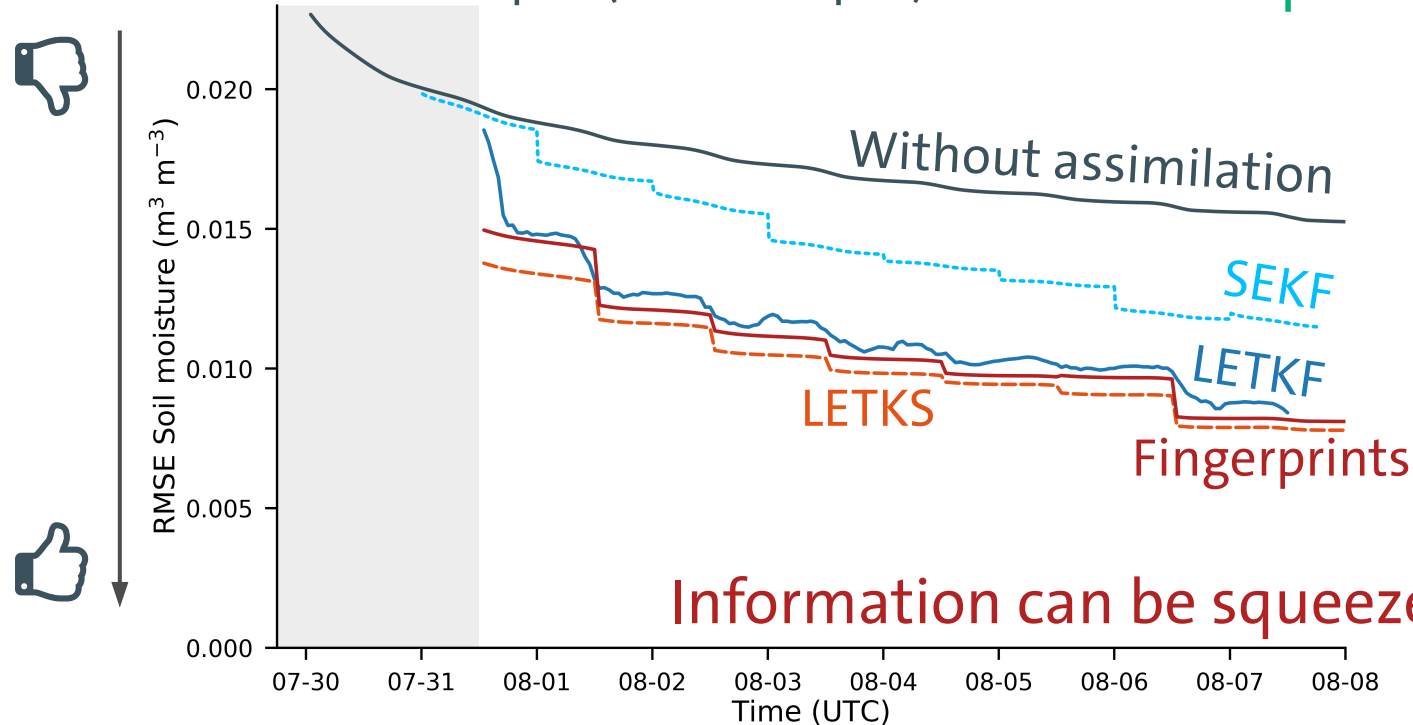
Feature-based data assimilation (Morzfeld, 2018)



Almost as good as using the raw observations

Soil moisture in root-depth (0.21 m depth)

↗ Improvement (LETKF): 5 %



LETKS framework

24 hour window

Same localisation
+ small inflation

Information can be squeezed into two features

Conclusions

Emerging potential of localised EnKF framework to update soil moisture with screen-level observations

Direct assimilation of screen-level observations into the soil moisture with an hourly interval possible

Fingerprint operators allow a flexible use of observational information to make the coupled data assimilation problem easier

Do you have questions?

Feel free to write me an email: tobias.finn@enpc.fr

Or take a look at: Finn, T. S. (2022), doi:10.17617/2.3381204