







27.05.2022 ESA Living Plant Symposium - Bonn

Learning and screening of neural networks for sub-grid-scale parametrisations of sea-ice dynamics

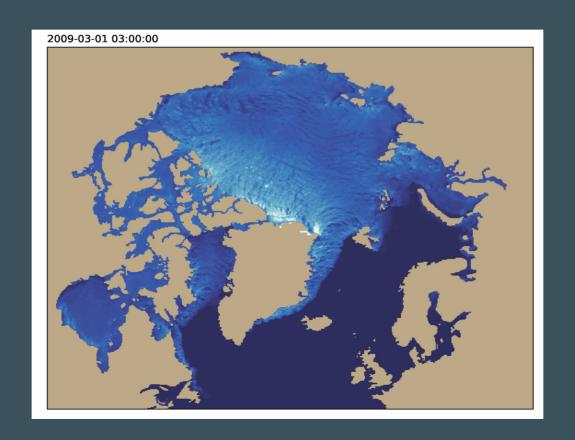
Tobias Sebastian Finn



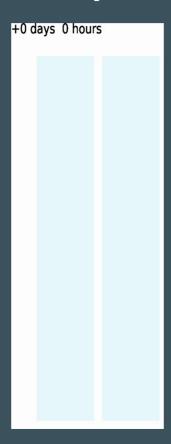
Charlotte Durand, Alban Farchi, Marc Bocquet, Yumeng Chen, Alberto Carrassi, Veronique Dansereau



For the first time, one blink away from predicting sea-ice

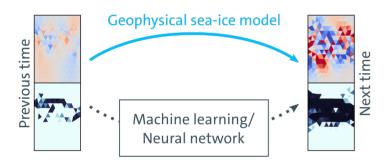


These advanced geophysical sea-ice models are not perfect



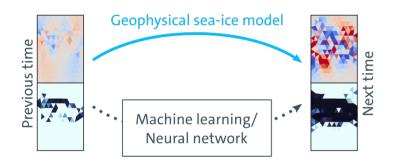


Correct forecast errors of sea-ice dynamics with machine learning before they appear





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Already possible (not exclusive):

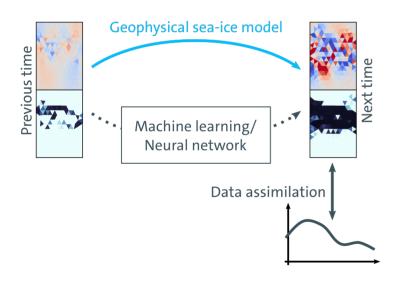
Cloud convection (Rasp et al., 2018)

Atmospheric boundary layer (Chen et al., 2022)

Ocean turbulence (Bolton and Zanna, 2020)



Correct forecast errors of sea-ice dynamics with machine learning before they appear



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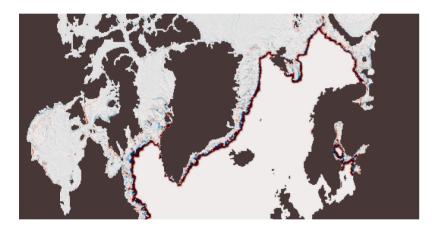
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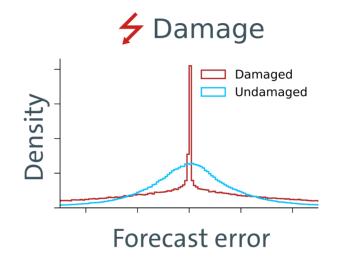
We can even learn the dynamics from observations (Bocquet et al. 2020, Gottwald and Reich 2021, Farchi et al. 2021)

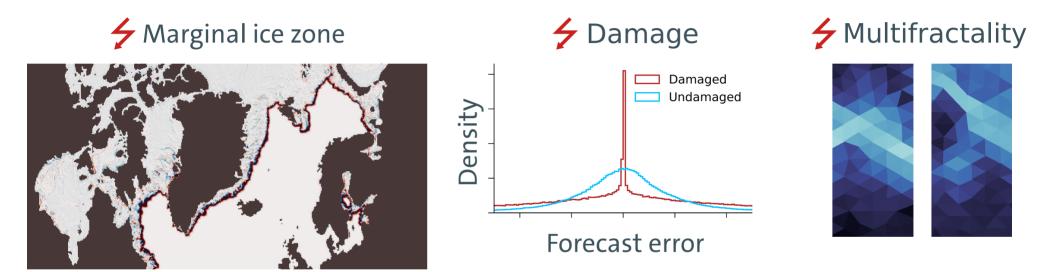
How can we use similar approaches for the sea-ice dynamics?

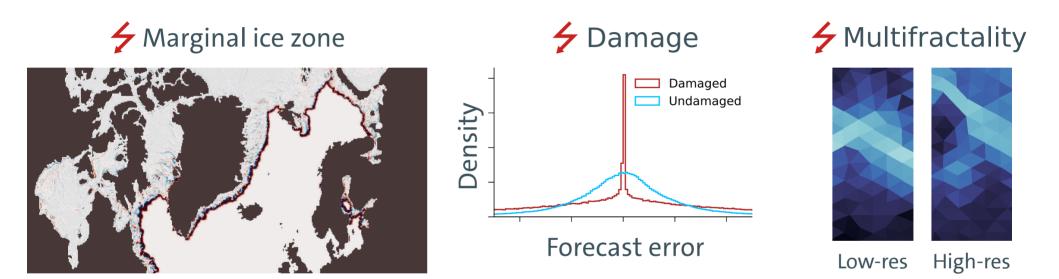
★ Marginal ice zone

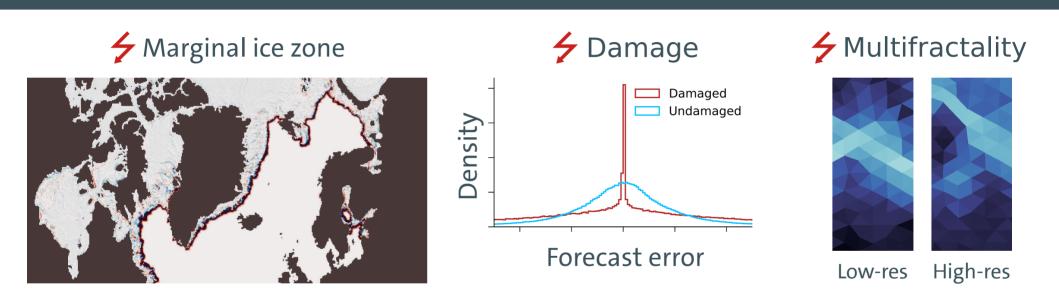




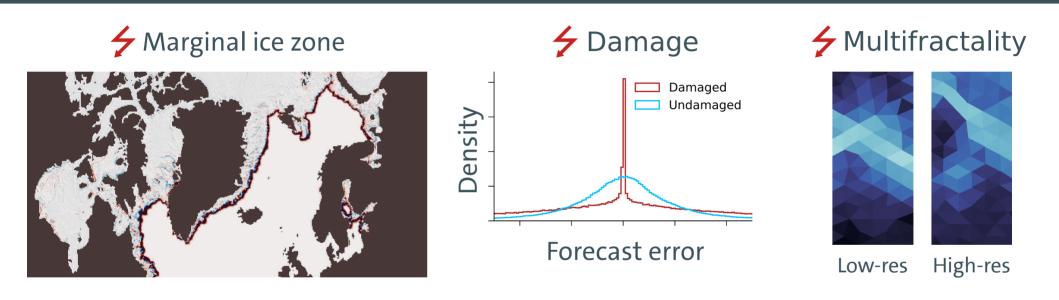








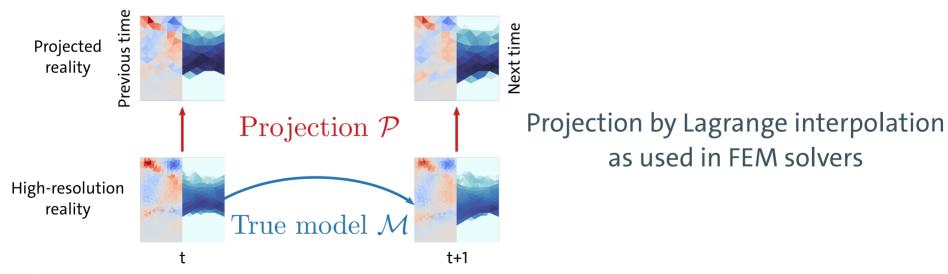
Scaling from small-scale model to Arctic-scale model

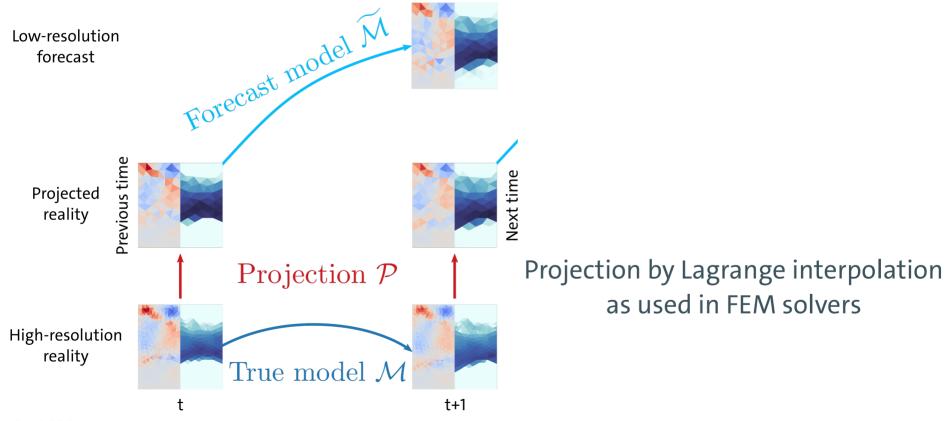


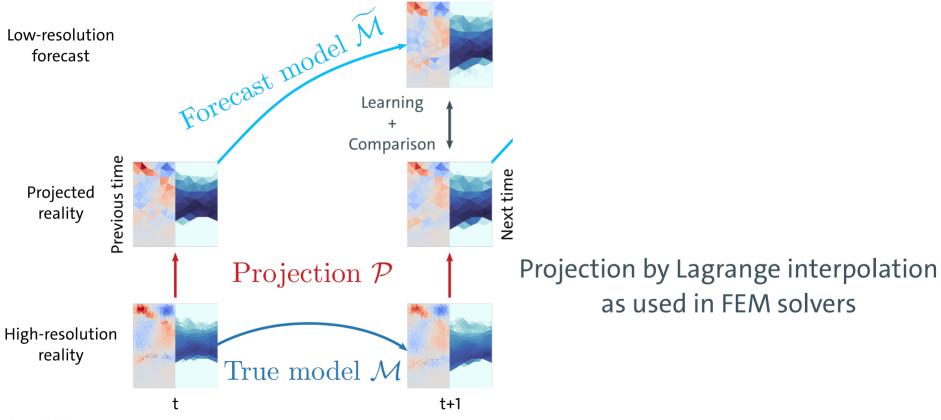
Scaling from small-scale model to Arctic-scale model

→ Screening of possible approaches



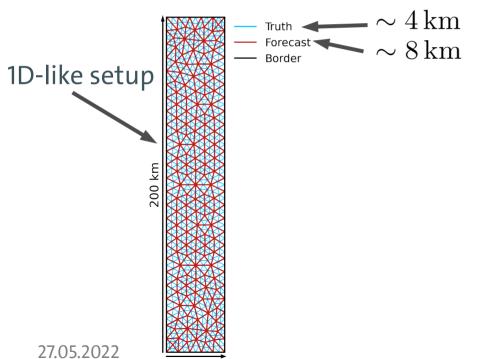




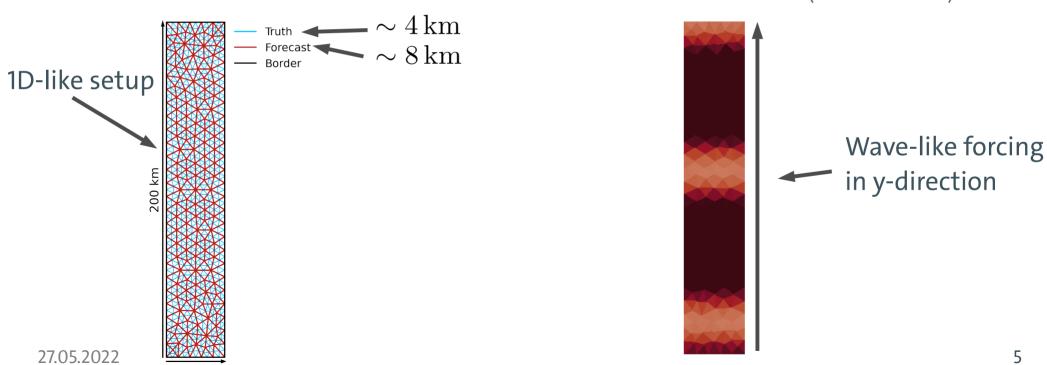


Maxwell-Elasto-Brittle model (Dansereau et al. 2016; Dansereau et al. 2017) based on discontinuous Galerkin finite elements and Rheolef solver (Saramito 2020)

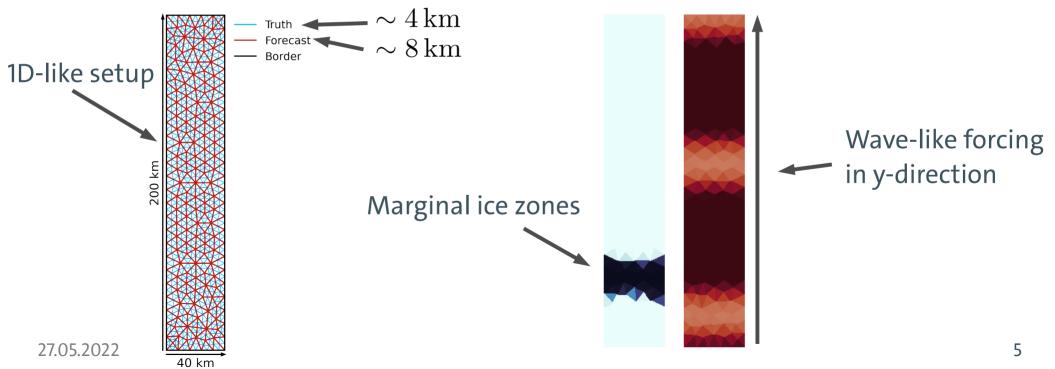
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How to train for all nine variables at the same time?

$$\mathcal{L}_{tot} = \lambda_1 \mathcal{L}_1 + \lambda_2 \mathcal{L}_2 + \dots + \lambda_9 \mathcal{L}_9$$

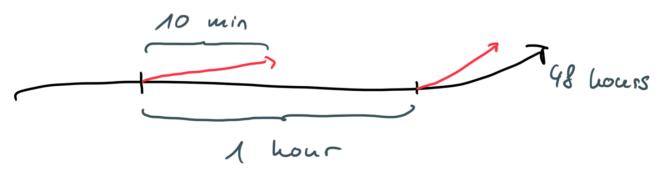
Use maximum likelihood approach

$$\mathcal{L}_{tot} = \lambda_1 \mathcal{L}_1 + \lambda_2 \mathcal{L}_2 + \cdots + \lambda_9 \mathcal{L}_9$$
 Maximum likelihood approach Global per-variable uncertainty

$$\mathcal{L}_{tot} \approx \frac{1}{\text{scale}_1} \mathcal{L}_1 + \log(2 \operatorname{scale}_1) + \dots + \frac{1}{\text{scale}_9} \mathcal{L}_9 + \log(2 \operatorname{scale}_9)$$

Training based on an ensemble of trajectories

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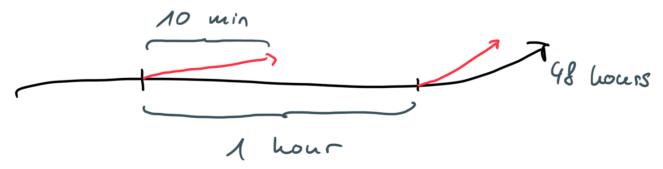
Ensemble of forcing parameters and initial cohesion

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Ensemble of forcing parameters and initial cohesion

How to make use of inductive bias for triangular data?

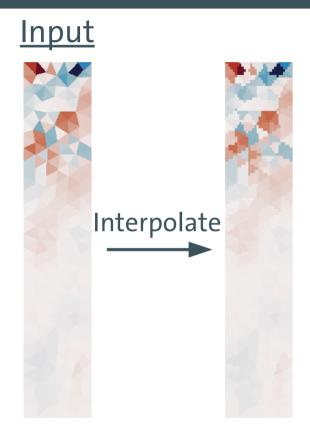
<u>Input</u>



Prediction



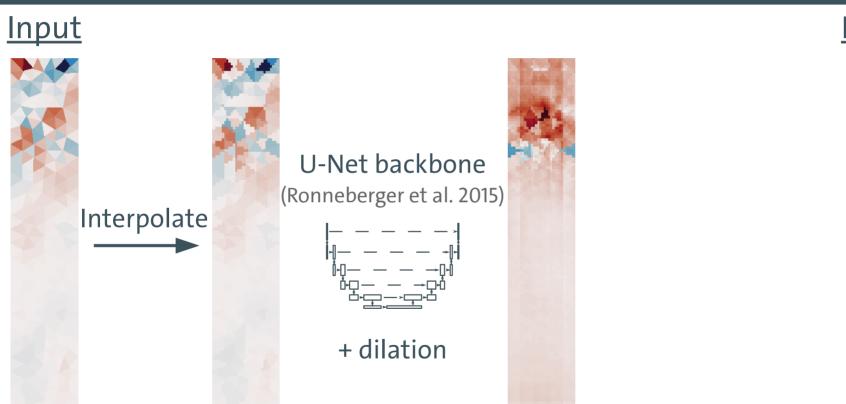
Project into Cartesian space



Prediction



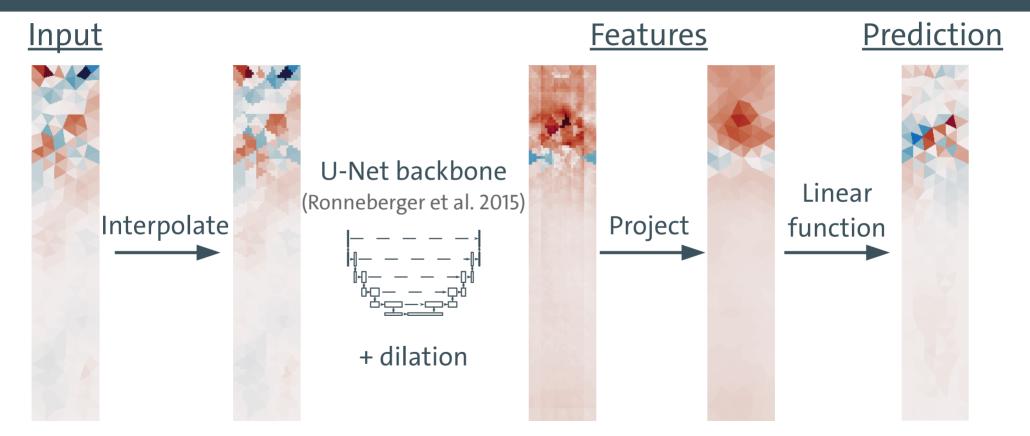
Project into Cartesian space and apply convolutional neural network



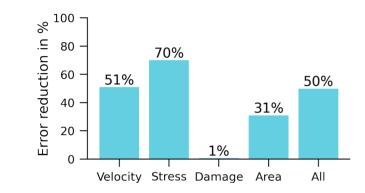
Prediction

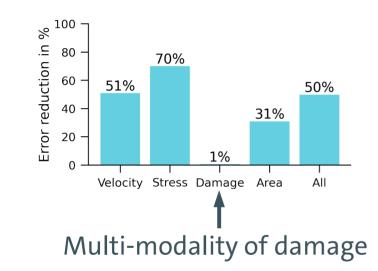


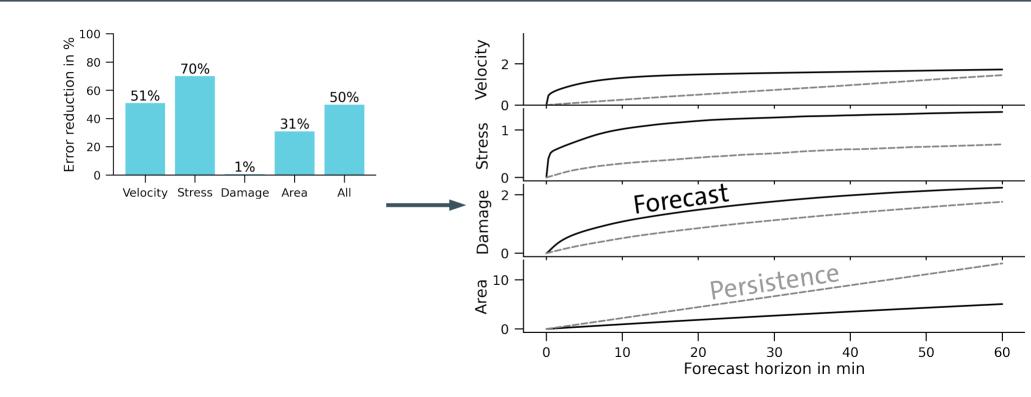
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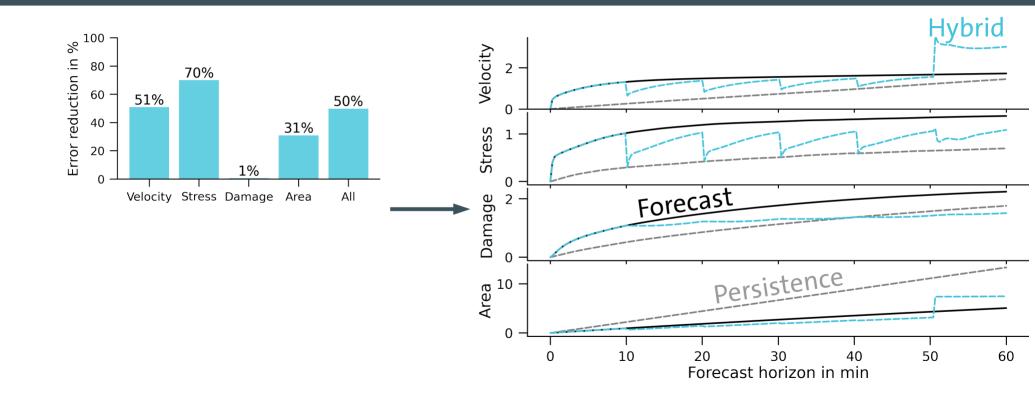


How is the performance of our neural network?

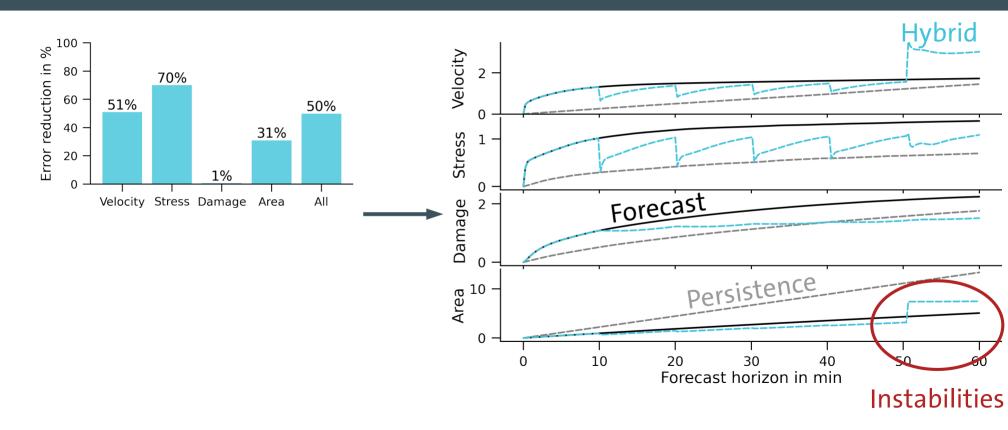




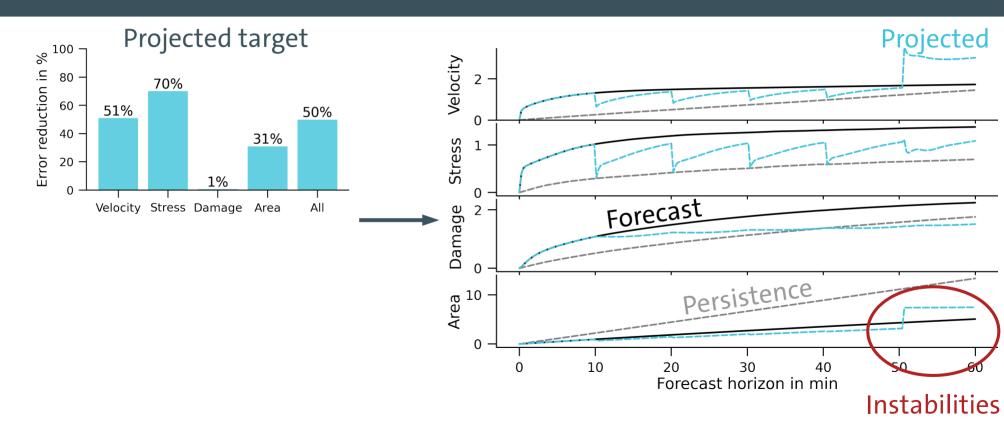




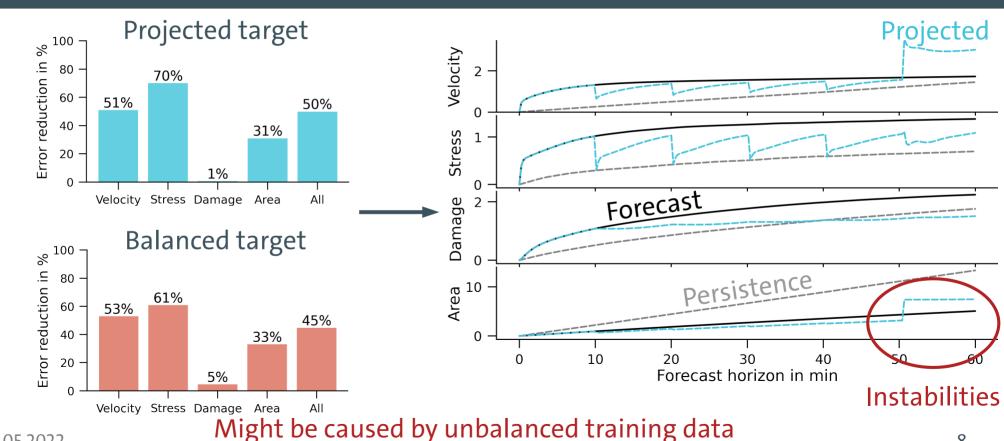
Forecast error reduced in offline testing dataset



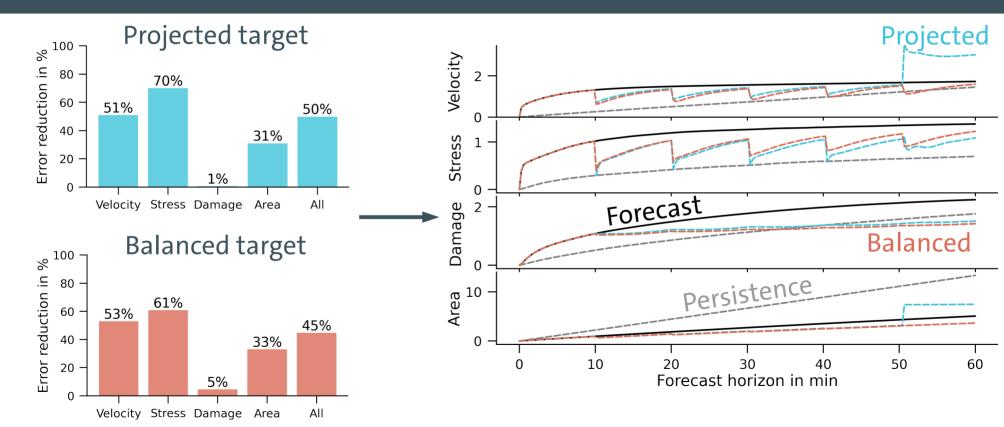
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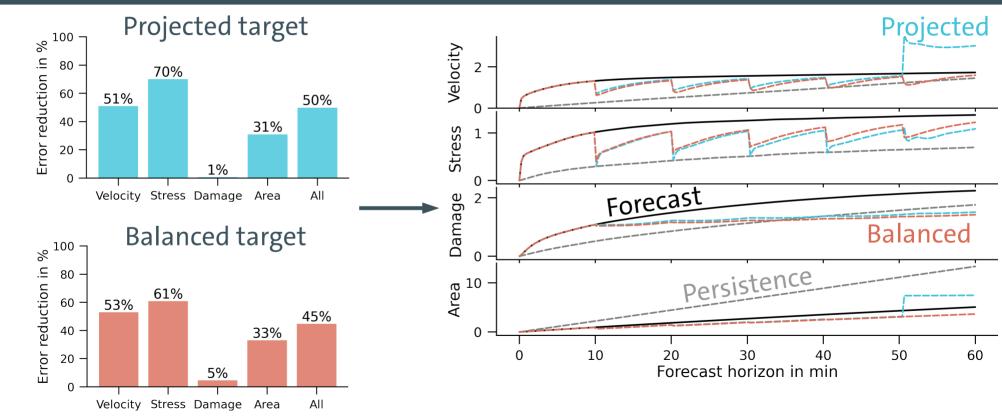
Balancing step has only little impact on offline performance



Balancing step within training data stabilises hybrid forecast



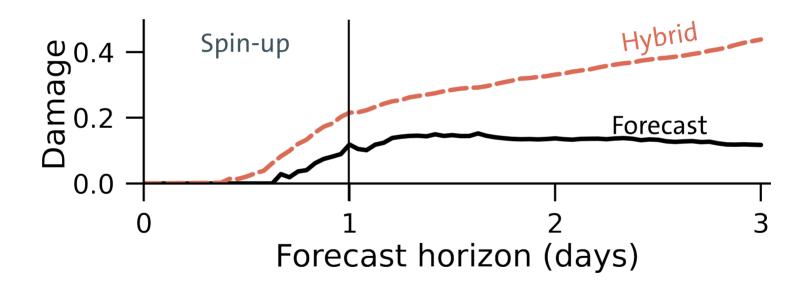
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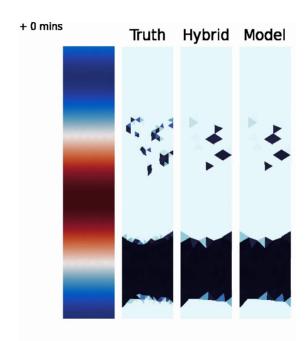
First promising results for hybrid modelling

Network is trained after spin-up

Network is trained after spin-up → at the moment problems with spin-up



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Forecast errors reduction by around 45% in a 1D MEB model setup + first promising results in the hybrid modelling setup

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Do you have questions?

Feel free to also write me an email: tobias.finn@enpc.fr