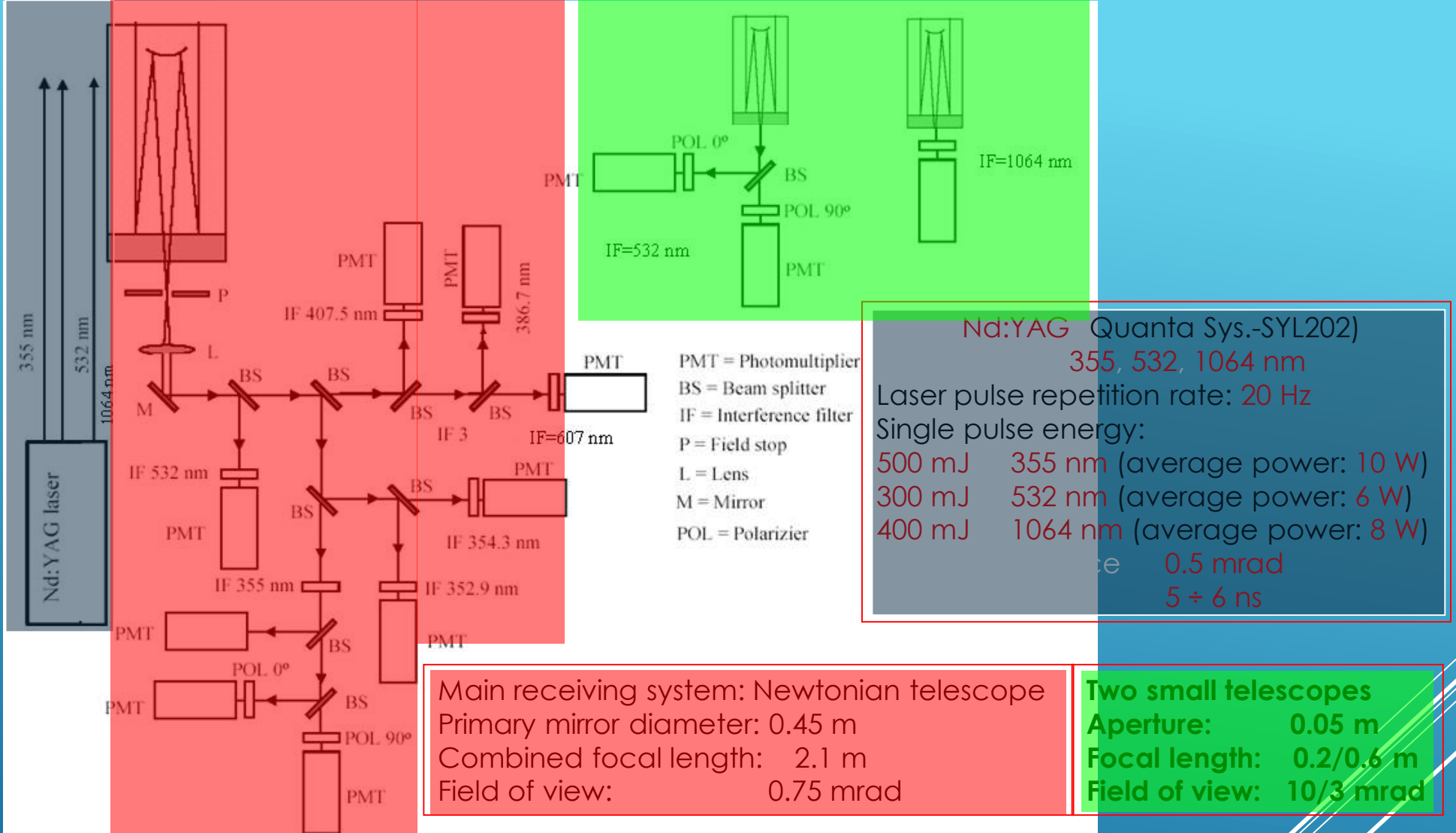


ABL DETERMINATION BY RAMAN LIDAR WITH DIFFERENT APPROACHES IN THE FRAME OF HYMEX SOP1

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SPECTRAL SELECTION: based on Interference Filters

				N ₂ @355	H ₂ O@355	N ₂ @532	Hi J RR	Low J RR
Wavelength (nm)	1064	532	355	387	407	607	354.3	352.9

BASIL Raman Lidar

$$3\beta + 2\alpha + 2\delta + \text{H}_2\text{O} + \text{T}$$

Measured parameters:

- particle backscattering coeff. @ 355, 532 and 1064 nm [3b]
- particle extinction coeff. @ 355 and 532 nm [2a]
- depolarization ratio @ 355 & 532 nm,
- atmospheric temperature (Rotational Raman technique)
- water vapour mixing ratio (Vibrational Raman technique)
- relative humidity from simultaneous measurements of temperature and water vapour mixing ratio

Resolution of raw data:

vertical 7.5 m, temporal 1-10 sec

Typical resolution of measured parameters:

vertical 30 m, temporal 1 min



PBI through rotational and water vapour signals gradient

The Range corrected signals is used to create the map of October 16-19 to highlight the structures present in the observation period from BASIL system at wavelength of 532nm.

The RCS can be easily expressed in terms of measured lidar signals taking into account:

$$P_{RCS}(z) = [P_{\lambda_0}(z) - P_{bgd}(z)]z^2$$

Where $P_{\lambda}(z)$ represents the power received at a given wavelength that in our case $\lambda=532$ nm

$$P_{RCS}(z) = \frac{P_{HiJ}(z[T])}{P_{LoJ}(z[T])} \cong \exp [T(z)]$$

$$\chi_{H_2O}(z) = K \frac{P_{H_2O}(z)T_{N_2}(z)}{P_{N_2}(z)T_{H_2O}(z)}$$

In order to determine an estimate of the height of ABLH, we directly apply the derivative method exploiting the logarithm of the quantity.

$$ABLH = \min \left\{ \frac{d}{dz} [\log(P_{RCS}(z))] \right\}$$

PBL by MIPA FRAMEWORK Algorithm

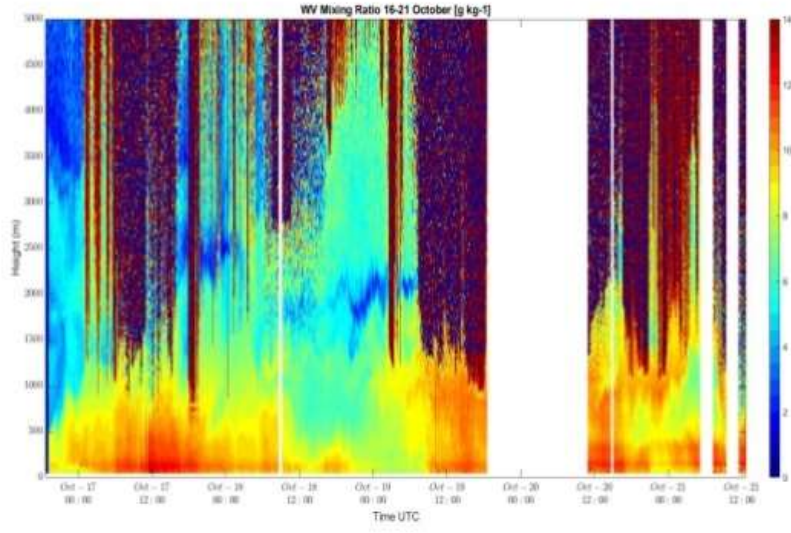
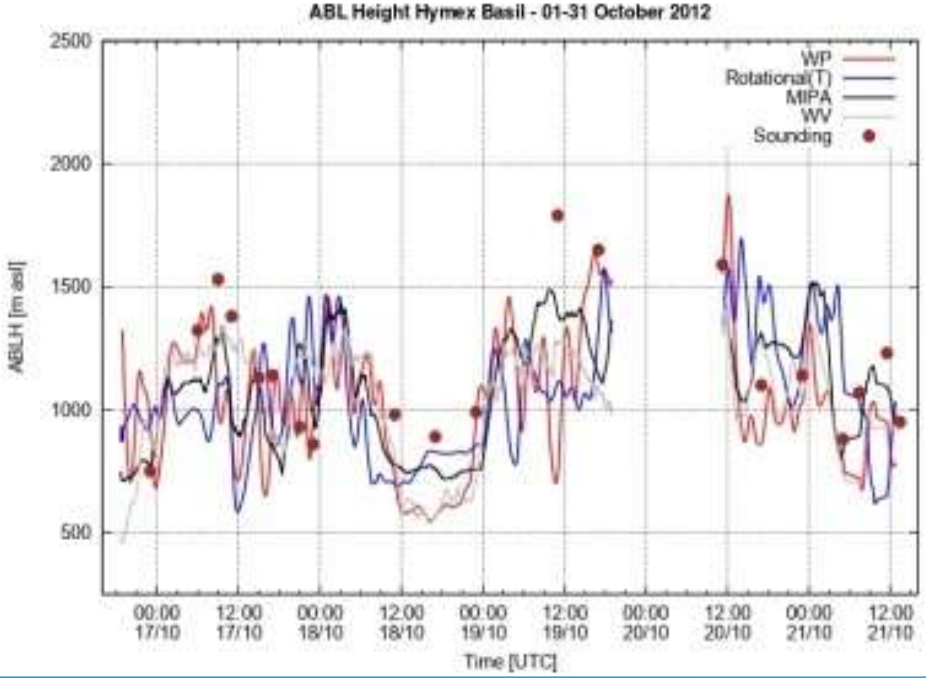
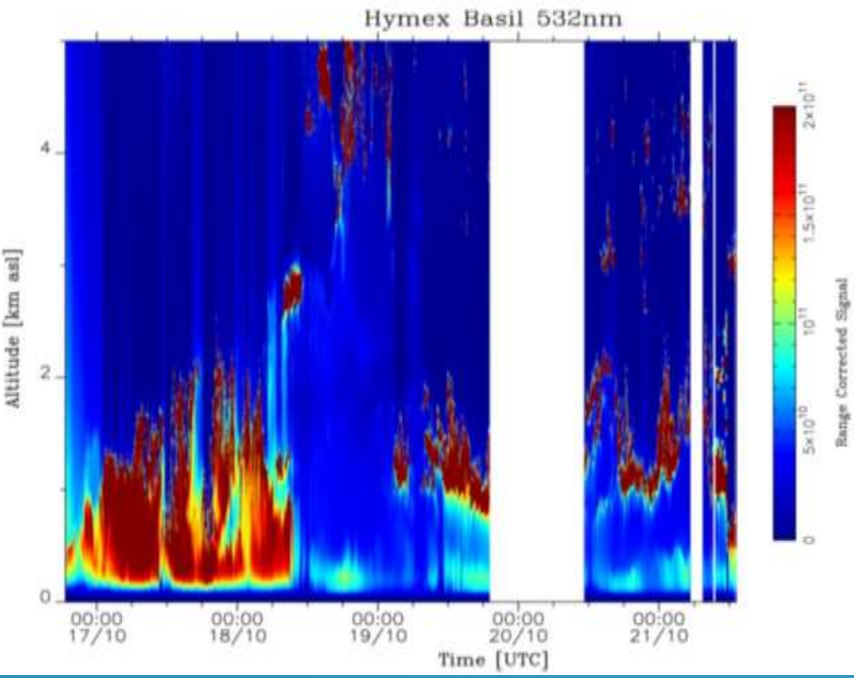
Morphological Image Processing Approach (MIPA) framework used to detect the ABL when lidar data are involved. These latter can be represented as an image of range corrected vertically-resolved profiles acquired sequentially in time. MIPA consists of four main blocks:

- a. a vertical spatial resolution adjustment step to reach a (target) working spatial resolution (around 20 m);
- b. a pre-processing based on mathematical morphology;
- c. an edge detector (i.e., the Wavelet Covariance Transform (WCT) in this work);
- d. a post processing relied upon both mathematical morphology and an object-based analysis to get the final result. It is worth to be remarked that MIPA is a blind approach and, thus, it does not exploit any prior information.

Algorithm 1 The MIPA framework.

- Vertical spatial resolution adjustment of \mathbf{I} by a factor R to get \mathbf{I}_D
 - Pre-process \mathbf{I}_D by low-pass filtering using half-gradients to get \mathbf{I}_{pre}
 - Detection of the edges of \mathbf{I}_{pre} using the WCT to get the edge map \mathbf{E}
 - Post-process \mathbf{E} using directional morphological filters and an object-based analysis to get \mathbf{E}_{out}
-

RESULTS:



Methods	MIPA	Rotational(T)	WP	WV
Mean	207.67	281.31	235.68	238.61
Std.dev	127.5	178.9	241.19	144.44
Std.err	29.25	41.04	55.33	33.13
Min	11.81	27.39	27.16	5.15
Max	505.22	591.22	573.62	568.68
I Quartile	132.72	158.82	70.86	127.21
II Quartile	201.25	283.93	167.71	227.72
III Quartile	267.27	379.21	329.09	307.49
IV Quartile	227.31	319.21	309.19	301.39

table of results



COCLUSIONS and future works

- ❑ The preliminary results show a good agreement with the different techniques compared with the respective radiosondes placed in the CV-site of the campaign.
- ❑ These results are comforting as they allow to study and characterize the PBL even in complex cases with strong convective activity.

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