



Representing Microphysical Uncertainty in Convective-Scale Data Assimilation Using Additive Noise

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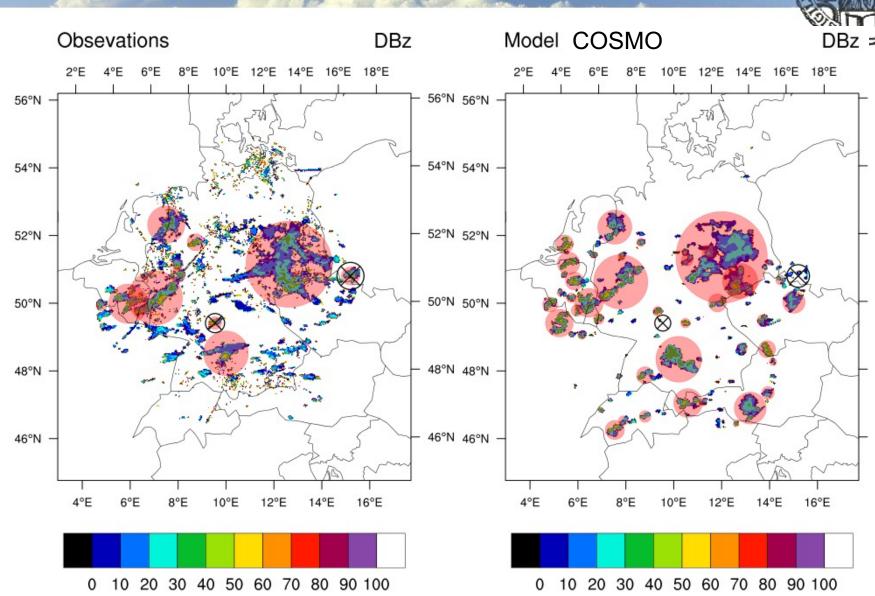
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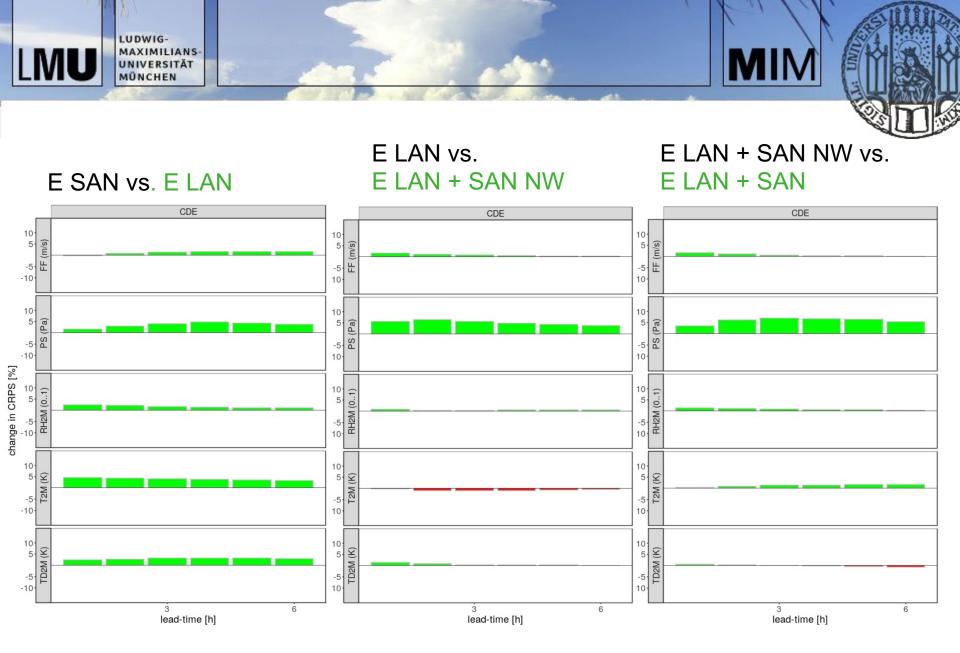
Additive noise

$$\mathbf{x}^{a(i)} \leftarrow \mathbf{x}^{a(i)} + \alpha_a \boldsymbol{\eta}^{(i)} + \alpha_a^{\mathrm{s}} \boldsymbol{\eta}^{(i)} \qquad \boldsymbol{\eta}^{(i)} = \tilde{\mathbf{B}}^{\frac{1}{2}} \boldsymbol{\gamma}$$

 $\eta^{(i)\rm s}$ for unresolved scales model error samples calculated as difference between COSMO 2.8 km and 1.4 km offline for a different historical time

- $oldsymbol{\eta}^{(i)}$ velocity u, v, temperature, pressure and relative humidity qv are perturbed
- $\eta^{(i)}$ s velocity u, v, w, temperature and relative humidity qv are perturbed using randomly chosen sample from historical data base

DA: 40 members, KENDA, EMVORADO, **All hydrometeors updated with LETKF** 20 members are used for 6-h ensemble forecasts, initiated at 10, 11, ..., 18:00 UTC **Observation error:** 10 dBZ for reflectivity, 1h updates



Relative difference of CRPS in percentage. Strong forcing conditions





Uncertainty in microphysics

ICON DA

$$\mathbf{x}^{a(i)} \leftarrow \mathbf{x}^{a(i)} + \alpha_a \boldsymbol{\eta}^{(i)} + \alpha_a^{\mathsf{m}} \boldsymbol{\eta}^{(i)\mathsf{m}} \quad \boldsymbol{\eta}^{(i)} = \tilde{\mathbf{B}}^{\frac{1}{2}} \boldsymbol{\gamma}$$

 $\eta^{(i)^{\rm m}}$ representing uncertainty in **m**icrophysics, as a difference between simulations with one and two-moment scheme

 $\eta^{(i)^{\mathrm{m}}}$ qi, qr, qg, qs, qc are perturbed using randomly chosen sample from historical data base

In addition to LAN, in which velocity u, v, temperature, pressure and relative humidity qv are perturbed





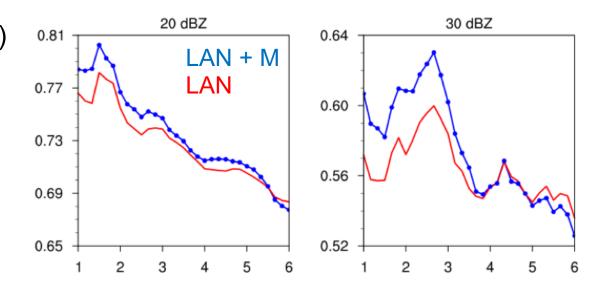
Uncertainty in microphysics

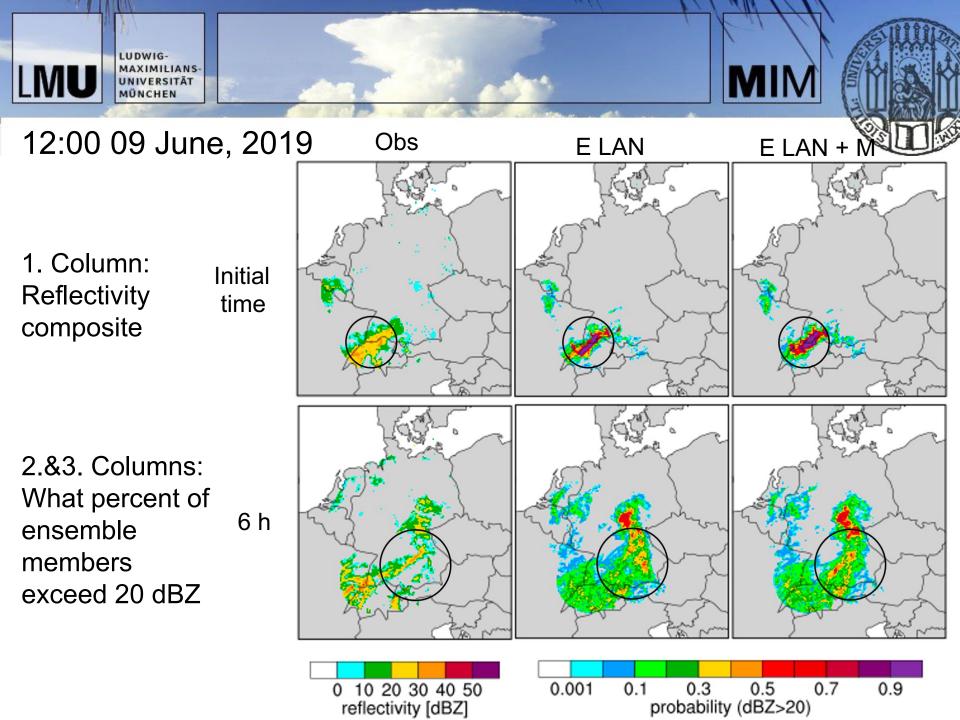
ICON DA

$$\mathbf{x}^{a(i)} \leftarrow \mathbf{x}^{a(i)} + \alpha_a \boldsymbol{\eta}^{(i)} + \alpha_a^{\mathsf{m}} \boldsymbol{\eta}^{(i)\mathsf{m}} \quad \boldsymbol{\eta}^{(i)} = \tilde{\mathbf{B}}^{\frac{1}{2}} \boldsymbol{\gamma}$$

 $\eta^{(i)^{\rm m}}$ qi, qr, qg, qs, qc are perturbed using randomly chosen sample from historical data base

FSS (70 km)









Conclusion

- ➤ The higher resolution models are able to resolve strongly nonlinear dynamics and start to resolve physical processes that have traditionally been parameterized such as, for example, convection.
- Small-scale additive noise based on model truncation error or microphysics error improves large-scale additive inflation for shortterm precipitation forecast.
- Further improvement over additive model truncation error can be obtained by adding time variable information from data or on weather regime (Zeng et al. 2020).
- Still to be shown for time variable microphysics error.



References



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