



Unraveling the mystery of DeepMind's rainfall nowcasting: A step-by-step tutorial for hydrologists

Presentors

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Stay tuned with the update of our
reproduction of DGMR on Github!



Check out our abstract!

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DGMR: Deep Generative Models of Radar proposed by DeepMind



In 2021, DeepMind proposed a deep-learning-based model, ***Deep Generative Models of Radar***, that achieved a great success in the field of **short-term rainfall nowcasting** (Ravuri et al., 2021).

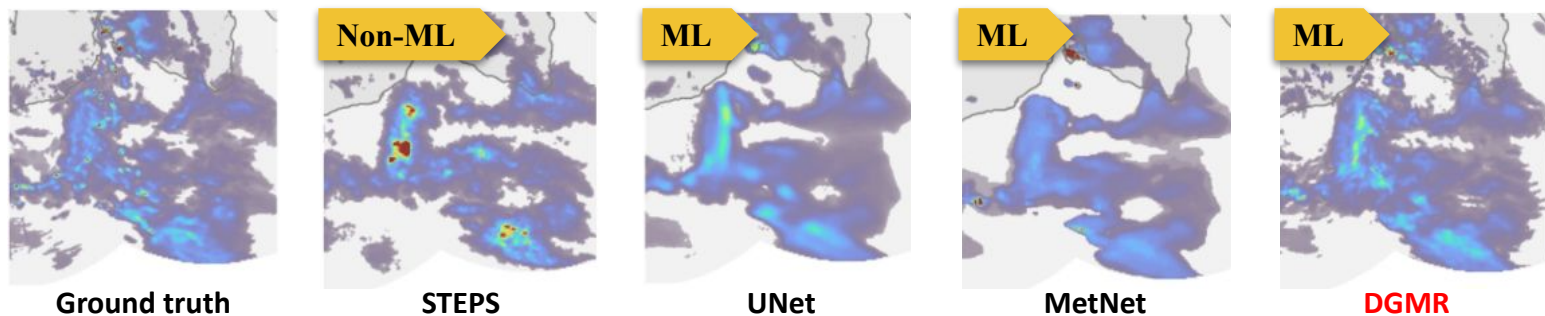


Figure. Case study of performance on a challenging precipitation event starting on = 24 June 2019 at 16:15 UK, showing convective cells over eastern Scotland (Ravuri et al., 2021).



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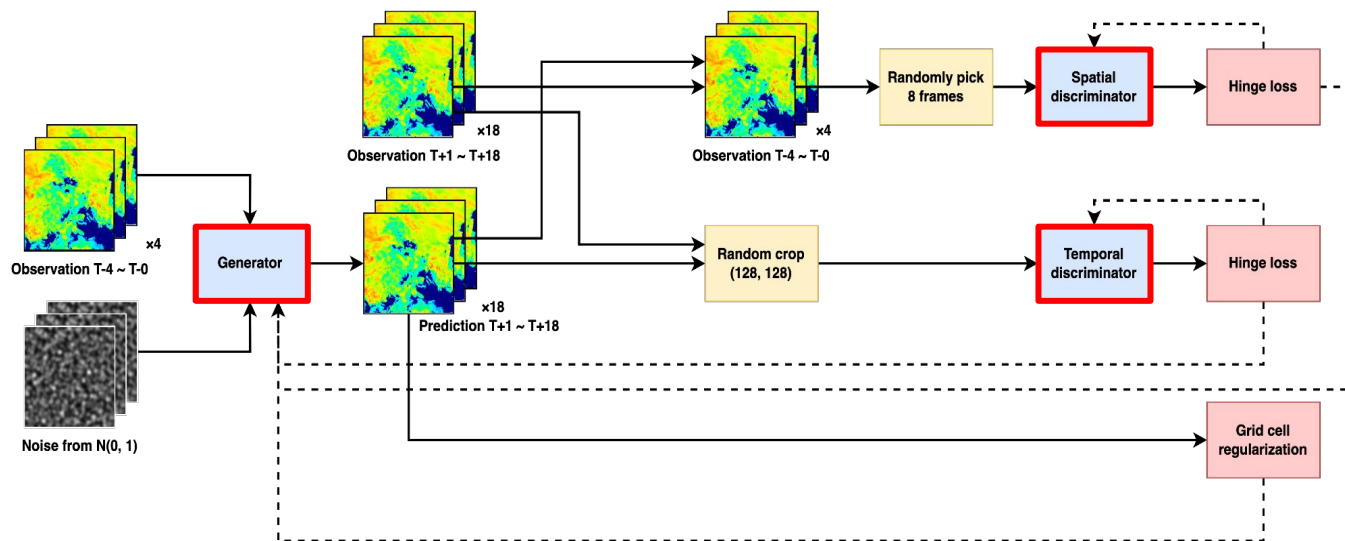
DGMR: A rainfall nowcasting model trained with the GAN technique



DGMR includes three main models, which are trained simultaneously via an adversarial process.

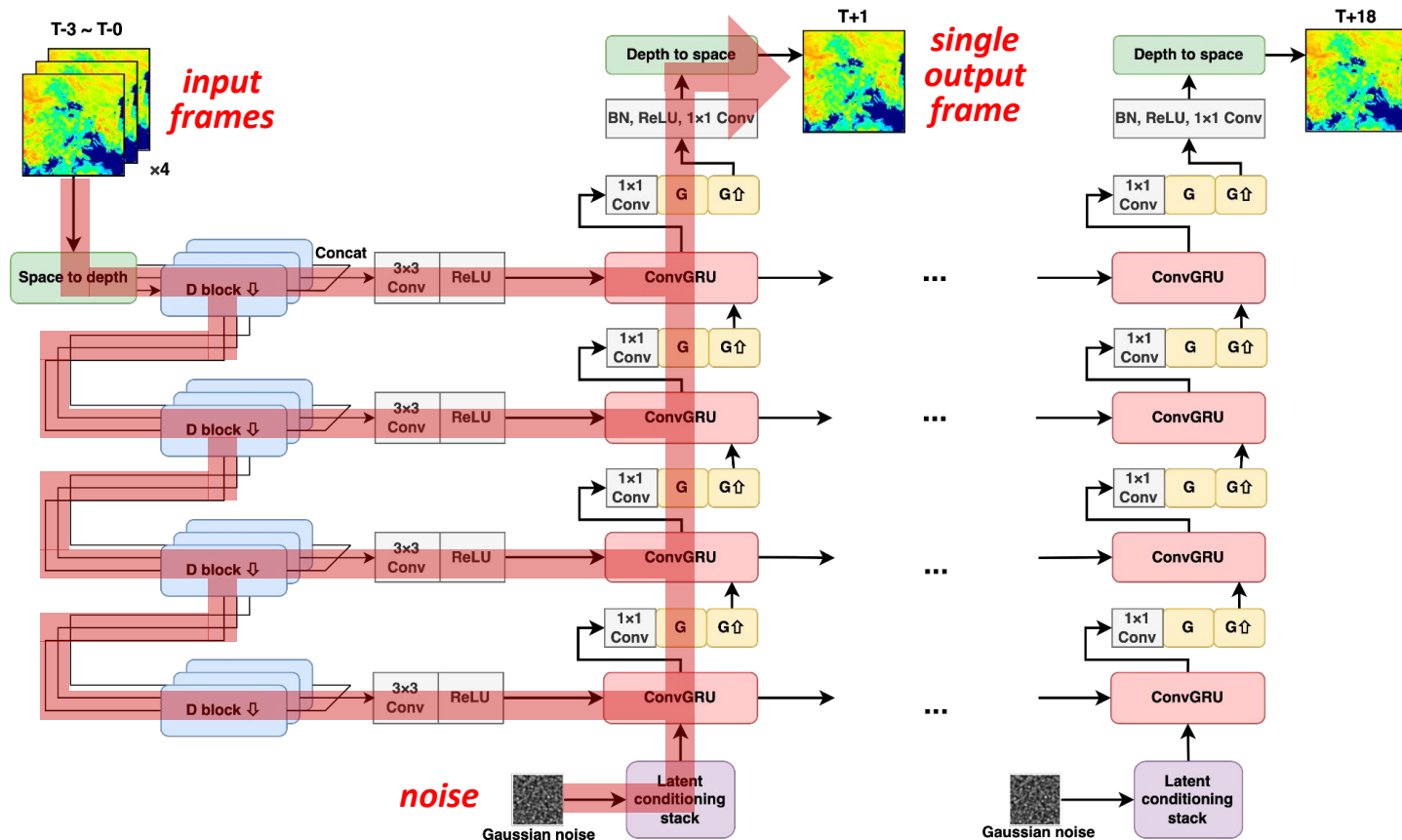
These models are:

- **A Generator** that produces rainfall nowcasts.
- **Two Discriminators** that discriminate if the generated nowcasts are 'similar enough' to the ground truth in terms of their spatial and temporal features, respectively.



Check out DGMR's article!

Overview of the DGMR generator





DGMR: Key techniques leading to better nowcasts

Through reproducing the DGMR, we identify the following four key techniques that make DGMR better than other AI-based models:

- **Space to Depth (S2D)**

- A downsampling method.
- Reduce image size with S2D, rather than pooling, can better preserving spatial details.

- **Hierachical feature extractor**

- A feature extraction framework.
- Extract image features across a wide range of spatial scales.

- **ConvGRU along downsampling axis**

- A feature extraction framework.
- Establish relationship across multi-scale spatial and temporal features.

- **Generative Adversarial Network (GAN)**

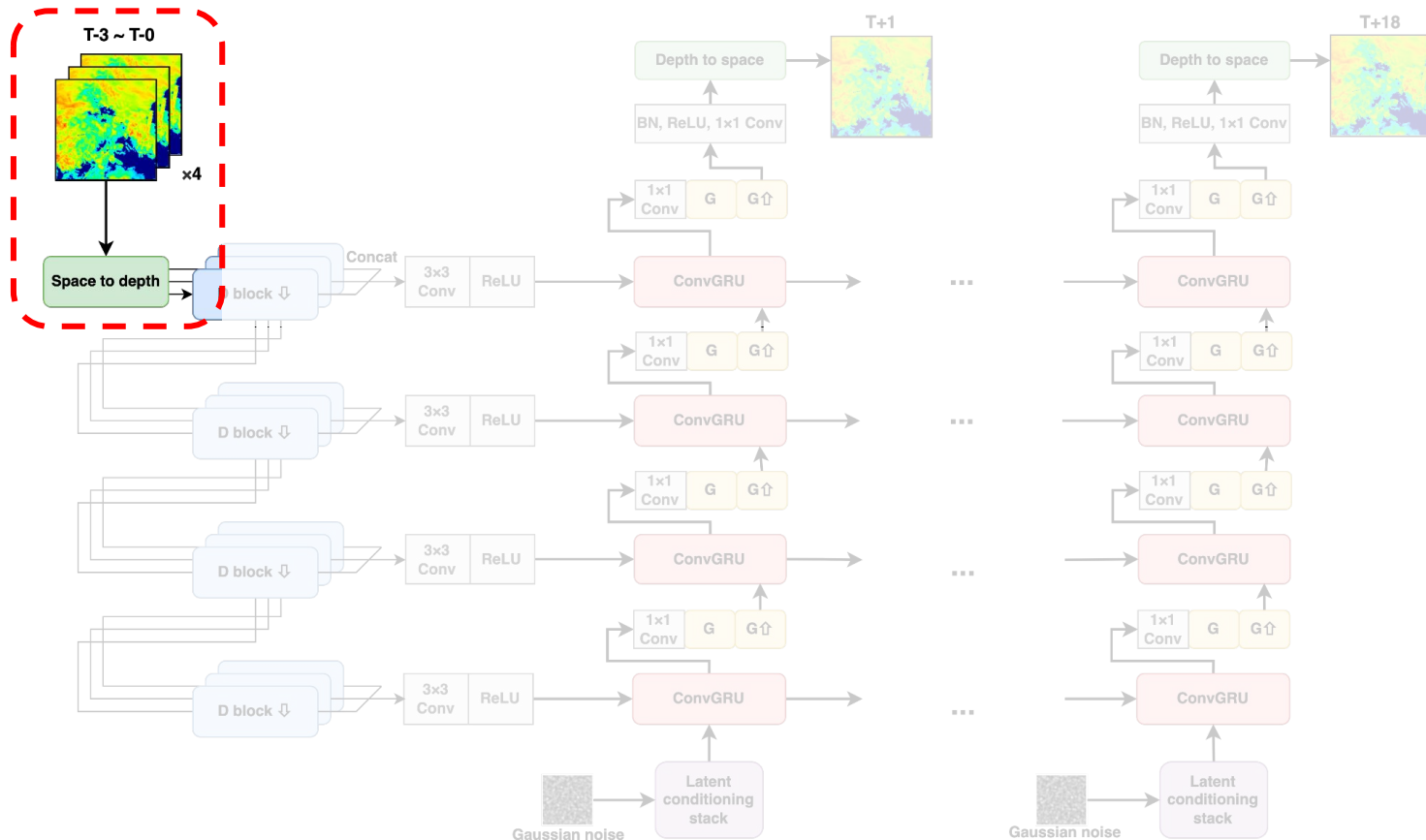
- A model training framework.
- Reduce smoothness between spatial details.



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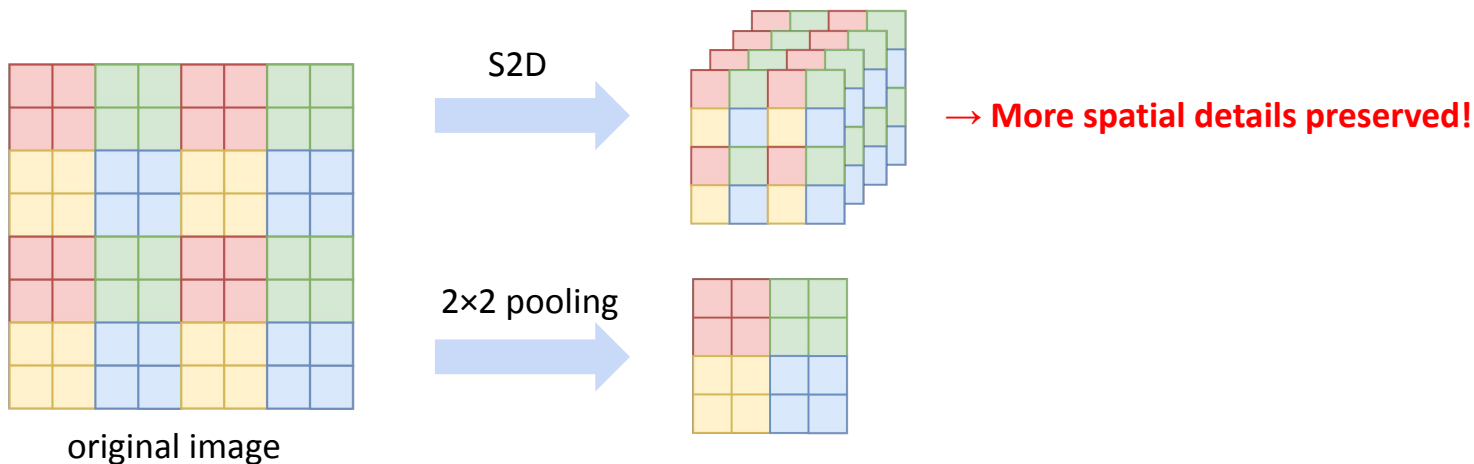
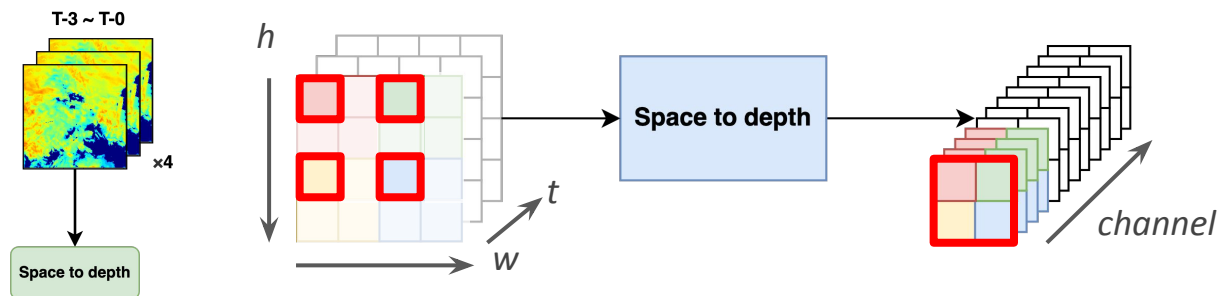


DGMR: Space to depth (S2D)

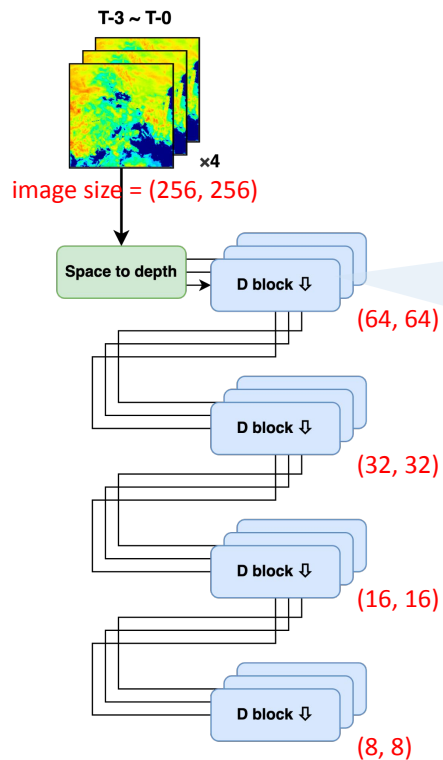


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(1) Space to depth: Reduce image size while preserving spatial details



(2) Hierarchical feature extractor: Extract features across a wide range of spatial scales

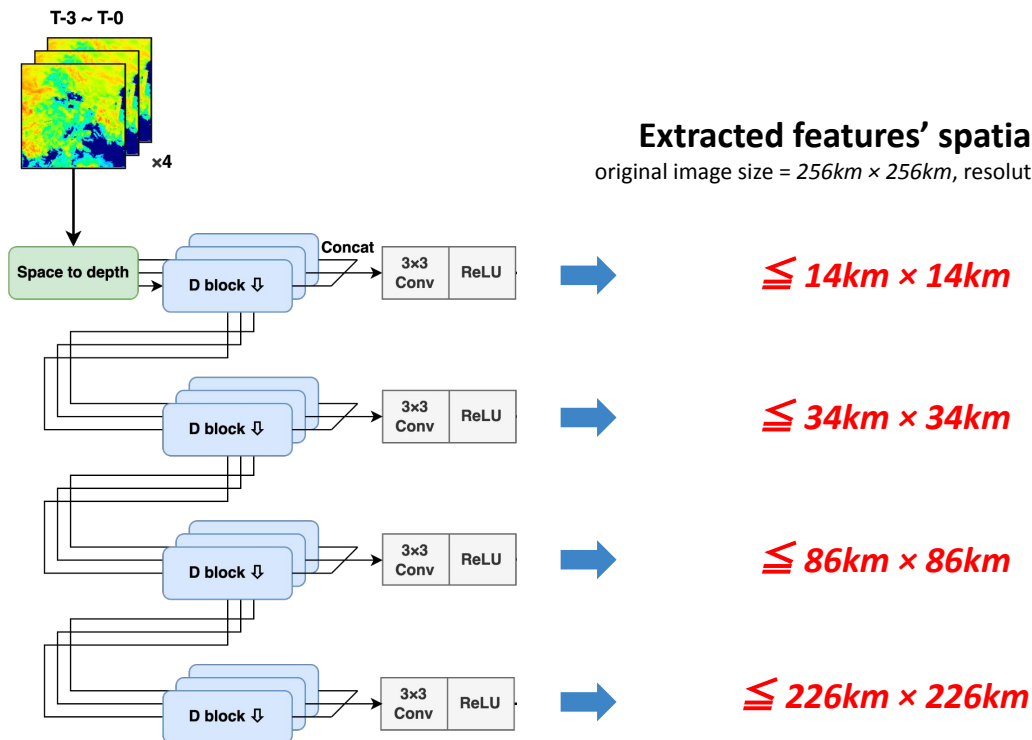


Operations a single D block contains:

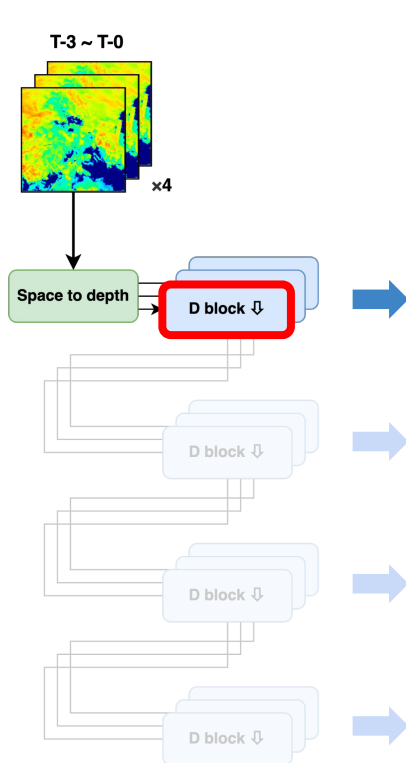
- (1) **1×1 convolution**
 - (2) **3×3 convolution**
 - (3) **space to depth** (after convolutions)
- } operates in parallel



(2) Hierarchical feature extractor: Extract features across a wide range of spatial scales



(2) Hierarchical feature extractor: Extract features across a wide range of spatial scales

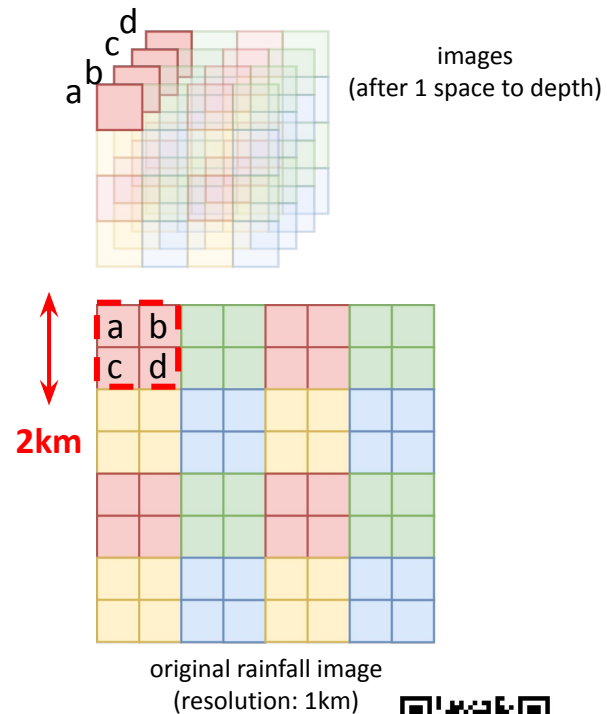


Extracted features' spatial extent
original image size = $256\text{km} \times 256\text{km}$, resolution = $1\text{km} \times 1\text{km}$

1×1 convolution

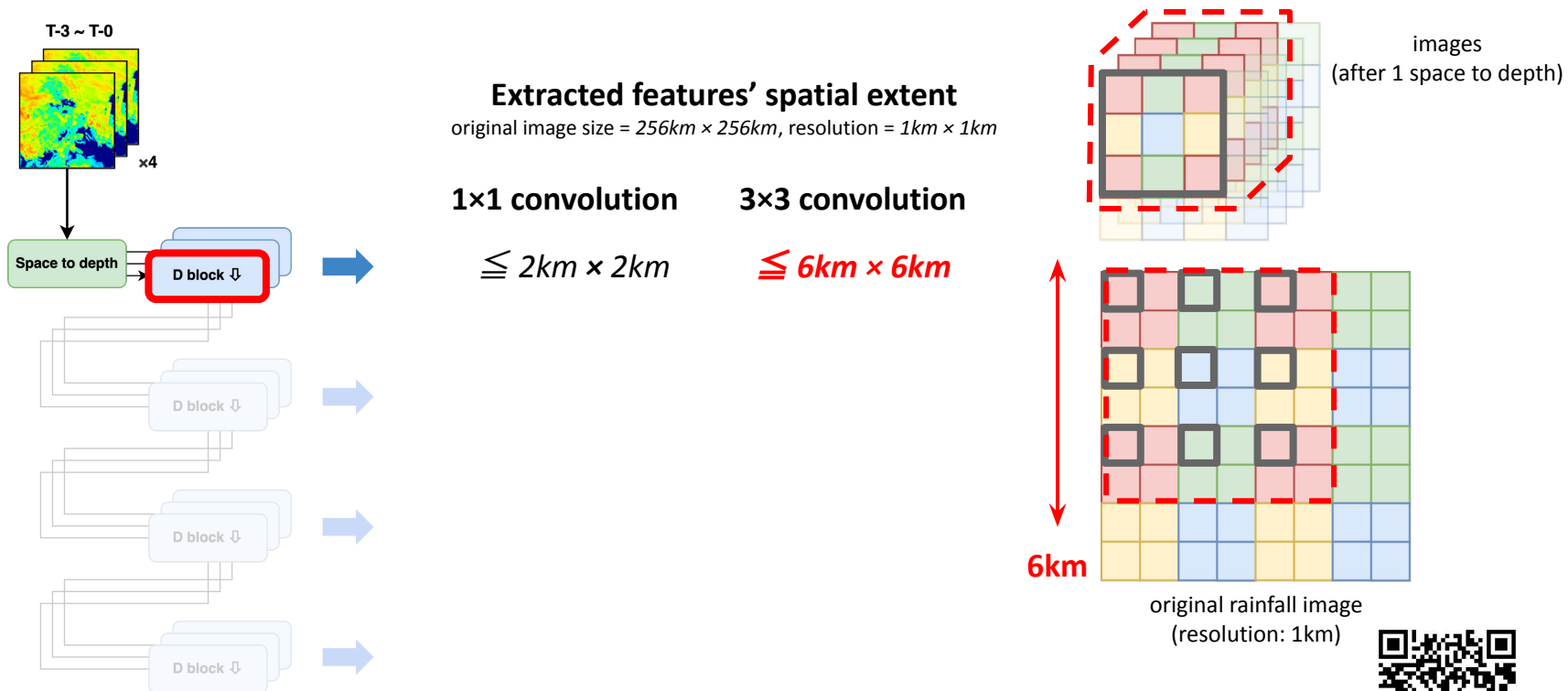
3×3 convolution

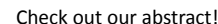
$\leq 2\text{km} \times 2\text{km}$



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(2) Hierarchical feature extractor: Extract features across a wide range of spatial scales

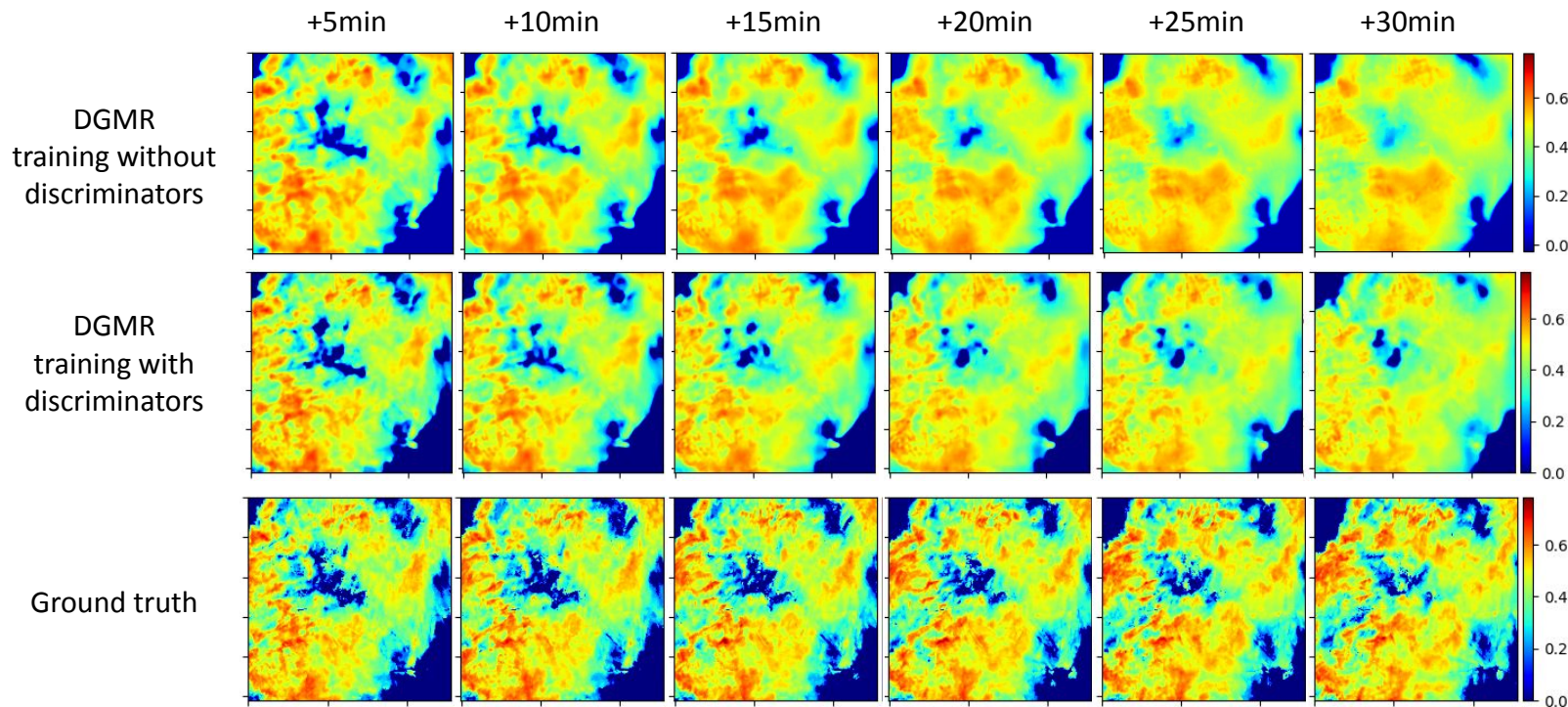






(4) GAN: Reduce smoothness of spatial details

More details can be preserved in the fields with GAN.



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A more detailed explanation can be found in our full tutorial!



Tutorial Outline

- **Deep Learning 101: How does DL work?**
- **What is Convolution?**
 - How does it work on a 2-dimensional images?
- **What is Space to Depth?**
 - How does it work?
 - Space to Depth + Convolution
 - Hierarchical feature extractor
- **What is GRU (Gated Recurrent Units)?**
 - How does GRU work?
 - The role of ConvGRU in DGMR
- **What is GAN?**
 - GAN framework in a nutshell
 - The benefit of using GAN



Article of DGMR



Our abstract



Full tutorial on YouTube!



Our reproduction of DGMR
on Github
(weights are yet to update)

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