hydroMOPSO: A versatile Particle Swarm Optimisation R-package for multi-objective calibration of environmental and hydrological models

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Motivation

- Many hydrological models available, some R-based (e.g., TUWmodel, airGR, topmodel) and some need to be run from the system console (e.g. SWAT+, Raven, WEAP, VIC).
- The implementation of multi-objective optimisation algorithms with a user-defined hydrological model requires a long programming time and is prone-to-error.
- There is a lack of flexible, efficient and effective multi-objective optimisation tools that can be easily plugged-in with a user-defined hydrological model.



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- Is an R-package for multi-objective optimisation.
- It can be run in GNU/Linux, MacOS and Windows machines.
- It can be easily combined with R-based or R-external hydrological models
- It takes advantage of multi-core machines and network clusters → important reduction of execution time.
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Case studies

Benchmark functions

- Three well-known DTLZ problems: DTLZ1, DTLZ2 and DTLZ3 (Deb et al., 2005).
- Each one with three objectives (M = 3).

Objective

- Identify the Pareto Optimal Front (POF)
- Use the hypervolume (HV) (Zitzler and Thiele, 1999) to assess the accuracy and diversity the POF.
- Evaluate the number of model runs required to achieve the POF → efficiency.

Hydrological models

Two R-based models in a pluvio-nival catchment: **GR4J** (Perrin et al., 2003) and **TUWmodel** (Parajka et al., 2007), with two objectives:

- KGE': For mid- and high flows (Kling et al., 2012).
- *iKGE'_{Garcia}*: for low flows (Garcia et al., 2017).

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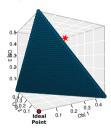
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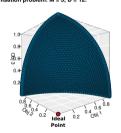
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Pareto Optimal Front - Benchmark functions

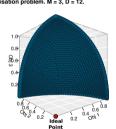
DTLZ1 problem
Minimisation problem. M = 3, D = 7.



DTLZ2 problem
Minimisation problem. M = 3. D = 12.

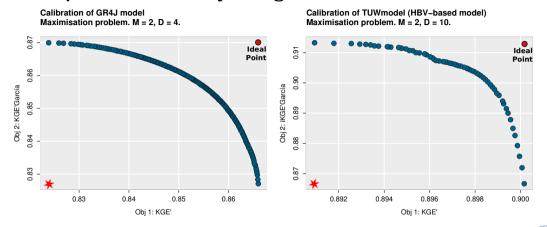


DTLZ3 problem
Minimisation problem, M = 3, D = 12.



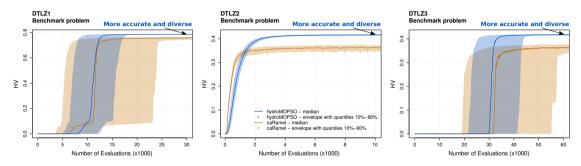


Pareto Optimal Front - Hydrological models



- The true POF is unknown for the optimisation of hydrological models.
- The true POF was **estimated** using hydroMOPSO with thousands of iterations. To corroborate, we also use caRamel, another R-packge package for MOC.

Hypervolume (HV) - Benchmark functions

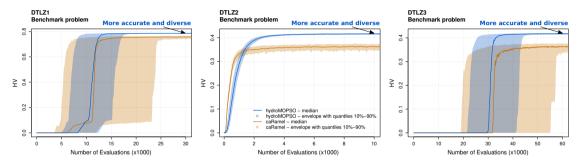


All problems were solved with two hundred different initialisations, with each method.

hydroMOPSO **vs** caRamel:

- hydroMOPSO achieves a higher HV than caRamel → POF more accurate and diverse.
- hydroMOPSO requires less model runs than caRamel to achieve the best HV.

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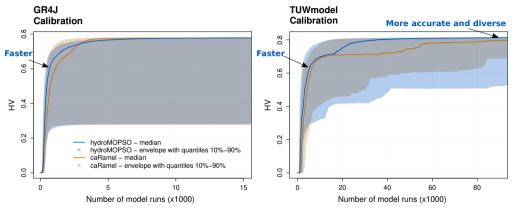


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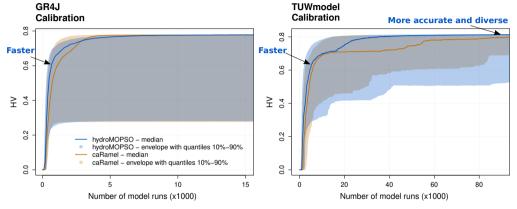
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Conclusions

- hydroMOPSO was able to **effectively solve** three well-known DTLZ benchmark optimisation problems.
- hydroMOPSO was more efficient and more effective than caRamel in optimising two hydrological models (GR4J, TUWmodel).

- hydroMOPSO will be soon available on GitLab and CRAN
- Manuscript is ongoing
- Upcoming vignettes (tutorials): TUWmodel, GR4J, SWAT+, Raven platform WEAP,

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Thank you very much for your attention!

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(References on the next slides)

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