

Scaling of the geomagnetic secular variation time scales

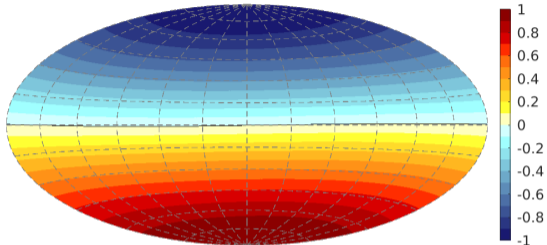
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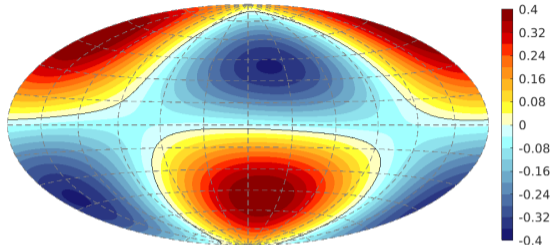
Chris Jones
University of Leeds

Time variation of the geomagnetic field at different spatial scales

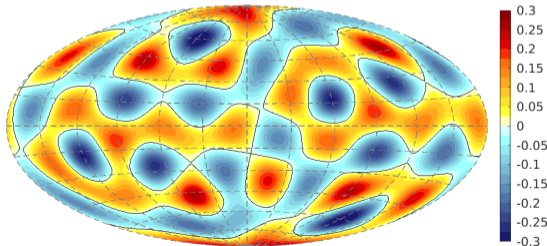
B_r for $l = 1$ at $t = 2.01795$



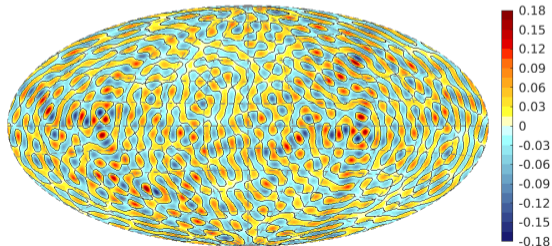
B_r for $l = 2$ at $t = 2.01795$



B_r for $l = 8$ at $t = 2.01795$

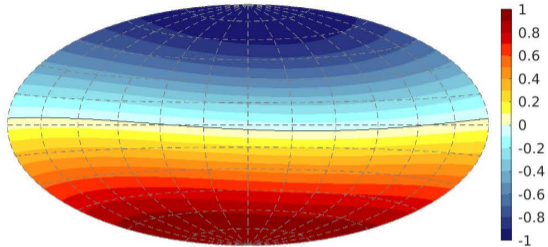


B_r for $l = 40$ at $t = 2.01795$

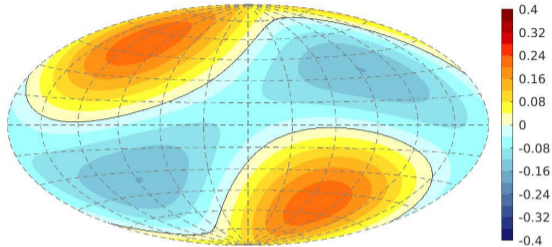


Time variation of the geomagnetic field at different spatial scales

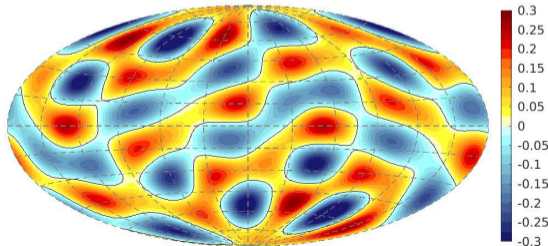
B_r for $l = 1$ at $t = 2.03795$



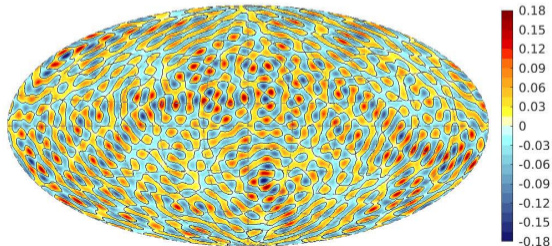
B_r for $l = 2$ at $t = 2.03795$



B_r for $l = 8$ at $t = 2.03795$



B_r for $l = 40$ at $t = 2.03795$



Spectra: to study properties at different spatial scales

(1) Lowes spectrum ($r \geq r_{\text{cmb}}$)

$$R(l, r, t) = \left(\frac{a}{r}\right)^{2l+4} (l+1) \sum_{m=0}^l [g_{lm}^2(t) + h_{lm}^2(t)],$$

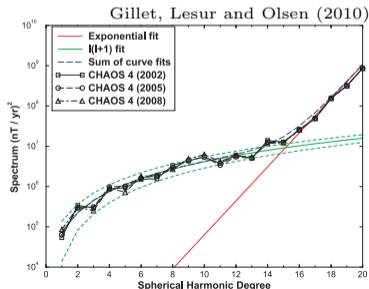
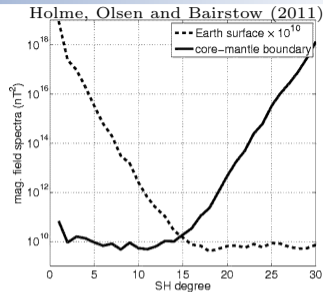
$$\sum_{l=1}^{\infty} R(l, r, t) = \frac{1}{4\pi} \oint |\mathbf{B}(r, \theta, \phi, t)|^2 \sin \theta \, d\theta \, d\phi$$

(a = Earth's radius)

(2) Secular variation spectrum ($r \geq r_{\text{cmb}}$)

$$R_{\text{SV}}(l, r, t) = \left(\frac{a}{r}\right)^{2l+4} (l+1) \sum_{m=0}^l [\dot{g}_{lm}^2(t) + \dot{h}_{lm}^2(t)]$$

$$\sum_{l=1}^{\infty} R_{\text{SV}}(l, r, t) = \frac{1}{4\pi} \oint |\dot{\mathbf{B}}(r, \theta, \phi, t)|^2 \sin \theta \, d\theta \, d\phi, \quad \dot{\mathbf{B}} = \frac{\partial \mathbf{B}}{\partial t}$$



Secular variation time-scale spectrum

$R(l) \sim$ “amount” of B^2 in spatial scale l

$R_{\text{sv}}(l) \sim$ “amount” of \dot{B}^2 in spatial scale l

$$\tau_{\text{sv}}(l, t) = \sqrt{\frac{R}{R_{\text{sv}}}} = \sqrt{\frac{\sum_{m=0}^l (g_{lm}^2 + h_{lm}^2)}{\sum_{m=0}^l (\dot{g}_{lm}^2 + \dot{h}_{lm}^2)}} \quad (r \geq r_{\text{cmb}})$$

- **characteristic time scale** of magnetic field structures with spatial scale characterised by l
- numerical simulations and *some* satellite data support the simple **power-law**: $\tau_{\text{sv}}(l) \sim l^{-1}$ (there are still some debates about this)
- theoretically, a common argument based on the **frozen-flux hypothesis**:

$$\dot{B}_r = -\nabla_{\text{h}} \cdot (\mathbf{u}_{\text{h}} B_r)$$

$$\nabla_{\text{h}} \sim \sqrt{l(l+1)} \sim l \quad \text{and} \quad \mathbf{u}_{\text{h}} \sim U$$

$$\tau_{\text{sv}} \sim B_r / \dot{B}_r \sim l^{-1}$$

Questions

- τ_{sv} is defined using the Gauss coefficients obtained from \mathbf{B} outside the outer core.

Do τ_{sv} and the scaling law $\tau_{sv} \sim l^{-1}$ describe the time variation of \mathbf{B} *inside* the outer core?

[No. Inside the outer core, \mathbf{B} is not potential. \dot{B}_r , \dot{B}_θ and \dot{B}_ϕ may all be important.]
- Does the *frozen-flux argument* explain the scaling $\tau_{sv} \sim l^{-1}$ observed at the surface?

[No. Magnetic diffusion is important near the CMB.]
- What *mechanisms* lead to the observed scaling $\tau_{sv} \sim l^{-1}$?

[Briefly, balance between $\nabla \times (\mathbf{u} \times \mathbf{B})$ and $\nabla^2 \mathbf{B}$ at the CMB.

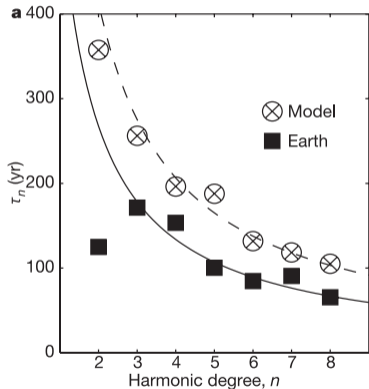
Details depend on the boundary conditions.]

Scaling of $\tau_{SV}(l)$: observations and numerical models

Christensen and Tilgner (2004)

observation data 1840–1990

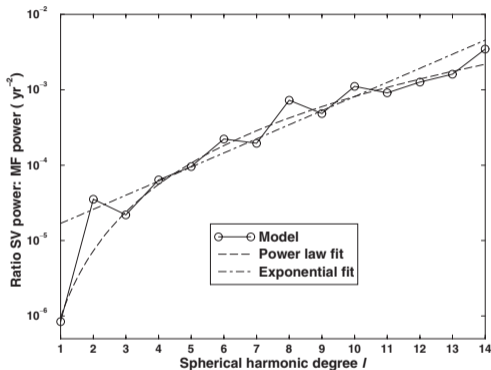
and numerical dynamo models



$$\tau_{SV} \sim l^{-1}$$

Holme and Olsen (2006)

satellite data 1999–2003



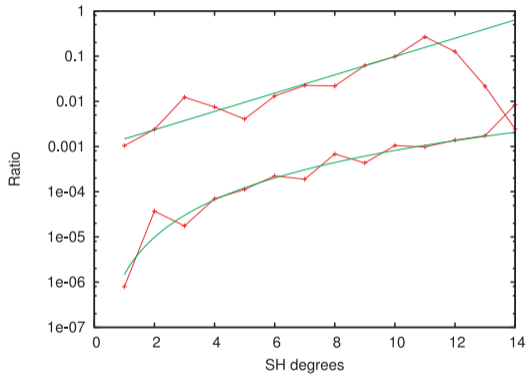
$$\frac{R_{SV}}{R} \sim l^{2.9}$$

$$\Rightarrow \tau_{SV} \sim l^{-1.45}$$

Scaling of $\tau_{\text{sv}}(l)$: observations and numerical models

Lesur et al. (2008)

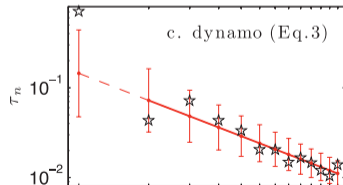
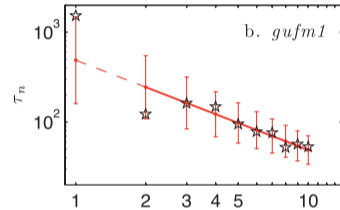
6yr CHAMP + 5yr observatory data



$$\frac{R_{\text{sv}}}{R} \sim l^{2.75}$$
$$\implies \tau_{\text{sv}} \sim l^{-1.38}$$

Lhuillier et al. (2011)

'historical data' 1840–1990, satellite data (2005) and numerical dynamo models



$$\tau_{\text{sv}} \sim l^{-1}$$

The scaling exponent γ

$$\tau_{\text{sv}}(l) \sim l^{-\gamma} \quad (\text{excluding } l = 1)$$

- numerical models: $\gamma = 1$
- observations: mixed results, $1.32 < \gamma < 1.45$ and $\gamma = 1$
- time average vs. snapshot
- **why study τ_{sv}** : infer properties of the magnetohydrodynamics inside the outer core from observations at the surface

We should first ask:

Is τ_{sv} relevant to the time scale of $\dot{\mathbf{B}}$ *inside* the outer core?

Generalisation to inside the dynamo region (outer core)

Recall the definition of the Lowes spectrum $R(l, r, t)$ for $r \geq r_{\text{cmb}}$,

$$\mathbf{B} = -\nabla\Psi, \quad \Psi(r, \theta, \phi, t) = a \sum_{l=1}^{\infty} \sum_{m=0}^l \left(\frac{a}{r}\right)^{l+1} \hat{P}_{lm}(\cos\theta) [g_{lm}(t) \cos m\phi + h_{lm}(t) \sin m\phi]$$

$$\frac{1}{4\pi} \oint |\mathbf{B}(r, \theta, \phi, t)|^2 \sin\theta \, d\theta \, d\phi = \sum_{l=1}^{\infty} R(l, r, t)$$

$$R(l, r, t) = \left(\frac{a}{r}\right)^{2l+4} (l+1) \sum_{m=0}^l [g_{lm}^2(t) + h_{lm}^2(t)]$$

For any r , expand in vector spherical harmonics,

$$\mathbf{B}(r, \theta, \phi, t) = \sum_{lm} [q_{lm}(r, t) \hat{\mathbf{Y}}_{lm}(\theta, \phi) + s_{lm}(r, t) \hat{\mathbf{\Psi}}_{lm}(\theta, \phi) + t_{lm}(r, t) \hat{\mathbf{\Phi}}_{lm}(\theta, \phi)]$$

We define the **magnetic energy spectrum** $F(l, r, t)$ for all r :

$$\sum_{l=1}^{\infty} F(l, r, t) \equiv \frac{1}{4\pi} \oint |\mathbf{B}(r, \theta, \phi, t)|^2 \, d\Omega = \sum_{l=1}^{\infty} \left[\frac{1}{(2l+1)} \sum_{m=0}^l (|q_{lm}|^2 + |s_{lm}|^2 + |t_{lm}|^2) (4 - 3\delta_{m,0}) \right]$$

Generalisation to inside the dynamo region (outer core)

$$F(l, r, t) = \frac{1}{(2l+1)} \sum_{m=0}^l (|q_{lm}|^2 + |s_{lm}|^2 + |t_{lm}|^2)(4 - 3\delta_{m,0})$$

Similarly, define the **time variation spectrum** $F_{\dot{B}}(l, r, t)$:

$$\dot{\mathbf{B}}(r, \theta, \phi, t) = \sum_{lm} [\dot{q}_{lm}(r, t) \hat{\mathbf{Y}}_{lm}(\theta, \phi) + \dot{s}_{lm}(r, t) \hat{\mathbf{\Psi}}_{lm}(\theta, \phi) + \dot{t}_{lm}(r, t) \hat{\mathbf{\Phi}}_{lm}(\theta, \phi)]$$

$$\sum_{l=1}^{\infty} F_{\dot{B}}(l, r, t) \equiv \frac{1}{4\pi} \oint |\dot{\mathbf{B}}(r, \theta, \phi, t)|^2 d\Omega = \sum_{l=1}^{\infty} \left[\frac{1}{(2l+1)} \sum_{m=0}^l (|\dot{q}_{lm}|^2 + |\dot{s}_{lm}|^2 + |\dot{t}_{lm}|^2)(4 - 3\delta_{m,0}) \right]$$

Then, the **magnetic time-scale spectrum** is defined as:

$$\tau(l, r) = \left\langle \sqrt{\frac{F(l, r, t)}{F_{\dot{B}}(l, r, t)}} \right\rangle_t$$

Outside the dynamo region: $F = R$, $F_{\dot{B}} = R_{sv}$, $\tau = \tau_{sv}$

A numerical model of geodynamo

Boussinesq, compositional driven, rotating convection of a electrically conducting fluid:

$$\frac{D\mathbf{u}}{Dt} + 2\frac{Pm}{Ek}\hat{\mathbf{z}} \times \mathbf{u} = -\frac{Pm}{Ek}\nabla\Pi' + \left(\frac{RaPm^2}{Pr}\right)C'\mathbf{r} + \frac{Pm}{Ek}(\nabla \times \mathbf{B}) \times \mathbf{B} + Pm\nabla^2\mathbf{u},$$

$$\frac{\partial\mathbf{B}}{\partial t} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \nabla^2\mathbf{B}$$

$$\frac{DC}{Dt} = \frac{Pm}{Pr}\nabla^2C - 1$$

$$\nabla \cdot \mathbf{u} = 0$$

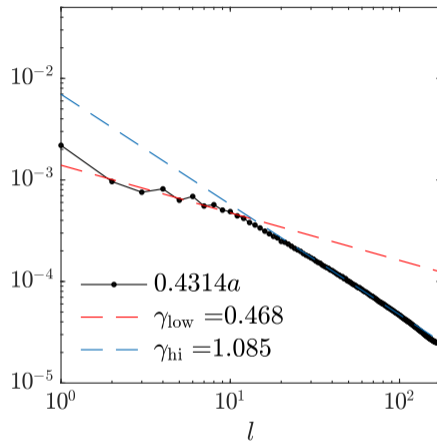
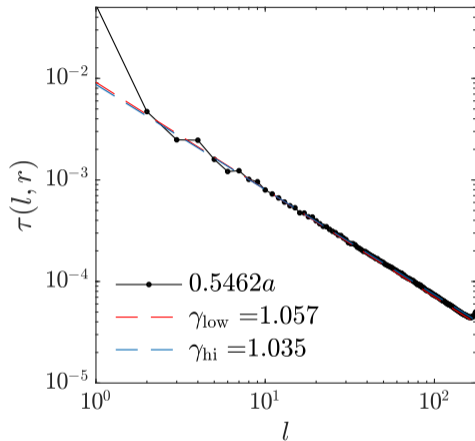
$$\nabla \cdot \mathbf{B} = 0$$

Boundary conditions: **no-slip** for \mathbf{u} , Neumann for C

Domain: a spherical shell $0.1912a \leq r \leq 0.5462a$

$$Ra = 2.7 \times 10^8, Ek = 2.5 \times 10^{-5}, Pm = 2.5, Pr = 1$$

Magnetic time-scale spectrum $\tau(l, r)$ at different depth

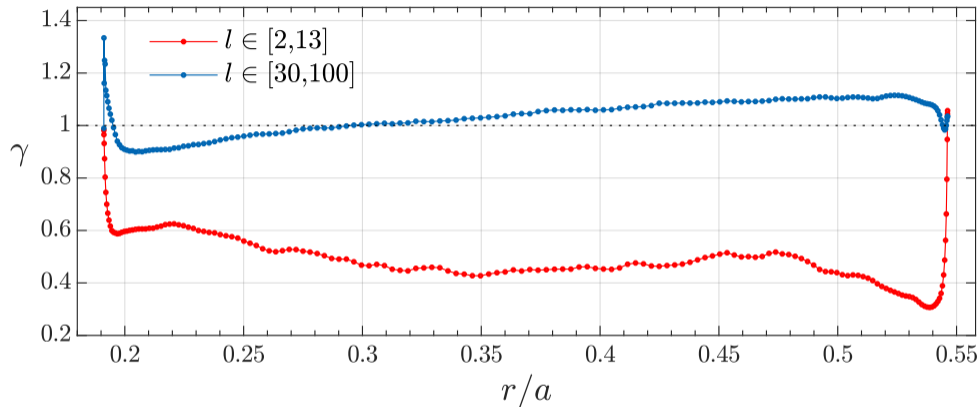


For the **large-scale** modes (small l),

● at the surface: $\tau \sim l^{-1}$

● in the interior: $\tau \sim l^{-0.5}$, *the large-scale modes speeds up in the interior!*

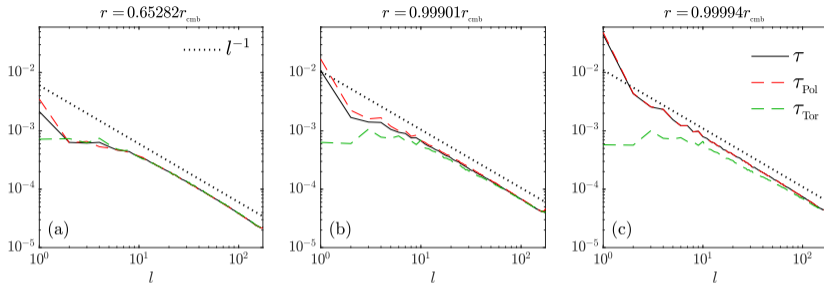
Change in the scaling of τ : where does it occur?



● γ for the large-scale modes increases sharply within a boundary layer under CMB

Focus on the large scales in following discussion ...

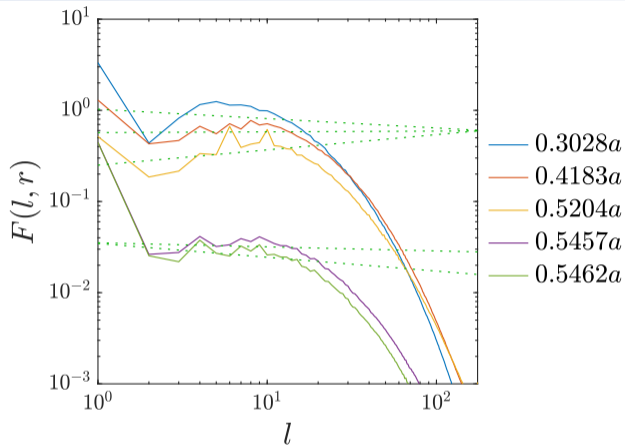
Poloidal and toroidal time scales



$$\mathbf{B} = \mathbf{B}_{\text{Pol}} + \mathbf{B}_{\text{Tor}} , \quad \tau_{\text{Pol}} = \sqrt{\frac{\text{spectrum of } \mathbf{B}_{\text{Pol}}}{\text{spectrum of } \dot{\mathbf{B}}_{\text{Pol}}}} , \quad \tau_{\text{Tor}} = \sqrt{\frac{\text{spectrum of } \mathbf{B}_{\text{Tor}}}{\text{spectrum of } \dot{\mathbf{B}}_{\text{Tor}}}}$$

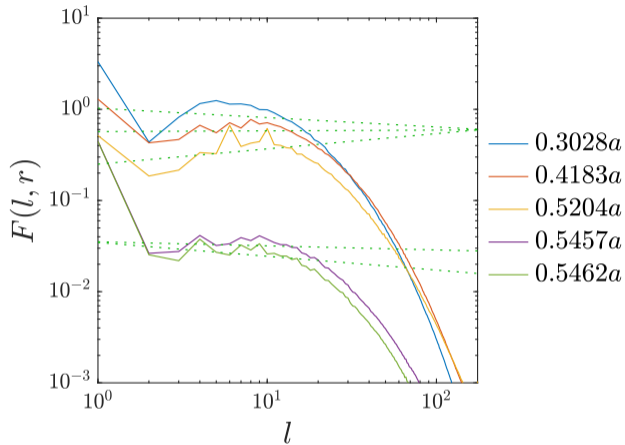
- interior: \mathbf{B}_{Pol} and \mathbf{B}_{Tor} are equally important, $\tau = \tau_{\text{Pol}} = \tau_{\text{Tor}}$ all have the same shape
- CMB: $\mathbf{B}_{\text{Tor}} \rightarrow \mathbf{0}$ due to the magnetic boundary condition, so $\mathbf{B} \approx \mathbf{B}_{\text{Pol}}$
 - τ_{Tor} has the same shape as in the interior but it is irrelevant
 - τ_{Pol} changes shape as $r \rightarrow r_{\text{cmb}}$, $\tau = \tau_{\text{Pol}} \sim l^{-1}$
- contribution of \dot{B}_θ and \dot{B}_ϕ to $\dot{\mathbf{B}}$ in the interior masked by the boundary conditions

Change in the scaling of τ : who causes it?



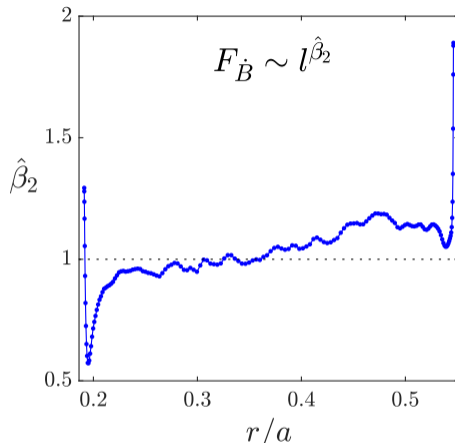
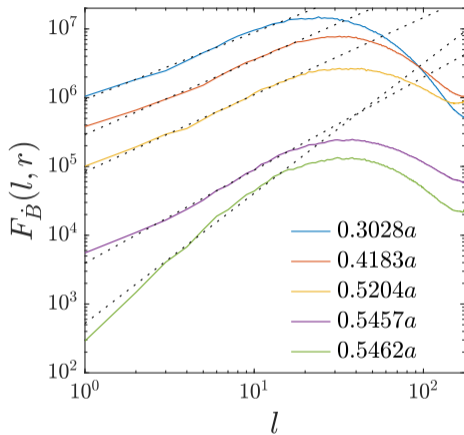
$$\tau \sim \sqrt{\frac{F}{F_{\dot{B}}}}$$

Change in the scaling of τ : who causes it?



$$\tau \sim \sqrt{\frac{F}{F_{\dot{B}}}} \sim \sqrt{\frac{l^0}{F_{\dot{B}}}} \sim F_{\dot{B}}^{-\frac{1}{2}}$$

Change in the scaling of τ : who causes it?

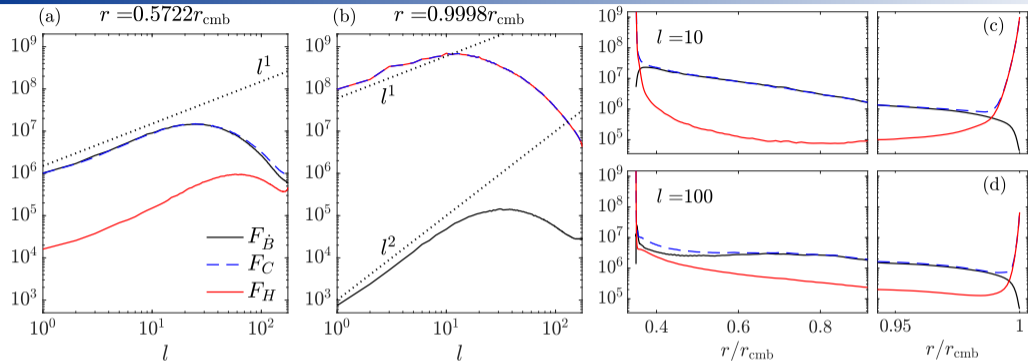


$$\tau \sim \sqrt{\frac{F}{F_{\dot{B}}}} \sim \sqrt{\frac{l^0}{F_{\dot{B}}}} \sim F_{\dot{B}}^{-\frac{1}{2}}$$

$$F_{\dot{B}} \sim l \implies \tau \sim l^{-0.5} \quad (\text{interior})$$

$$F_{\dot{B}} \sim l^2 \implies \tau \sim l^{-1} \quad (\text{surface})$$

Balance of terms (large scales) in the induction equation



$$\dot{\mathbf{B}} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B} = \mathbf{C} + \mathbf{H}$$

- interior: $F_C \sim F_H \sim l$, $F_{\dot{B}} \approx F_C$ (magnetic diffusion negligible), $F_{\dot{B}} \sim l$
- CMB: $F_C \sim F_H \sim l$, $F_C \approx F_H$ (\mathbf{C} and \mathbf{H} cancel to leading order), $F_{\dot{B}} \sim l^2$
- \mathbf{H} is important \Rightarrow frozen-flux argument is not applicable in explaining $\tau \sim l^{-1}$ at CMB

Summary

- scaling of $\tau(l, r)$ with l observed outside the outer core is different from that in the interior
- for the large scales:

$$\tau \sim l^{-0.5}, \quad \text{in the interior}$$

$$\tau \sim l^{-1}, \quad \text{at the CMB}$$

the transition occurs within a boundary layer under the CMB

- time variation of \mathbf{B}_{Tor} in the interior is hidden from surface observation
- for the large scales, $F_{\dot{\mathbf{B}}}$ is responsible for the transition ($\tau = \sqrt{F/F_{\dot{\mathbf{B}}}}$)
 - in the interior, induction term \mathbf{C} dominates, $\dot{\mathbf{B}} \approx \mathbf{C}$ and $F_{\dot{\mathbf{B}}} \sim l$
 - at the CMB (no-slip), balance between the induction term and magnetic diffusion leads to $F_{\dot{\mathbf{B}}} \sim l^2$, meaning frozen-flux argument not applicable