

Overview and future steps

Dust orientation is an ongoing investigation in recent years [1; 2]. Its potential proof will be a paradigm shift for dust remote sensing, invalidating the currently used simplifications of randomly-oriented particles.

Vertically-resolved measurements of dust orientation can be acquired with the new polarization lidar "WALL-E", designed to target the off-diagonal elements of the backscatter matrix which are non-zero only when the particles are oriented [3]. Herein, we present first measurements of WALL-E lidar acquired during the ESA Aeolus Cal/Val Campaign "ASKOS" at Cabo Verde (June and September 2022).

We acquired orientation measurements for rain, as expected, a first test of the capabilities of WALL-E lidar to provide observations of oriented particles in the atmosphere.

The dust particles in the Sahara Air Layer, for the specific cases, show small orientation signals that are within the measurement uncertainty, thus they are considered randomly-oriented.

More measurements are planned in Athens, Greece, for further investigating the phenomenon of possible dust orientation in the atmosphere

REFERENCES

[1] Ulanowski, Z., et al, Atmos. Chem. Phys., 7, 6161–6173, 2007 [2] Mallios, S., et al., J. Aerosol Sci., 151, 2021

[3] Tsekeri, A., et al, Atmos. Meas. Tech., 14, 7453–7474, 2021

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How do we detect oriented particles with a lidar?





DUST ORIENTATION MEASUREMENTS

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WALL-E lidar

WALL-E lidar is designed to monitor particle orientation in the atmosphere [3].

- 2 lasers: linearly- and elliptically-polarized at 1064 nm
- 2 telescopes detecting the backscattered light from both lasers. With suitable optical elements, different polarization states of the backscattered signal are measured
- Products:
- Orientation flags of "yes" or "no" orientation
- Information on dust microphysical properties (*work in progress*)
- Capability of measuring at different viewing angles (zenith and azimuth)

Backscatter matrix of randomly-oriented and oriented particles

- Orientation will result in non-zero values of the off-diagonal elements
- These are the elements we measure with WALL-E lidar
- Specifically, with laser B we acquire the orientation flag

ented			
11	F_{12}	F_{13}	<mark>F₁₄]</mark>
12	F_{22}	F_{23}	F 24
13	$-F_{23}$	F_{33}	<i>F</i> ₃₄
4	<i>F</i> 24	$-F_{34}$	F_{44}

0 0

 $\begin{bmatrix} 0 & F_{44} \end{bmatrix}$

r₃₃

$F_{LB_TA} = \frac{1}{\eta_{TA}} \frac{I_{LB_TA_R}}{I_{LB_TA_R}} = \frac{1 - f_{12} + f_{13} - f_{23} + g_{11}}{1 + f_{12} + f_{13} + f_{23} + g_{11}}$

$F_{LB TA} = 1$ in case of no-oriented particles, whereas for oriented particles $F_{LB TA} \neq 1$



Rain orientation



Established by the European Commission

