

Background & Objectives

- Ensemble Variational methods (EnVar) are appropriate for indirect measurements nonlinearly related to forecast variables.
- A localization method such as observation space localization (OL) is required for highdimensional problems, but how to introduce OL to EnVar has been less investigated.
- In this study, we introduce two types of OL to the maximum likelihood ensemble filter (MLEF)^[1].

Optimization with OL

Consider local costs at *n*-th iteration; $\int J_i^{(n)} = \frac{1}{2} \mathbf{w}_i^{(n)T} \mathbf{w}_i^{(n)}$ $+ \frac{1}{2} [\mathbf{y} - H(\mathbf{x}^{(n)})]^{\mathrm{T}} \mathbf{R}_{i}^{-1} [\mathbf{y} - H(\mathbf{x}^{(n)})]$ $\int \nabla_{\mathbf{w}} J_i^{(n)} = \mathbf{w}_i^{(n)} - \mathbf{Z}_i^{(n)T} \mathbf{R}_i^{-1/2} [\mathbf{y} - H(\mathbf{x}^{(n)})]$ $\mathbf{\mathbf{X}}_{i}^{(n)} = \mathbf{R}_{i}^{-1/2} [H(\mathbf{x}^{(n)} + \mathbf{X}_{f}) - H(\mathbf{x}^{(n)})]$

w around y_i are required to update $H_i(x)$, which prevents independent analysis. **Global optimization (LMLEFG)** Update $\mathbf{x}^{(n)}$ globally in each iteration^[2].

This is equivalent to optimizing sum of J_i .

Local optimization (LMLEFL) Update $[\mathbf{x}^{(n)}]^j$ by $\mathbf{w}_i^{(n)}$ assuming locally constant weights^[3]. J_i can be optimized independently.

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Observation space localizations for the maximum likelihood ensemble filter *Saori Nakashita¹ and Takeshi Enomoto^{2,3}^{1.} Graduate School of Science, Kyoto University, Japan 2. Disaster Prevention Research Ins 3. Japan Agency for Marine-Earth Science and Technology, Yokohama, Kanagawa, Japan 1. Graduate School of Science, Kyoto University, Japan 2. Disaster Prevention Research Institute, Kyoto University, Japan

Comparison to LETKF Lorenz96^[4] $H(\mathbf{x}) = 0.5\mathbf{x}\{1 + (0.1 | \mathbf{x} |)^{\gamma - 1}\}^{[5]}$ **Averaged RMSE of 50 trials** LETKF LMLEFG LMLEFL #observation=1

LMLEFs outperform LETKF with stronger nonlinearity or less observations. **LETKF** is unstable with strong nonlinearity.

Summary

- Optimization provides more robust and accurate analysis than LETKF.
- Global optimization accelerates spin-up.
- Local optimization is suitable for sparse observations in AGCM.



Attendance: Tuesday, 25 April 14:00–15:45 contact: nakashita@dpac.dpri.kyoto-u.ac.jp