



$$H(X) = - \sum_{x \in \mathcal{X}} p(x) \log_b p(x)$$

$$h(X) = - \int_S f(x) \log_b f(x) dx$$

UNITE

EGU 2023

Supplemental Material

Manuel Álvarez Chaves

SimTech

Junior Research Group for Statistical Model-Data
Integration

25.04.2023



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$$H(X) \quad H(X, Y) \quad D_{KL}(p||q) \quad I(X; Y)$$

(...) establishing of such applications is not a trivial matter of translating words to a new domain, but rather the slow tedious process of hypothesis and experimental verification.

Shannon (1956)

- Collection of methods to estimate information-theoretic quantities from data.
 - binned frequencies, KDE, kNN.
- Inspired by and reliant on NumPy  and SciPy .
- Simple and easy to use (with some care).



```
[1]: from scipy import stats

dist = stats.norm(loc=0.0, scale=0.6577)
samples = dist.rvs(size=(10_000, 1), random_state=42)
```

```
[2]: from unite_toolbox import knn_estimators

est_h = knn_estimators.calc_knn_entropy(samples)
print(f"Est. H = {est_h:.3f} nats")
print(f"True H = {dist.entropy():.3f} nats")
```

```
Est. H = 1.002 nats
True H = 1.000 nats
```

- Collection of methods to estimate information-theoretic quantities from data.
 - binned frequencies, KDE, kNN.
- Inspired by and reliant on NumPy  and SciPy .
- Simple and easy to use (with some care).

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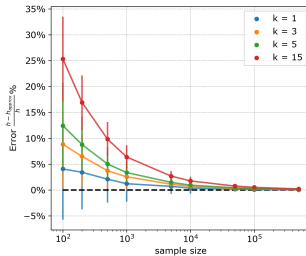
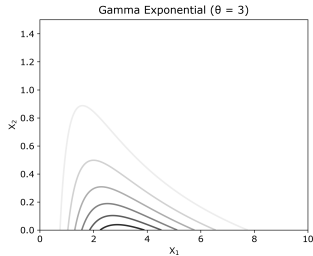
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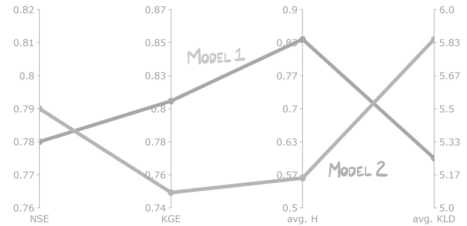
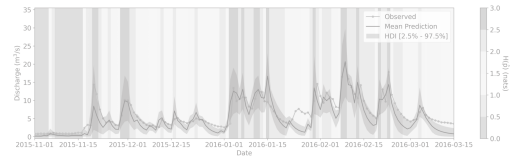
```
Est. H = 1.002 nats
True H = 1.000 nats
```

Estimator Assessment



University of Stuttgart

Applications in Model Evaluation



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Part 2

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The background of the slide is a vertical gradient transitioning from dark purple on the left to bright orange on the right. A large, solid white circle is centered in the upper half of the image. The word "Data" is written in a bold, black, sans-serif font, centered within the white circle.

Data

Attert catchment

Data available from the Catchments as Organized Systems (CAOS) project.

Area = 247.32 km²

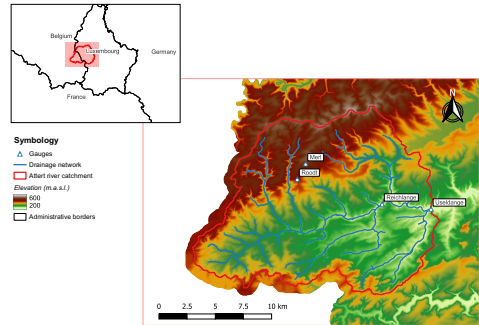
Precipitation inputs from three stations:
Roodt (55%), Reichlange (36%) and
Useldange (9%).¹

Temperature (USL), humidity (USL), wind
speed (ROD), net radiation (MER).

Discharge measured at Useldange

Periods available:

- Training: 01.11.2012 → 31.10.2015
- Testing: 01.11.2015 → 31.10.2016




¹Area averaged precipitation when required.

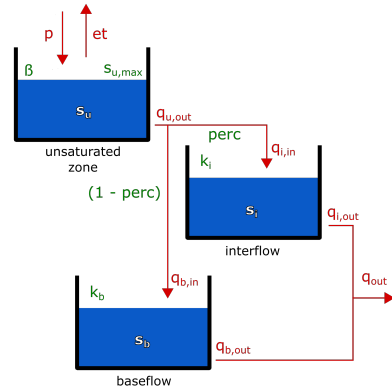
Models

sSHM - (simpler) Simple Hydrological Model

Lumped hydrological model adapted from Ehret et al. (2020).

sSHM was implemented in  PyTorch (Paszke et al., 2019).

Three storage components [s_u , s_i , s_b] and five parameters [$s_{u,max}$, β , $perc$, k_i , k_b].



Optimization

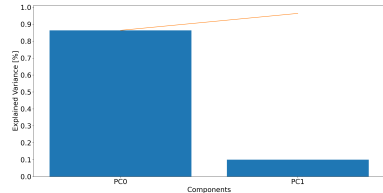
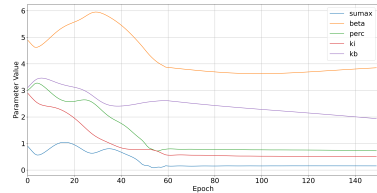
Dimensionality reduction

Principal component analysis (PCA) to reduce from parameter space (5-d) to PCA space (2-d).

Loadings: each PC is given by the linear combination of the original variables:

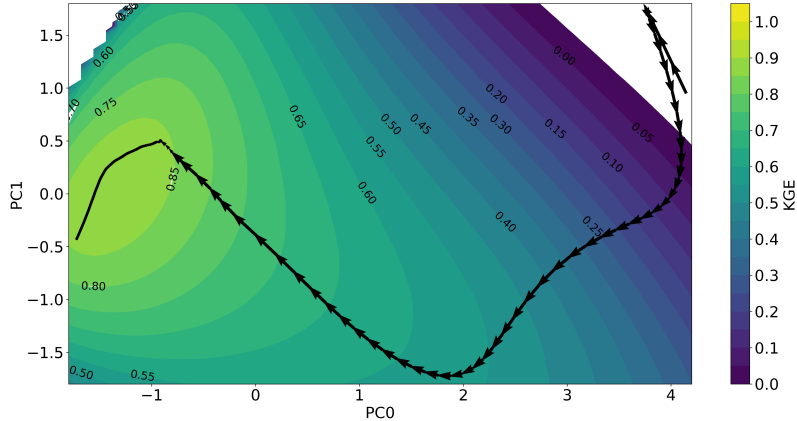
$$PC_1 = w_{11}X_1 + w_{12}X_2 + \dots + w_{1p}X_p$$

Parameter	PC0	PC1
su_{max}	0.459	-0.319
β	0.416	-0.674
$perc$	0.474	0.036
k_i	0.455	0.393
k_b	0.430	0.538

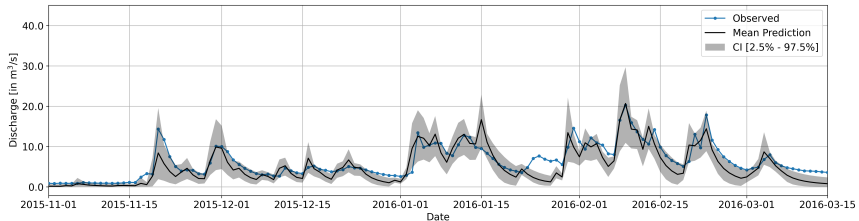


PCA

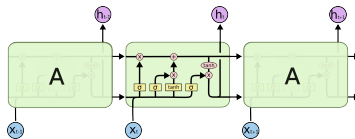
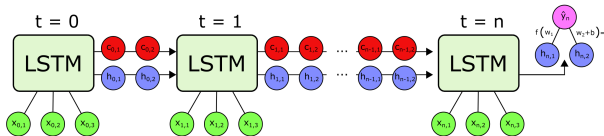
In the training set:



- Equifinality: rejection of an optimal model in favour of multiple possibilities for producing simulations that are acceptable (Beven and Freer, 2001).
- GLUE (generalized likelihood uncertainty estimation) → ABC (approximate Bayesian computation).



- LSTM is a recurrent neural network (RNN) where the cell and hidden states of the network are able to store long time dependencies in the data.
- Monte Carlo dropout for uncertainty (Klotz et al., 2022).
- 64 internal states.



LSTM (cont.)

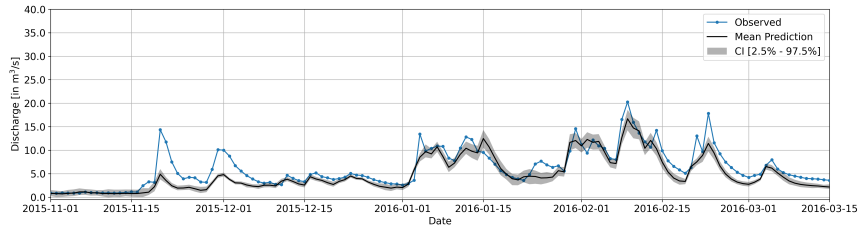


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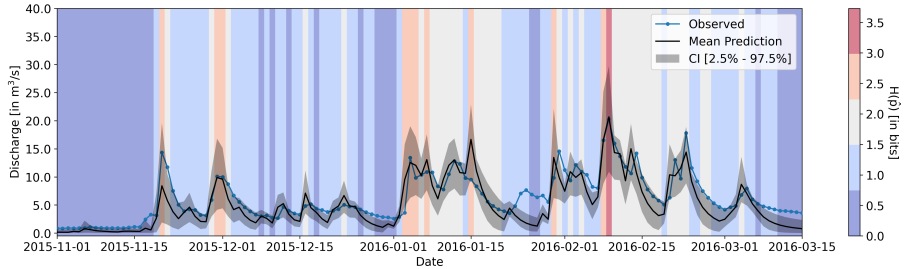
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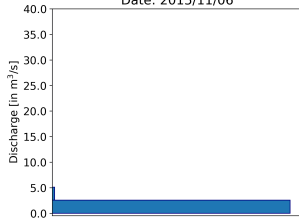
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Evaluation

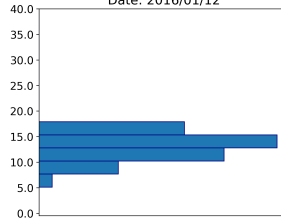
sSHM - Entropy



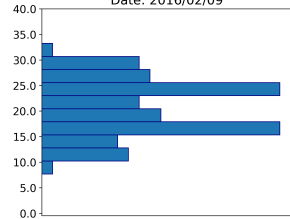
Entropy = 0.08 bits
Date: 2015/11/06

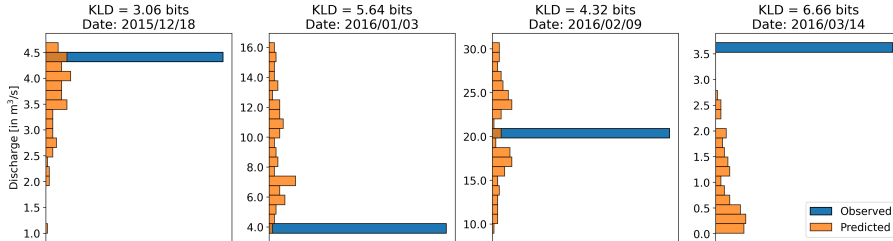
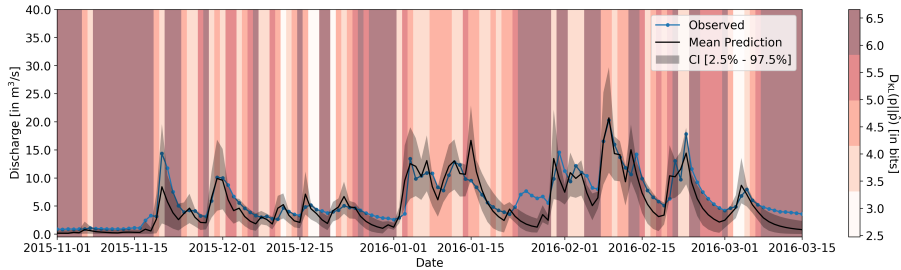


Entropy = 2.08 bits
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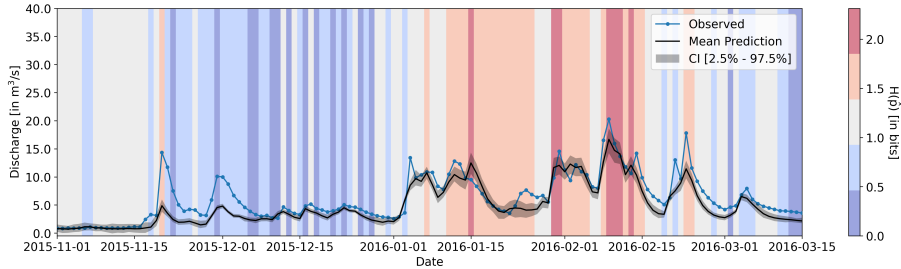


Entropy = 3.06 bits
Date: 2016/02/09

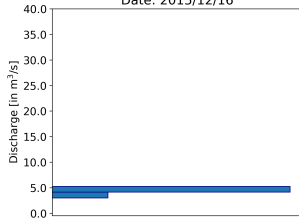




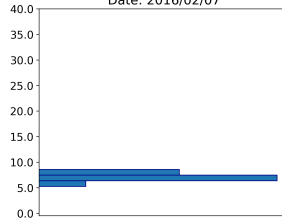
LSTM - Entropy



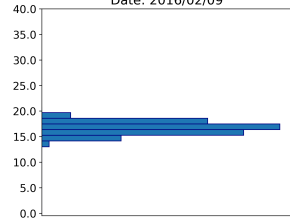
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Date: 2015/12/16



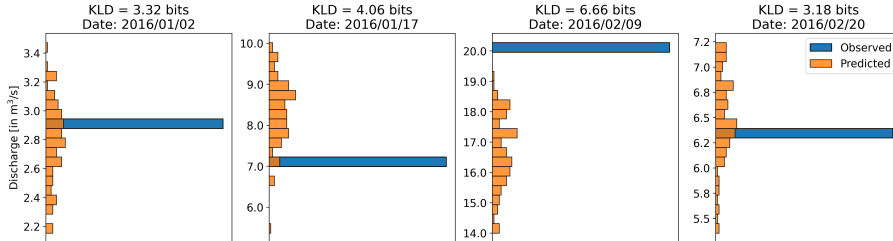
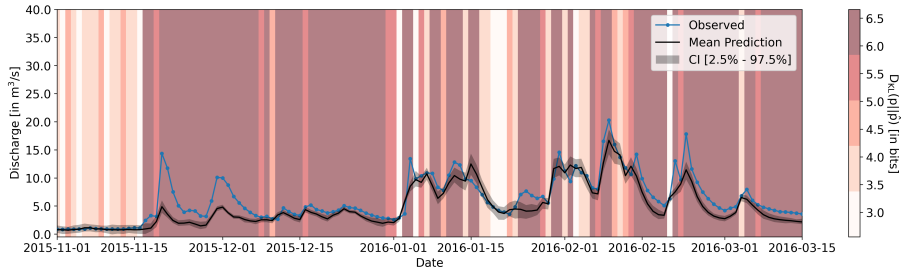
Entropy = 1.24 bits
Date: 2016/02/07



Entropy = 2.21 bits
Date: 2016/02/09



LSTM - KLD



sSHM

- NSE = 0.78
- KGE = 0.81
- avg. H = 0.84 bits
- avg. KLD = 5.24 bits

LSTM

- NSE = 0.79
- KGE = 0.75
- avg. H = 0.57 bits
- avg. KLD = 5.87 bits

Metrics - Summary (cont.)

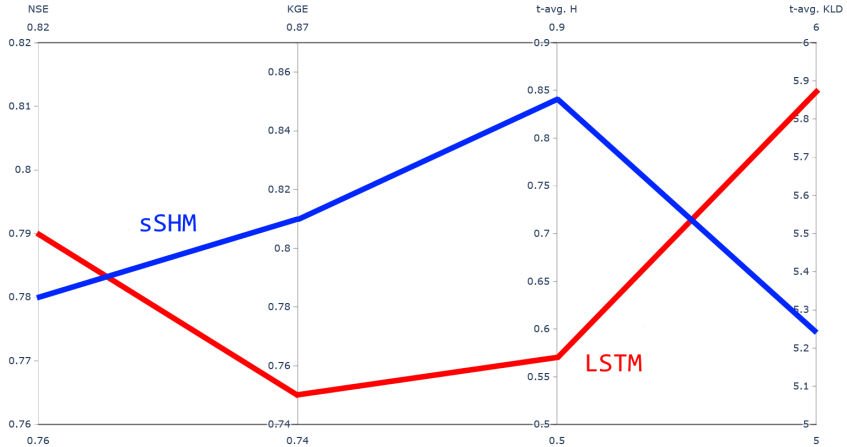


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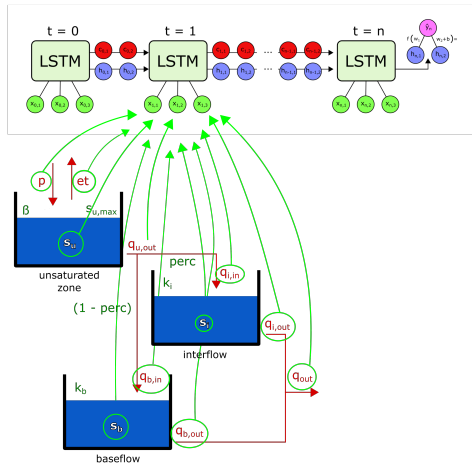
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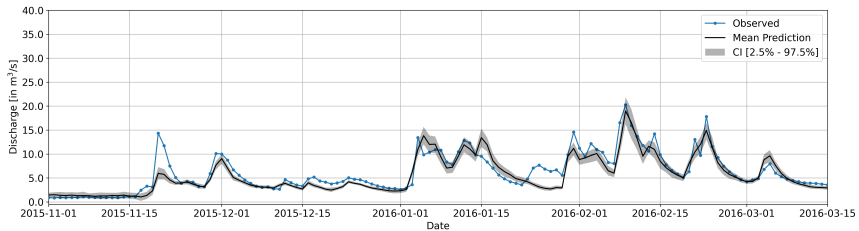
Hybrids

sSHM \rightarrow LSTM

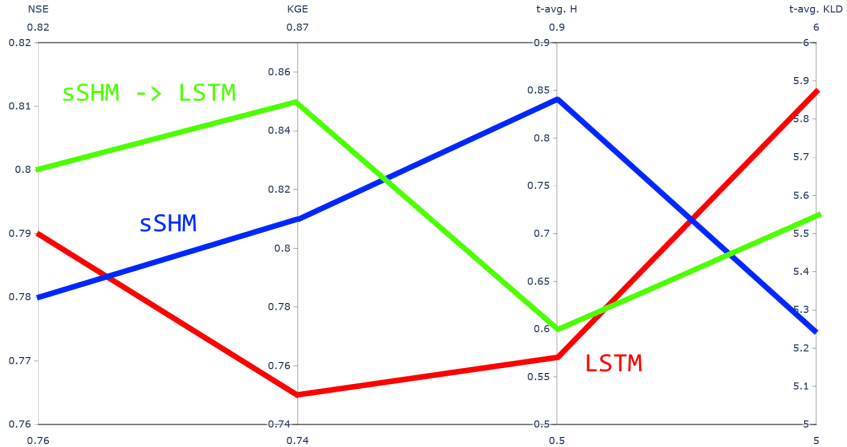
- Concept adapted from Chabok (2022) and Frame et al. (2021).
- Post-processing of the conceptual model to boost performance.



- NSE = 0.80
- KGE = 0.85
- avg. H = 0.60 bits
- avg. KLD = 5.55 bits

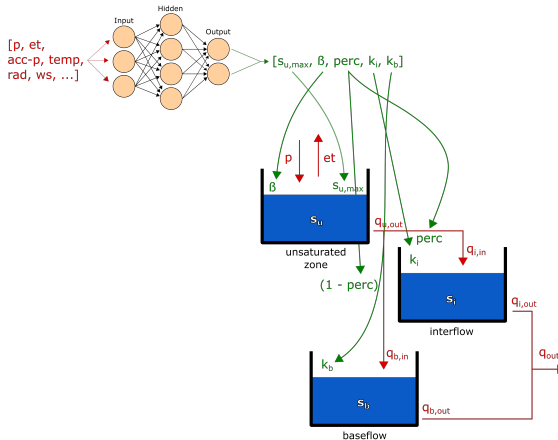


sSHM → LSTM (cont.)

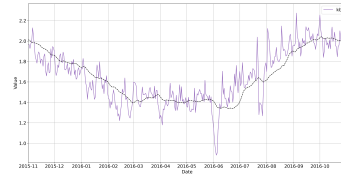
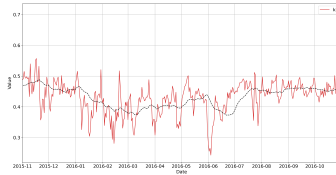
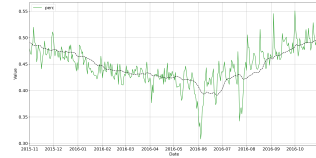
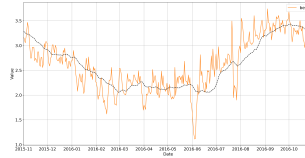
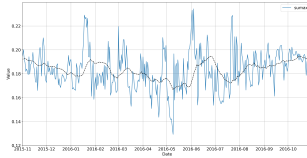


ANN \rightarrow sSHM

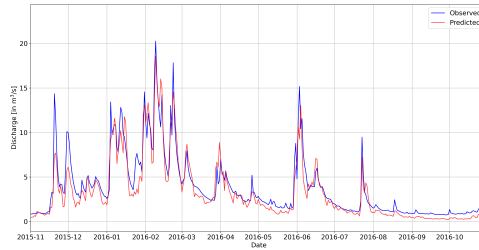
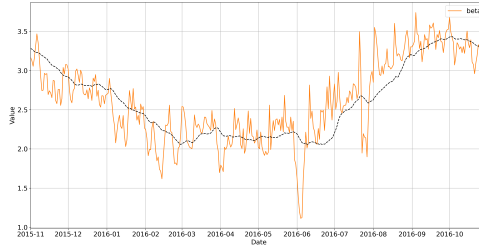
- Predicting sSHM model parameters through a simple artificial neural network (ANN).
- Dynamic model.



ANN \rightarrow sSHM (cont.)



ANN \rightarrow sSHM (cont.)



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Entropy

$$h(X) = - \int_S f(x) \log(x) dx$$

Entropy as a measure of variability.

Kullback–Leibler Divergence

$$D(f||g) = \int_G f \log \left(\frac{f}{g} \right)$$

KLD as a measure of the predictive capacity.

Mutual Information

$$I(X; Y) = H(Y) - H(Y|X)$$

Reduction in entropy by conditioning.
Mutual dependence between variables.

$$I(X; Y) = H(X) + H(Y) - H(X, Y)$$

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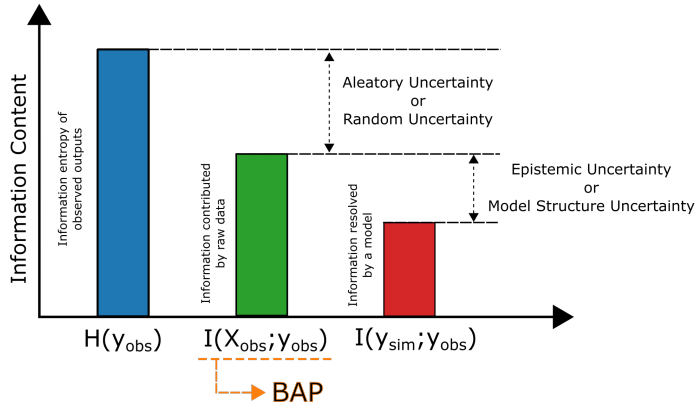
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Framework

- Initial proposal by Gong et al. (2013).
- BAP: best achievable performance.



- $I(x_i; Y)$: relevance of a single input on the target.
- $I(X; Y)$: relevance of a set of input features on the target.
- Estimation of high-dimensional mutual information, from samples, using non-parametric density estimators.
- Plug-in estimators: quantization (binning), kernel density estimates, **k -nearest neighbours**.

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If $p(x)$ is an unknown probability mass function, the k NN density of p at x_i is:

$$\hat{p}_k(x_i) = \frac{k}{n-1} \cdot \frac{1}{c_1(d) \cdot \rho_k^d(i)}$$

Where:

- $c_1(d)$: is the volume of a d -dimensional unit ball.
- $\rho_k^d(i)$: is the distance between x_i and its k^{th} nearest neighbour.

Entropy

$$h(X) = - \int_S f(x) \log(x) dx$$

Kullback–Leibler Divergence

$$D(f||g) = \int_G f \log \left(\frac{f}{g} \right)$$

Mutual Information

$$I(X; Y) = \int_{\mathcal{Y}} \int_{\mathcal{X}} P_{(X,Y)}(x, y) \log \left(\frac{P_{(X,Y)}(x, y)}{P_X(x)P_Y(y)} \right) dx dy$$

kNN Estimators (cont.)

Entropy (Kozachenko and Leonenko, 1987)

$$\hat{H}(X) = \psi(N) - \psi(k) + \log(c_d) + \frac{d}{N} \sum_{i=1}^N \log(\epsilon(i))$$

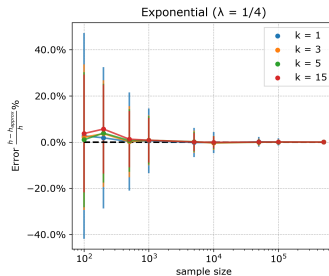
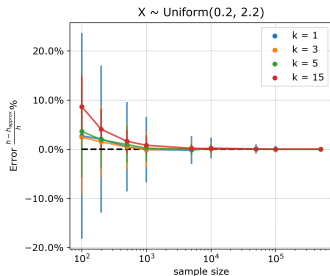
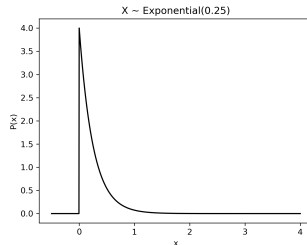
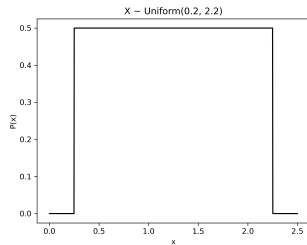
Kullback–Leibler Divergence (Wang et al., 2009)

$$\hat{D}(f||g) = \frac{d}{N} \sum_{i=1}^n \log \left(\frac{\nu(i)}{\rho(i)} \right) + \log \left(\frac{M}{N-1} \right)$$

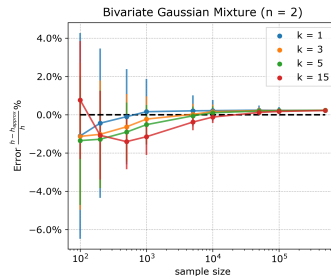
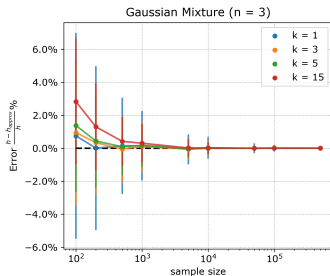
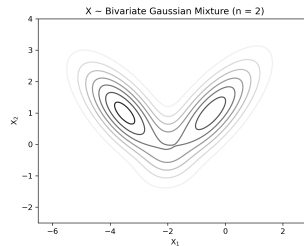
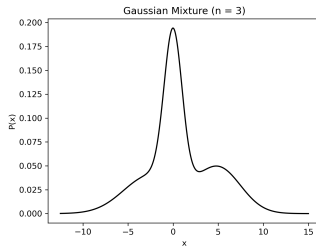
Mutual Information (Kraskov et al., 2004)

$$\hat{l}(X; Y) = \psi(k) - \frac{1}{N} \sum_{i=1}^N \mathbb{E} [\psi(n_{i,x}) + \psi(n_{i,y})] + \psi(N)$$

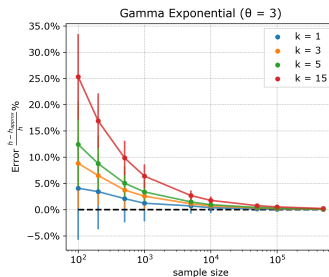
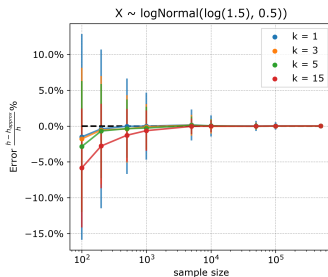
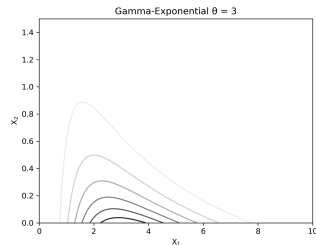
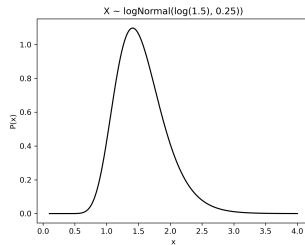
kNN Entropy



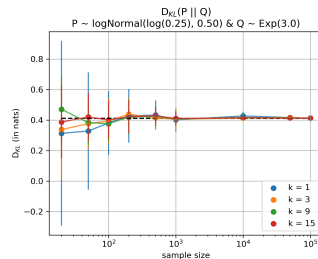
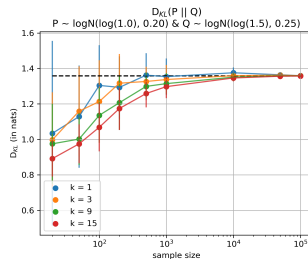
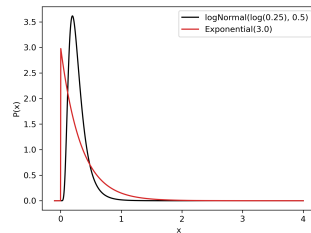
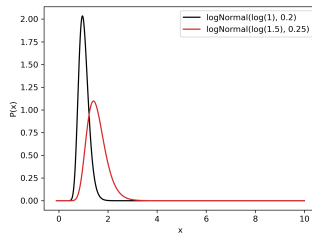
kNN Entropy (cont.)



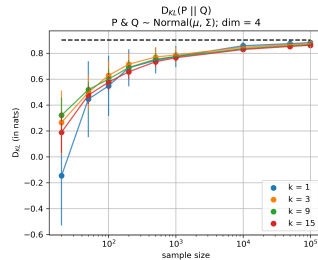
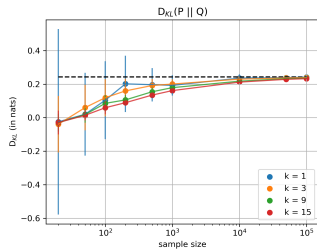
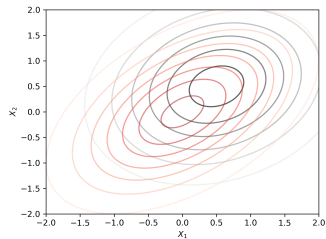
kNN Entropy (cont.)

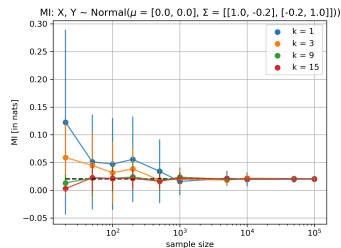
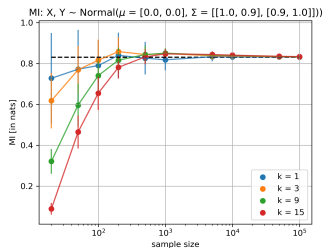
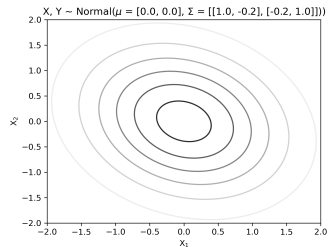
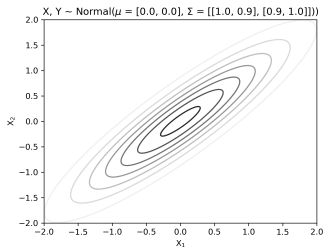


kNN KLD



kNN KLD (cont.)





kNN MI (cont.)

$$I(X_1, X_2 \dots X_{m-1}; X_m) = -\frac{1}{2} \log(1 - \rho^2)$$

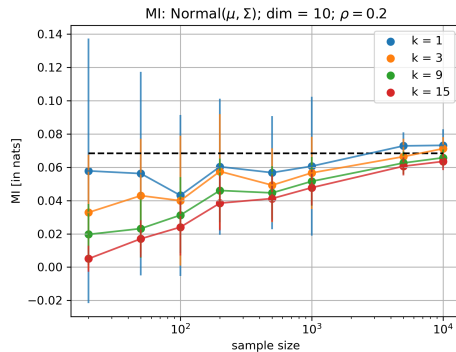
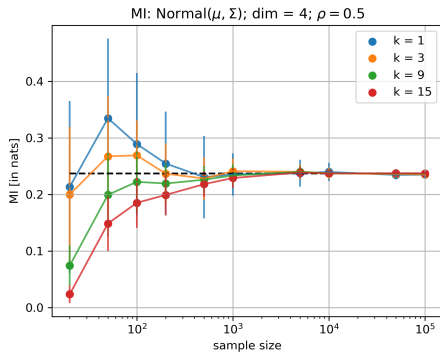


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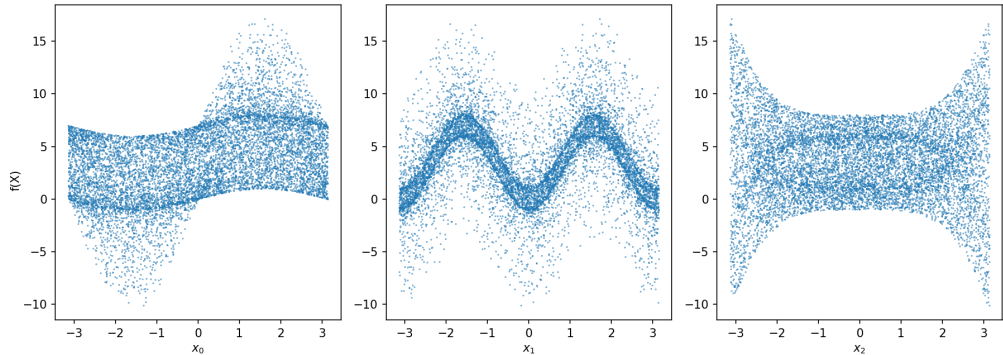
k-Nearest Neighbors

Toy Example: The Ishigami Function

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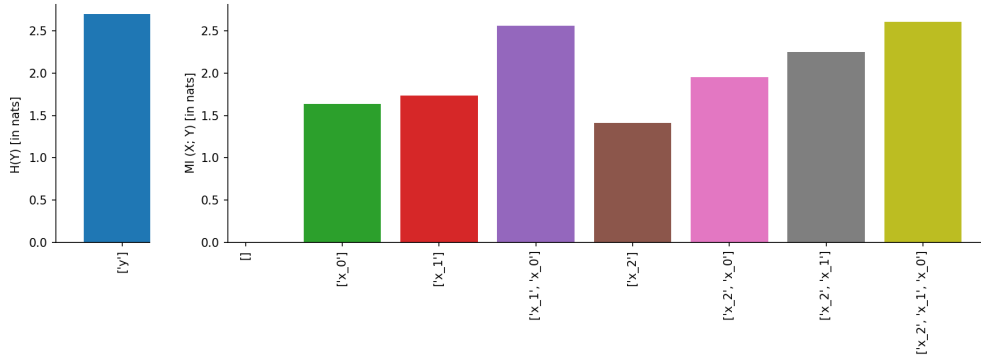
kNN MI → Ishigami Function

$$f(X) = \sin(x_0) + 7 \cdot \sin^2(x_1) + 0.1 \cdot x_2^4 \cdot \sin(x_0)$$

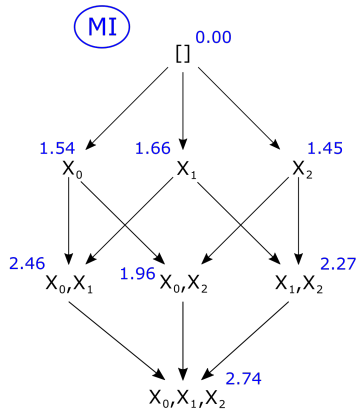


kNN MI → Ishigami Function (cont.)

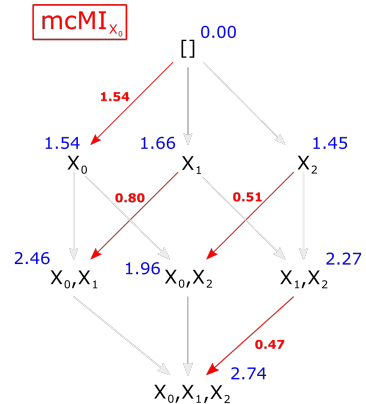
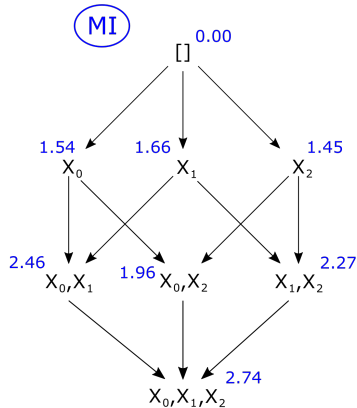
$$f(X) = \sin(x_0) + 7 \cdot \sin^2(x_1) + 0.1 \cdot x_2^4 \cdot \sin(x_0)$$



kNN MI \rightarrow Ishigami Function (cont.)

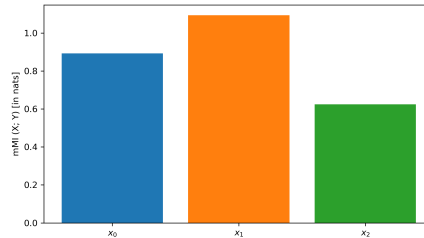
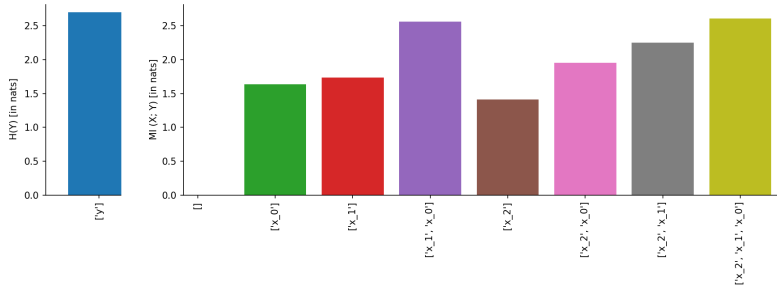


kNN MI → Ishigami Function (cont.)



$$\begin{aligned} \text{mcMI}_{X_0} &= \frac{1}{3} (1.54) + \frac{1}{6} (0.80) + \frac{1}{6} (0.51) + \frac{1}{3} (0.47) \\ &= \mathbf{0.89} \end{aligned}$$

kNN MI → Ishigami Function (cont.)





University of Stuttgart
Germany



Thank you!



Manuel Álvarez Chaves

manuel.alvarez-chaves@simtech.uni-stuttgart.de

+49 711 685-60130

University of Stuttgart

