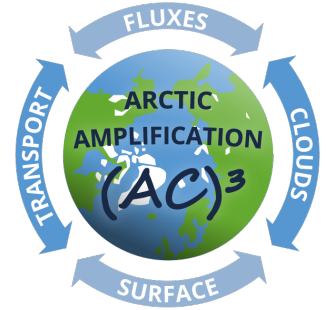




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EGU23-5000:

Airborne observations of riming in arctic mixed-phase clouds during HALO-(AC)³



EGU AS1.10, 25.04.23

Nina Maherndl¹, Maximilian Maahn¹, Manuel Moser^{2,3}, Johannes Lucke³,
Mario Mech⁴, and Nils Risse⁴

¹Leipzig Institute of Meteorology (LIM), University of Leipzig, Germany

²Institute for Physics of the Atmosphere, Johannes Gutenberg-Universität, Mainz, Germany

³Institute for Physics of the Atmosphere, German Aerospace Center (DLR), Wessling, Germany

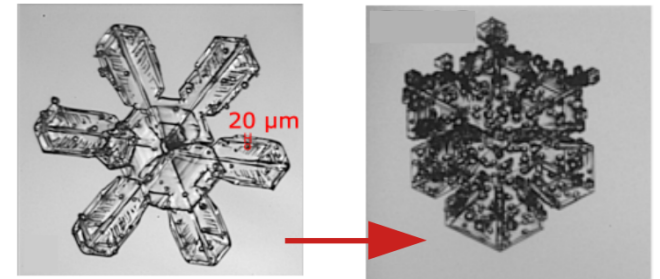
⁴Institute for Geophysics and Meteorology, University of Cologne, Cologne, Germany

abstract & slides



Riming in arctic mixed-phase clouds (MPC)

- Supercooled **liquid** droplets freeze onto **ice** crystals
- Impact on
 - density, shape, mass, fall speed, scattering properties,
...
- Research mainly qualitative



Adapted from Waitz et al. (2022)

Riming in arctic mixed-phase clouds (MPC)

- Supercooled **liquid** droplets freeze onto **ice** crystals
- Impact on
 - density, shape, mass, fall speed, scattering properties, ...
- Research mainly qualitative
- In this study:
 - **Normalized rime mass M** (Seifert et al., 2019)

$$M = \frac{m_{rime}}{m_g}$$

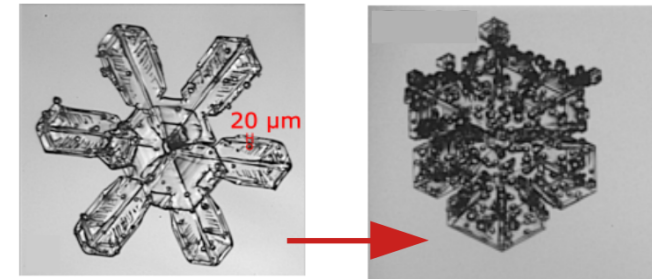
$$m_g = \frac{\pi}{6} \rho_{rime} D_{max}^3$$

D_{max} ... maximum dimension (m)

m_{rime} ... rime mass (kg)

m_g ... mass of D_{max} equivalent graupel (kg)

ρ_{rime} ... rime density (700 kg/m³)



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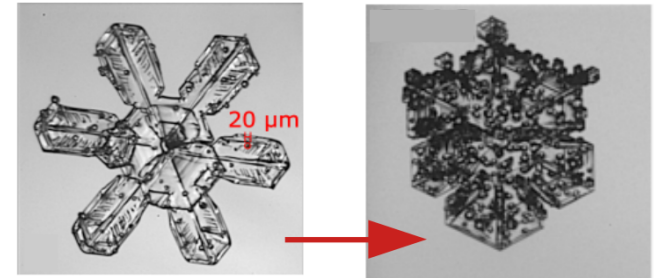
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Adapted from Waitz et al. (2022)

How can we derive M from airborne radar and in situ measurements?

Ice particle properties depend on riming

Normalized rime mass $M = \frac{m_{rime}}{m_g}$

Interlinked with:

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- Mass size relationship $m(D_{max}) = a_m \cdot D_{max}^{b_m}$
- Particle shape
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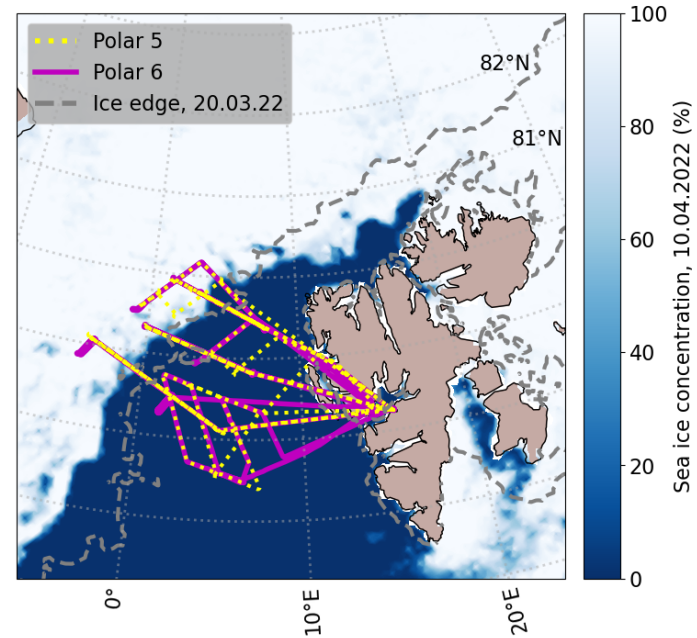
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► Parameterizations based on model calculations (Maherndl et al., 2023a, b)



(Collocated) Flights during HALO-(AC)³

- March / April 2022, Svalbard





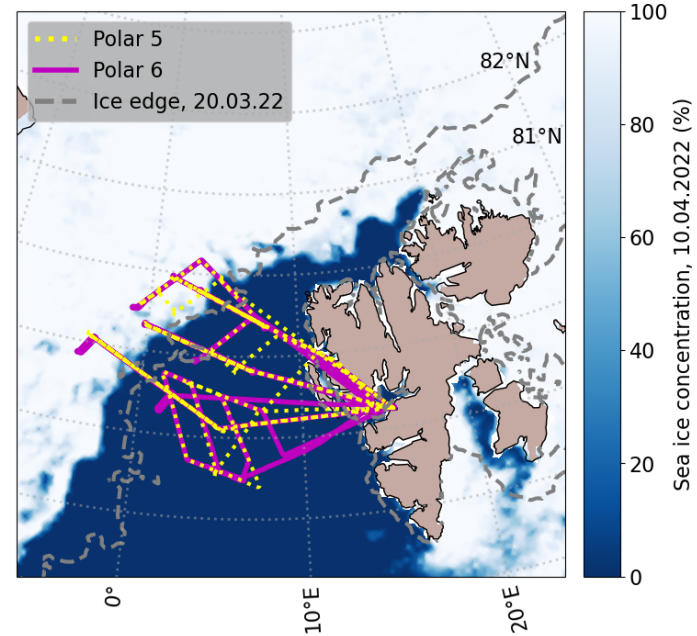
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(a) Polar 5



(b) Polar 6



(Collocated) Flights during HALO-(AC)³

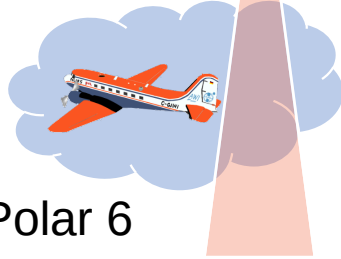
- March / April 2022, Svalbard



Radar



(a) Polar 5



(b) Polar 6

(a) Remote sensing → Polar 5

- 94 GHz FMCW radar
- Property: reflectivity Z_e



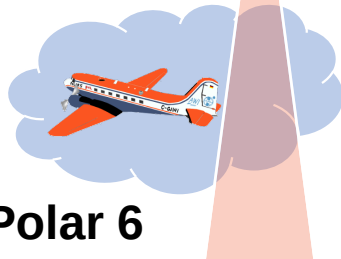
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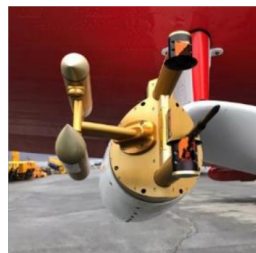


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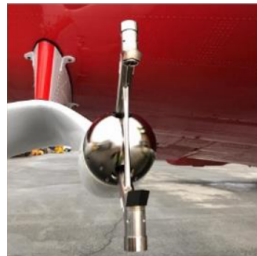


(b) Polar 6

CDP+CIP



PIP



(a) Remote sensing → Polar 5

- 94 GHz FMCW radar
- Property: reflectivity Z_e

(b) Cloud probes → Polar 6

- CDP, CIP, PIP
- Properties:
 - PSD (CDP+CIP+PIP)
 - area, perimeter (CIP+PIP)



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Radar

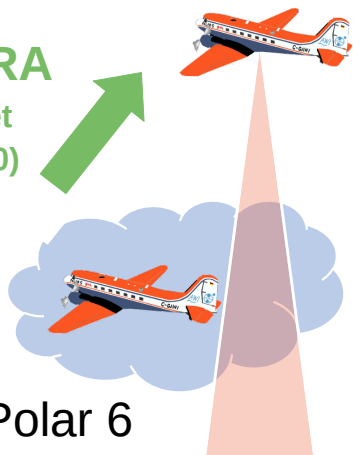


(a) Remote sensing → Polar 5

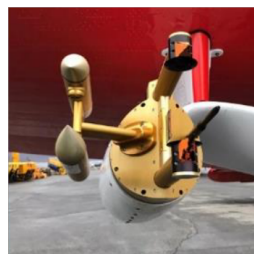
- 94 GHz FMCW radar
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PAMTRA

(Mech et al., 2020)



CDP+CIP



PIP



(b) Cloud probes → Polar 6

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Methods

I. COMBINED RETRIEVAL

II. IN SITU SHAPE

Step 1

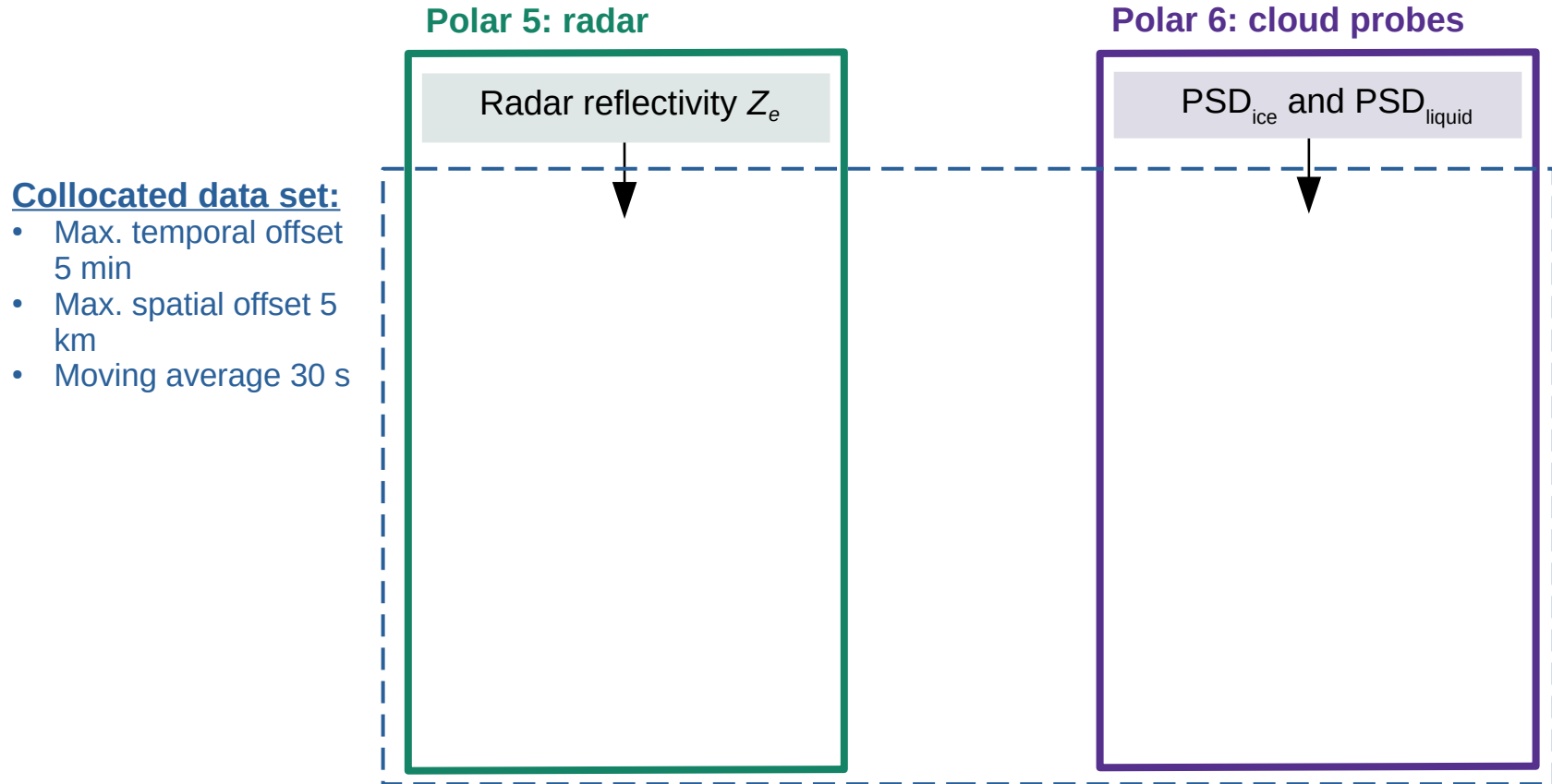
Polar 5: radar

Radar reflectivity Z_e

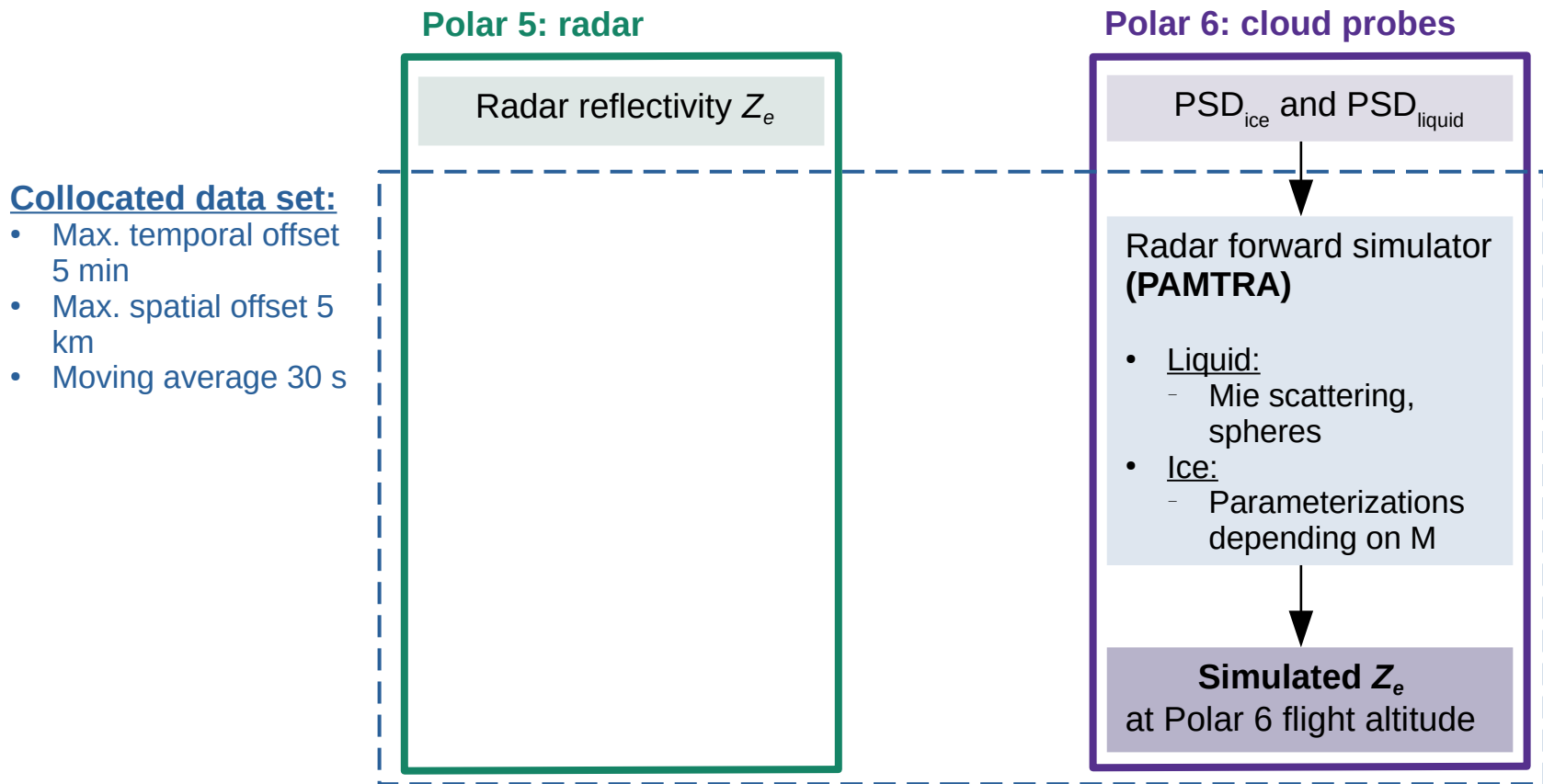
Polar 6: cloud probes

PSD_{ice} and PSD_{liquid}

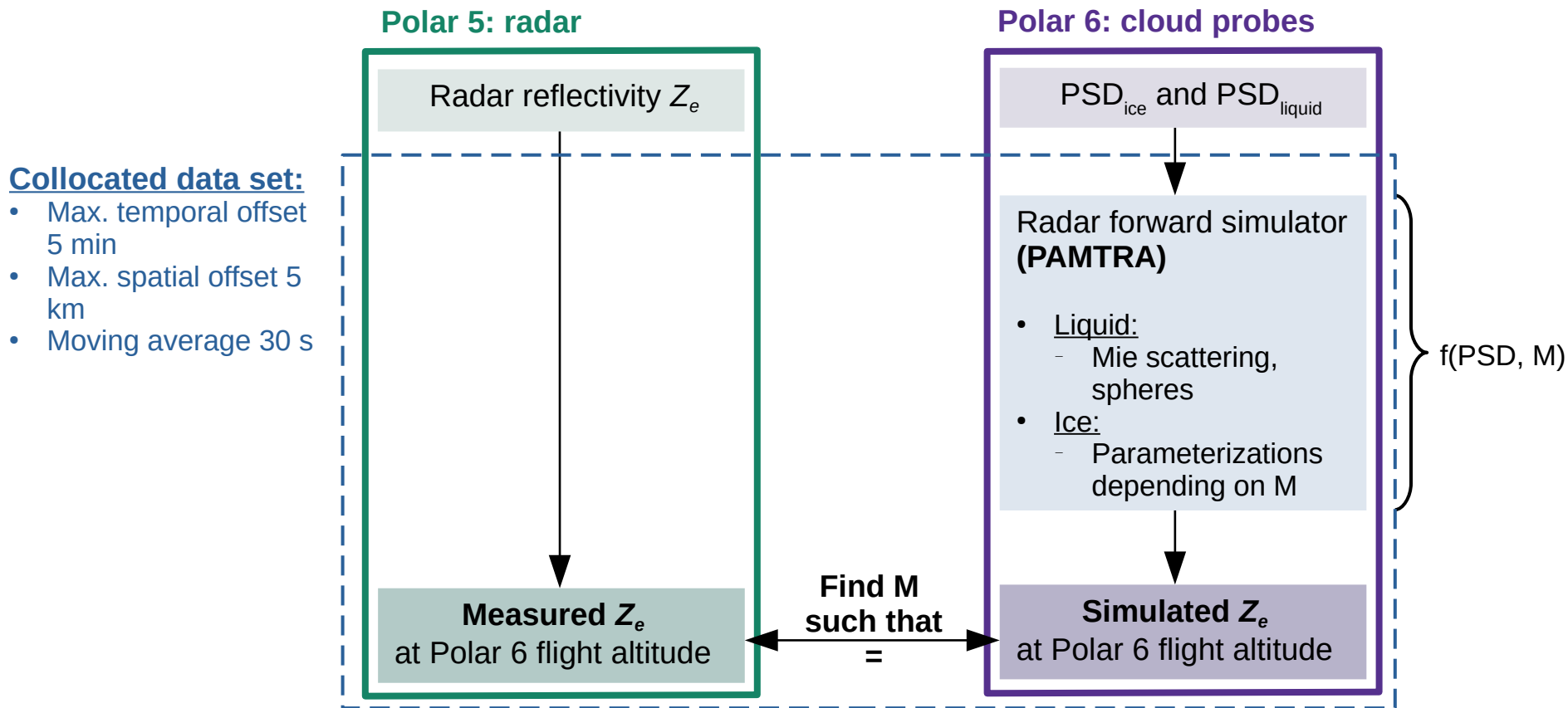
Step 2



Step 3



Step 4



Methods

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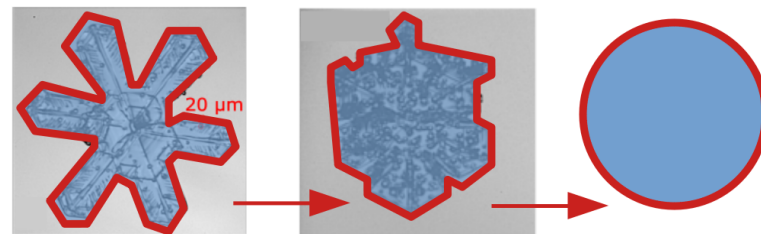
II. IN SITU SHAPE

Particle shape as proxy for riming

- The rounder the more riming
- **Complexity χ** (Garrett and Yuter, 2014)

$$\chi = \frac{P}{2\sqrt{\pi A}}$$

- But: not physical
- And depends on size / resolution of images



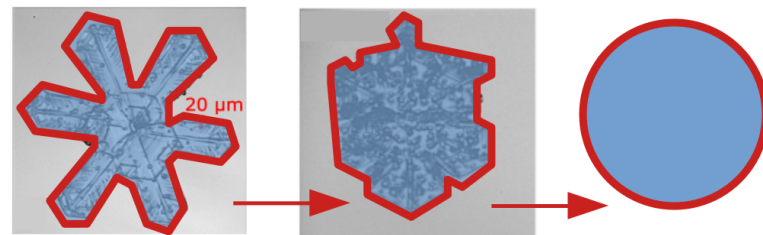
Figures from [Waitz et al., 2021](#)

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Figures from [Waitz et al., 2021](#)

But: method can only applied to particles larger 14 px

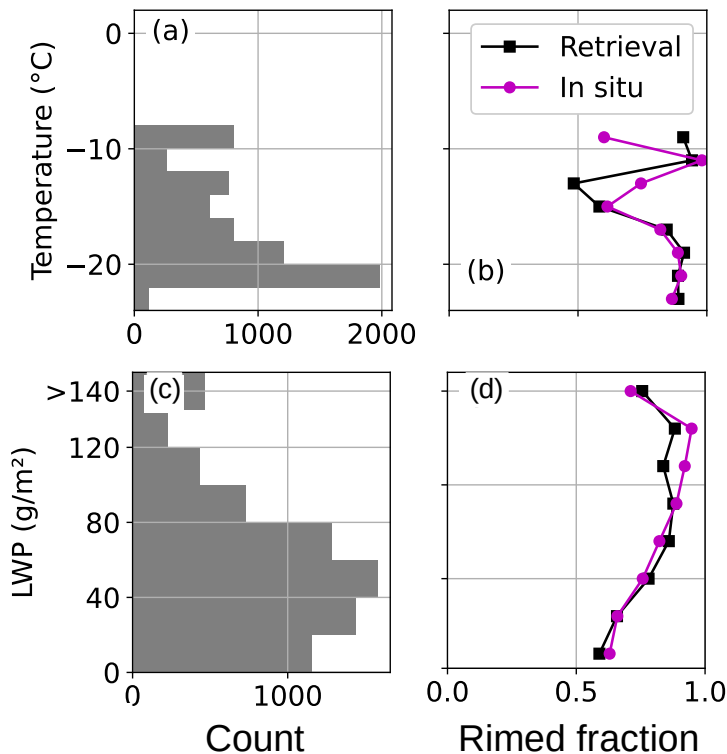
Results

RIMING DURING HALO-(AC)³

Occurance of riming

Only collocated segments

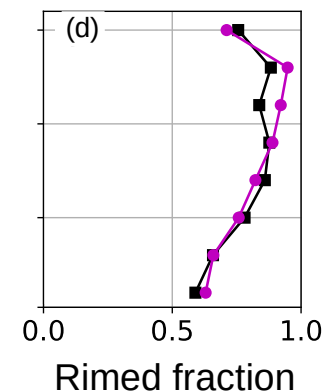
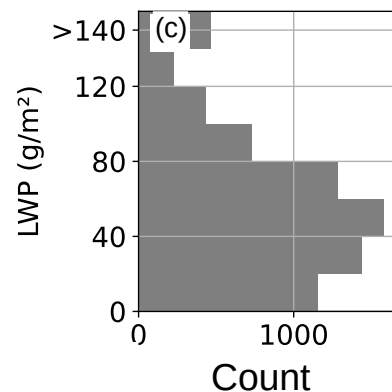
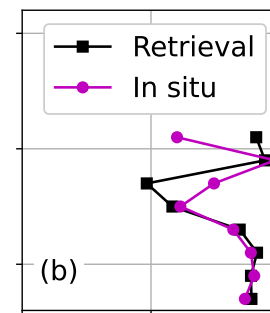
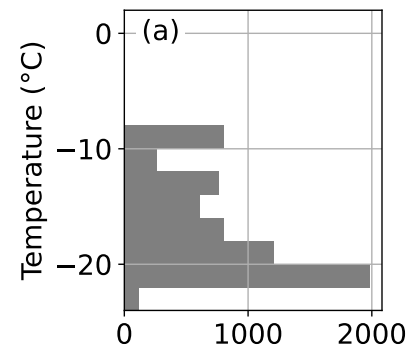
- Rimed fractions ($M \geq 0.01$)
 - **Combined:** 77 %
 - **In situ:** 75 %



Occurance of riming

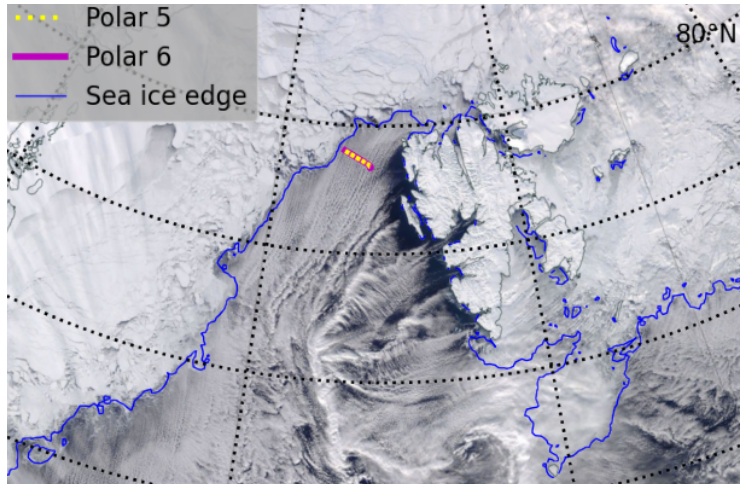
Only collocated segments

- Rimed fractions ($M \geq 0.01$)
 - **Combined:** 77 %
 - **In situ:** 75 %
- Mean
 - **Combined:** 0.027
 - **In situ:** 0.028
- Median [25 %, 75 % quantiles]
 - **Combined:** 0.018 [0.010, 0.032]
 - **In situ:** 0.016 [0.009, 0.028]



Case study

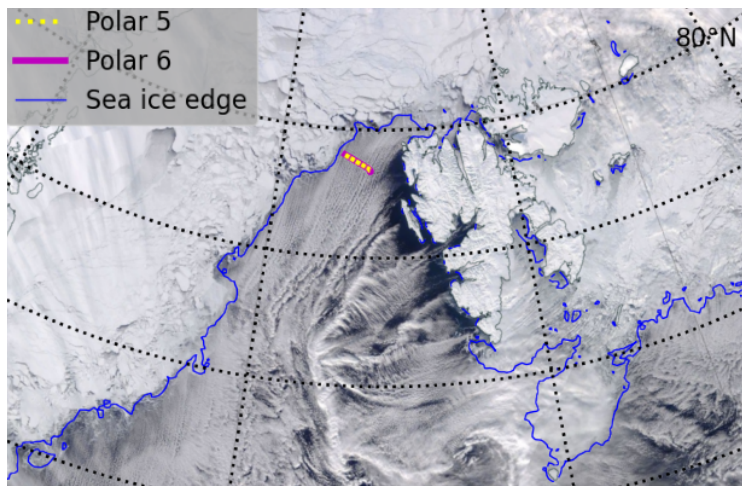
- **01 April ~ 11:25 – 11:35 UTC:**
- Collocated flight segment over open ocean



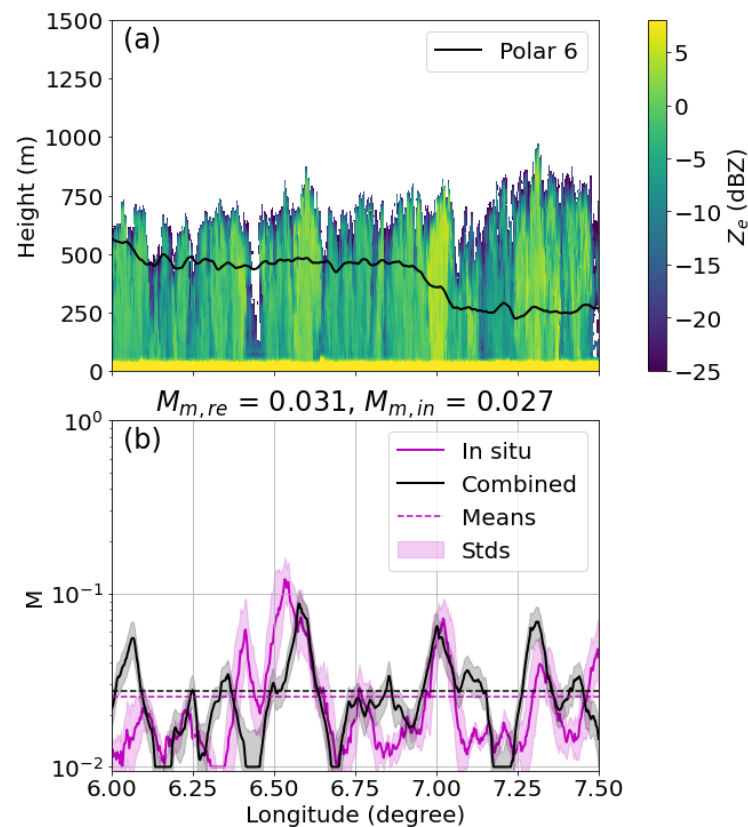
MODIS Terra (NASA worldview)

Case study

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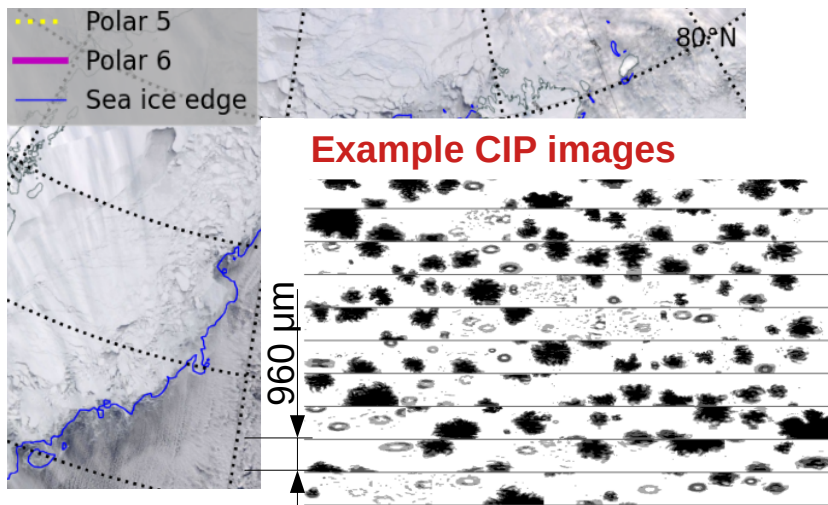


MODIS Terra (NASA worldview)



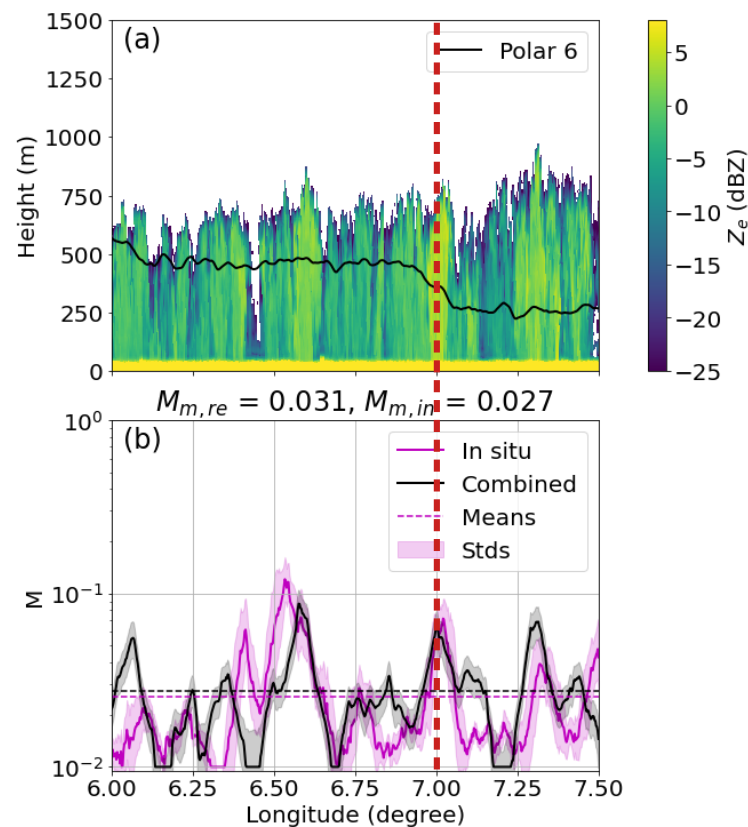
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Example CIP images

MODIS Terra (NASA worldview)



Summary

- Two methods to derive normalized rime mass M :
 - **Combined method** (radar + in situ PSD retrieval)
 - **In situ method** (in situ shape)

Summary

- Two methods to derive normalized rime mass M :
 - **Combined method** (radar + in situ PSD retrieval)
 - **In situ method** (in situ shape)
- Generated large data set of simulated rimed aggregates
 - Parameterizations of physical and scattering properties as function of M
 - **Maherndl et al., 2023a** (QJRMS, in revision)
 - **Maherndl et al., 2023b** (zenodo data set)

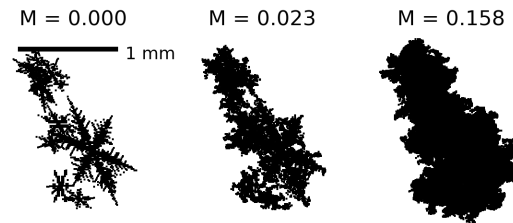


Summary

- Two methods to derive normalized rime mass M :
 - **Combined method** (radar + in situ PSD retrieval)
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Manuscript to be submitted to AMT soon

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THANK YOU

Nina Maherndl

Institute for Meteorology (LIM)

research group **drOPS**

cloud and **p**Recipitation **O**bservations for
Process **S**tudies

Stephanstr. 3, Room EG 9

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Abstract
& slides:



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Appendix

I. PARAMETERIZATIONS

II. IN SITU METHOD

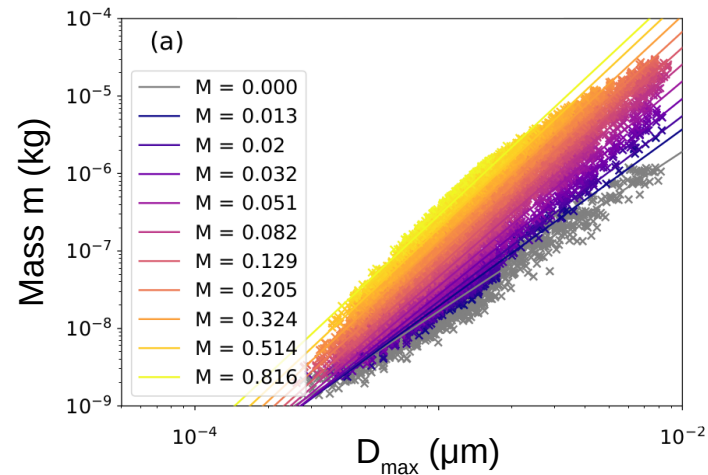
III. COMPARISION

Model calculations



Aggregation and riming model (Leinonen, 2013; Leinonen & Moisseev, 2015; Leinonen & Szyrmer, 2015)

- Monomer crystals
 - From exponential PSD (mean 100 / 200 μm)
 - Resolution 20 μm
- Aggregation followed by riming



snowScatt (Ori et al., 2021)

- Derive SSRGA parameters for modeled snowflakes for different amounts of riming

empirical relations
SSRGA parameter $\Leftrightarrow M$

Results summarized in Maherndl et al. (2023) → in revision (QJRMS)

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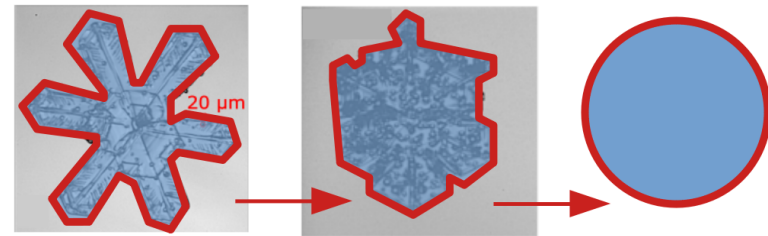
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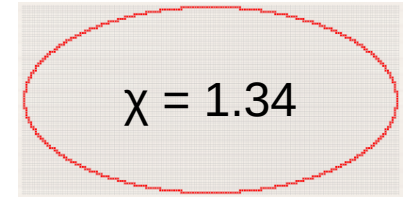
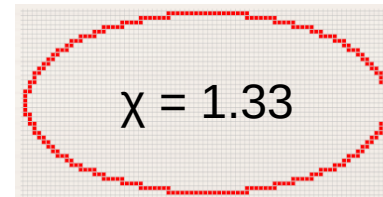
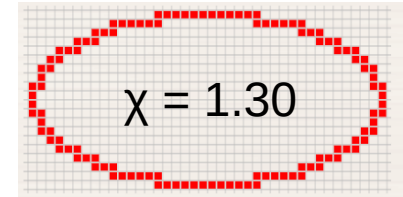
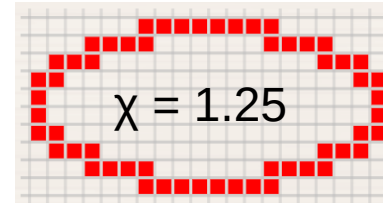
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Figures from Waitz et al., 2021



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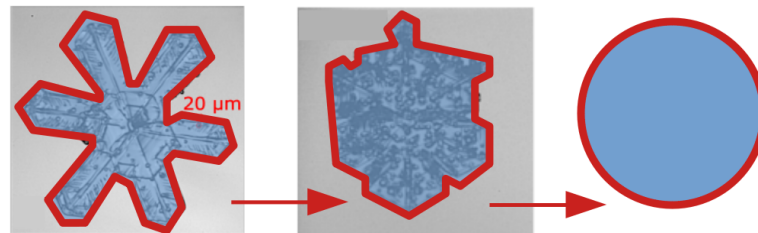
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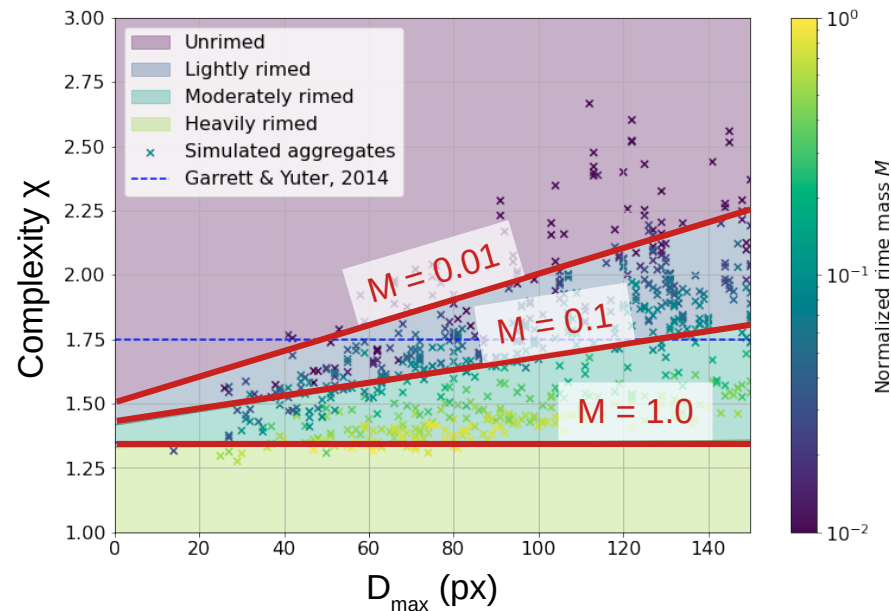
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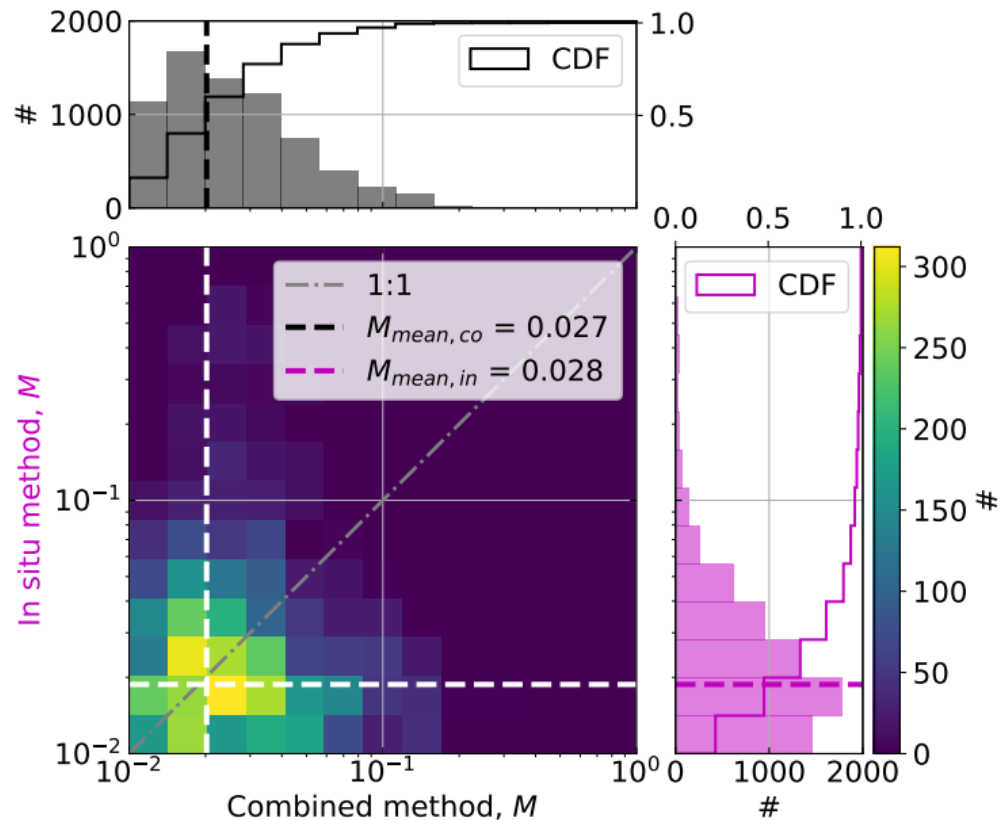
Appendix

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II. IN SITU METHOD
III. COMPARISION

Comparison

Only collocated segments

- 2d histogram
- Individual distributions
- CDF ... cumulative distribution function



Comparison of methods

	Combined method	In situ method
Polar 5 instruments and data	<u>MIRAC:</u> <ul style="list-style-type: none"> Radar reflectivity Z_e 	-
Polar 6 instruments and data	<u>CDP, CIP and PIP:</u> <ul style="list-style-type: none"> Combined PSD 	<u>CIP and PIP:</u> <ul style="list-style-type: none"> Area Perimeter
Particle size range	2 – 6400 μm	210 – 960 μm , 1400 – 6400 μm
Collocation	yes	no
Limitations	In situ measurements need to be representative of radar volume	Needs good statistics >7 particles per second in size range