

Earthquake Magnitude Prediction Using a Machine Learning Model

Neri Berman^{1,2}, Oleg Zlydenko², Oren Gilon², and Yohai Bar-Sinai¹

¹ Tel Aviv University, Physics, Tel Aviv, Israel

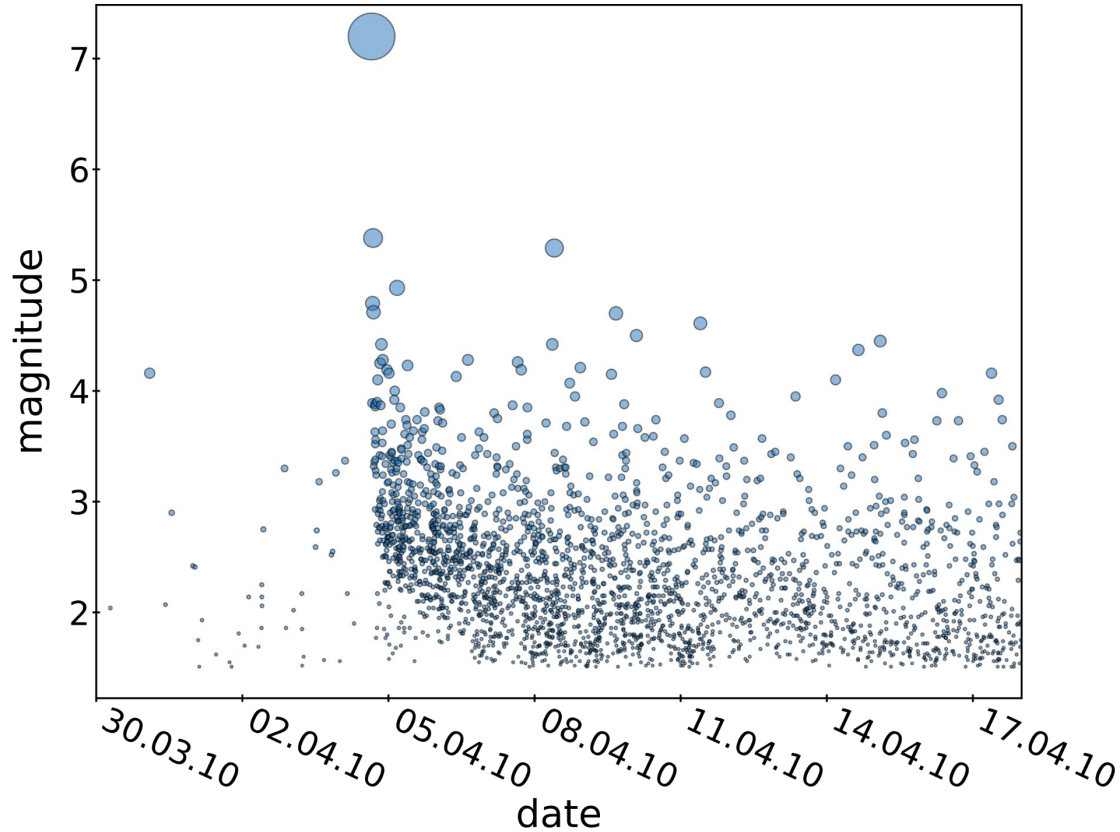
² Google Research, Tel Aviv, Israel



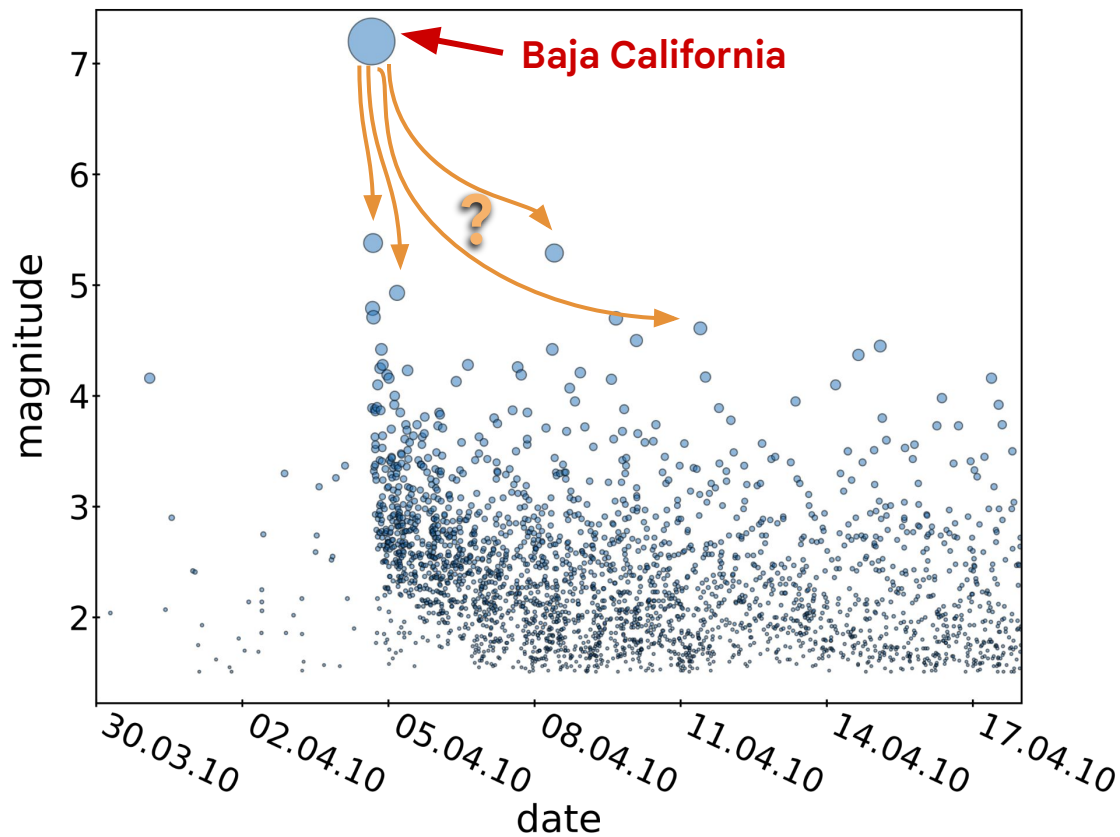
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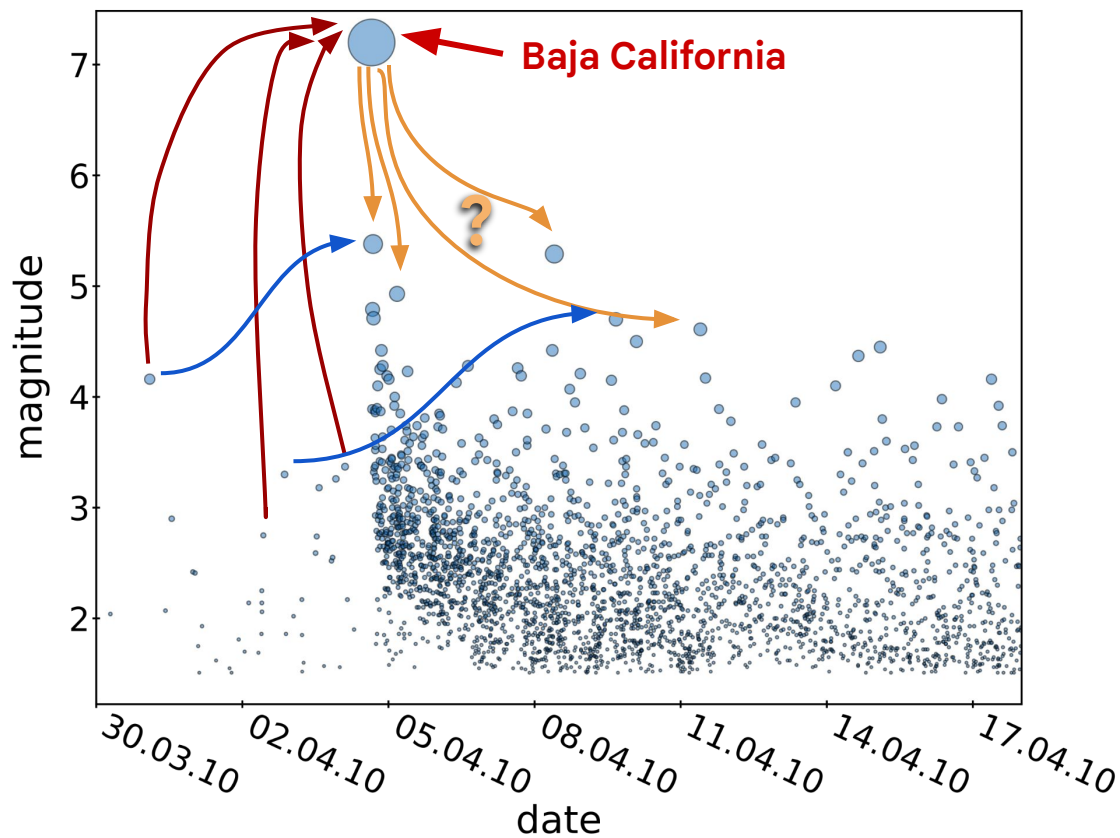
Are earthquake **magnitudes** history dependent?



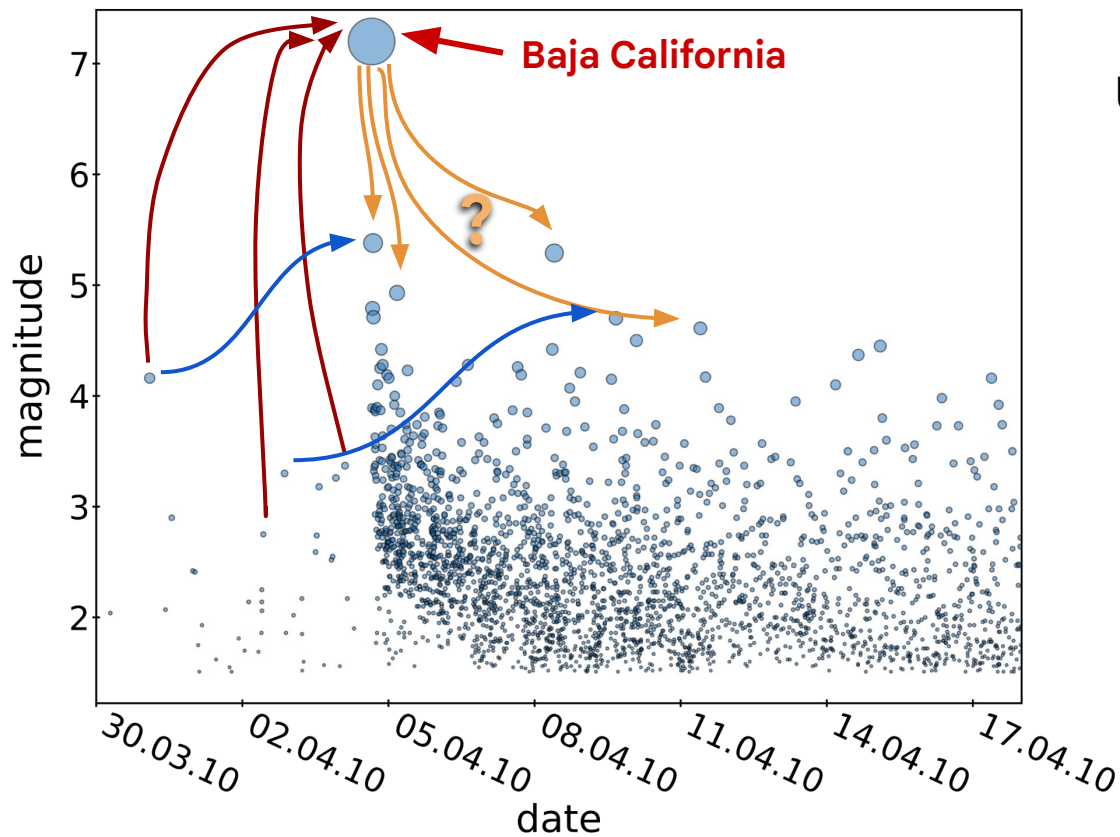
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Under debate...

- Petrillo and Zhuang , 2022
- A. Stallone and W. Marzocchi, 2019
- J. Davidsen et al, 2012
- J. Davidsen and A. Green, 2011
- E. Lippiello et al, 2008
- M. J. Werner and D. Sornette, 2008
- P. Bak and C. Tang, 1989
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- ...

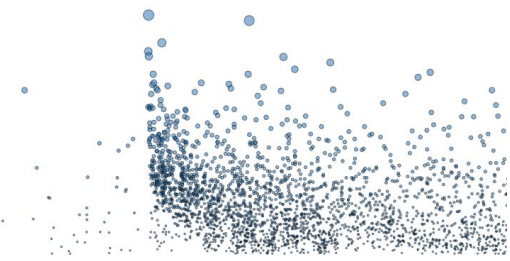
Are earthquake **magnitudes** history dependent?

In practice, It's common to consider magnitudes as independent

As in ETAS

$$\lambda(t, x, y) = \mu(x, y) + \sum_{i:t_i < t} \kappa(m_i) g(t - t_i) f(x - x_i, y - y_i; m_i)$$

● Seismicity rate Background rate Magnitude predictor Temporal dependence Spatial dependence



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Background rate

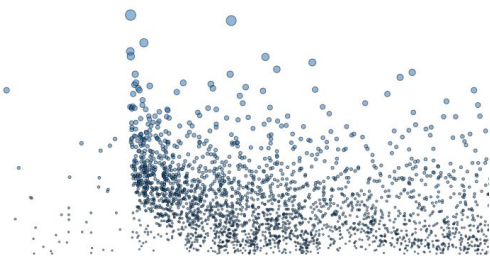
Magnitude predictor

Temporal dependence

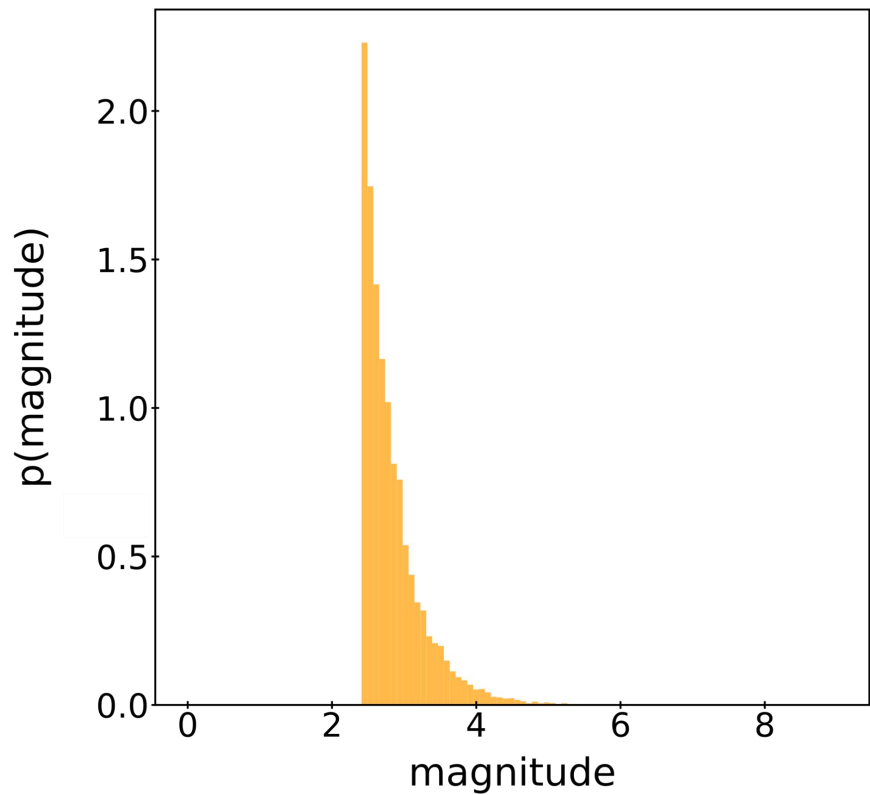
Spatial dependence

→ Independent of time, space and history

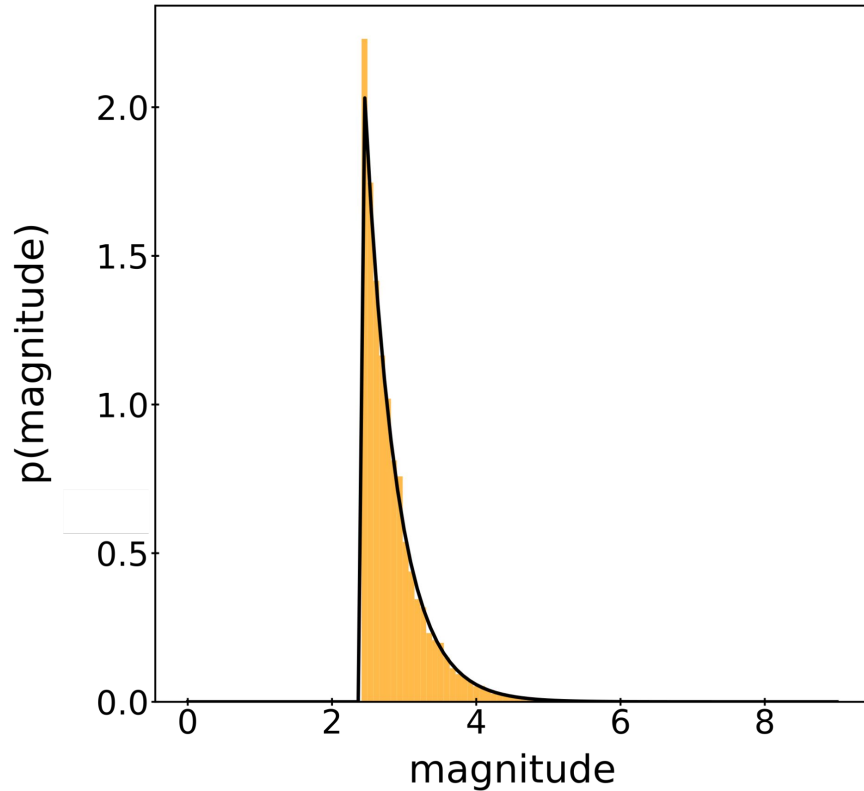
→ **Magnitudes are statistically independent**



$\kappa(m_i)$ - Gutenberg-Richter as a magnitude predictor



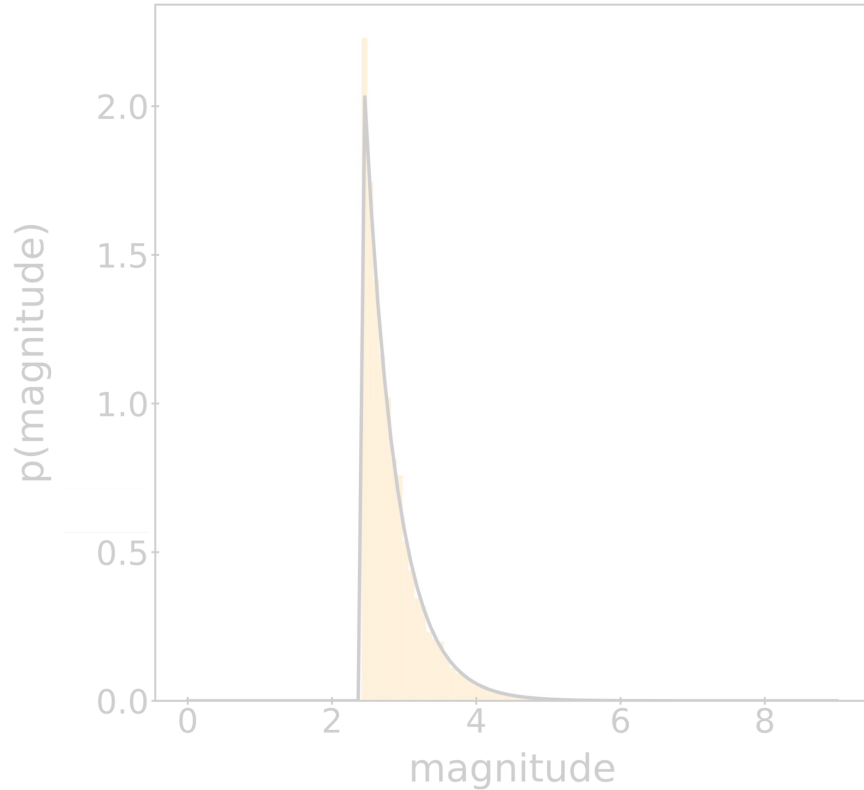
$\kappa(m_i)$ - Gutenberg-Richter as a magnitude predictor



The Gutenberg Richter distribution

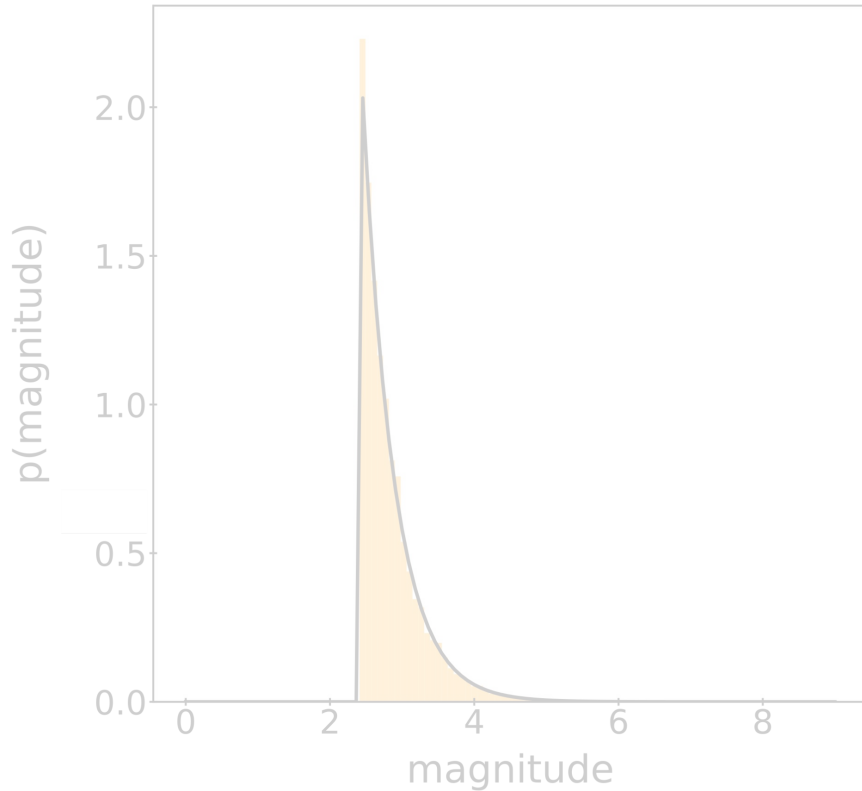
$$\kappa(m) = \beta e^{-\beta(m_c - m)}$$

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Better prediction of magnitudes based on history?

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Better prediction of magnitudes based on history?

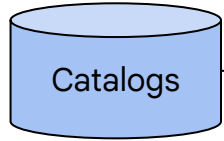
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Replacing with a ML model

$$\tilde{\kappa}_{\vec{x}, t}(m | \text{history prior to } t)$$

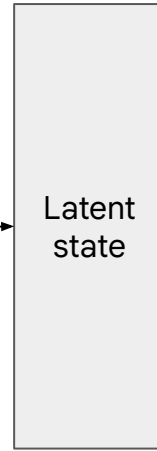
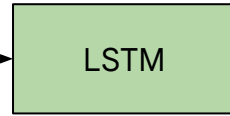
Model architecture

Data source



Data encoding

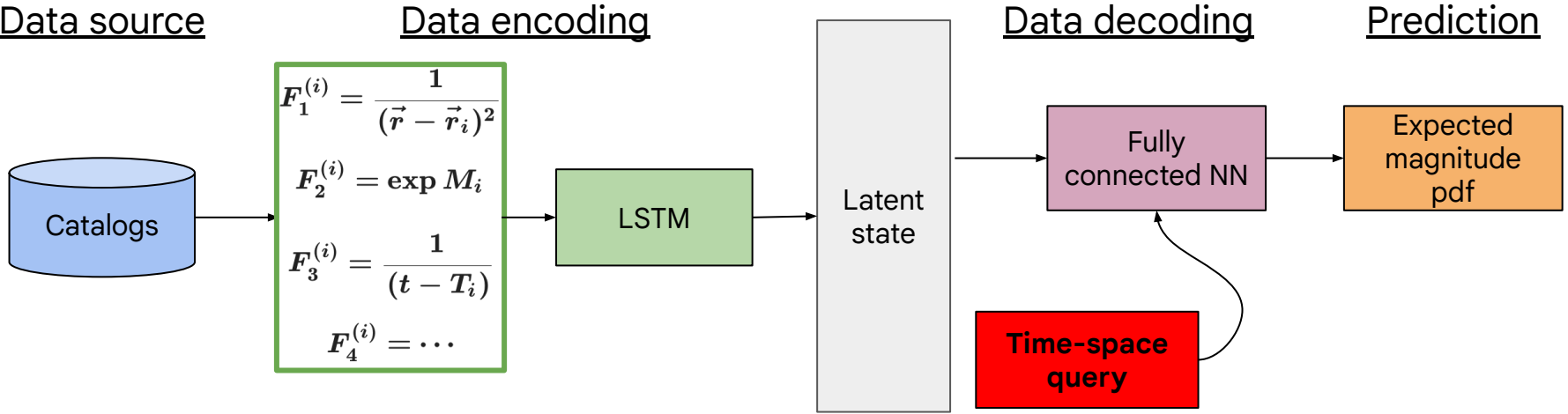
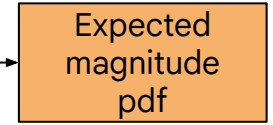
$$F_1^{(i)} = \frac{1}{(\vec{r} - \vec{r}_i)^2}$$
$$F_2^{(i)} = \exp M_i$$
$$F_3^{(i)} = \frac{1}{(t - T_i)}$$
$$F_4^{(i)} = \dots$$



Data decoding



Prediction



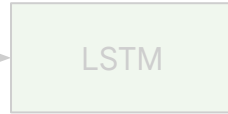
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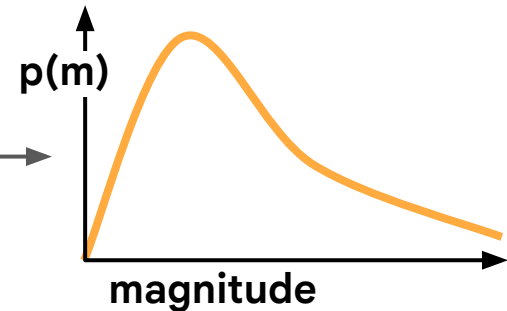
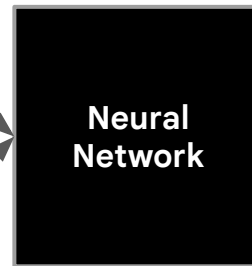
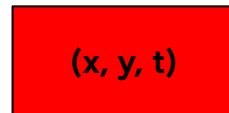
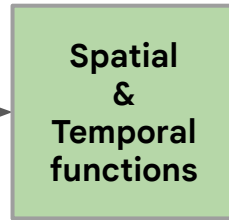
Data decoding



Prediction

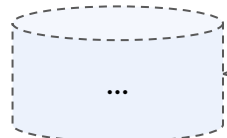
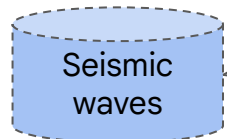
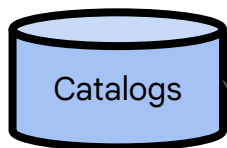


time	x	y	depth	M_w
t_1	x_1	y_1	d_1	m_1
\vdots	\vdots	\vdots	\vdots	\vdots
t_N	x_N	y_N	d_N	m_N

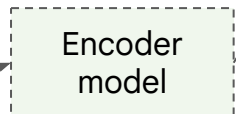
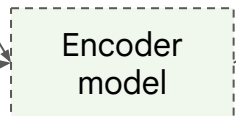
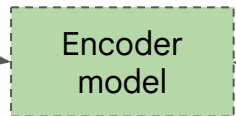
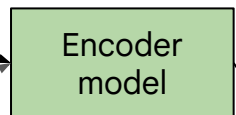


The wider effort

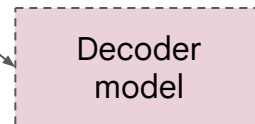
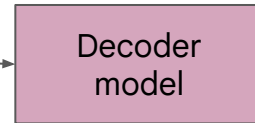
Data sources



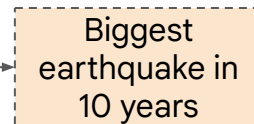
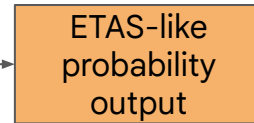
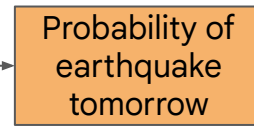
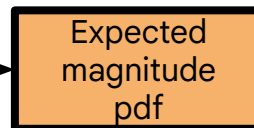
Data encoding



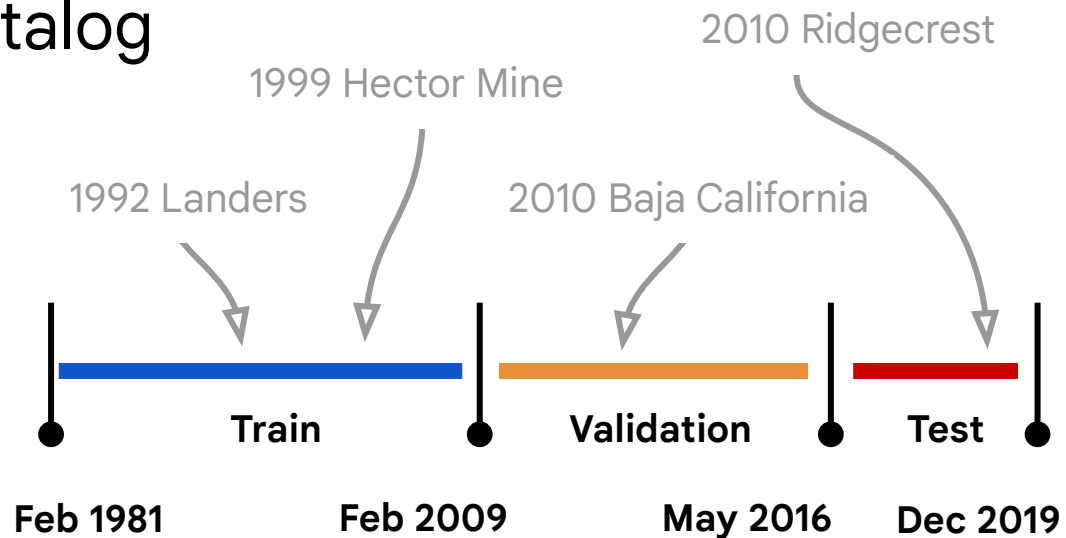
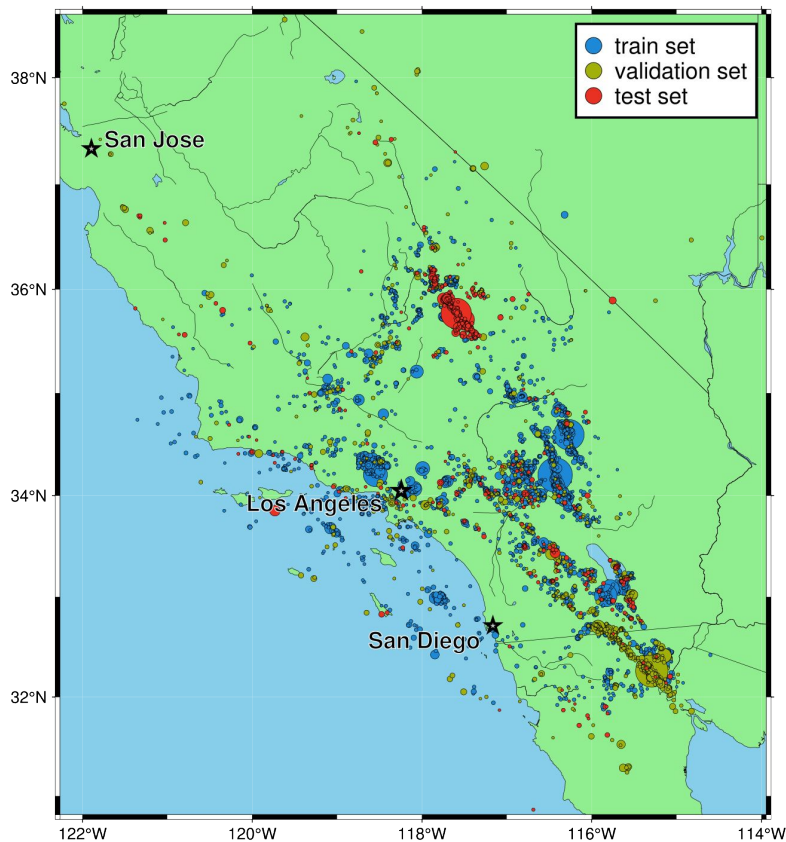
Data decoding



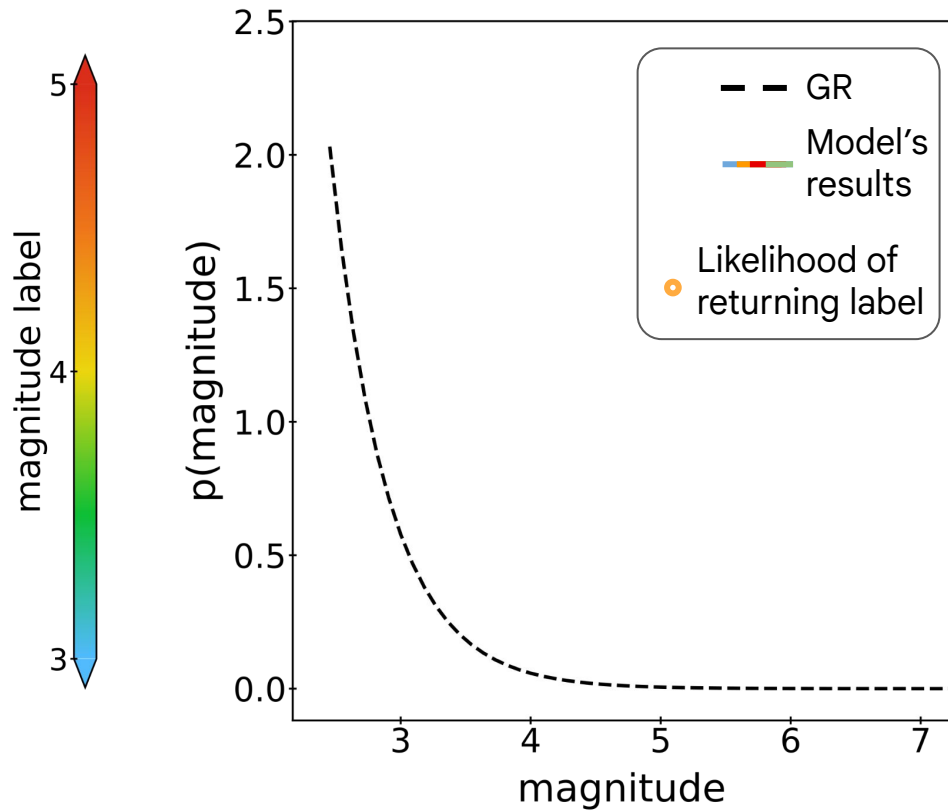
Prediction



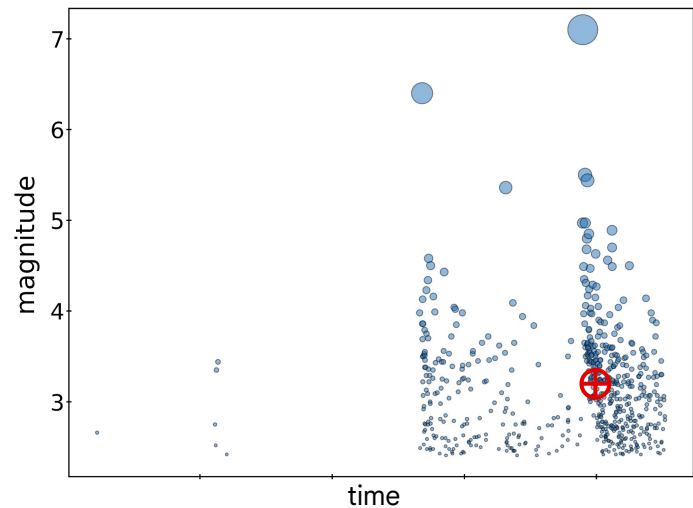
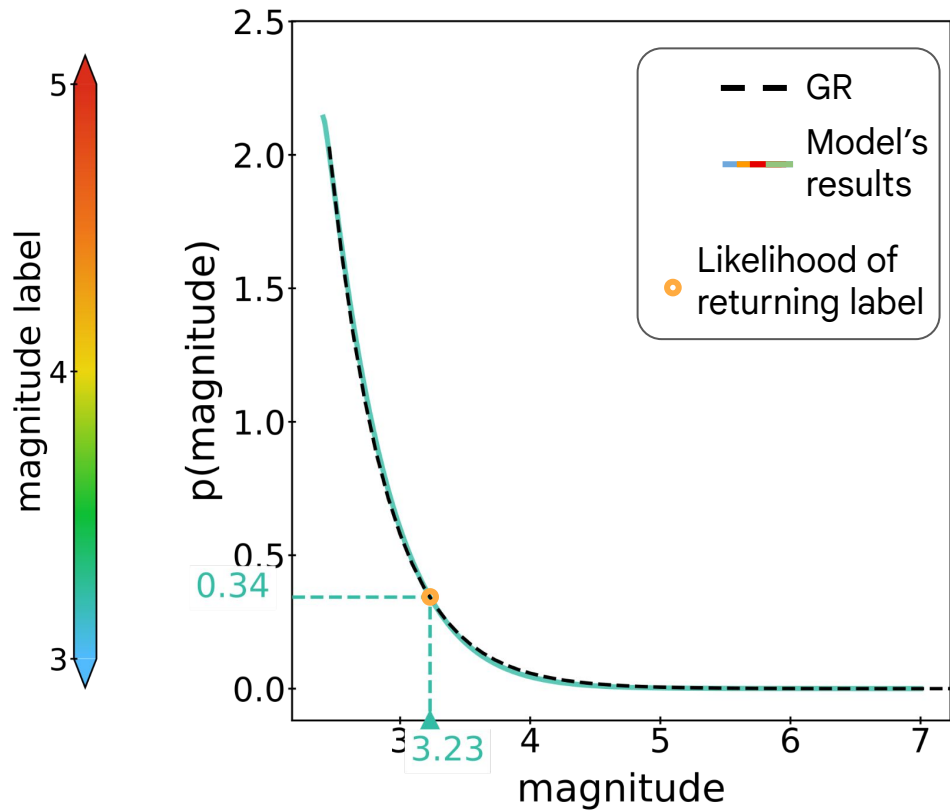
Input data - Hauksson catalog



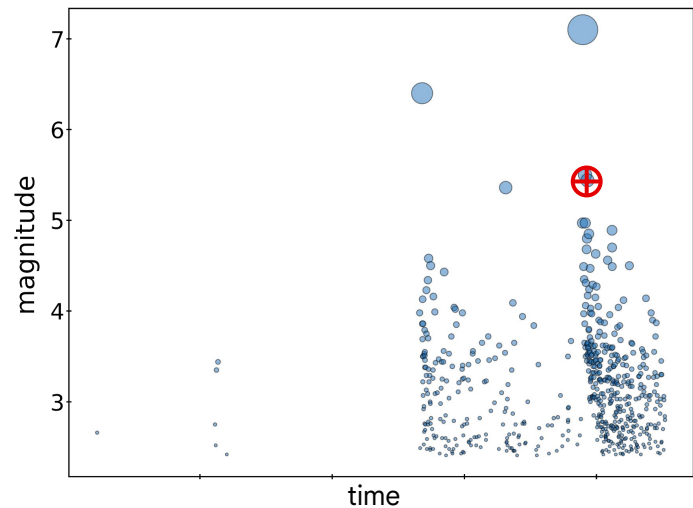
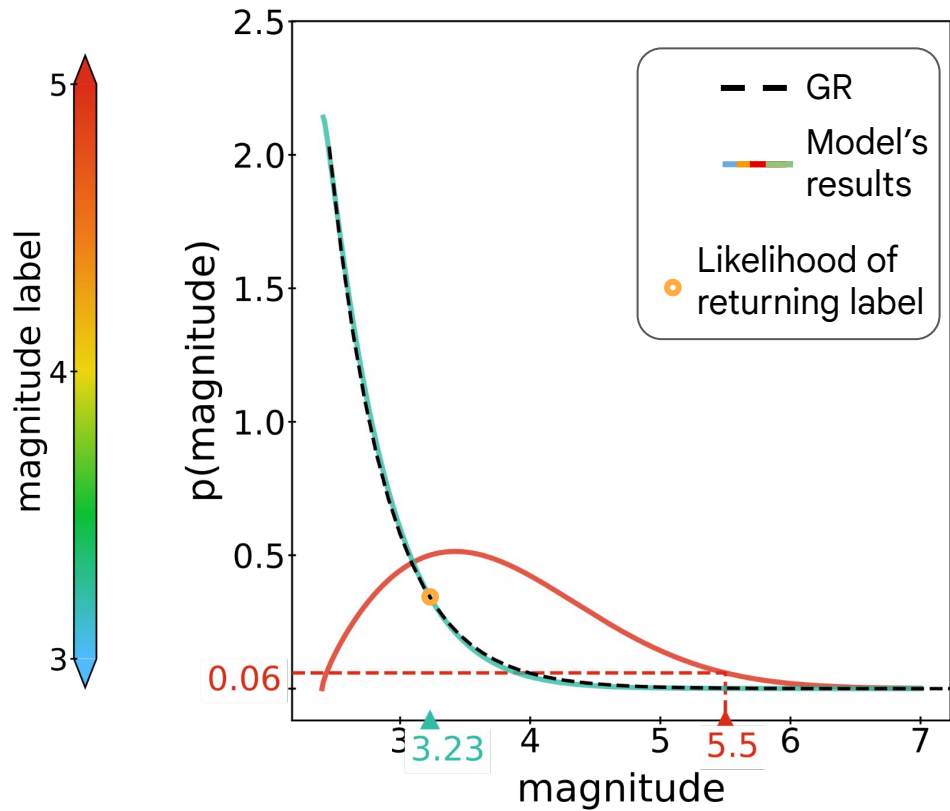
Results - magnitude sampling functions



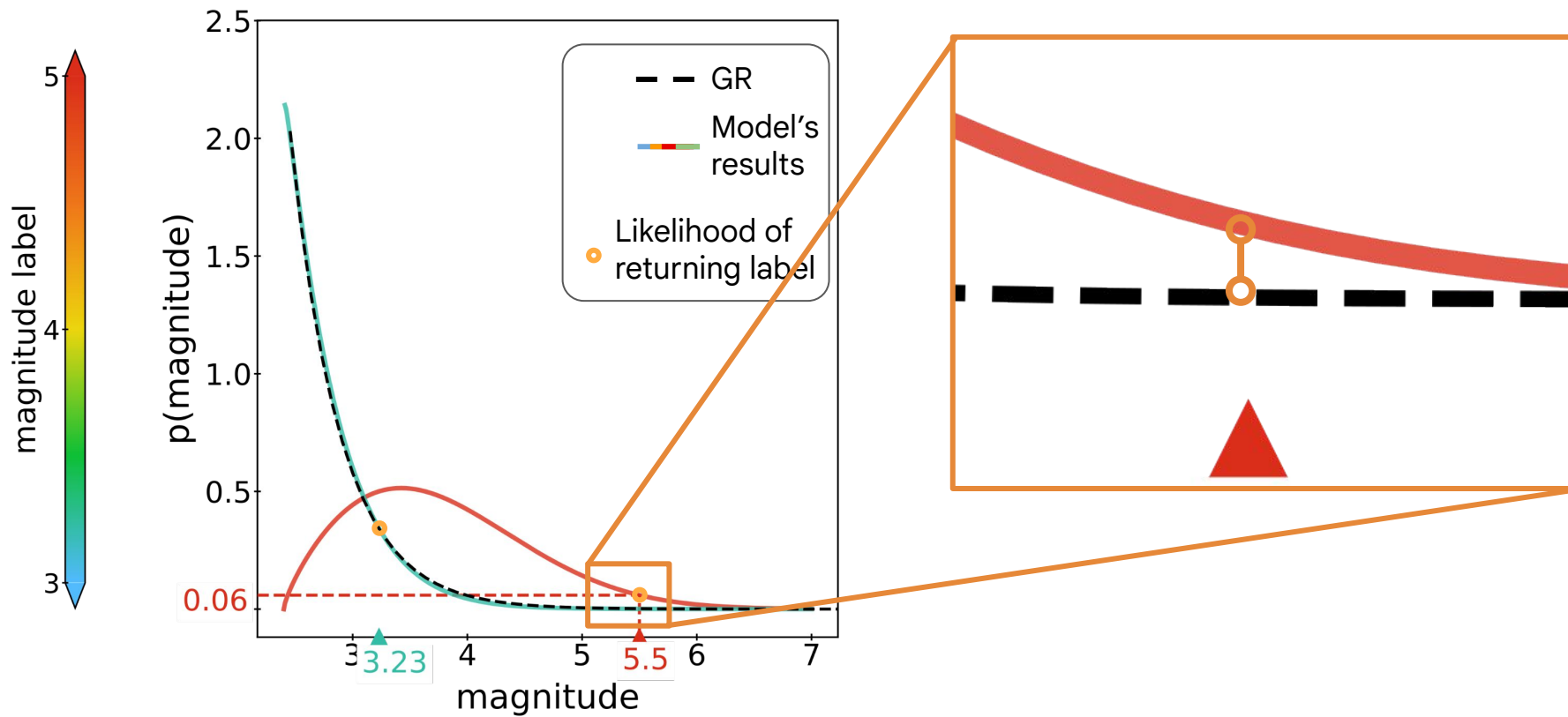
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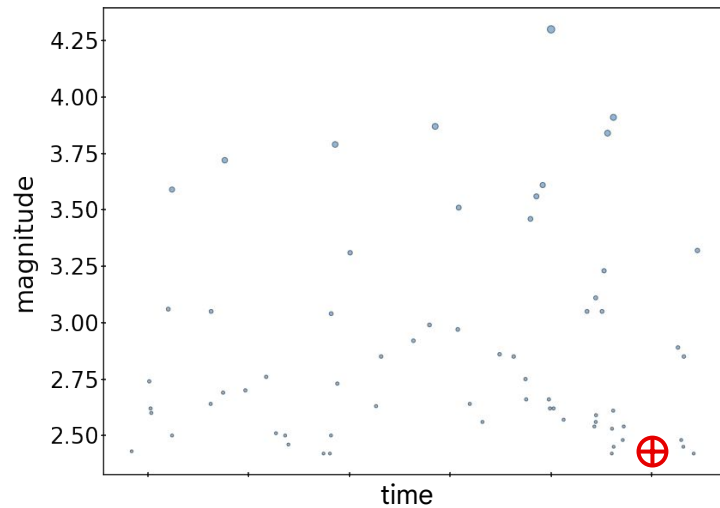
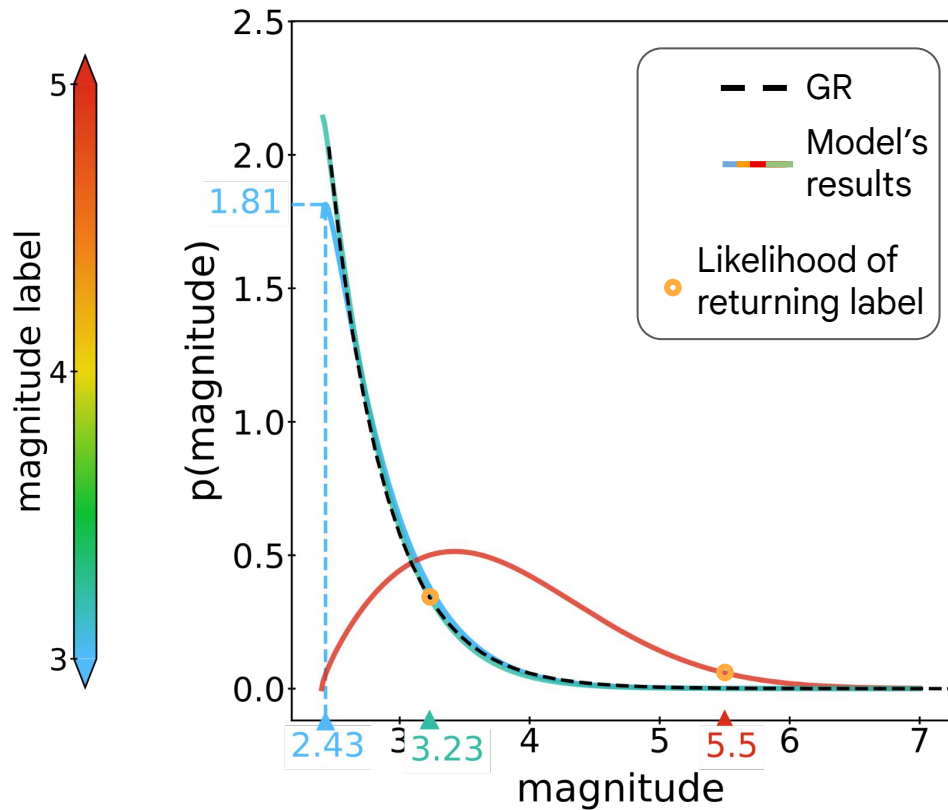
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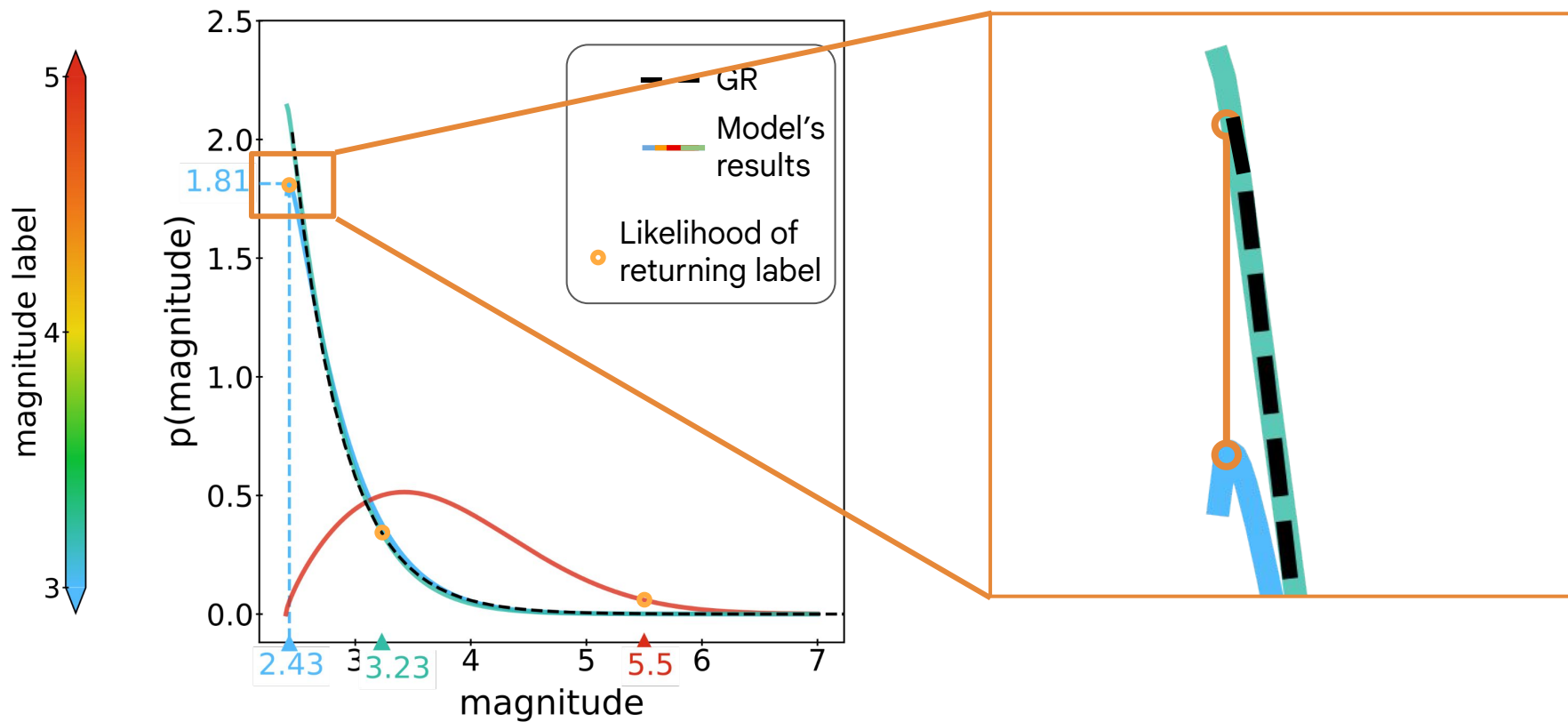
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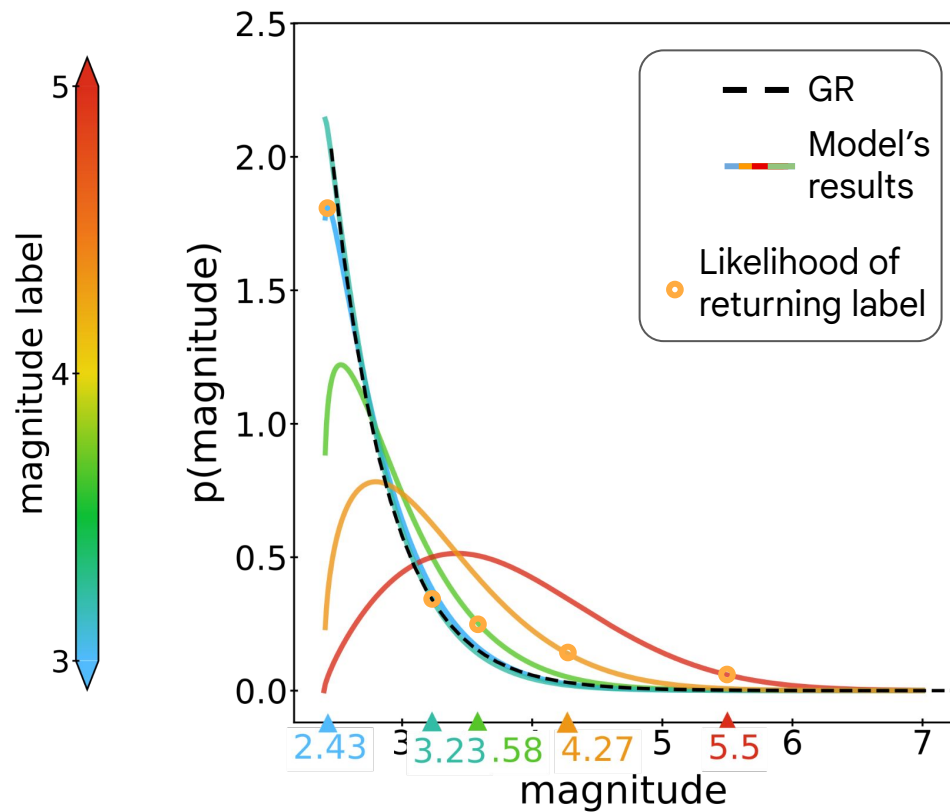
Results - magnitude sampling functions



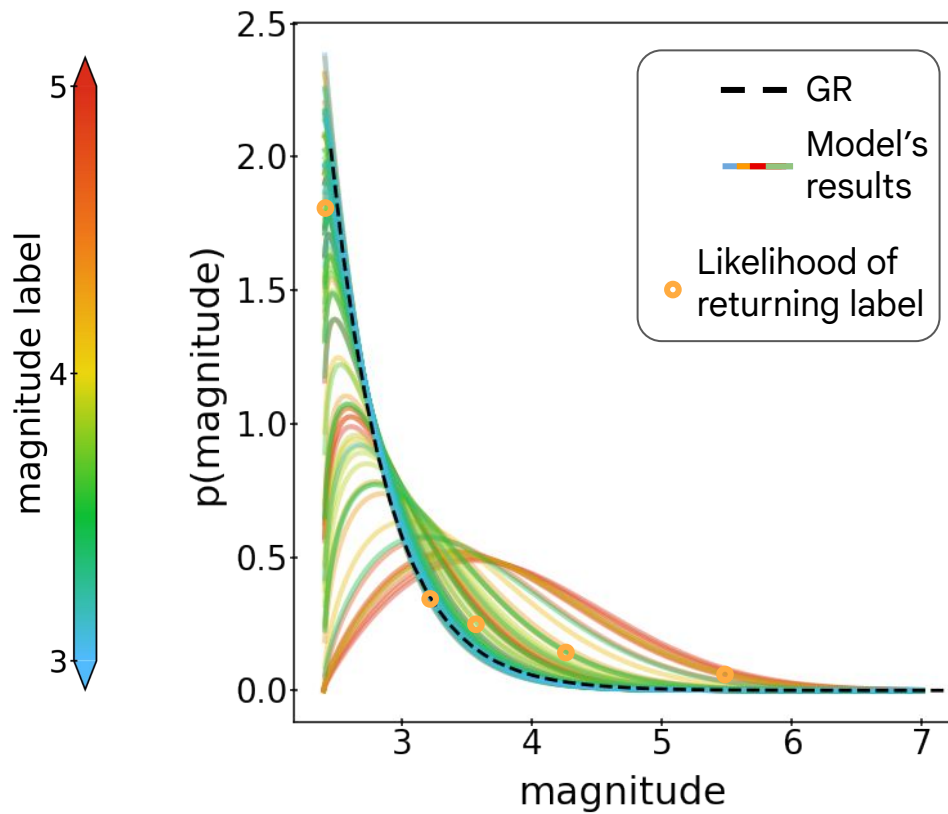
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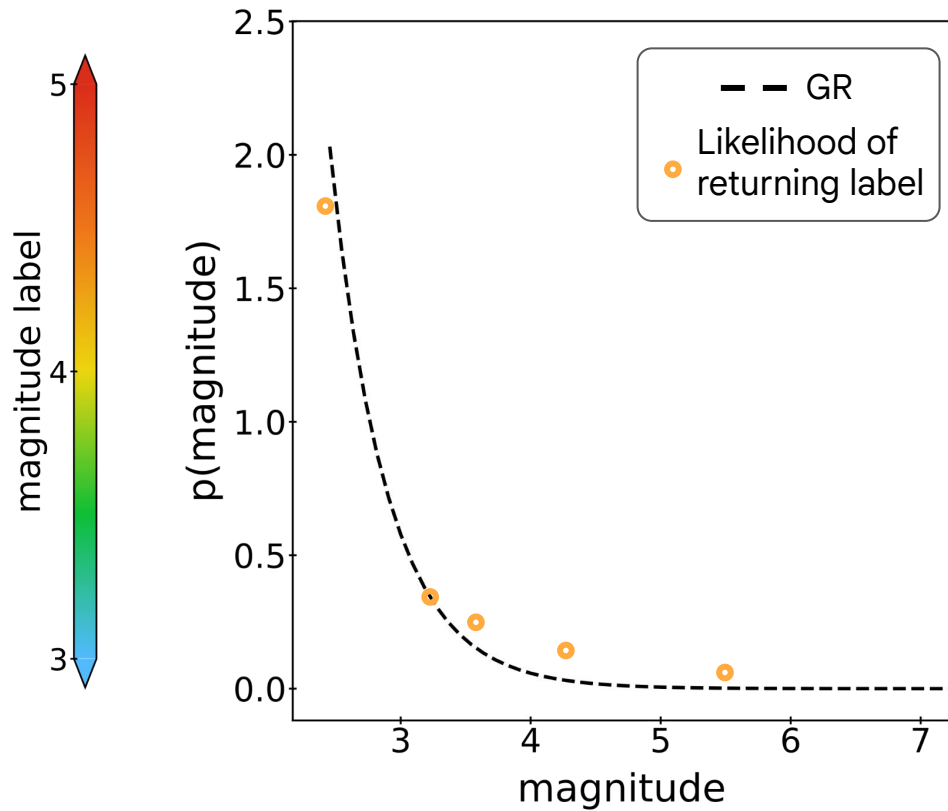
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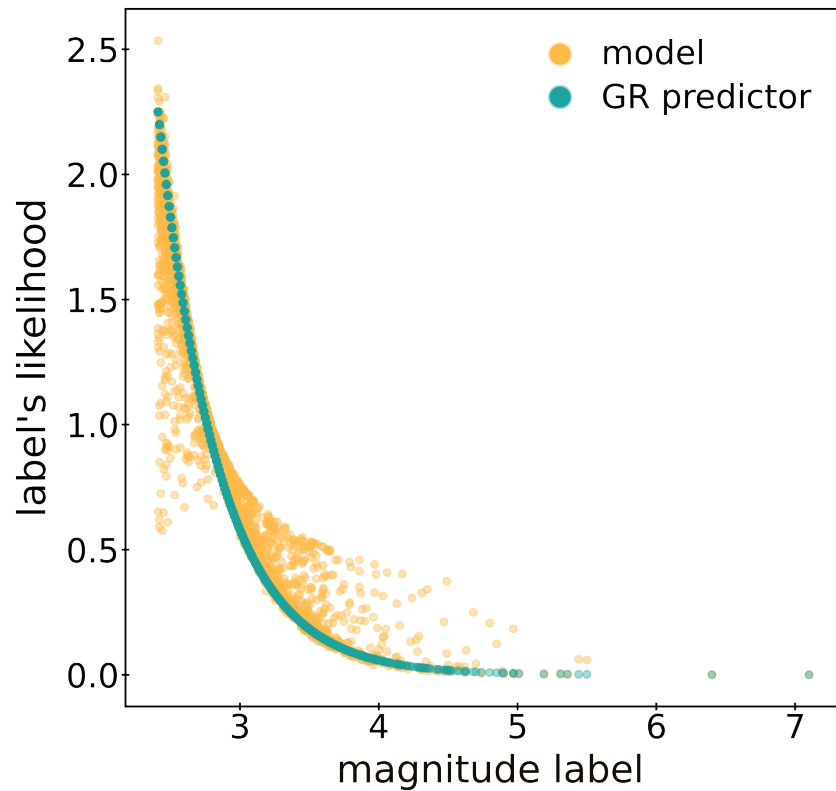
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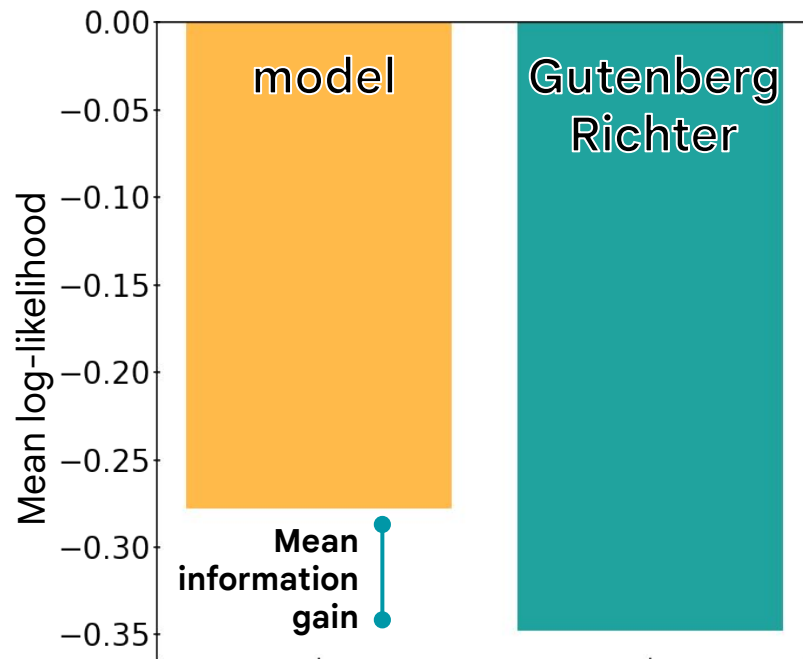
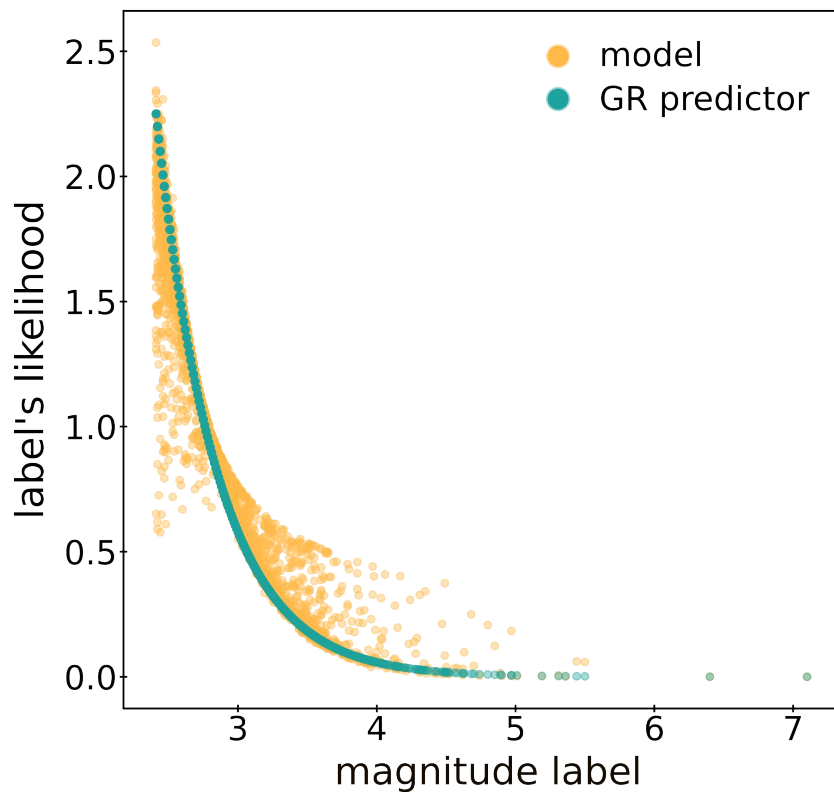
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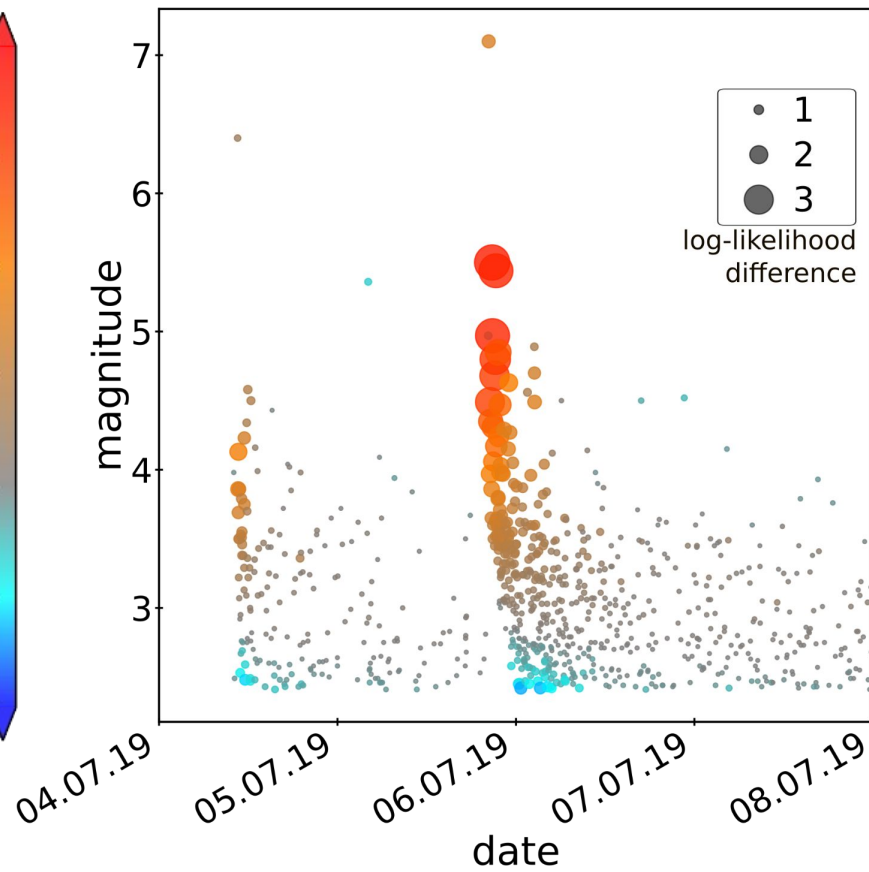
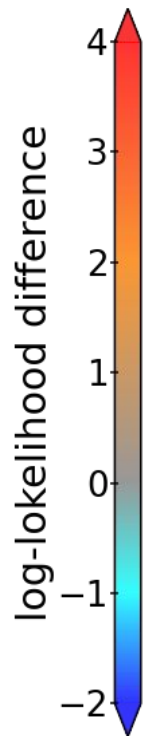
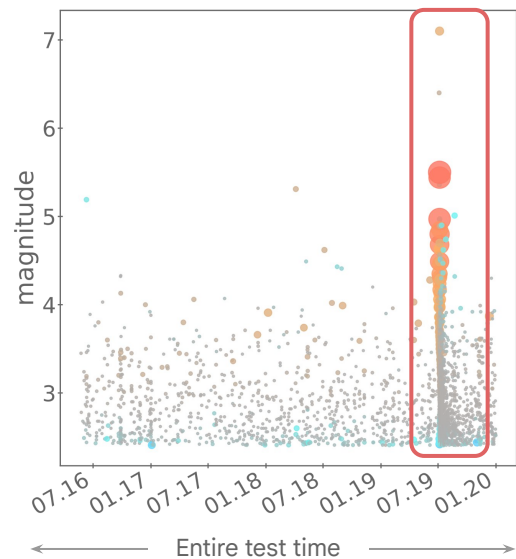
Results - likelihood per example



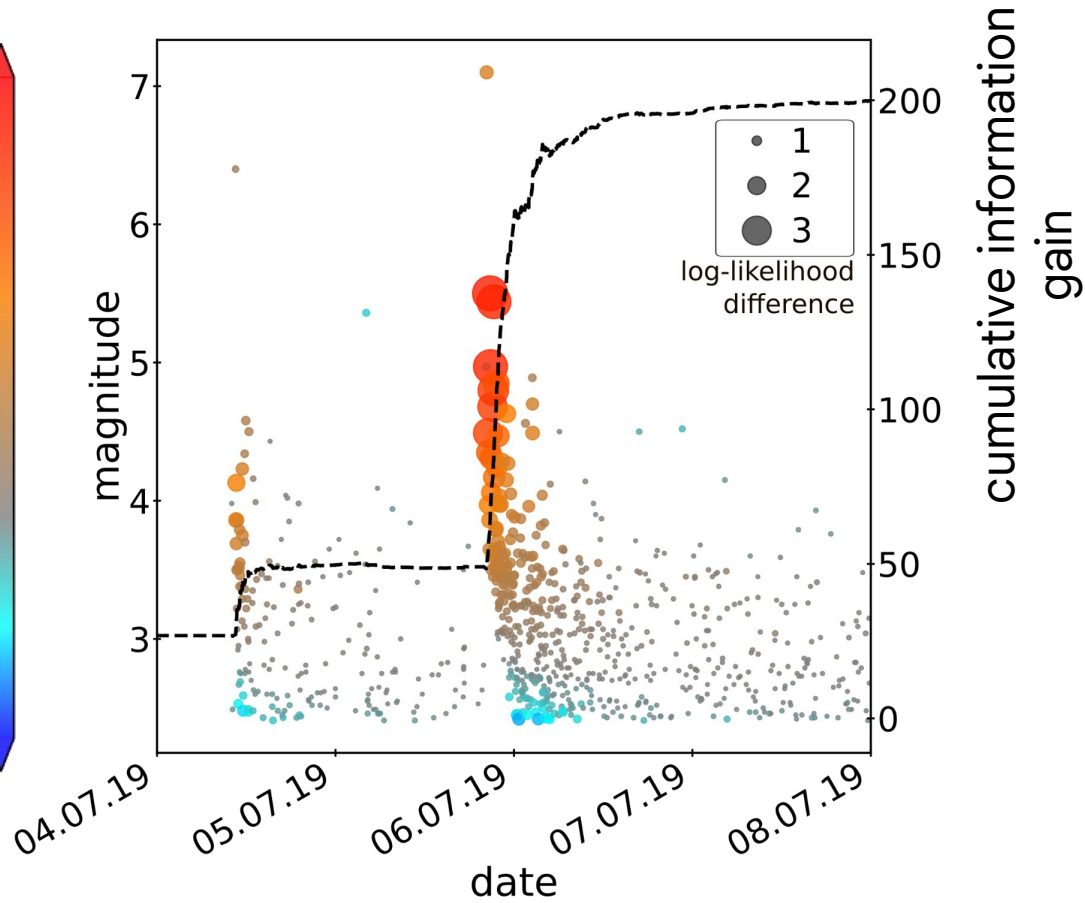
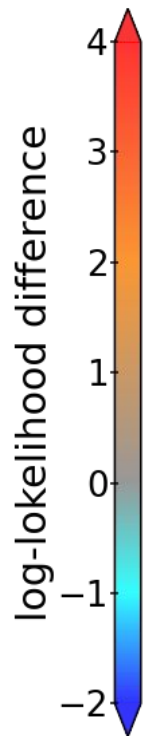
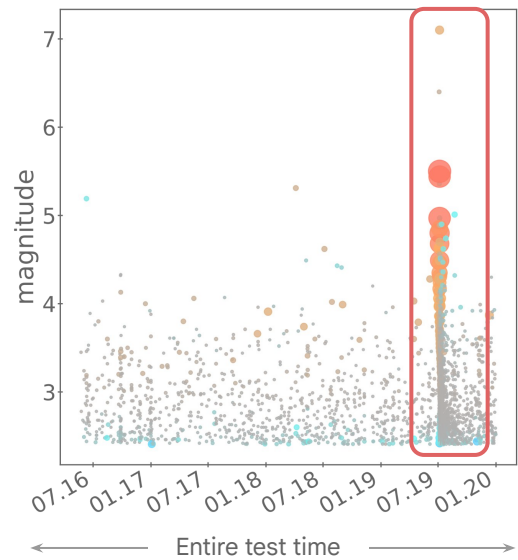
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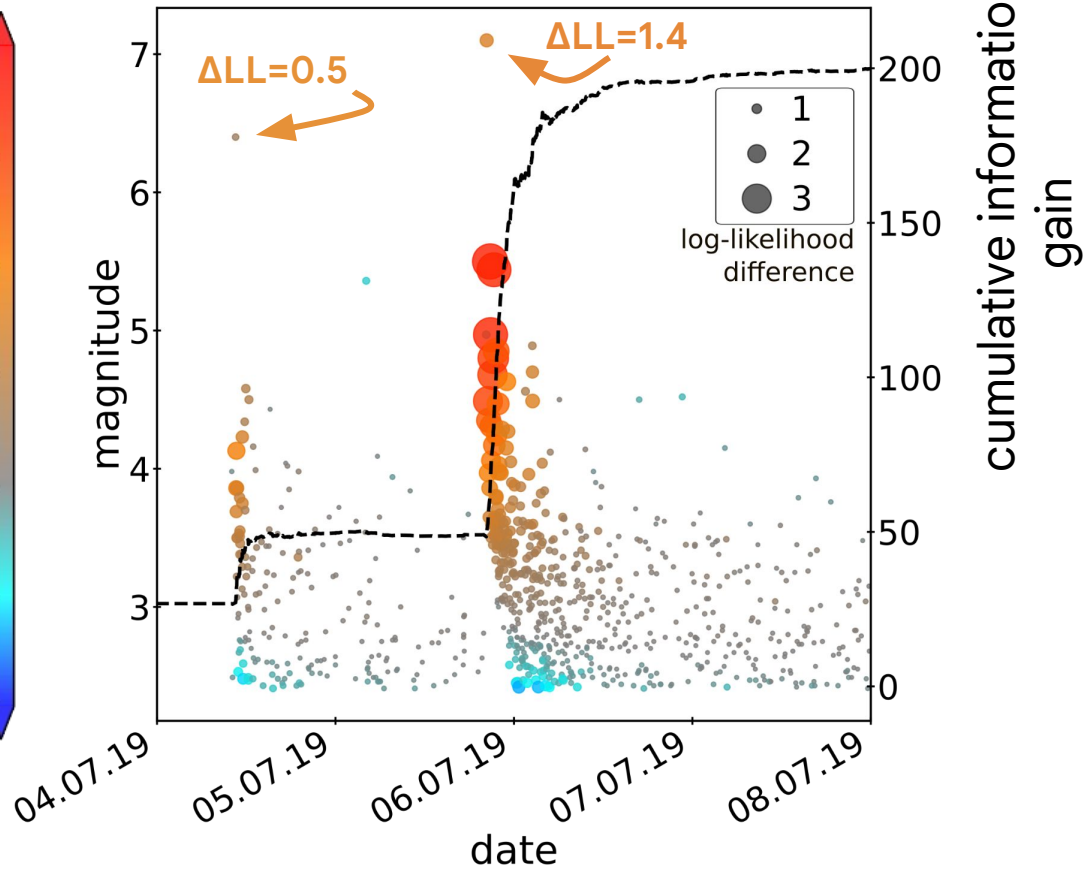
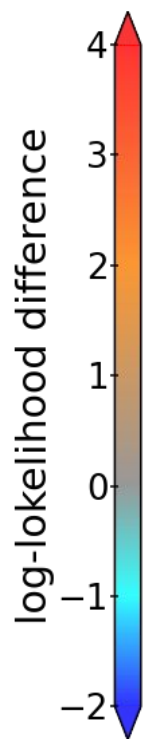
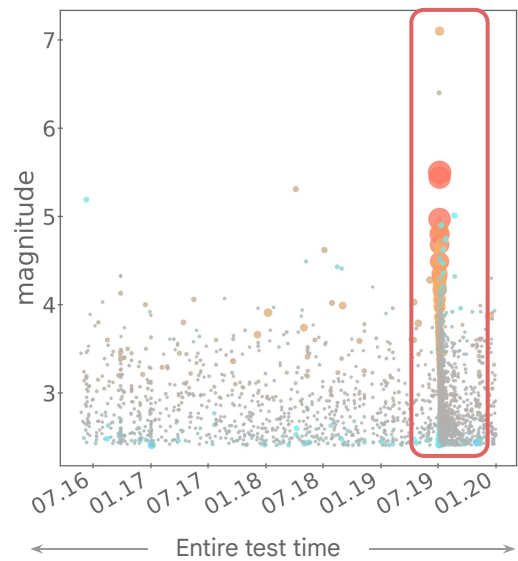
Model's advantage per event



Model's advantage per event



Model's advantage per event



Conclusion

Improvement in magnitude prediction

-- ➔ **Magnitudes are history dependent**

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Future directions

- Use the model as an oracle
E.g: “What will be the the probability for $m > 4$ in the next 24 hours?”
- Use as a replacement in an ETAS-like model:

$$\lambda(t, x, y) = \mu(x, y) + \sum_{i:t_i < t} \tilde{\kappa}_i(m_i | t - t_i, x - x_i, y - y_i, m_{t_j < t_i})$$

- $g(t - t_i)$
- $f(x - x_i, y - y_i; m_i)$

Thanks!

