

# Performance Analysis of the ATLID Lidar: A Multi-Parameter Statistical Approach Using L1 Data

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## Abstract

We propose a set of parameters, which would characterize the behavior of the ATLID lidar system on a day-to-day basis using the L1 data as an input. With the help of this set we will trace:

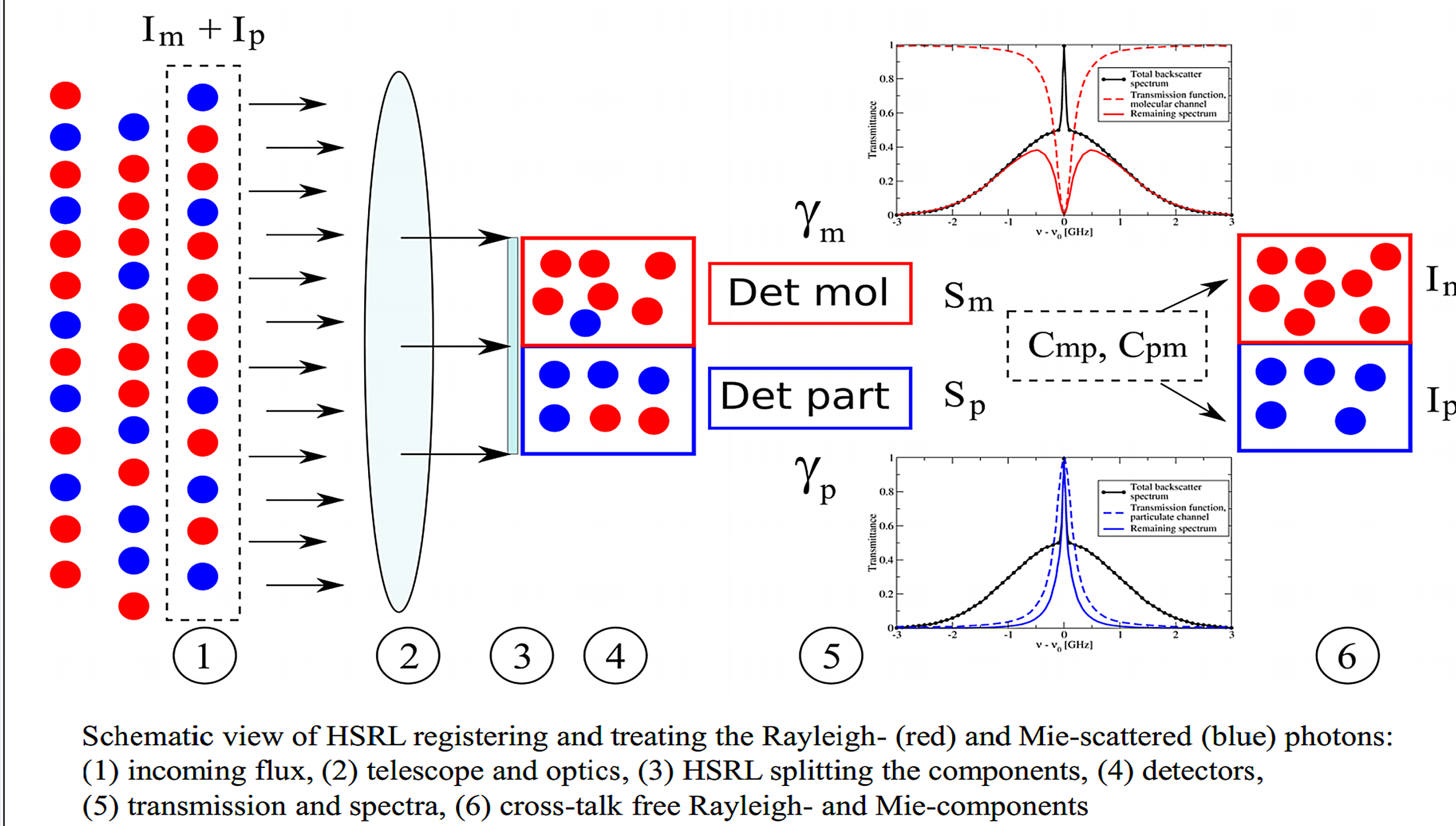
- (a) the stability of the detection chain for ATLID channels (Rayleigh, Mie, and the cross-polarized one);
- (b) the accuracy of cross-talk coefficients;
- (c) the stability of day- and nighttime noise;
- (d) the stability of the radiation detection for all atmospheric scenarios and over the whole globe using a clustering algorithm applied to the scattering ratio (SR) histograms.

We define 11 parameters: 3 related to surface reflection, 6 related to stratospheric day- and nighttime noise for 3 channels, and 2 related to the SR histogram analysis. We demonstrate the feasibility of the approach using CALIOP L1 data for polarized and cross-polarized attenuated backscatter (ATB) components in 2008–2015.

## Calibrating space-borne instruments

- Calibration in the laboratory: high precision, repeatability, versatility. Not 100% consistent with the instrument after launch.
- Calibration in space using onboard sources and/or known external sources (stars, moon): typical for passive instruments.
- Calibration through collocation: ground-based stations, balloons, aircraft – compares the products (L2), involves L0→L1→L2 conversion, limited number of overlaps.
- Statistically based **quality control**: not equal to calibration, helps to identify issues in calibration and performance of the instrument, needs only a day-to-day flow of L1 data.

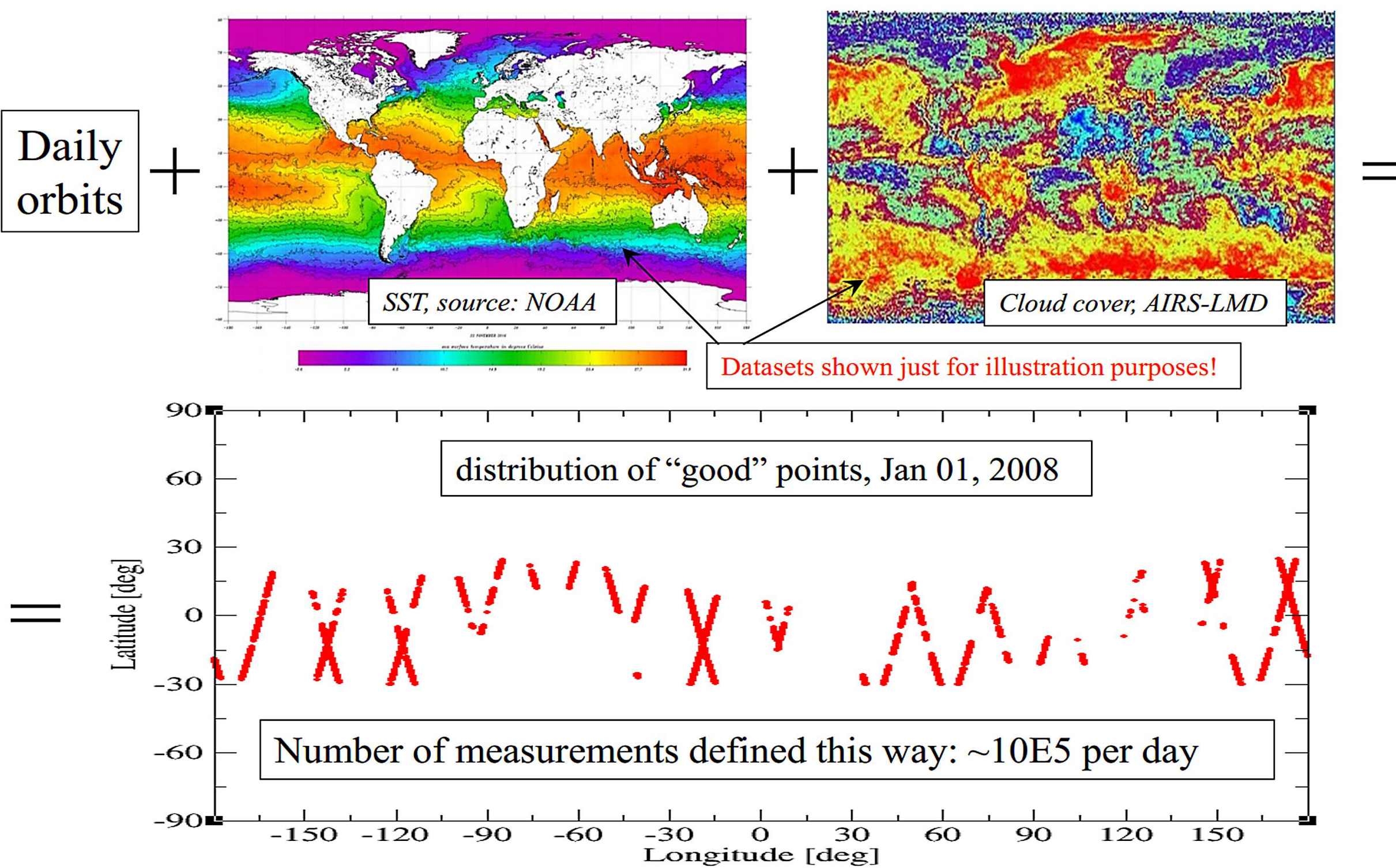
## High Spectral Resolution Lidar (HSRL)



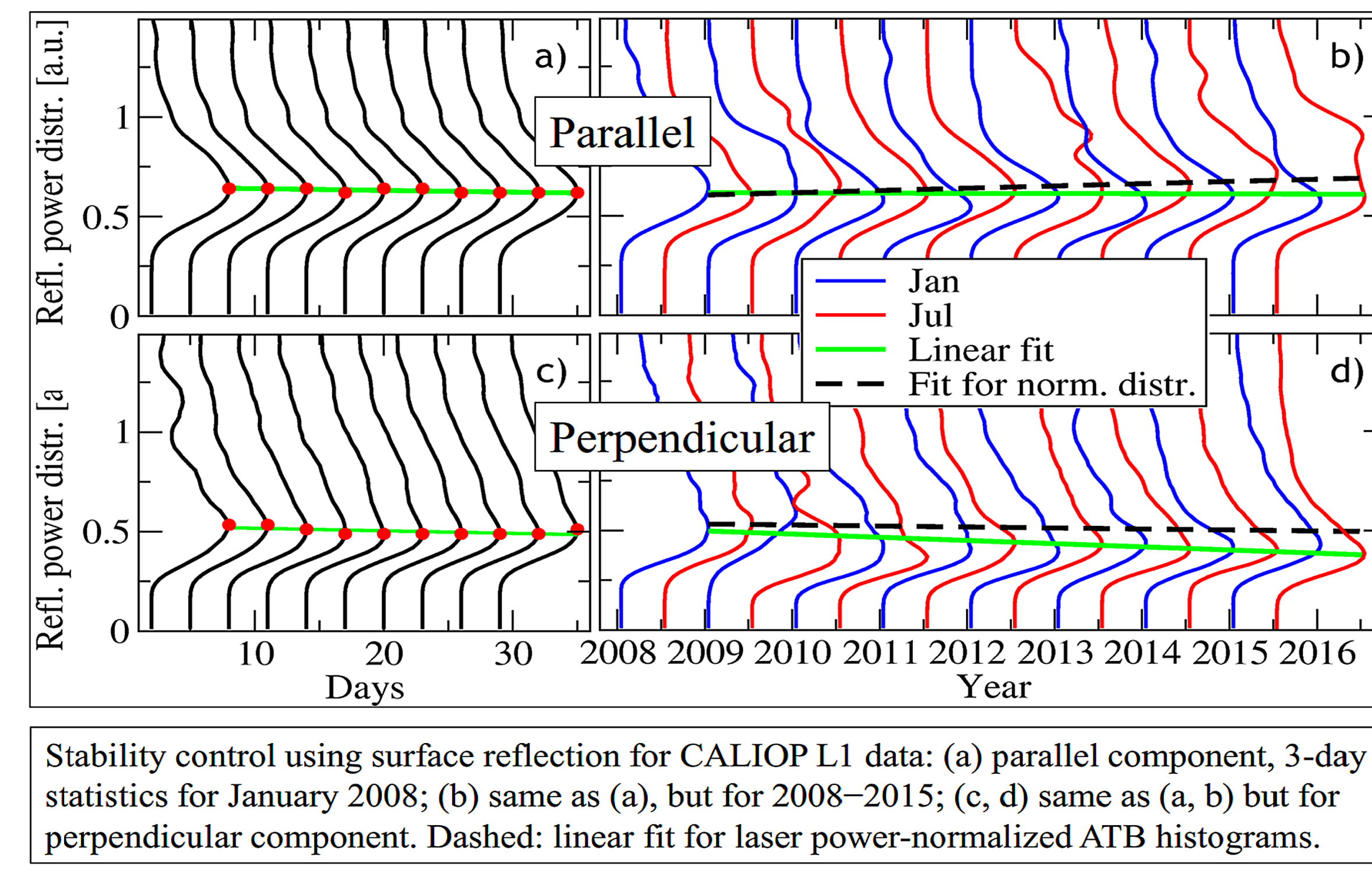
## Formulation of the problem

- Elements of spaceborne lidar, related to calibration:
  - molecular channel
  - aerosol channel
  - cross-polarized channel
  - laser power measurement
  - sending and receiving optics (alignment, coatings, degradation)
  - data acquisition system (noise, electronic cross talk, etc)
- L0→L1 conversion requires knowledge of HSRL cross-talk coefficients (+ cross-talk for cross-polarized channel)
- How to detect drifts and offsets using only a flow of L1 data?
- Ideally, a set of parameters calculated on a day-to-day basis is needed:  $\Delta_i < \text{threshold}_i$  ( $i=1 \dots N$ )

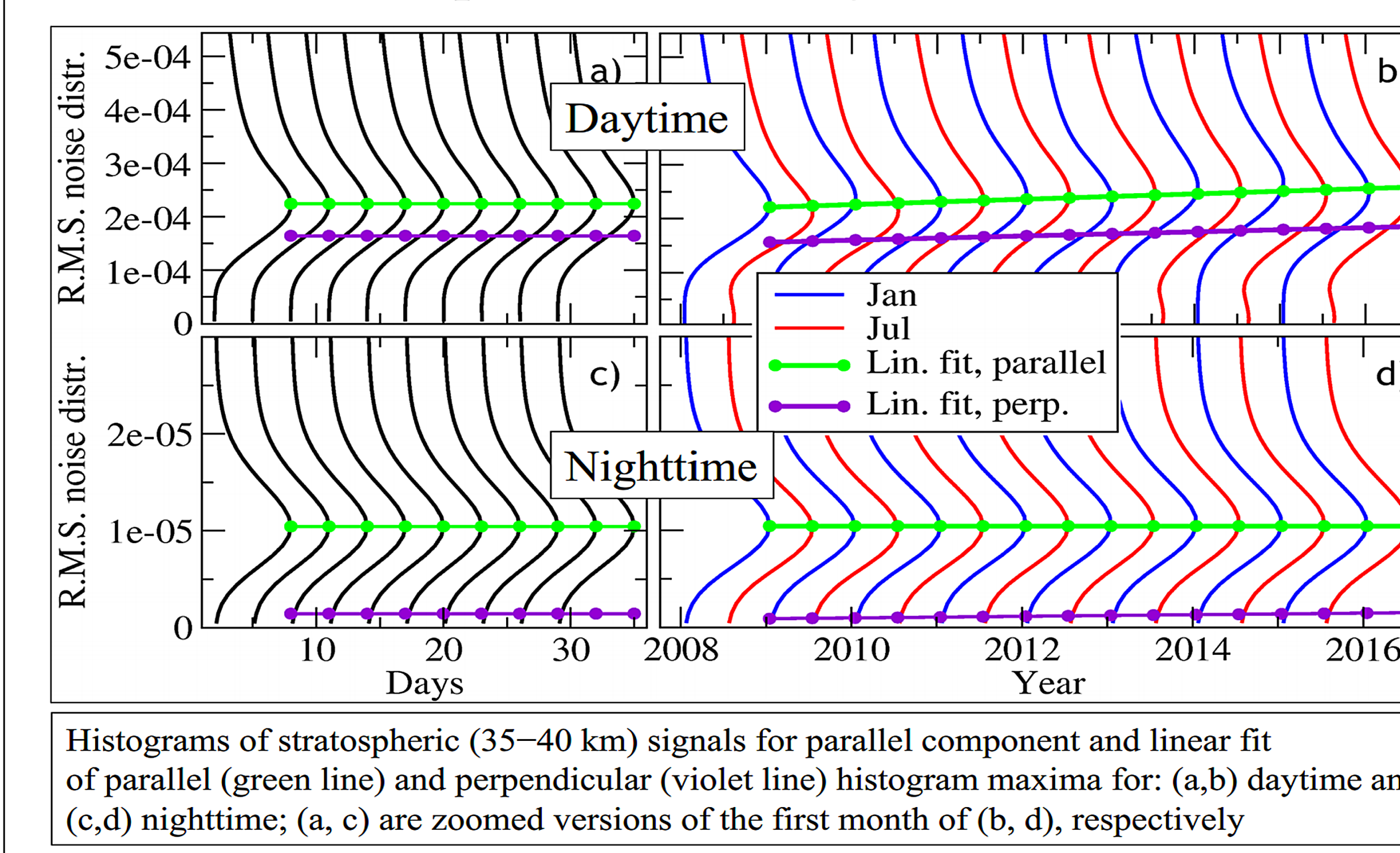
## Stability control using surface backscatter



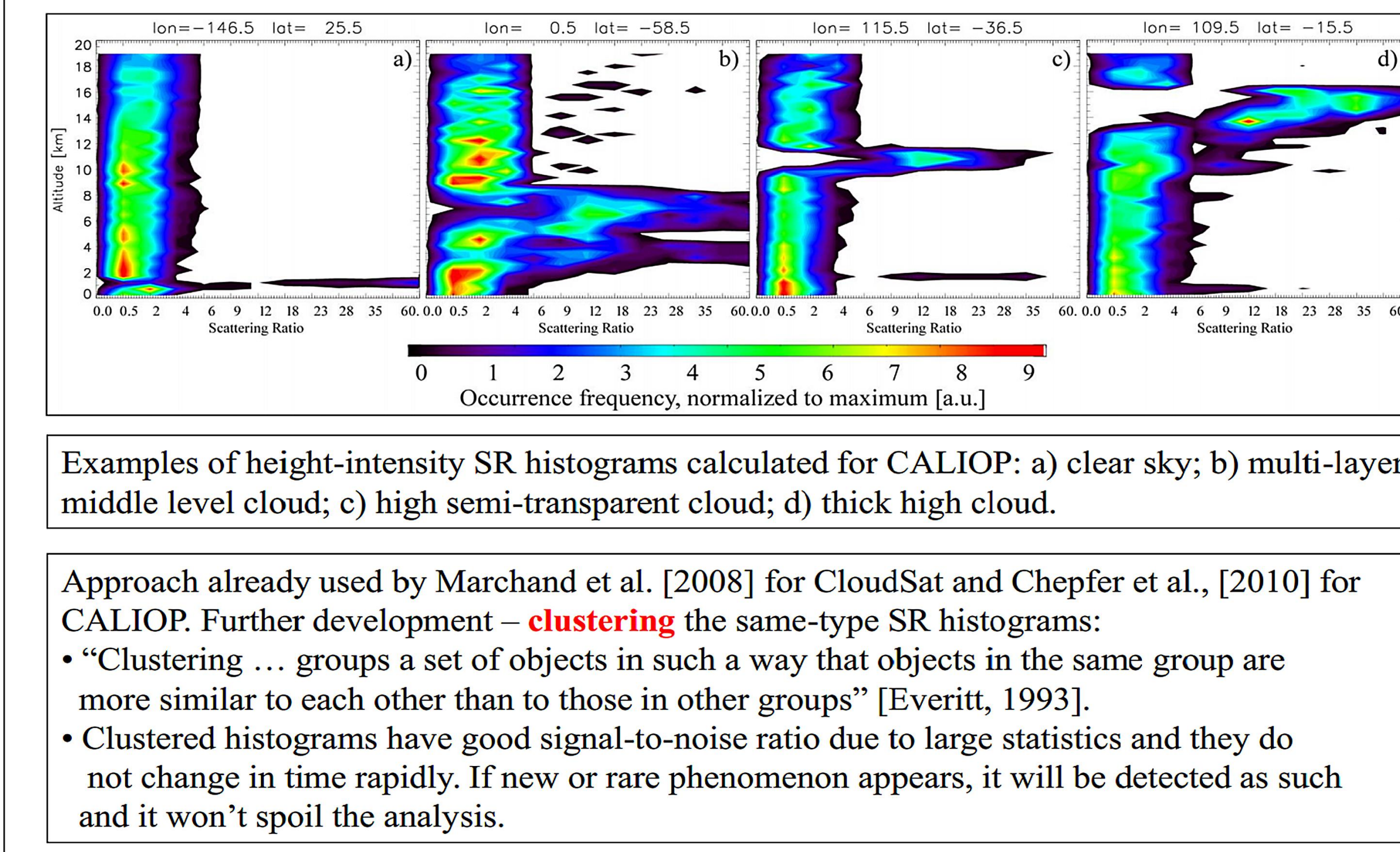
## Stability control using surface backscatter: CALIOP



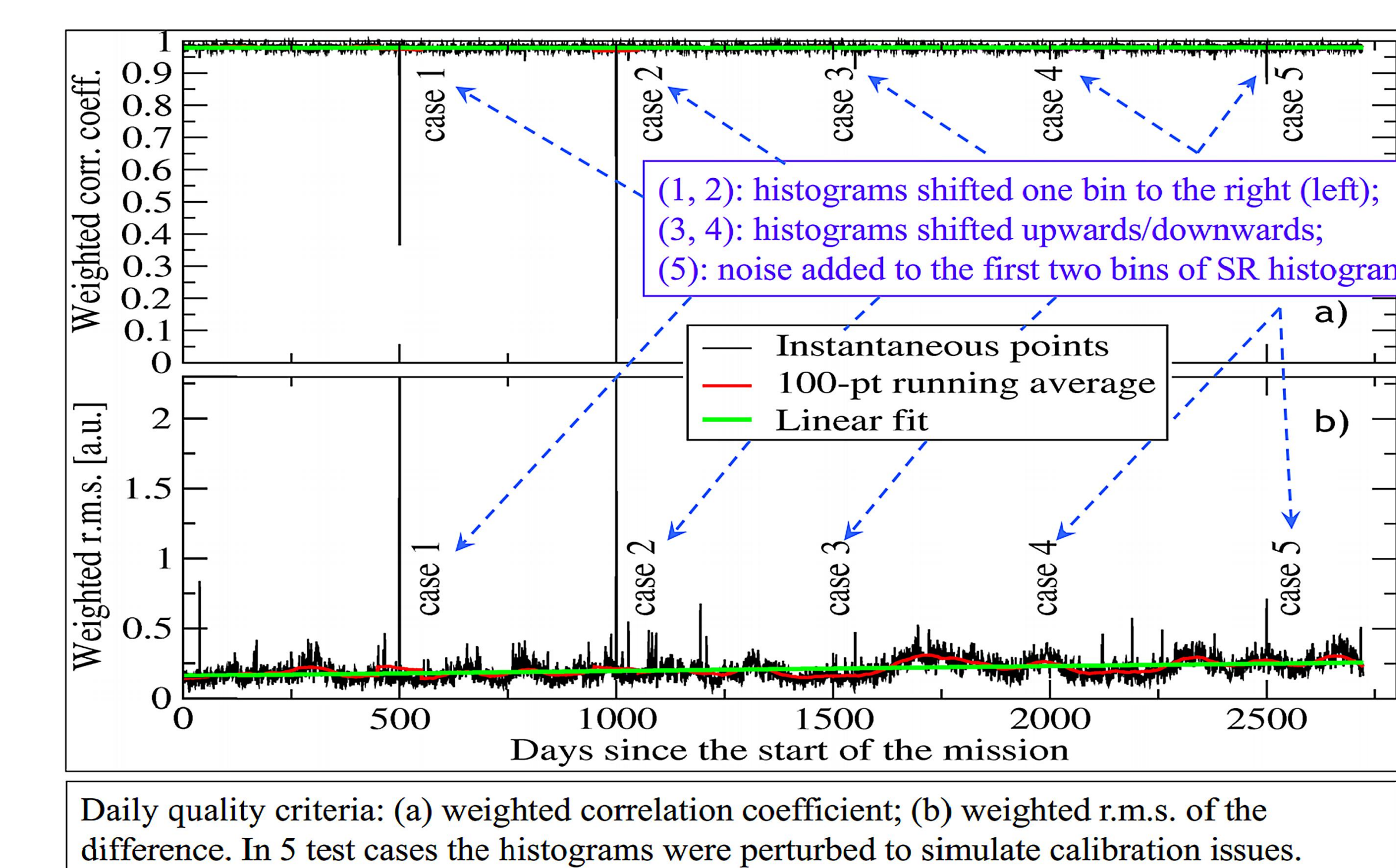
## Stratospheric noise analysis: CALIOP



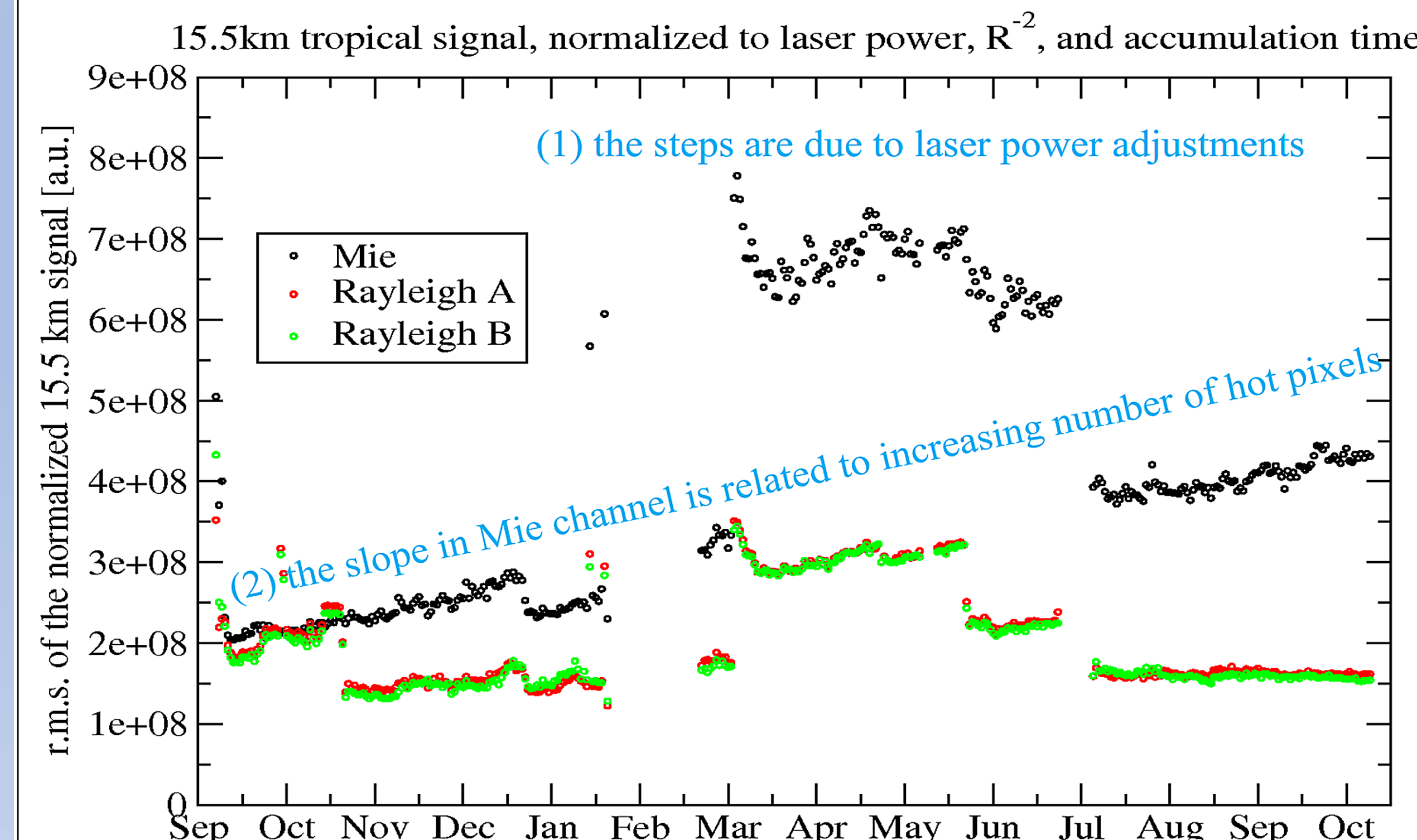
## Scattering ratio histograms: typical scenes



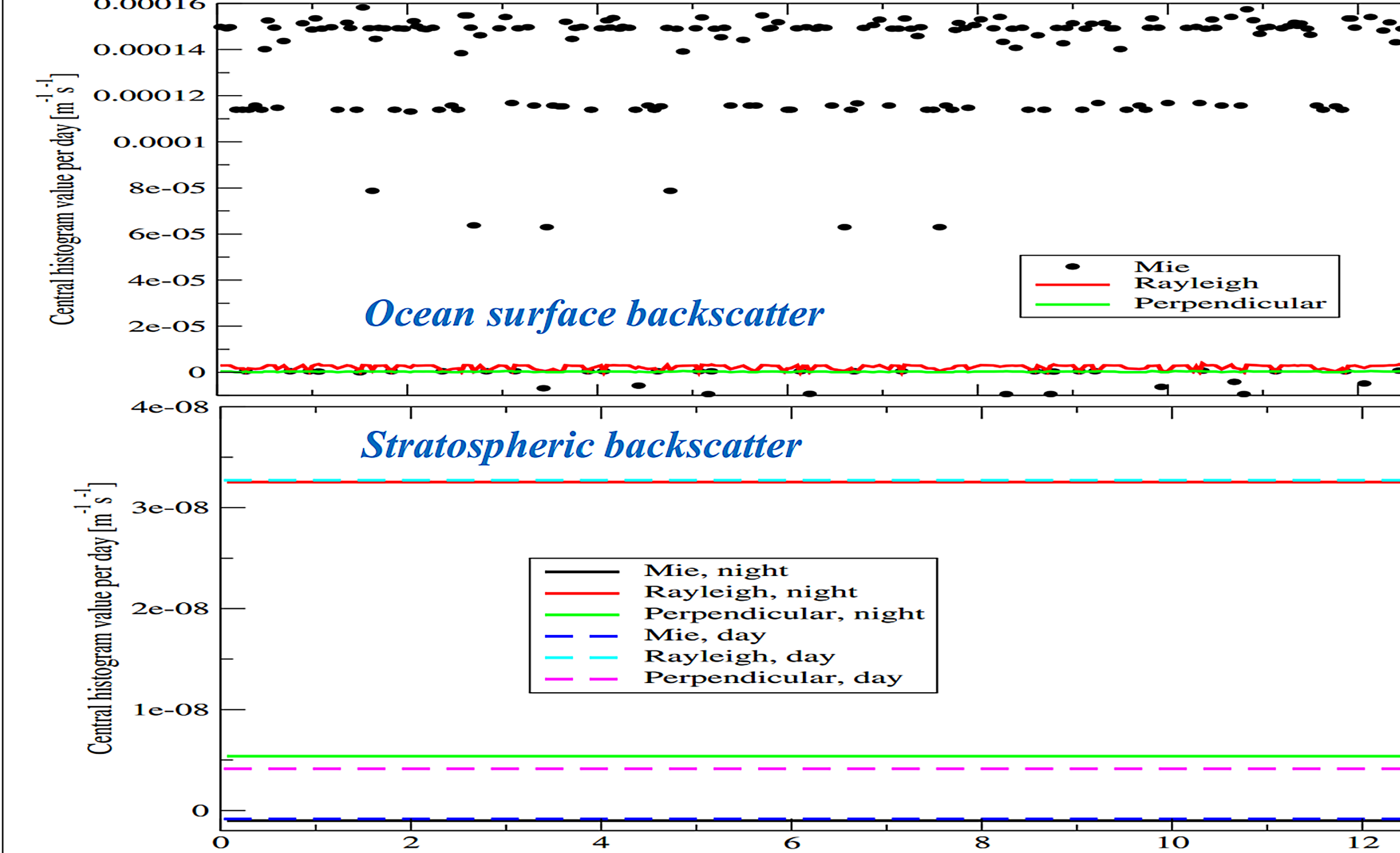
## Quality control using SR clustering: 8 years of CALIOP



## Application to ALADIN / Aeolus



## ATLID rehearsal results



## Summary

- We propose a set of 11 quality control parameters:

N	Channel/data	Description
1	Mol.	Center values of histograms of radiance reflected from the ocean with $T_{\text{surf}} = 300 \pm 1$ K.
2	Part.	
3	Perp.	
4	Mol. day	
5	Part. day	Center values of histograms of daytime and nighttime stratospheric molecular signal (~35km) or noise (higher altitudes).
6	Perp. day	
7	Mol. night	
8	Part. night	
9	Perp. night	
10	$K_{\text{corr}}$ , SR histo	Weighted average of the correlation coefficient or deviation for the clustered scattering ratio histograms w.r.t. the reference or the first day
11	R.M.S., SR histo	

- We demonstrate the feasibility using 8 years of CALIOP data.
- Application to Aeolus data revealed laser power adjustments and increasing number of hot pixels.
- ATLID rehearsal shows the readiness to real data flow.