Groundwater recharge estimates in agriculturally managed site in NE Germany: combining Cosmic ray neutron sensing and soil hydrological modelling

Methods and data

Marquardt Cluster, Potsdam, NE Germany

- Area 10ha; diversity of agricultural plots
- Sandy soils
- Gentle hillslope over a glacial till aquifer
- Distance to water table 1.5 10 m
- Subsurface water storage monitoring: • 13 CRNS
 - 23 point-SM-profiles with different measurement depths





Basic principle of CRNS. Neutrons scattered back from the soil are counted in the passive detector, neutron abundance depends on SM state

Cosmic-ray neutron sensing (CRNS)

- moisture (SM)
- Inverse relationship neutrons ~ SM
- Integral field water content
- Depth of 15 80 cm

Calibration results





Exemplary water balance for 3 years



- depth
- Constant over time



- Clear improvement after model calibration
- No surface runoff, high fraction of ET, low GWR
- Both, increased vegetation height and rooting depth reduce cumulative GWR to a similar extent
- Parameter ranges from equifinality smaller than from heterogeneity but similar range in GWR for both



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Equifinality of calibration and spatial heterogeneity

- Equifinality: the same performance in the calibration from different parameter combinations: repeat calibration several times
- Heterogeneity: use single locations in calibration (in combination with CRNS) instead of mean soil moisture from sensor network

Lower KGE resulting in lower GWR estimates





optimization on CRNS and profile mean

Simulated cum. GWR from single calibrations

References

Zhang, Y., & Schaap, M. G. (2017). Weighted recalibration of the Rosetta pedotransfer model with improved estimates of hydraulic parameter distributions and summary statistics (Rosetta3). Journal of Hydrology, 547, 39–53. https://doi.org/10.1016/j.jhydrol.2017.01.004

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Calibration data

 A combination of CRNS and point-scale SM observations provide field-scale **representative** calibration data

CRNS SM from different locations showing comparable dynamic between each other

• Higher variability in point sensors show subsurface heterogeneity

Calibration approach



HYDRUS-1D Model setup

- Daily input, atmospheric boundary, free drainage
- 6-month spin-up period
- 200 cm model domain, discretization 1cm
- Van-Genuchten-Mualem model (initial soil hydraulic properties (SHPs) derived from texture (Zhang and Schaap 2017) data using ROSETTA

Layer (cm)	θr (cm³∕cm³)
0- 30	0.02
31 - 200	0.03

Long term groundwater recharge

- Calibrated model, climate data Potsdam 1948 to 2023
- Main recharge period in winter to spring
- Declining linear trend (46 to 36 mm/year)
 - in deep water
 - storage
 - in pattern

(iii) Based on a calibrated n

model assess long-term

changes of GWR





CRNS provides hectare-scale water fluxes replenishing the storage of the vadose zone and aids GWR estimation

Outlook for model improvement and application:

- Calibration on models with varying vegetation properties
- Varying distance to groundwater



Model setup and calibration



Initial SHPs

for the two

layered

model

θs (cm³∕cm³)	α (1/cm)	n (-)	<i>Ks</i> (cm/d)	/ (-)
0.45	0.0258	1.75	185	0.5
0.38	0.0242	1.60	110	0.5



 Compare to other methods for GWR estimation at Marguardt • Apply approach for regional estimates in Brandenburg, including deep vadose zones

