

# Predictive uncertainty estimation in satellite precipitation data correction using machine learning

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## Abstract

Predictive uncertainty estimates for precipitation data acquired through merging satellite and ground-based observations are usually not provided. Here, we present the first benchmark experiments on the use of machine learning algorithms for fulfilling the task of delivering such estimates. These experiments compared six machine learning algorithms (i.e., quantile regression, quantile regression forests, generalized random forests, gradient boosting machines, light gradient boosting machines and quantile regression neural networks) and relied on 15-year-long monthly data that originate from across the contiguous United States. The comparison referred to the ability of the machine learning algorithms in delivering predictive quantiles at various levels. The results allow the ordering from the best to the worst of the machine learning algorithms for the problem of interest.

This poster is based on Papacharalampous et al. (2024).

A review on predictive uncertainty estimation with machine learning can be found in Tyrallis and Papacharalampous (2024).

## 1. Introduction

- Gridded precipitation data are often formed by merging satellite and gauge-measured data.
- However, uncertainty estimates for the precipitation data acquired in this manner are rarely provided.
- A few studies focus on how to provide such estimates by using machine learning algorithms (Bhuiyan et al. 2018, Zhang et al. 2022, Glawion et al. 2023, Tyrallis et al. 2023).
- Still, the benefits that machine learning can bring to the task of interest have not been explored so far through benchmark tests.
- The work summarized by this presentation has filled in this gap.

## 2. Summary of methods and comparative framework

### Machine learning algorithms

- Quantile regression (Koenker and Bassett 1978, Koenker 2005)
- Quantile regression forests (Meinshausen and Ridgeway 2006)
- Generalized random forests (Athey et al. 2019)
- Gradient boosting machines (Friedman 2001)
- Light gradient boosting machines (Ke et al. 2017)
- Quantile regression neural networks (Taylor 2000, Cannon 2011)

### Dependent variable

Gauge-measured precipitation at the location of interest

### Predictor variables

- Precipitation at the four PERSIANN grid points that are closest to the location of interest
- Precipitation at the four IMERG grid points that are closest to the location of interest
- Distances between the location of interest and each of its closest PERSIANN grid points
- Distances between the location of interest and each of its closest IMERG grid points
- Elevation at the location of interest

### Five-fold cross-validation

### Quantile levels

{0.025, 0.050, 0.100, 0.250, 0.500, 0.750, 0.900, 0.950, 0.975}

### Metrics

- Sample coverage
- Quantile prediction skill
- Quantile scoring rule skill

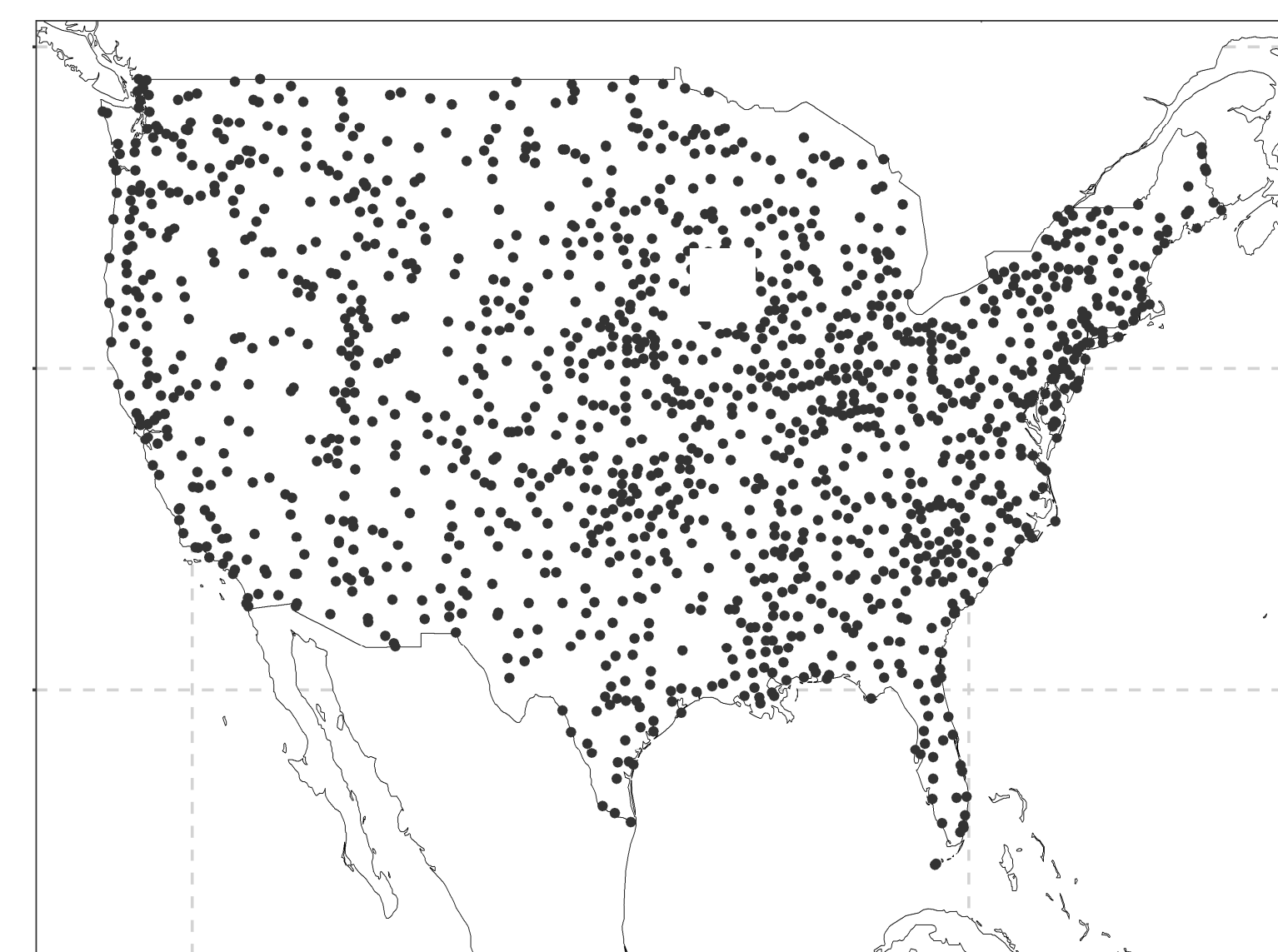
## 3. Summary of data

### ✓ Total monthly precipitation data from:

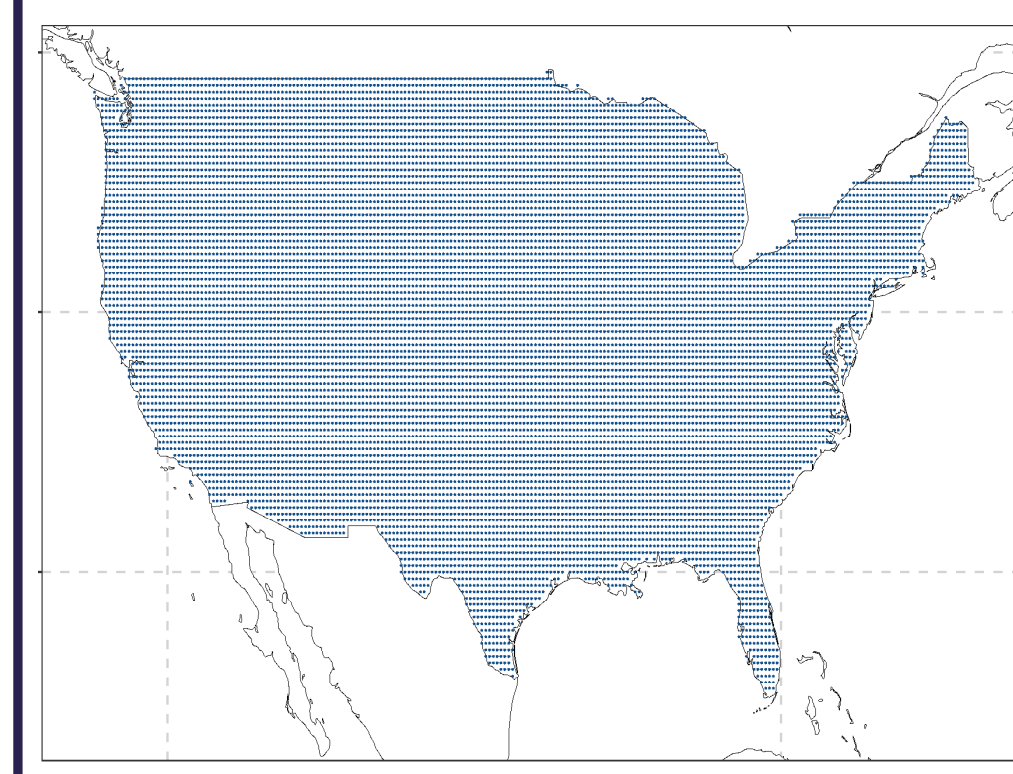
- The Global Historical Climatology Network monthly database, version 2 (GHCNm; Peterson and Vose 1997).
- Daily precipitation data of the current operational PERSIANN (Precipitation Estimation from Remotely Sensed Information using Artificial Neural Networks) system (Hsu et al. 1997, Nguyen et al. 2018, 2019).
- Daily precipitation data of the GPM IMERG (Integrated Multi-satellite Retrievals) late Precipitation L3 1 day 0.1 degree x 0.1 degree V06 dataset (Huffman et al. 2019).

### ✓ Elevation data from the Amazon Web Services (AWS) Terrain Tiles application.

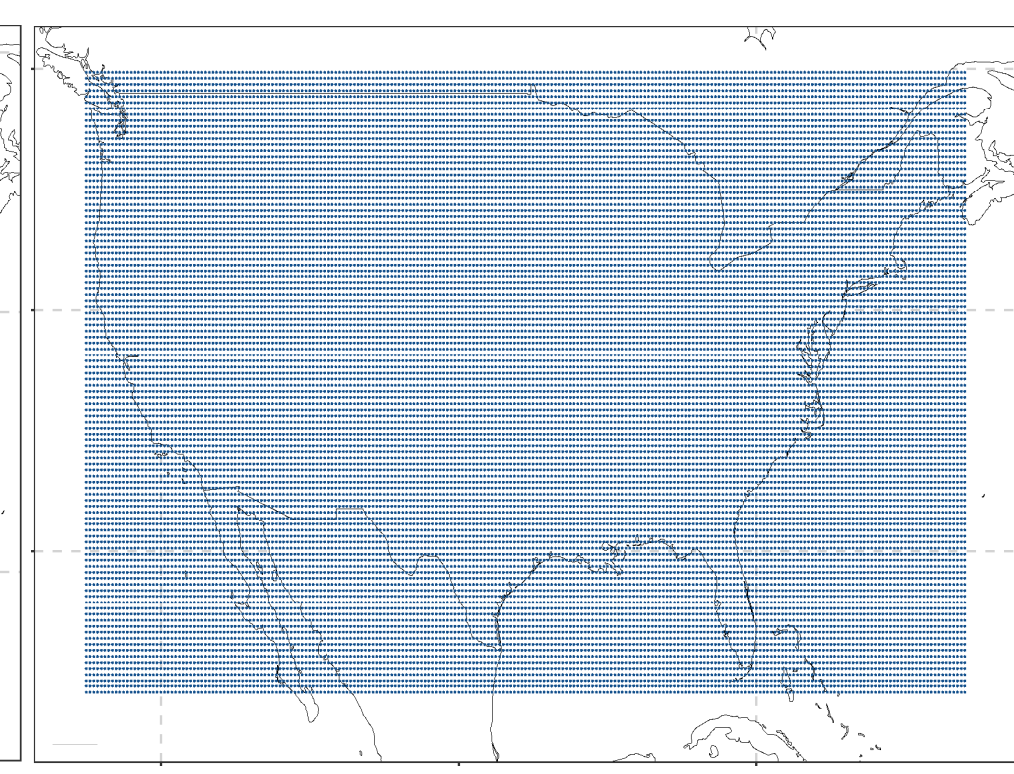
1 421 stations with data in the period 2001–2015



PERSIANN grid with data in the period 2001–2015

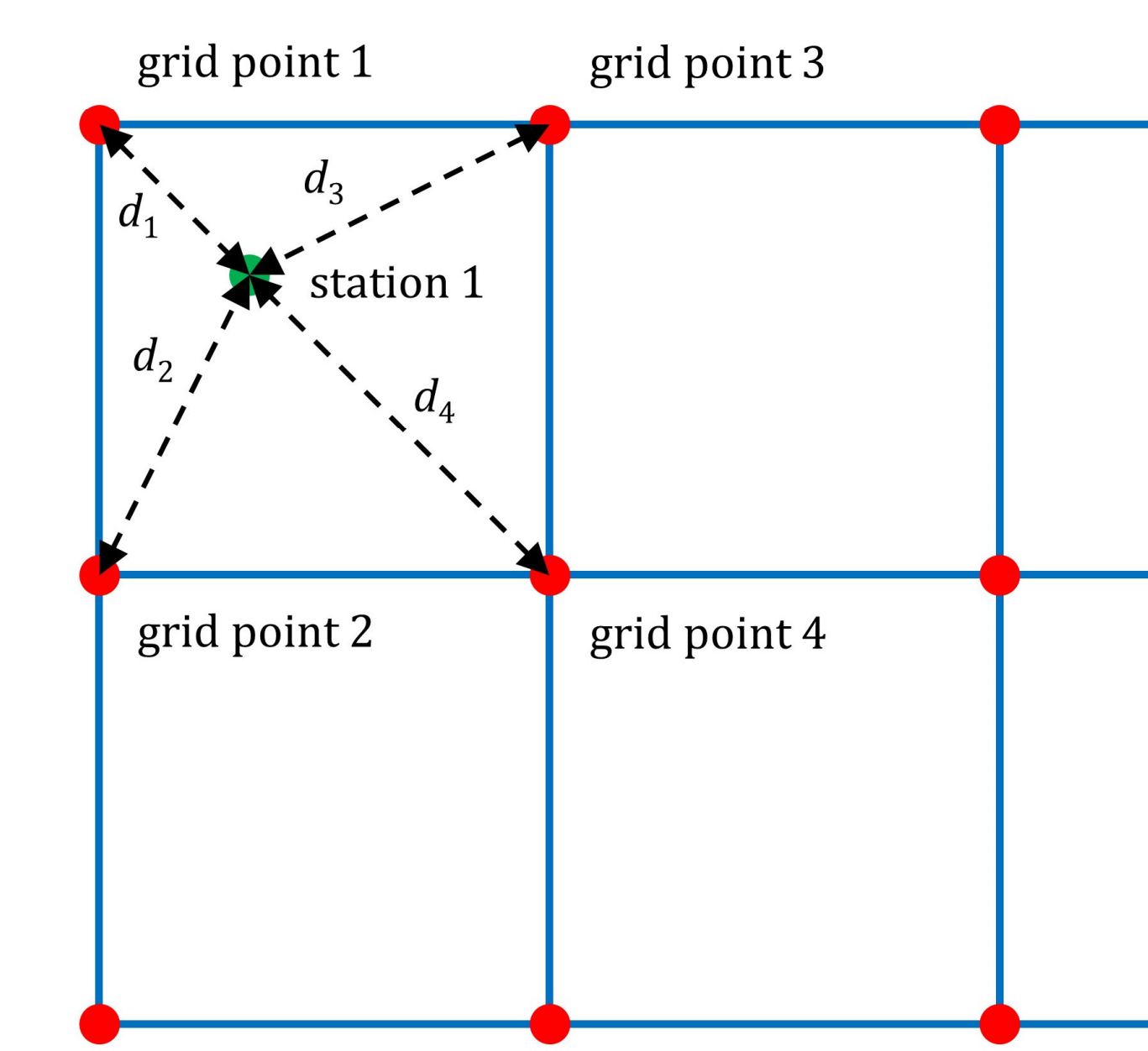


IMERG grid with data in the period 2001–2015

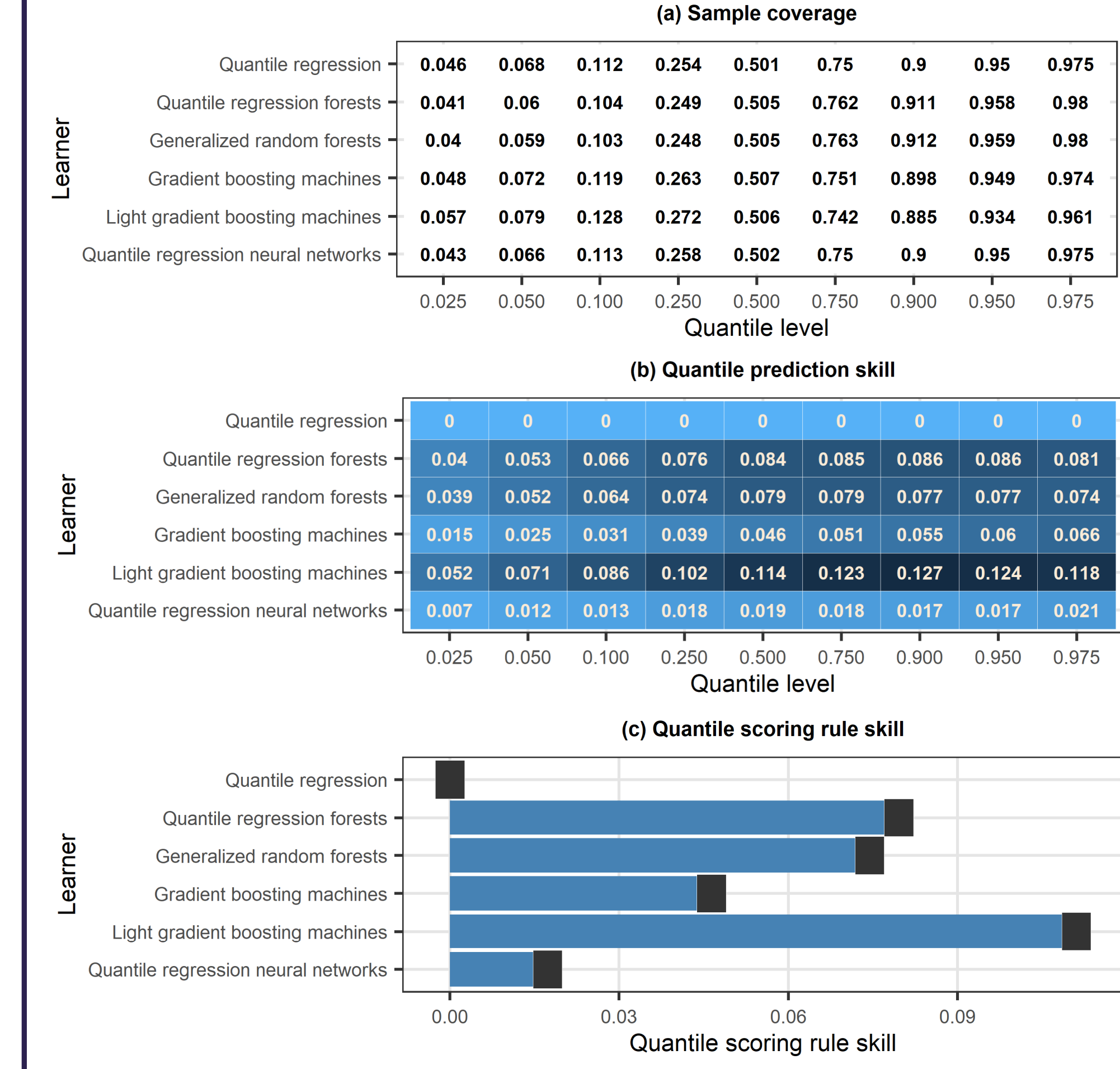


## 4. Spatial interpolation problem formulation

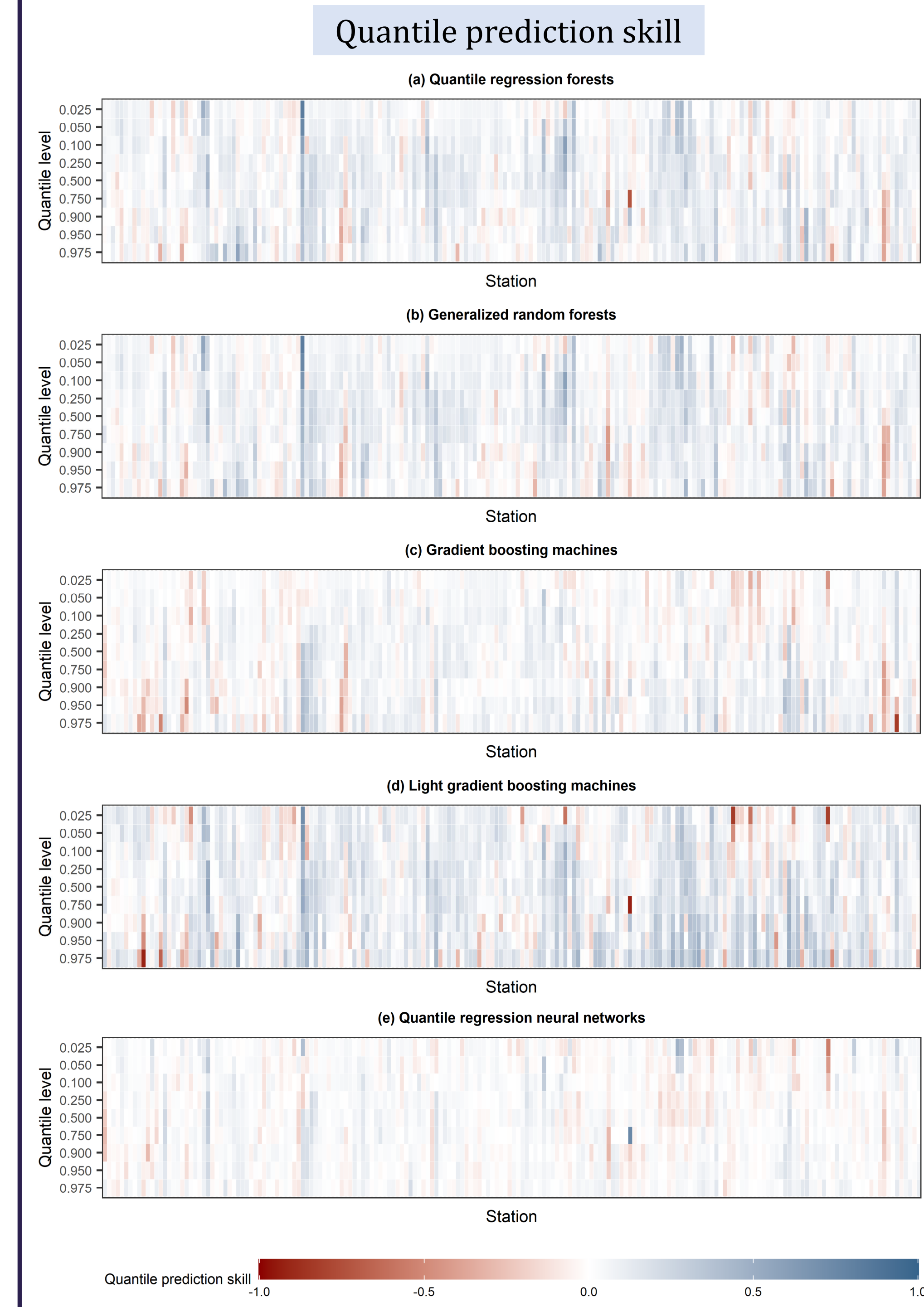
Satellite data grid	Gauge station
Distance, $d_i, i = 1, 2, 3, 4$	$d_1 < d_2 < d_3 < d_4$



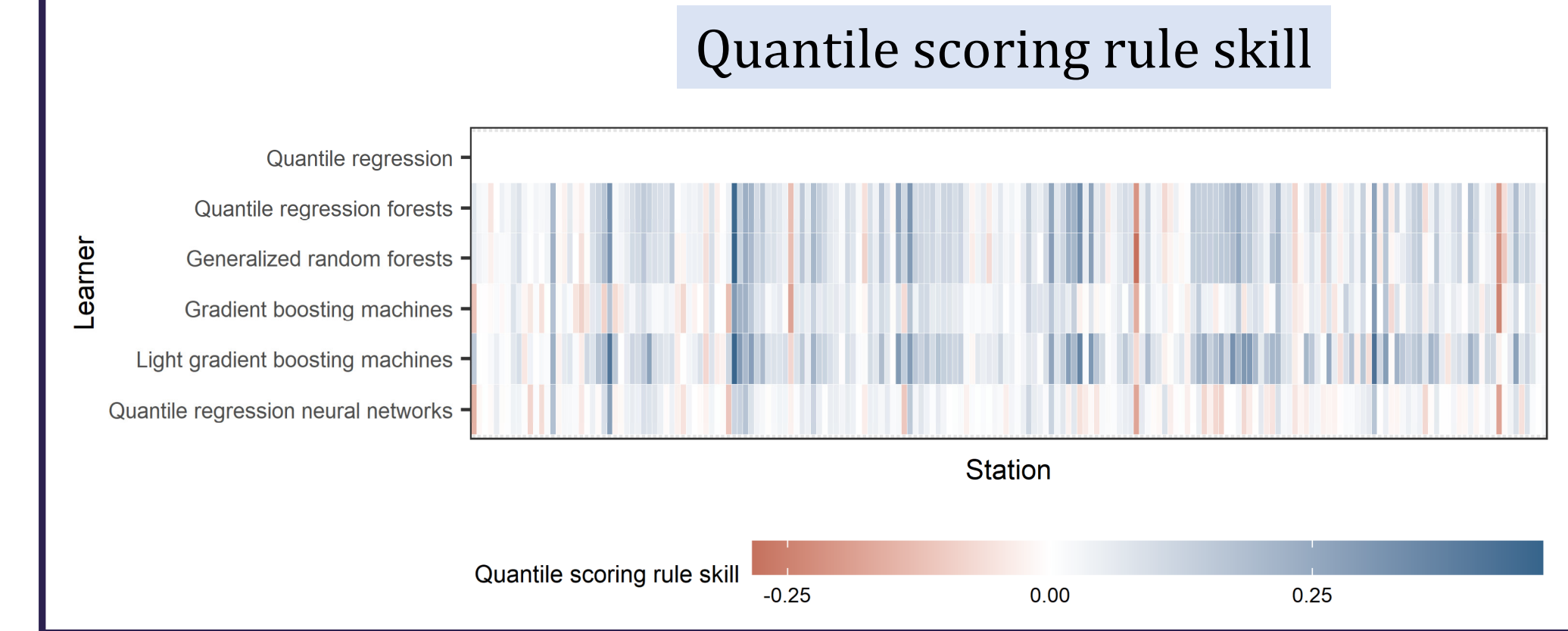
## 5. Comparison of machine learning algorithms



## 6. Type-1 investigations across stations



## 7. Type-2 investigations across stations



## 8. Summary of findings

- Light gradient boosting machines have the best performance.
- The remaining algorithms can be ordered from the best to the worst as follows: quantile regression forests, generalized random forests, gradient boosting machines, quantile regression neural networks and quantile regression.

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