

A Reduced Ordel Model for Aerosol Coagulation

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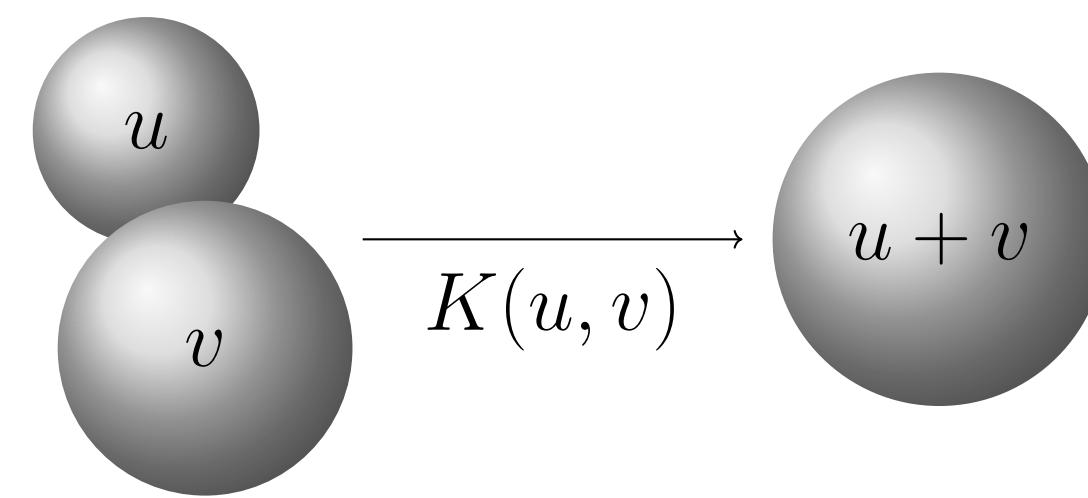
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Coagulation

Coagulation is a process affecting the size distribution of particles, describing the rate of collisions of particles and the formation of larger particles over time.

It behaves **non-linearly** and **non-locally** [Smo16], leading to prohibitive computational demands for high-resolution simulations.



$$\frac{\partial n}{\partial t}(v, t) = \frac{1}{2} \int_0^v K(u, v-u) n(u, t) n(v-u, t) du - n(v, t) \int_0^\infty K(v, u) n(u, t) du \quad (1)$$

Relevance to many domains of physics

Coagulation is involved in many types of interacting particle systems, such as

- Atmospheric aerosol and air quality [SP16]
- Cloud droplets [CS98]
- Polymerization in colloidal systems [Ada95]
- Protoplanet accretion [Cha43]

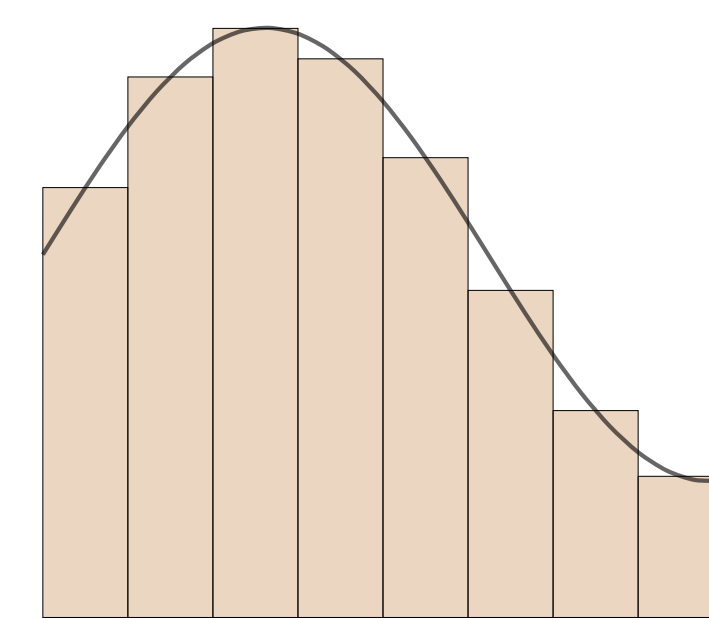
Full order model

Let $E = \text{Span}\{\phi_1, \dots, \phi_N\}$ a reference approximation subspace, for instance a finite element approximation supported on a fine mesh.

Let $\tilde{n}(v, t) = \sum_{i=1}^N \phi_i(v) \tilde{x}_i(t)$ the approximation of (1) in E .

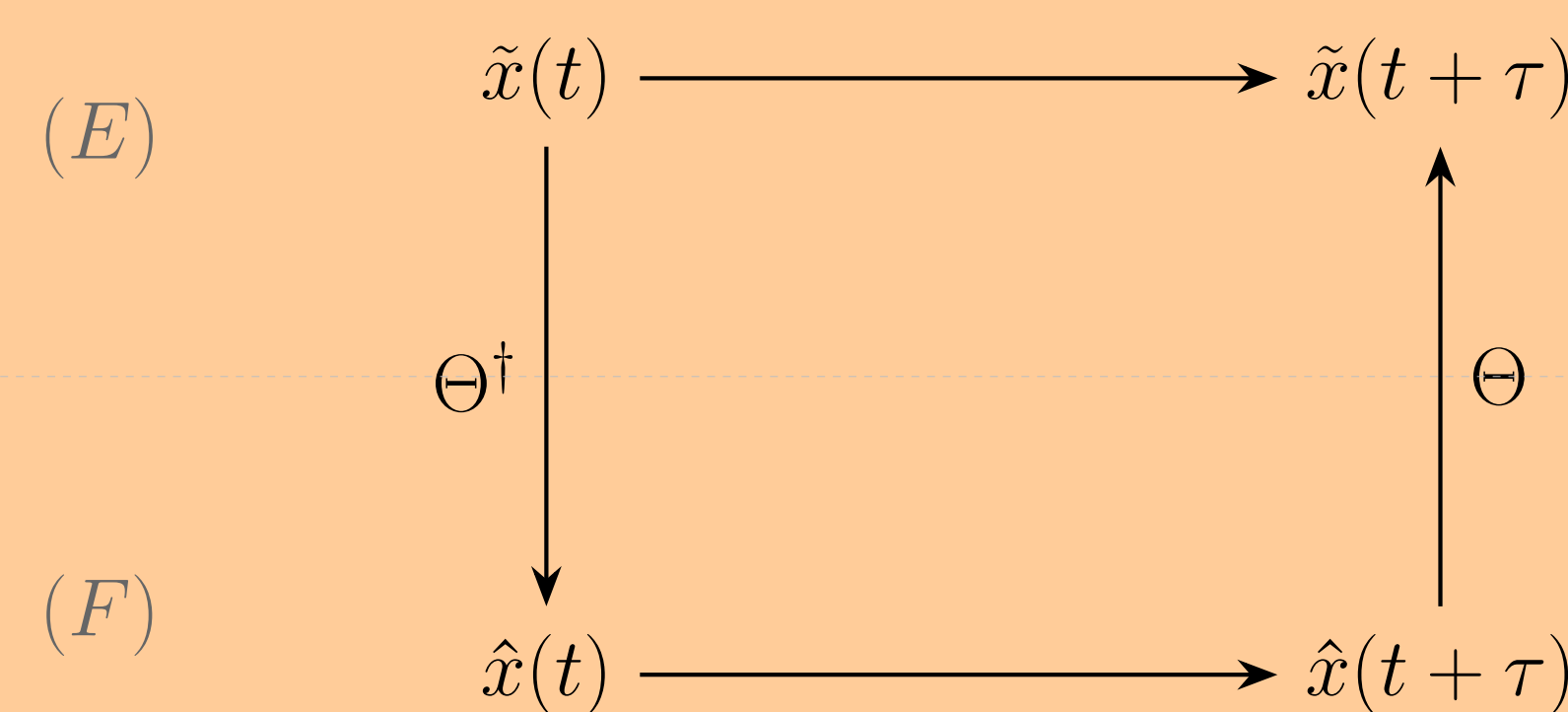
We are interested in the solution set \mathcal{S} corresponding to a given a set of initial conditions \mathcal{X}_0

$$\mathcal{S} = \{\tilde{n}(v, t) \mid \tilde{n}(v, 0) \in \mathcal{X}_0\} \quad (2)$$



Model order reduction

Our goal is to find a subspace F with reduced dimension such that \mathcal{S} is well approximated, but time-evolution in F can be performed at a lower cost.



Let $F = \text{Span}\{\varphi_1, \dots, \varphi_R\} \subset E$ with $\varphi = \phi\Theta$, with $\Theta \in \mathbb{R}^N$. We are looking for the optimal Θ such that $\|\tilde{n} - \hat{n}\|_2$ is minimized.

Identification of a suitable subspace

Singular Value Decomposition (SVD) :

$$M \in \mathbb{R}^{p \times q} = U \in \mathbb{R}^{p \times q} \Sigma \in \mathbb{R}^{q \times q} V^T \in \mathbb{R}^{q \times q}$$

The truncated SVD up to rank R provides the optimal R dimensional approximation in a least square sense.

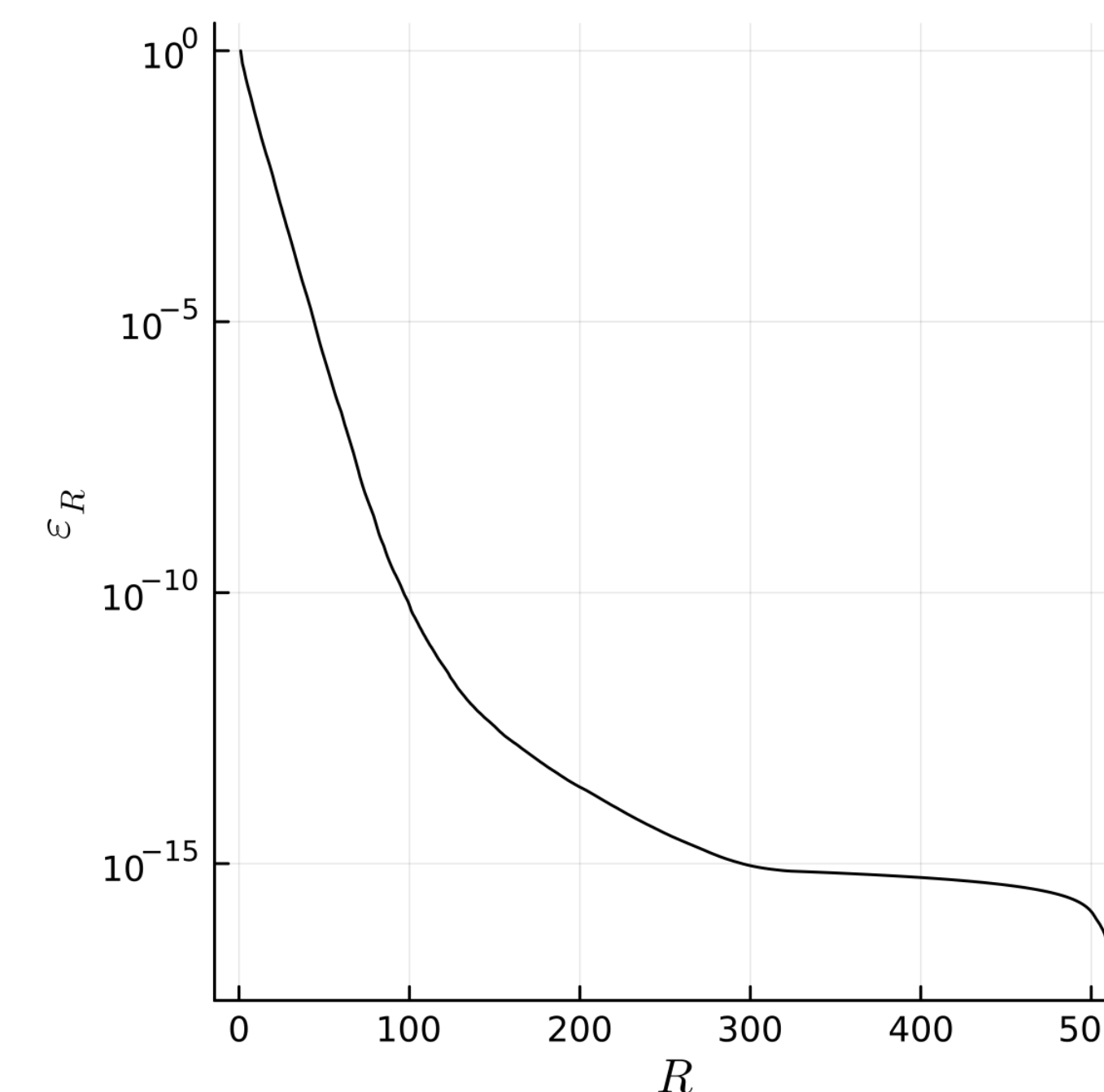


Figure 1. L^2 error associated with rank- R approximation of \mathcal{S} .

Reduction of the time-evolution operator

The time-evolution operator for the ROM can be precomputed *offline* such that the *online* cost scales only with R , independently of N .

$$\text{Full order model} \quad \left[\frac{\partial \tilde{x}}{\partial t} \right]_i = \sum_{j,k=1}^N \tilde{\chi}_{ijk} \tilde{x}_j \tilde{x}_k \quad (3)$$

$$\text{Reduced order model} \quad \left[\frac{\partial \hat{x}}{\partial t} \right]_i = \sum_{j,k=1}^R \hat{\chi}_{ijk} \hat{x}_j \hat{x}_k \quad (4)$$

with precomputed tensors

$$\tilde{\chi}_{ijk} = \sum_{i'=1}^N [g_\phi^{-1}]_{i,i'} \langle \phi_{i'}, \mathcal{B}[\phi_j, \phi_k] \rangle \quad \tilde{\chi} \in \mathbb{R}^{N \times N \times N} \quad (5)$$

$$\hat{\chi}_{ijk} = \sum_{i'=1}^R [g_\varphi^{-1}]_{i,i'} \langle \varphi_{i'}, \mathcal{B}[\varphi_j, \varphi_k] \rangle \quad \hat{\chi} \in \mathbb{R}^{R \times R \times R} \quad (6)$$

Mass-conservation

Mass conservation can be casted as an orthogonality condition :

$$M(t) = \int_0^\infty v n(v, t) dv \quad (7)$$

$$\frac{dM}{dt} = \int_0^\infty v \frac{\partial n}{\partial t}(v, t) dv = \left\langle v, \frac{\partial n}{\partial t} \right\rangle = 0 \quad (8)$$

A sufficient condition for mass conservation is that $v \mapsto v \in F$. Classical reduction does not lead to a mass conservative ROM. However, it can always be enforced from a non conservative one, at the cost of one extra degree of freedom.

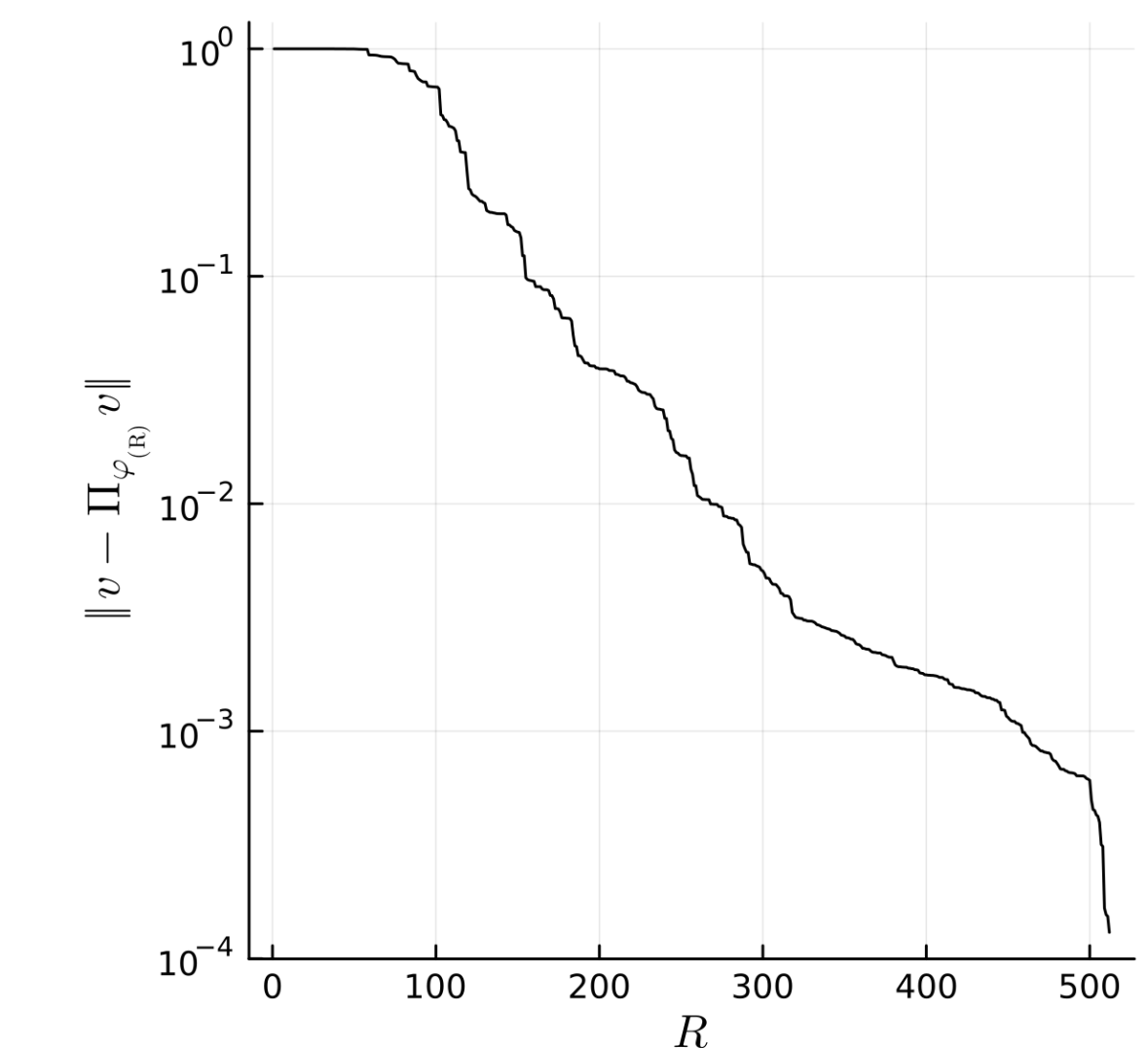


Figure 2. Projection error associated to mass imbalance

Certification through *a posteriori* error estimates

Quality of the ROM outputs can be certified by using *a posteriori* error estimates [HRS16]. The norm of the residual between the dynamics projected on E and F can be computed from the knowledge of \hat{x} only, at a cost independent of N .

$$\hat{r}[\hat{n}](v) = \Pi_E \mathcal{B}[\hat{n}, \hat{n}](v) - \Pi_F \mathcal{B}[\hat{n}, \hat{n}](v) \quad (9)$$

$$R = \|\hat{r}\| = \left(\sum_{i,j,k,l=1}^R \Delta_{ijkl} \hat{x}_i \hat{x}_j \hat{x}_k \hat{x}_l \right)^{1/2} \quad (10)$$

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