



Sensitivity of grounding-line migration to ice-shelf pinning

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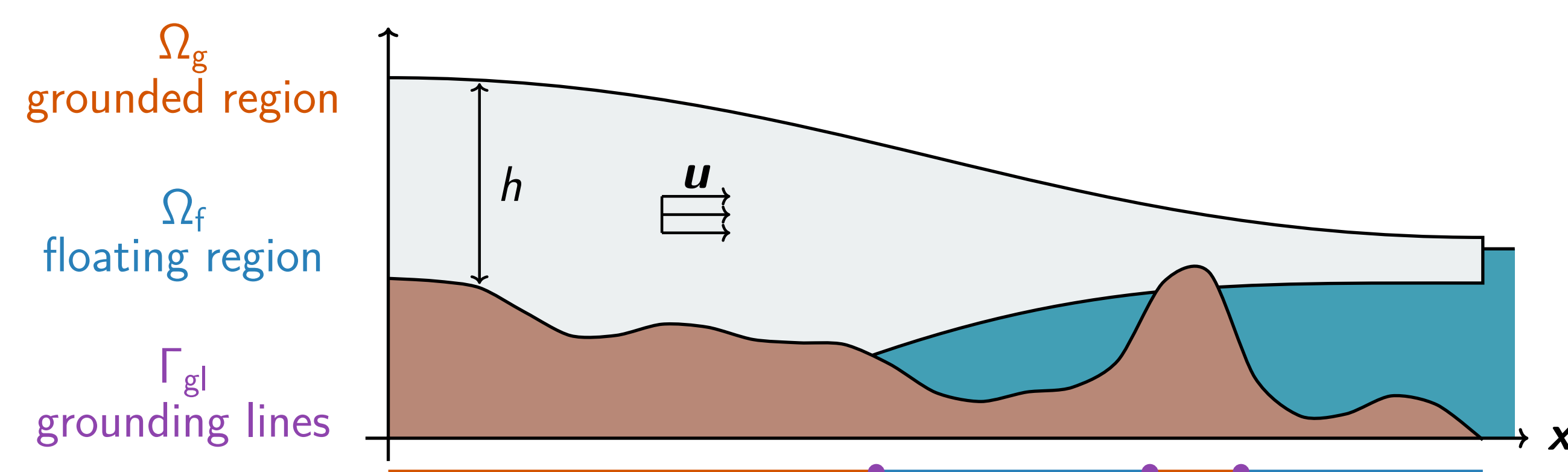
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Motivation

Pinning points –**bedrock features** that can **locally ground the floating ice**– can **stabilize ice shelves** by providing resistance to flow. However, recent observations indicate a progressive unpinning of Antarctic ice shelves, which may accelerate ice loss (Miles and Bingham, 2024). While **numerical** studies have explored their impact (e.g., Favier and Pattyn, 2015; Rydt and Gudmundsson, 2016; Henry et al., 2022), **theoretical** frameworks often neglect pinning dynamics (e.g., Schoof, 2007; Pegler, 2018). Here, we examine their effect on ice-sheet dynamics to **bridge this gap** and in particular assess the **well-posedness of models**.

Ice-flow model

Shallow-shelf approximation for isothermal marine ice sheets (Morland, 1987; MacAyeal, 1989): find $(h, \mathbf{u})$ that obey the following equations:



Mass balance:

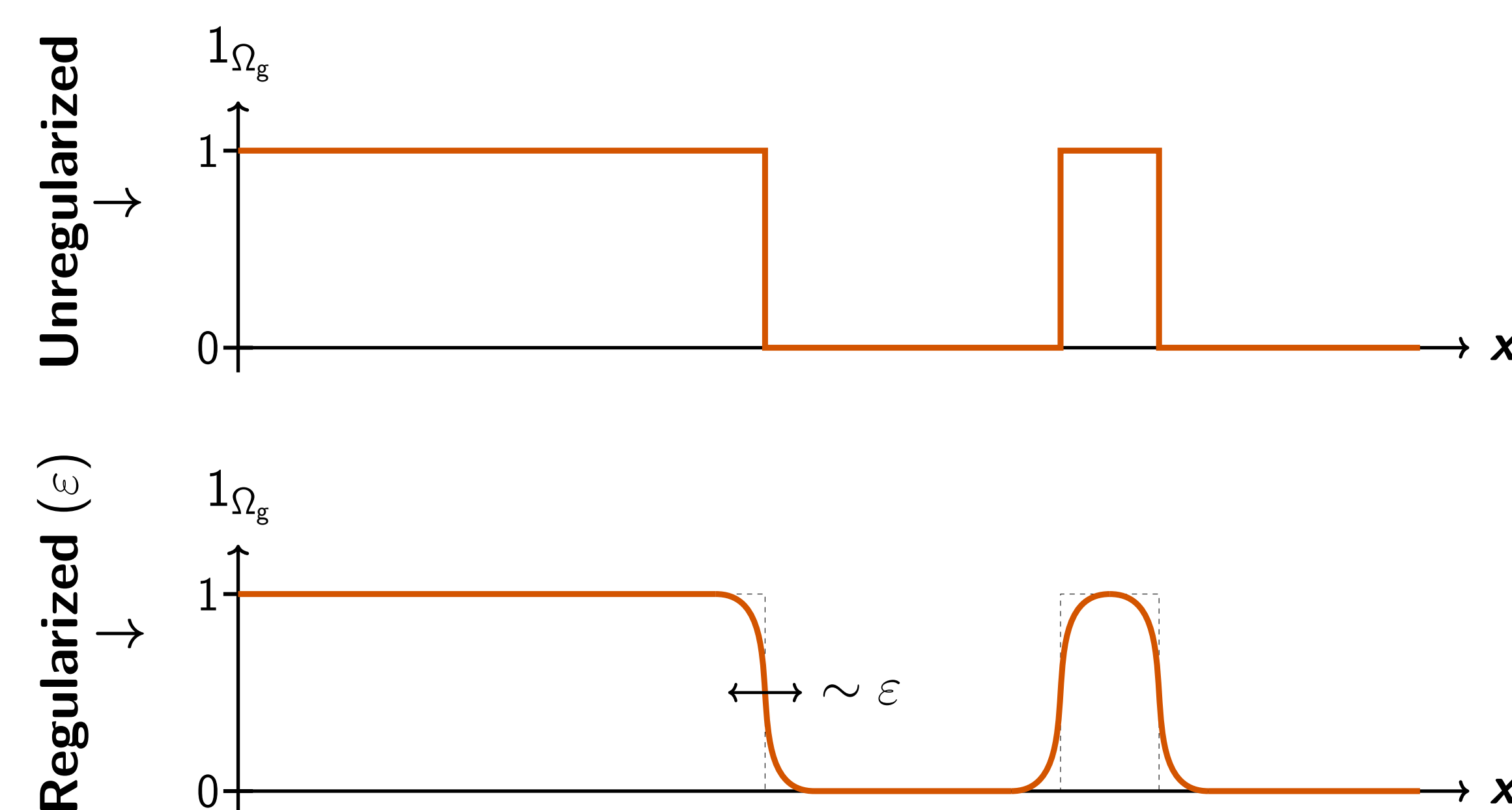
$$\partial_t h + \nabla \cdot (h \mathbf{u}) = a \quad \text{in } \Omega \quad (1)$$

Momentum balance:

$$\begin{cases} \nabla \cdot [2h \eta(\mathbf{u}) \Sigma(\mathbf{u})] + \tau_b = \tau_g & \text{in } \Omega_g \\ \nabla \cdot [2h \eta(\mathbf{u}) \Sigma(\mathbf{u})] = \tau_f & \text{in } \Omega_f \end{cases} \quad (2a)$$

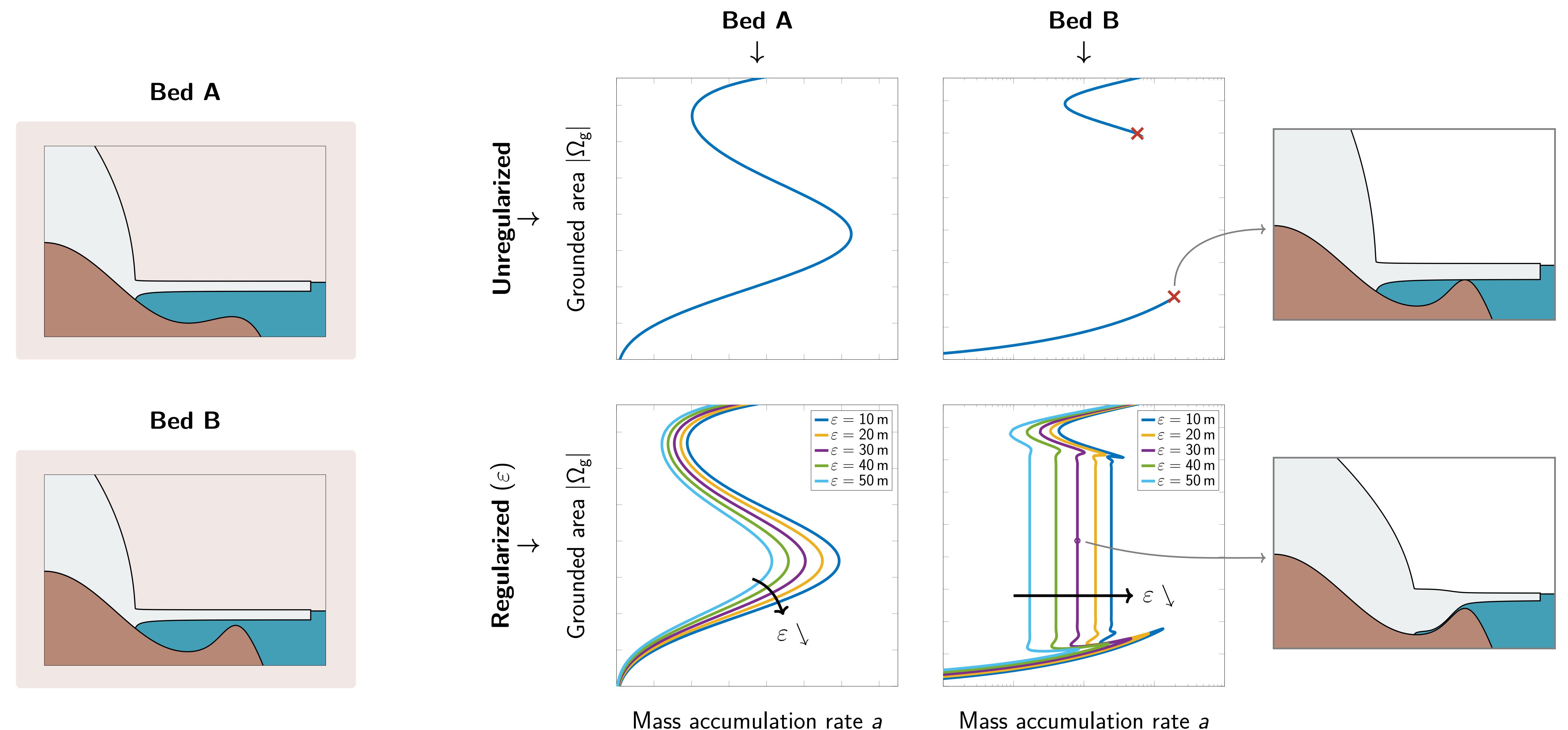
$$\nabla \cdot [2h \eta(\mathbf{u}) \Sigma(\mathbf{u})] = \tau_f \quad \text{in } \Omega \quad (2b)$$

$$\nabla \cdot [2h \eta(\mathbf{u}) \Sigma(\mathbf{u})] + 1_{\Omega_g} \tau_b = 1_{\Omega_g} \tau_g + 1_{\Omega_f} \tau_f \quad \text{in } \Omega \quad (2^*)$$



The equations (1)–(2) are written in a weak form and then discretized with the **finite-element method**. An appropriate quadrature rule is performed for the elements that contain both grounded and floating areas (Seroussi et al., 2014).

Numerical experiments: bifurcation plots



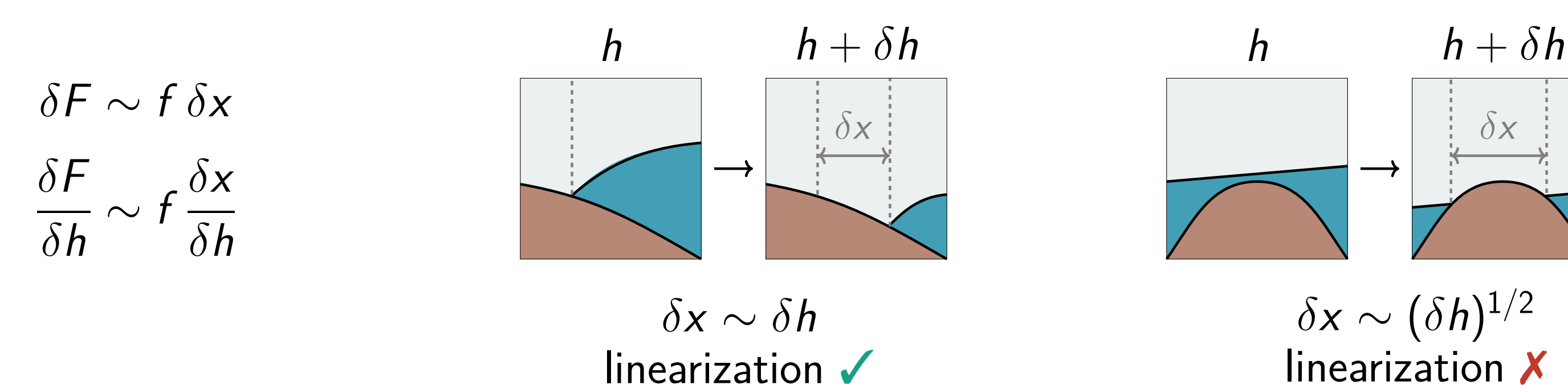
To better understand the impact of pinning points, we perform a series of numerical experiments on idealized set-ups. We consider two synthetic 2D bed geometries (**bed A/bed B**) and compute the associated bifurcation plots, which represent the set of **steady states** as a function of a . These plots are obtained for the two formulations (**unregularized/regularized**). To generate the bifurcation plots, we employ **numerical continuation** methods (e.g., Keller, 1977; Mulder et al., 2018).

Anatomy of a singularity

The weak form involves integrals over Ω_g and Ω_f .

Reynolds' theorem:

$$F(h) = \int_{\Omega_g(h)} f(h) d\Omega \Rightarrow \delta F = \underbrace{\int_{\Omega_g(h)} f(h + \delta h) d\Omega}_{\text{fixed domain}} + \underbrace{\int_{\Omega_g(h+\delta h)} f(h) d\Omega}_{\text{moving domain}}$$



Ingredient for singularity: $f \neq 0 \Rightarrow \tau_b \neq 0$ or $\tau_g \neq \tau_f$ at Γ_{gl} .

Here, the inequality $\tau_g \neq \tau_f$ is associated with a discontinuous upper-surface slope. Essentially, this stems from the assumption of a vertical cryostatic equilibrium in the momentum balance (see Schoof, 2011).

Take-home messages

Singularity:

- associated with pinning points
- due to geometry/momentum-balance coupling
- persists for smooth beds and vanishing friction

Practically:

- increased numerical sensitivity (Δx and Δt)
- regularization $\rightarrow$ nonphysical solutions
- regularization $\rightarrow$ strong dependency on ε

Perspectives:

- non-smooth method (e.g., contact approach)
- novel model (e.g., 'grounding zone')
- higher-order ice flow (full Stokes)