Visibility Prediction Study in China Based on Chemistry Weather Coupling Model

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Introduction

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IRST TIME

Low visibility (VIS) events, as typical disastrous weather, have great impacts on traffic and transportation, aircraft, and people's daily lives. Although the overall PM_{2.5} concentration in China has declined in recent years, large-scale low visibility events (LVEs) closely related to haze/fog pollution still occur occasionally. Timely and accurate low visibility predictions are urgently needed and meaningful.

A reasonable atmospheric extinction algorithm in the atmospheric chemistry model is the basis for quantitatively predicting low visibility. The original IMPROVE atmospheric extinction algorithm (OIMP) in the chemistry-weather (CW) interacted model CMA_Meso5.1/CUACE CW shows reasonable performance in visibility modeling in general but tends to overestimate the extremely low visibility (VIS <3km) under high relative humidity (RH) and light PM_{25} conditions.

Incorporating the revised IMPROVE atmospheric extinction algorithm (RIMP) into the CMA_Meso5.1/CUACE CW model to improve the prediction of low visibility in eastern China

Atmospheric Extinction Algorithm: IMPROVE

OIMP

 $b_{ext} = 3f(RH)[SF] + 3f(RH)[NI] + 4[OM] + 10[EC] + [Soils] + 0.6[CM] + b_{rayleigh}$

RIMP

 $\boldsymbol{b_{ext}} = 2.2f_s(RH)[Small SF] + 4.8f_L(RH)[Large SF] + 2.4f_s(RH)[Small NI] +$ $5.1f_L(RH)[Large NI] + 2.8[Small OM] + 6.1[Large OM] + 10[EC] + 0.6[CM] +$ $1.7f_{ss}(RH)[SS] + [Soils] + 0.33[NO_2(ppb)] + b_{rayleigh}$

Note. [SF], [NI], [OM], [EC], [SD], and [CM] represent sulfate, nitrate, organic carbon, elemental carbon, soil dust, and coarse mass concentrations ($\mu g \cdot m^{-3}$), respectively. $b_{rayleigh}$ represents Rayleigh scattering of air molecules.

Differences between RIMP and OIMP

• Develop a Split components extinction efficiency model (*Large, Small*);



Experiment Design



Fig 2. Model domain (a) and the study region (b), as well as its geographic location and topography.

Domain: 15.0° - 65.0° N, 70.0° - 145.0° E **Time:** Dec., 2016 to Feb., 2017 **Region:** Beijing-Tianjin-Hebei (**BTH**); Yangtze River Delta (**YRD**) Typical City: Beijing, Tianjin, Xingtai; Shanghai, Hangzhou, Nanjing

Dependence Relationship of VIS on RH and PM_{2.5}



Fig 3. Mean observed VIS, PM_{2.5} and RH in BTH and YRD of the three regional LVEs.



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Spatial Distribution and Hourly Changing



Fig 5. Mean observed and modeled (OIMP and RIMP) VIS in BTH and YRD of the three regional LVEs.



Fig 6. Hourly changing visibility at regional (a: BTH) and city scales (Beijing, c:Tianjin, d:Xingtai)

• RIMP reduces the VIS overestimation by OIMP in general;

• The VIS modeled by RIMP is much more consistent with observations than that by OIMP, and shows better performance at regional and city scales.

Static Evaluation

Table 1. RMSE (km) of modeled visibility levels (km) by OIMP, RIMP, and the RMSE (%) and TS changing from OIMP to RIMP

| | Scheme | RMSE of VIS | | | | |
|---------------|-------------|---------------------------------|---------------------------------|---------------------------------|--------------|--|
| ities/Regions | / Changing | $VIS \leq 3$ | $3 < VIS \le 5$ | $5 < VIS \le 10$ | $VIS \le 10$ | |
| Beijing | OIMP | 4.4 | 5.5 | 5.8 | 5.1 | |
| | RIMP | 2.7 | 3.5 | 4.1 | 3.3 | |
| | Changing of | ↓ 38.6% / ↑ | ↓ 36.4% / ↑ | ↓ 29.3% / ↓ | ↓ 35.3% | |
| | RMSE / TS | 0.27 | 0.10 | 0.01 | | |
| BTH | OIMP | 6.9 | 6.7 | 5.9 | 6.1 | |
| | RIMP | 4.3 | 4.0 | 4.5 | 3.7 | |
| | Changing of | ↓ 37.7% / ↑ | ↓ 40.3% / ↑ | \downarrow 23.7% / \uparrow | ↓ 39.3% | |
| | RMSE / TS | 0.15 | 0.21 | 0.08 | | |
| Shanghai | OIMP | 9.6 | 12.4 | 11.7 | 11.4 | |
| | RIMP | 6.1 | 5.9 | 4.2 | 5.3 | |
| | Changing of | ↓ 36.5% / 0.00 | \downarrow 52.4% / \uparrow | ↓ 64.1% / ↑ | ↓ 53.5% | |
| | RMSE / TS | | 0.15 | 0.33 | | |
| YRD - | OIMP | 11.6 | 11.1 | 8.8 | 9.0 | |
| | RIMP | 6.3 | 5.1 | 4.2 | 4.3 | |
| | Changing of | $\downarrow45.7\%$ / \uparrow | ↓ 54.1% / ↑ | ↓ 52.3% / ↑ | ↓ 52.2% | |
| | RMSE / TS | 0.01 | 0.13 | 0.33 | | |

Rivip (red) improves vis prediction compared to Onvip (blue) at regional and city scales. RMSE decreased >30%, TS increased 0.01~0.33.





Summary and Discussion

- 1. OIMP and RIMP schemes both showed reasonable performance in aerosolsinduced low VIS modeling in megacity clusters in eastern China;
- 2. The RIMP scheme cut down the overestimation of low VIS obviously and shows better capacity in low VIS prediction than the OIMP scheme;
- RIMP scheme also underestimated low VIS lower than 5 km, 3 km, or even lower VIS, showing it is not enough that only the impacts of the aerosols and its hygroscopic growth on atmosphere extinction for the accurate low VIS prediction.

NEXT STEP: An atmospheric extinction coefficient algorithm involves in full extinction factors:

• Extinction coefficients: haze (current), fog/cloud, rain, snow, graupel, and dust, etc.

 $b_{ext} = b_{ext_aero} + b_{ext_fog} + b_{ext_rain} + b_{ext_snow} + b_{ext_graupel}$

• Key factors: aerosols \Leftrightarrow fog/cloud droplets (transformation and interaction)

Table 2. Several droplet extinction algorithms.

| | parameter | | | |
|---|--|---|--|--|
| $\frac{K \cdot LWC^{f_b(N_D)}}{f_a(N_D)}$ | LWC | $f_a(N_D) = 0.242 N_D^{-0.0617} - 0.1351$ | <i>LWC</i> : liquid water content <i>N_D</i> : droplet number concentration | |
| | < 0.1 g \cdot m ⁻³ | $f_b(N_D) = -0.857 N_D^{0.0385} + 1.66$ | | |
| | LWC $> 0.1 \text{g} \cdot \text{m}^{-3}$ | $f_a(N_D) = 0.14 N_D^{-0.0226} - 0.0123$ | | |
| | | $f_b(N_D) = -0.00039 N_D^{0.7525} + 0.743$ | | |
| $\frac{K \cdot LWC^{f_b(N_D.re)}}{f_a(N_D)}$ | LWC > LWCcv $f_a(N_D) = a \cdot N_D^{-b} - c$ | | a, b, c, d, e, f are fit | |
| | LWC < LWCcv | $f_b(N_D \cdot re) = -d \cdot N_D \cdot \exp(-e \cdot r_e) + f$ | parameters. | |
| $C_k Q_{ext} n(D) \frac{1}{4} \pi D^2 \Delta D$ | physical process-based cloud extinction algorithm | | | |

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More Information

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