

1. Introduction



- Transient hydraulic tomography (THT) is the process of obtaining subsurface information from different perceptions.
- Multiple studies advocated SSLE and SimSLE geostatistical methods as best compared to other techniques in mapping the spatial distribution of aquifer parameters.
- However, the basic assumption of geostatistical methods is that the aquifer parameters follow second-order stationary stochastic Gaussian distributions.
- Fractured aquifers were found to have complex heterogeneity under multiple scales, and it is expected that the aquifer parameters do not follow Gaussian distribution.
- Hence, there is a need to test another method for THT inversion of fractured aquifers, which can effectively map the non-Gaussian distribution of aquifer parameters in fractured aquifers.
- The Gaussian mixture model is generally used to represent the complex unknown distribution as a linear combination of multiple Gaussian distributions.

2. Objectives

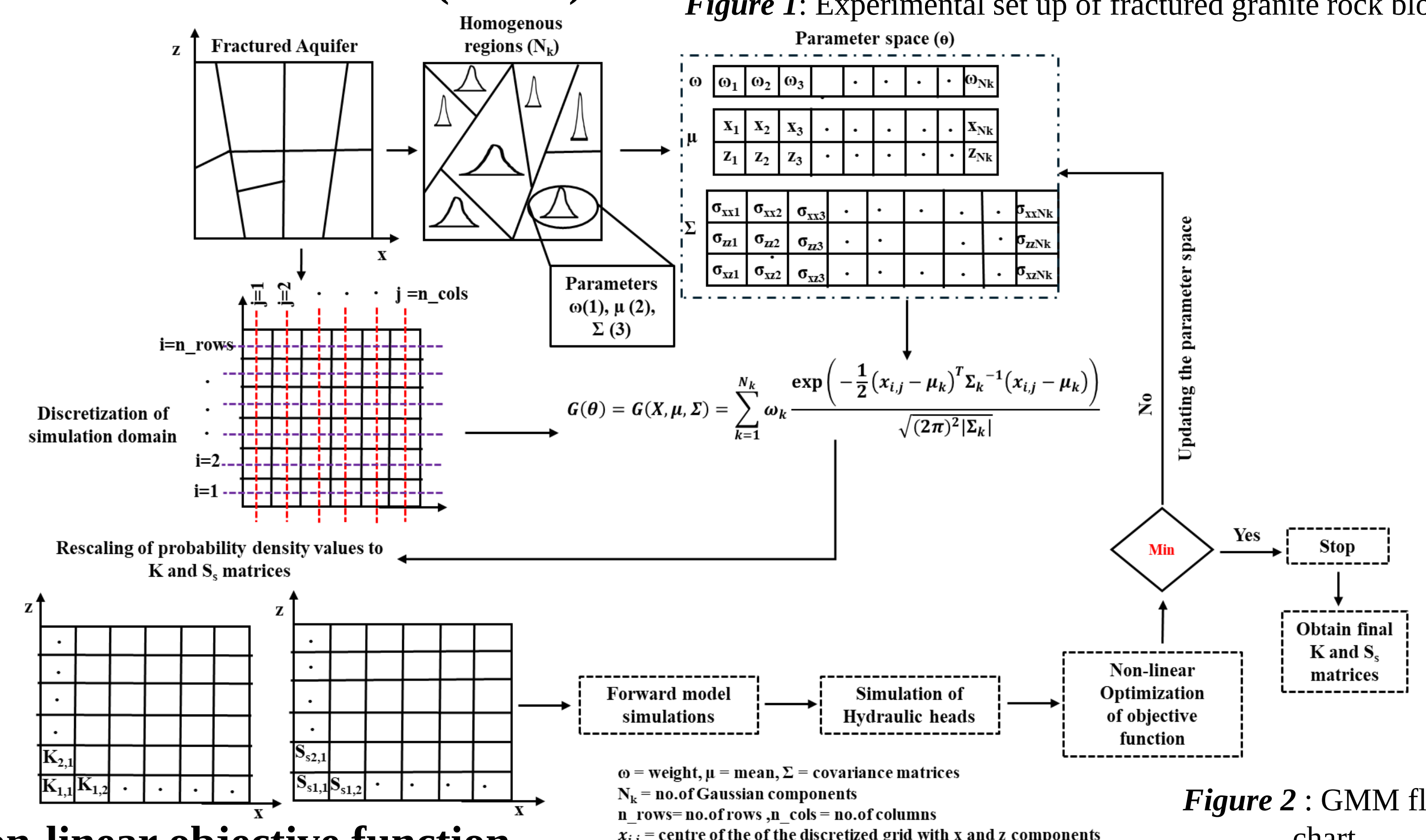


- To develop a Gaussian mixture inversion algorithm to effectively map the spatial distribution of aquifer parameters in fractured geologic settings.
- To examine the role of a number of Gaussian components on the performance of the Gaussian mixture inversion algorithm.
- To examine the influence of the selection of sampling strategy on GMM inversion of THT data.
- To study the role of pumping data quantity on the performance of GMM inversion.

Transient Hydraulic Tomography experiments

- 13 cross hole pumping experiments at a constant pumping rate of 35.71 ml/s were conducted and the hydraulic head responses were monitored at monitoring locations.
- 10 cross hole pumping data were used in the inversion process, and three were used for validation.

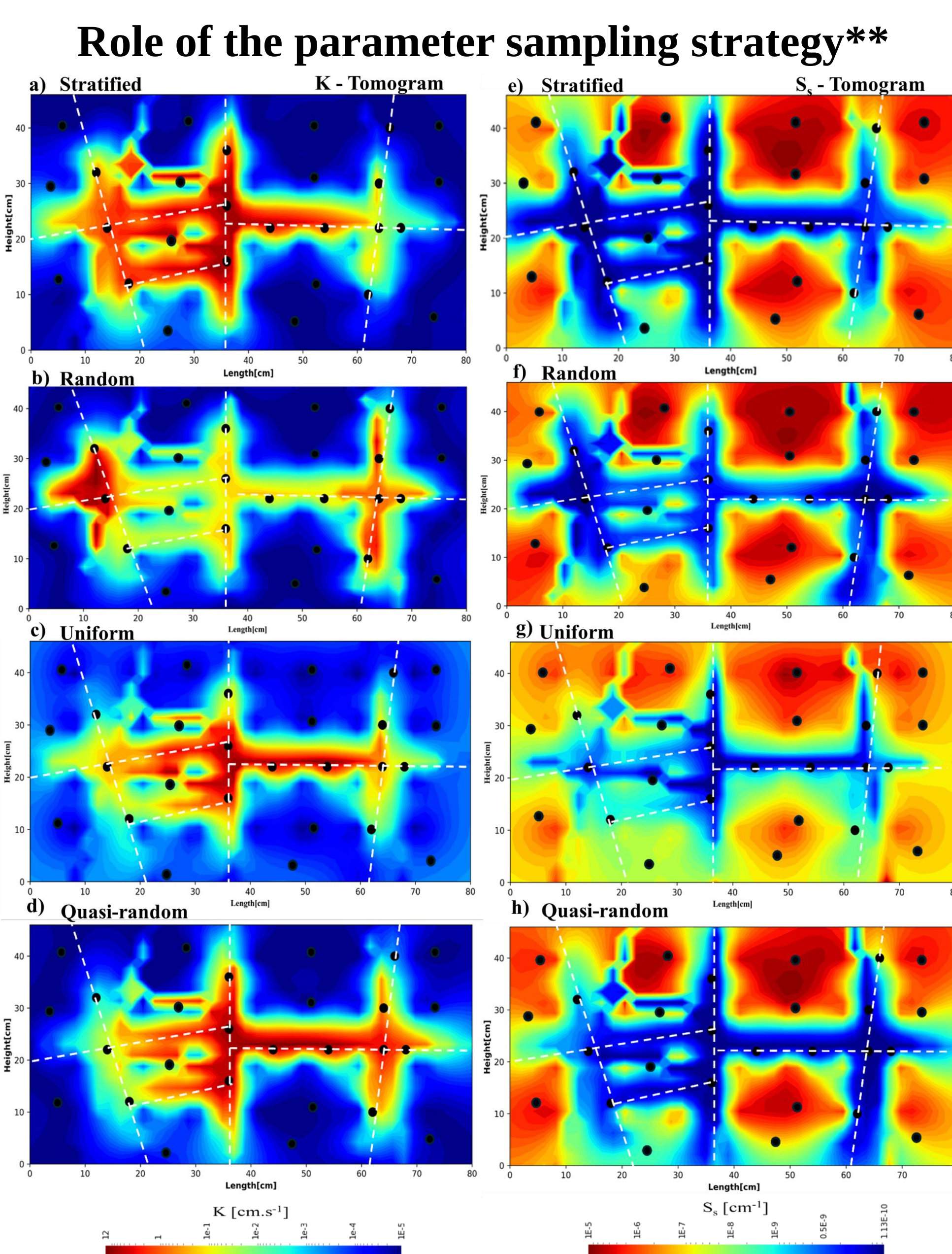
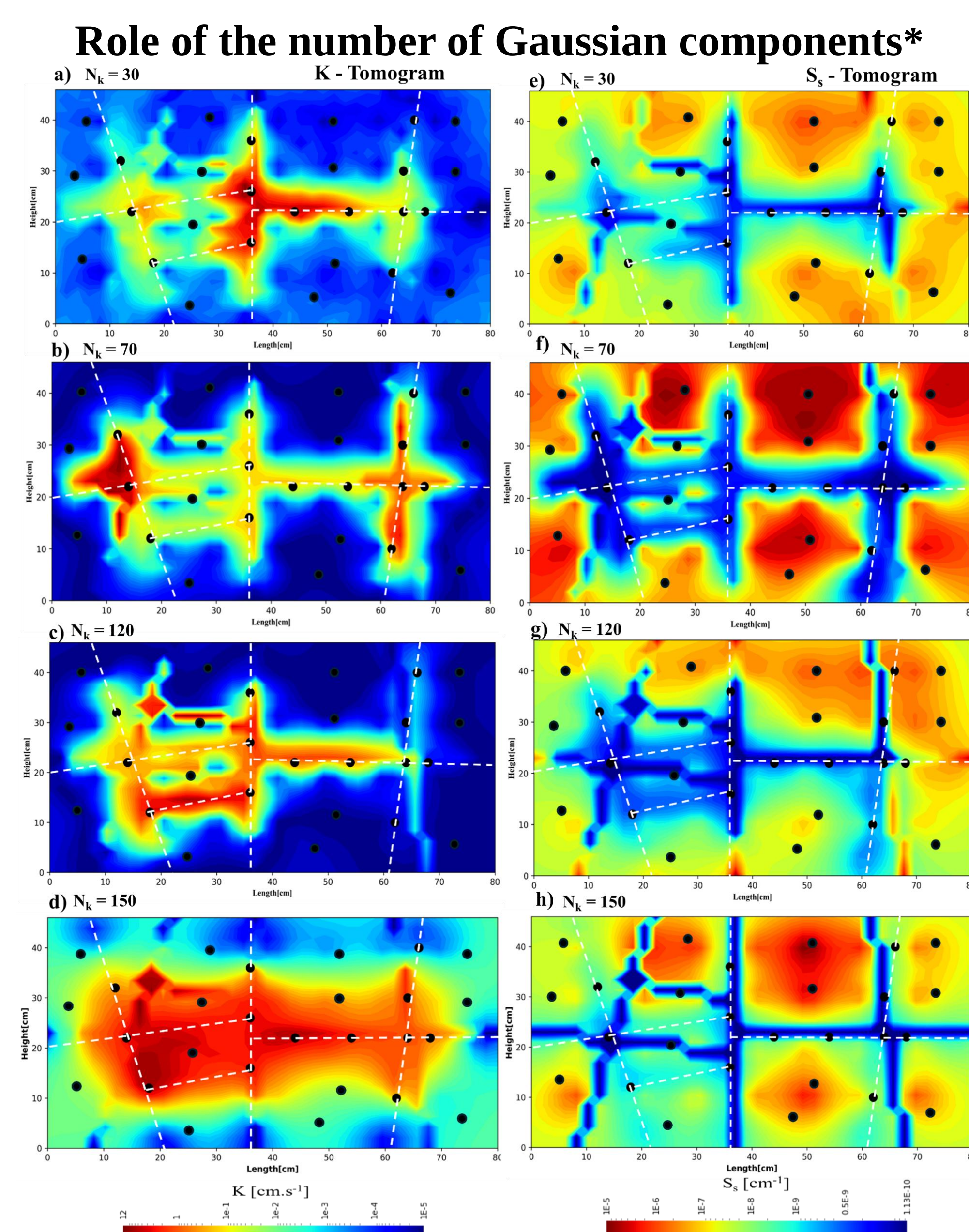
Gaussian Mixture Model (GMM)



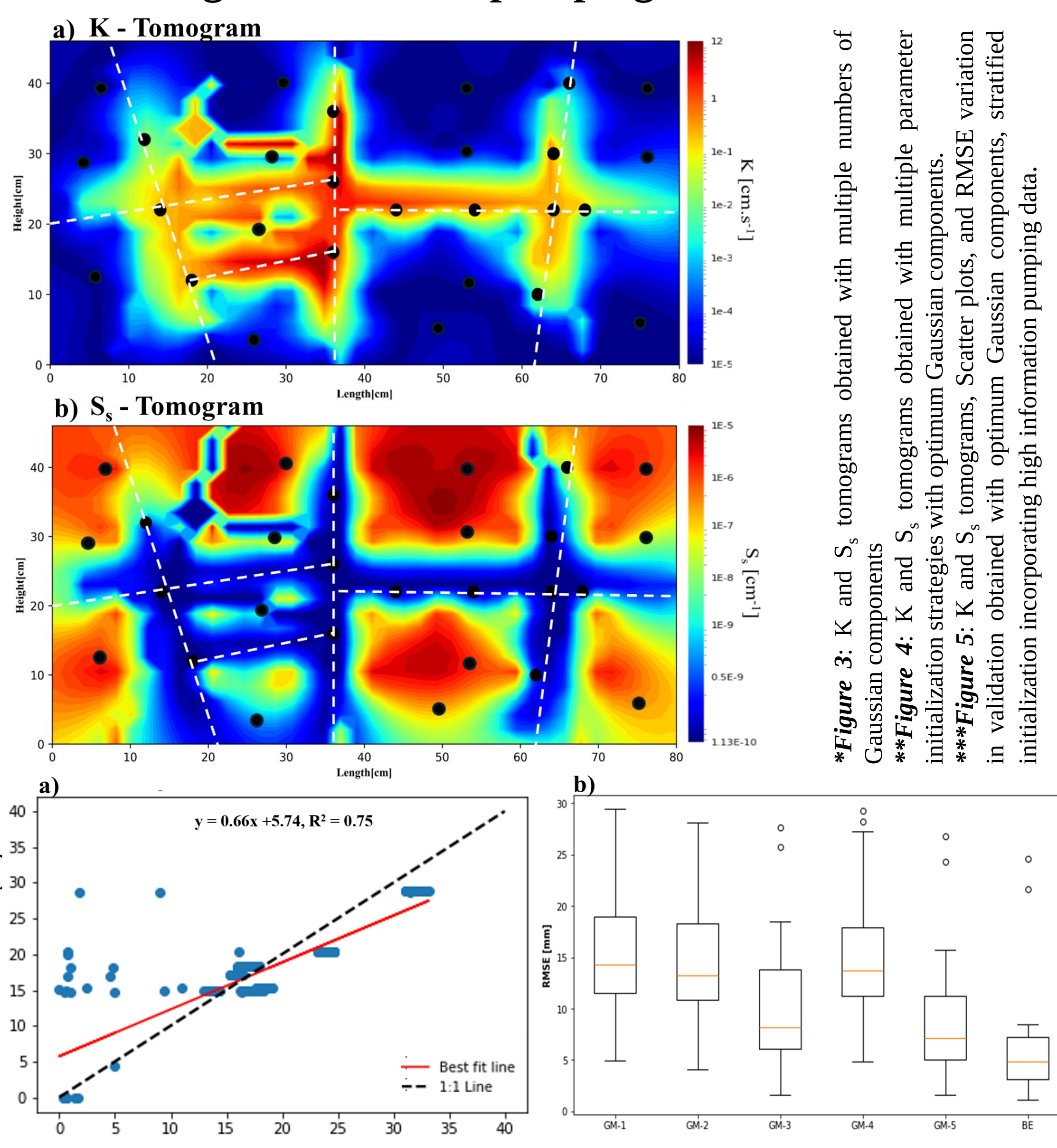
Non-linear objective function

$$F_d(\theta) = (1 - \lambda) \left[\phi_f \times \left[\sum_{i=1}^n \left[\sum_{t=1}^T (h_{it}(\theta) - h_{it}^*)^2 \right] \right] + \phi_x \times \left[\sum_{i=1}^{n-1} \left[\sum_{t=1}^T \left[\frac{dh_{it}(\theta)}{dx} - \frac{dh_{it}^*}{dx} \right]^2 \right] \right] + \phi_z \times \left[\sum_{i=1}^n \left[\sum_{t=1}^T \left[\frac{dh_{it}(\theta)}{dz} - \frac{dh_{it}^*}{dz} \right]^2 \right] \right] \right] + \lambda \times \left[\sum_{i=1}^m \left[\frac{dG(\theta)}{dx} \right]^2 + \sum_{i=1}^m \left[\frac{dG(\theta)}{dz} \right]^2 \right]$$

4. Results



Role of high information pumping data***



5. Conclusions



- The Gaussian mixture model (GMM) is successfully extended to transient hydraulic tomography on fractured geologic settings.
- The proposed sequential Gaussian mixture inversion algorithm effectively captured fracture patterns and their connectivity on the laboratory rock block.
- The performance of the sequential Gaussian mixture inversion algorithm is sensitive to the number of Gaussian components, and the parameter initialization strategy.

More About Me



Acknowledgments



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6. References



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