

ECHNISCHE UNIVERSITÄT WIEN



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Saturation area connectivity in the Hydrological Open Air Laboratory Dušan Marjanović¹, Juraj Parajka¹, Borbala Szeles¹, Camillo Ressl², Peter Strauss³, Günter Blöschl¹

Introduction and context



Downstream view of september 2024 event



Figure 1b – Upstream view of september 2024 event

- Traditional wavs surface runoff utilize rainfall event characteristics, soil characteristics, topography of the surface, as well as other hydraulic or empirical relations to predict catchment response to a rainfall event.
- accessibility to - Increased has opened cameras possibility of studying surface runoff phenomena by visual observation.
- This work presents a novel way of estimating runoff amounts and overland timings, using connectivity metrics.



Figure 2 – The HOAL experimental catchment

- This methodology is applied in Hydrological Open Air Laboratory. Which is a small (66 ha), densely instrumented experimental catchment located in Lower Austria.
- The primary instruments utilized for the study are the network camera (Sanyo 2 Megapixels VCC-HD5600 located at the weather station from 2015 – 2020), the tile drains, soil moisture sensors, discharge stations located at the inflows along the stream, as well as the main catchment outlet discharge station.
- The study period is from 2015-2020, for which there is a continuous dataset.

(1) Institute of Hydraulic Engineering and Water Resources Management, Technical University of Vienna, Austria (2) Department of Geodesy and Geoinformation, Technical University of Vienna, Austria (3) Institute for Land and Water Management Research, Federal Agency of Water Management, Austria

Contact: marjanovic@hydro.tuwien.ac.at

Hypothesis

faster and larger runoff response.

estimating

better up the flow



Figure 3 – Data overview of the first 6 months of observation Due to the angle and elevation of the camera, the selection of the events requires an unobstructed view from the camera to the observed part of the hillslope, as well as precipitation, soil moisture, and discharge measurements.

Methodology – Connectivity scale calculation

Pre-processing of camera images:



Figure 4a – Raw camera image

Figure 4b – Pre-processing results

The pre-processing of images is based on the work of Silasari et. al (2017); DOI: 10.1002/hyp.11272

Connectivity calculation:

The used spatial connectivity scale metric comes from Western et al. (2001), it is defined as following from the lag-dependent connectivity function $\tau(h)$: $\tau(h) = P(x \leftrightarrow x + h | x \in A, x + h \in G)$

Where: x is the pixel in question, h is the distance from the pixel, A is a connected patch, and G is a connected patch distinct from A. From which the connectivity scale is defined as the integral of the connectivity function – or in short **integral scale**:

$$I\tau = \int_0^h \tau(h)dh$$

Due to computational requirements, a FORTRAN module has been developed that calculates the connectivity scale.











