



A Multi-Scale Approach to Fault-Valve Systems and Their Evolution

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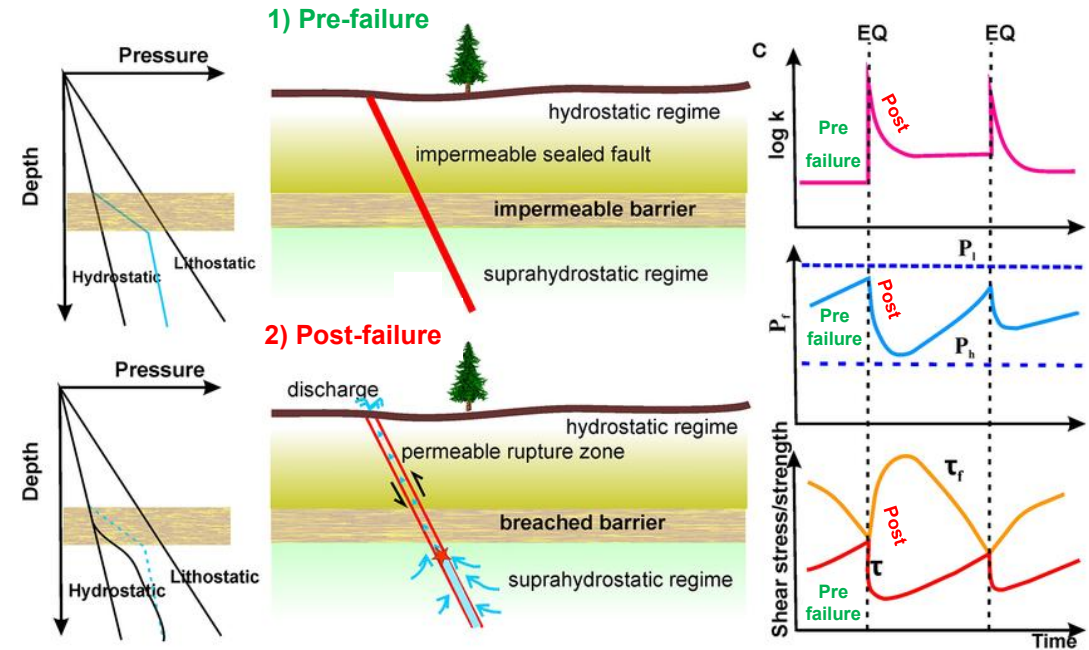


Full abstract

Faults act alternately as hydraulic barriers or conduits, reflecting the **Fault-Valve Behavior**

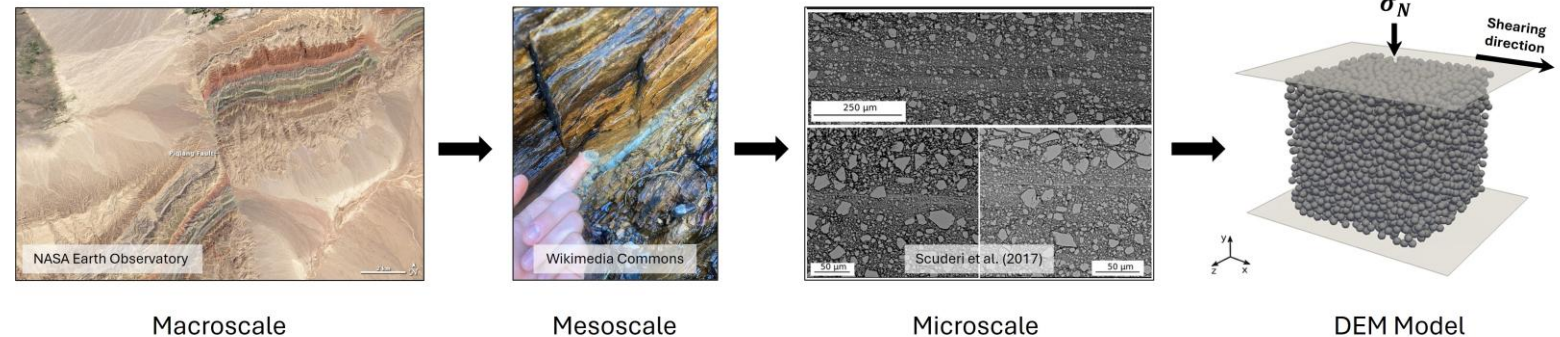
A key process in hydrothermal systems and industrial activities

Challenge : Fault reactivation involves complex permeability – strength coupling not fully captured by continuum models (Marguin & Simpson 2024, Zhu et al 2020)



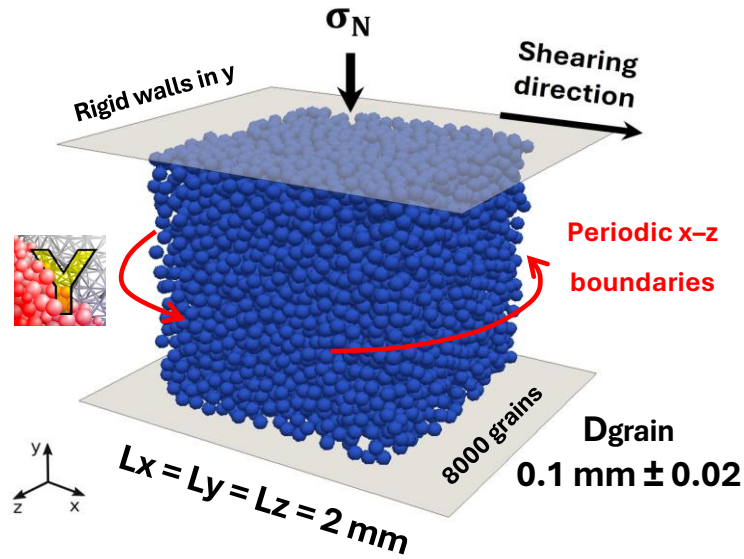
Fault Valve Schematics, **Sibson (2020)**

Proposed approach : Grain scale modeling using the **Discrete Element Method (DEM)**, to bridge micro and macro-scale behaviors



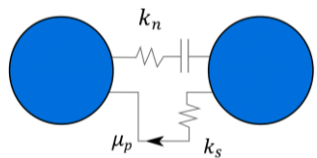
Numerical gouge set-up

We use 3D DEM formulation implemented in **Yade DEM** (<https://yade-dem.org/>)

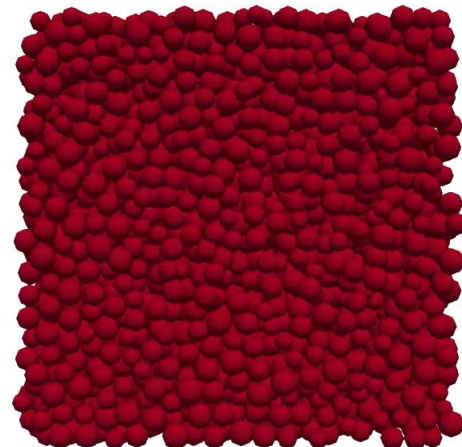


From grain-scale contacts to macroscopic friction

Linear elastic contact



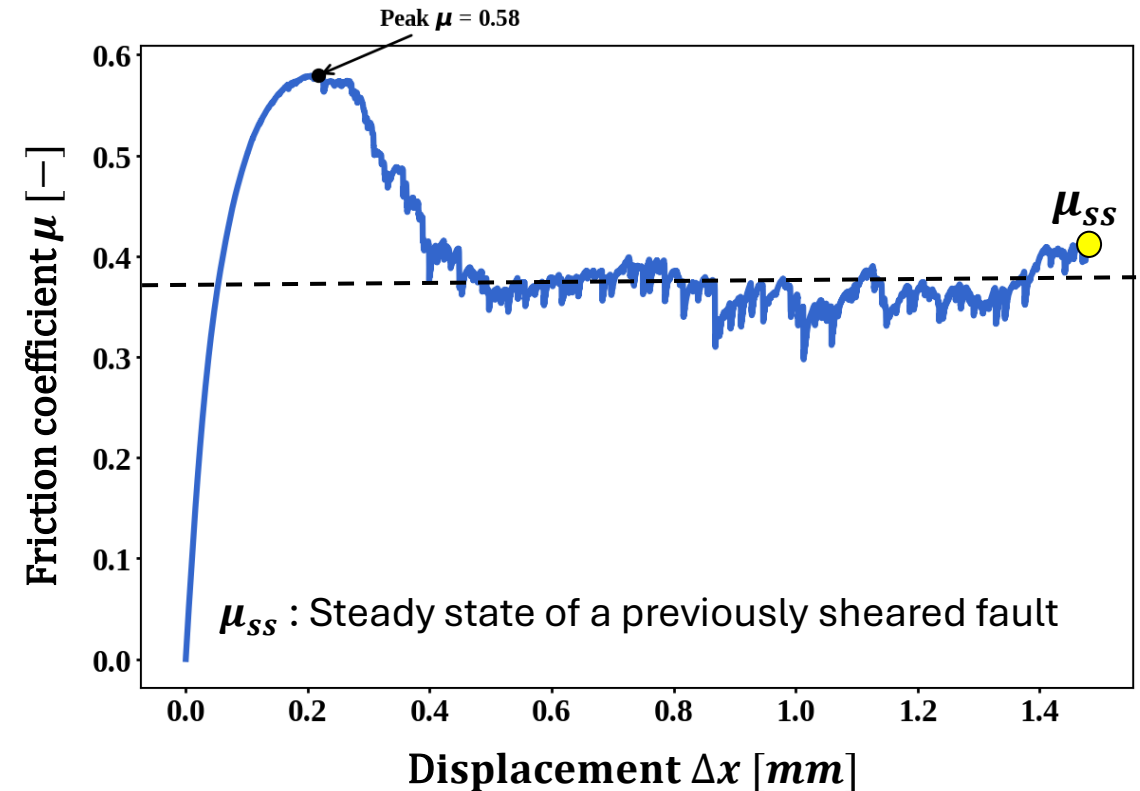
Emergent μ, G



Coulomb friction

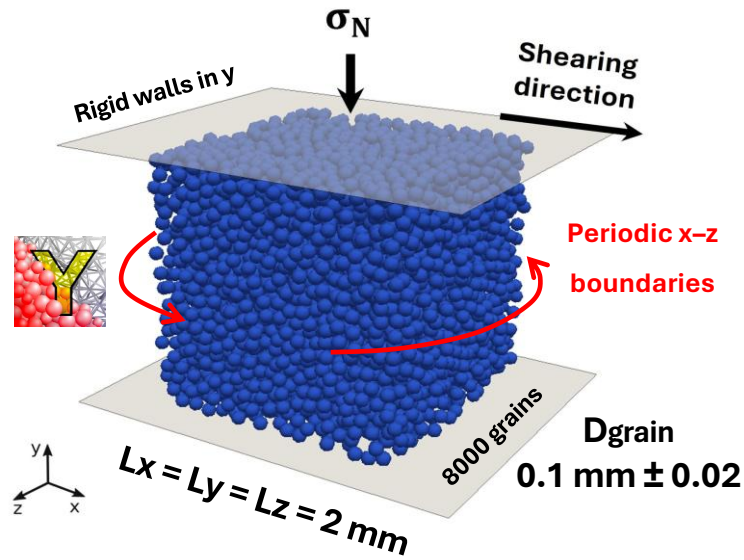
For example :

$V_x = 0.2 \text{ mm/s}$, $\sigma_n = 5 \text{ MPa}$



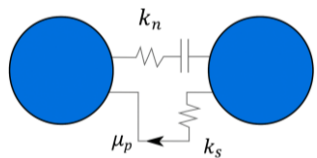
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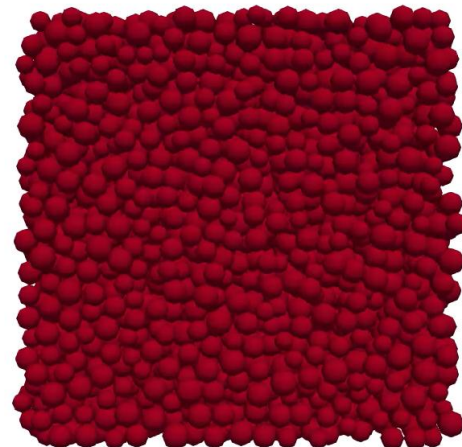


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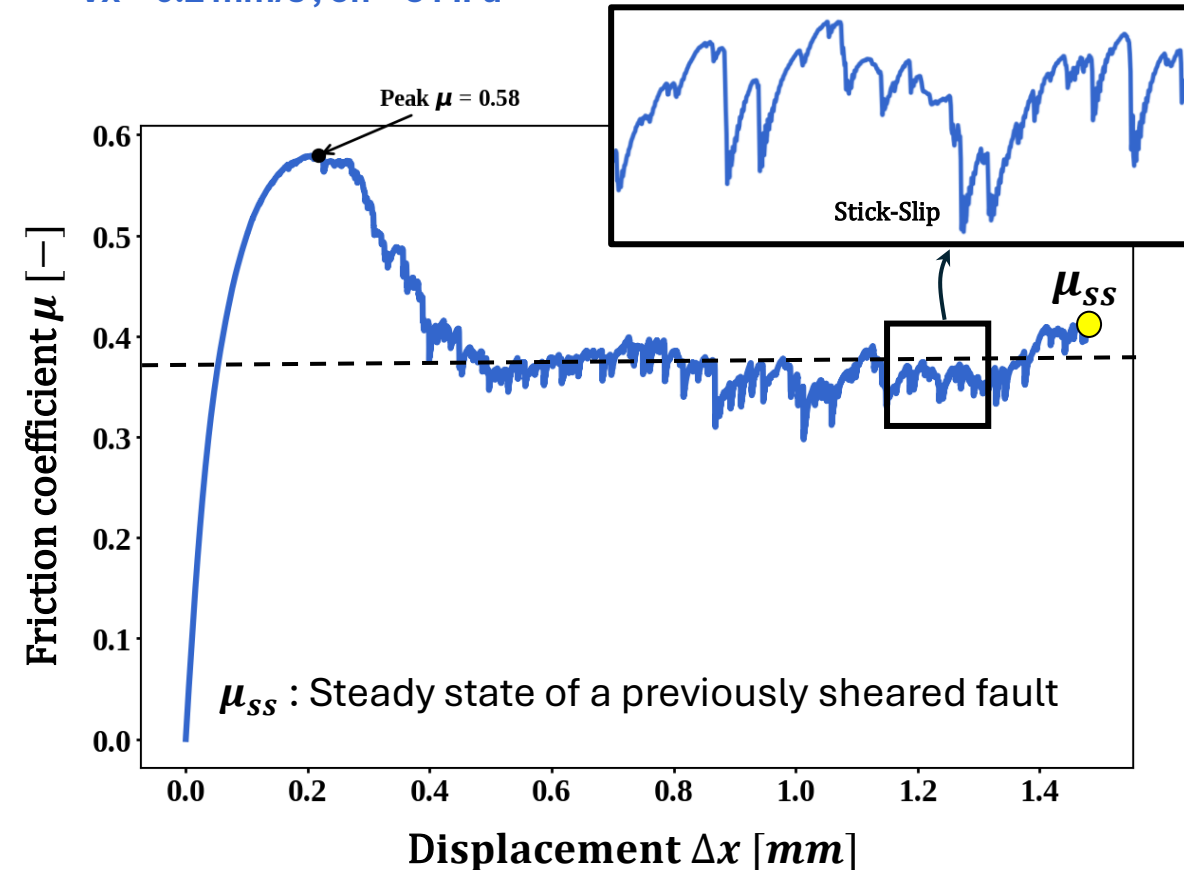
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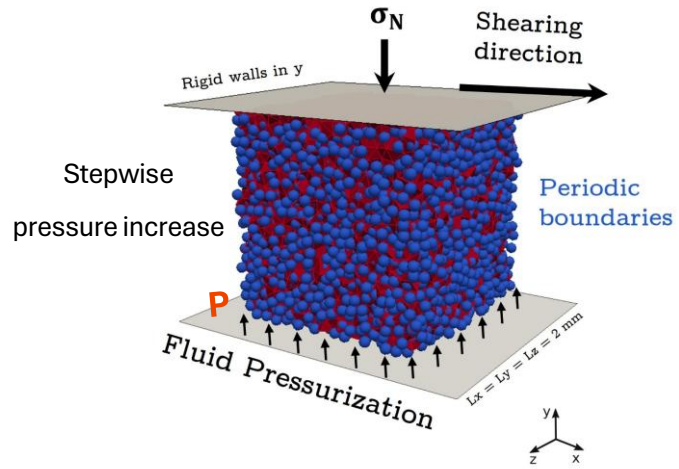
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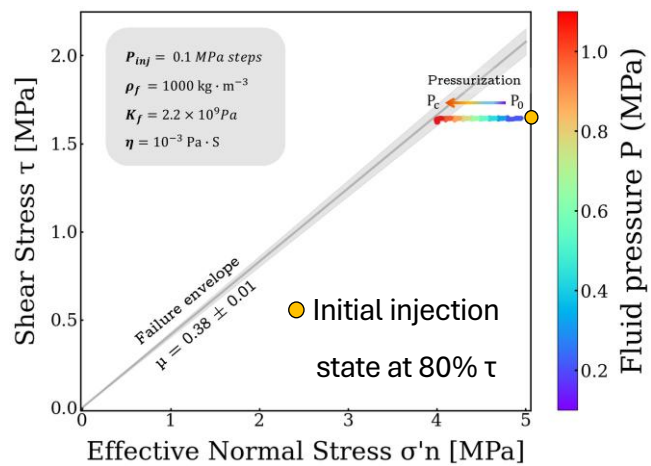


Our model shows classic fault behaviors such as **Stick-Slip** motion

Pore scale Finite Volume (PFV) method
in Yade to apply fluid forces to grains

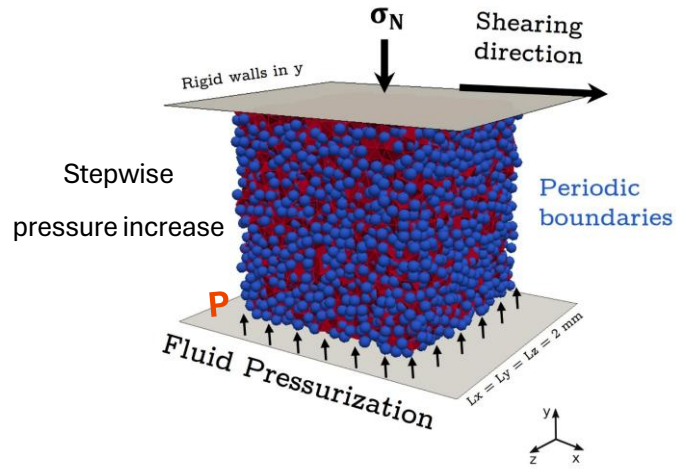


Loading Protocol :

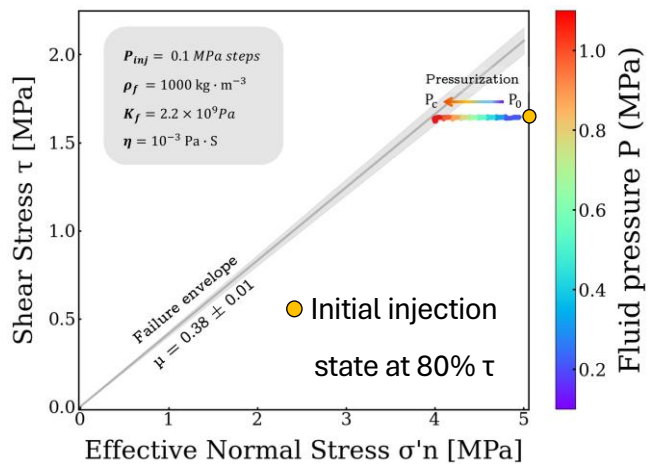


Pore scale Finite Volume (PFV) method in Yade to apply fluid forces to grains

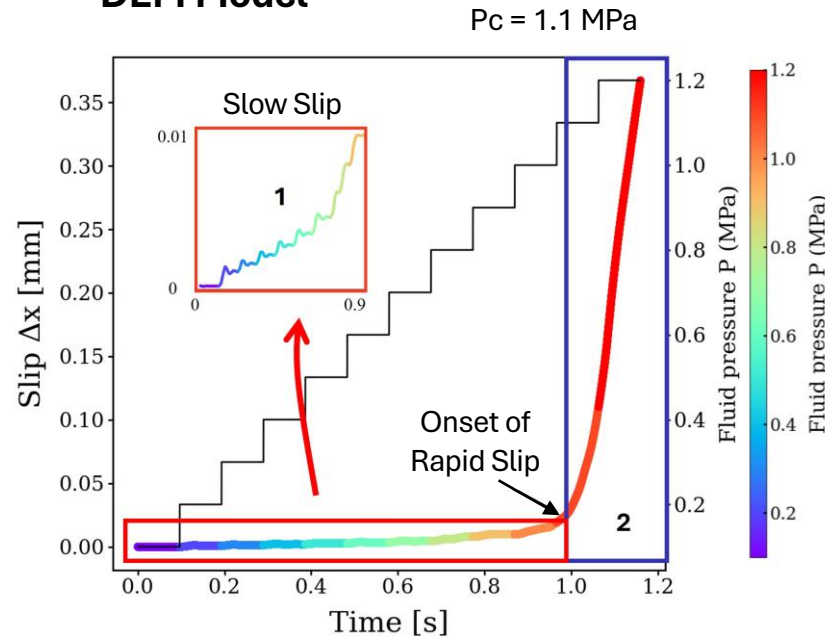
1) Monotonic Injection : to identify the onset of recativation



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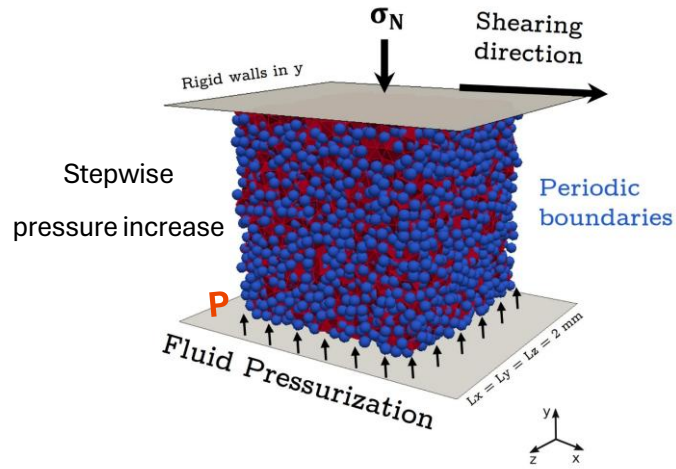
DEM Model



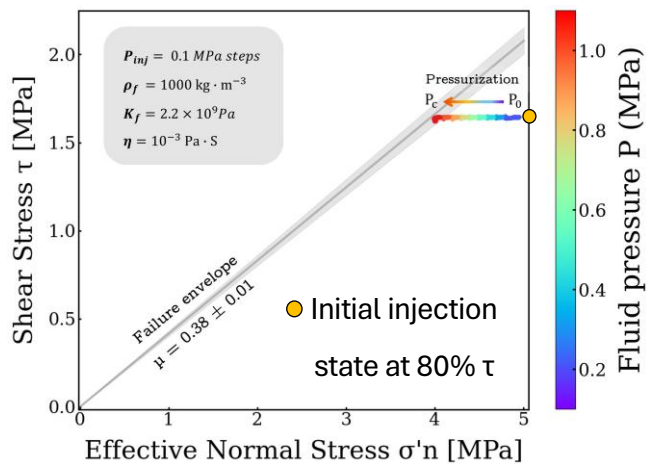
Two distinct stages are observed :

- 1) Initial Pressurization (Slow Slip)
- 2) Failure and Dynamic Slip

Pore scale Finite Volume (PFV) method in Yade to apply fluid forces to grains

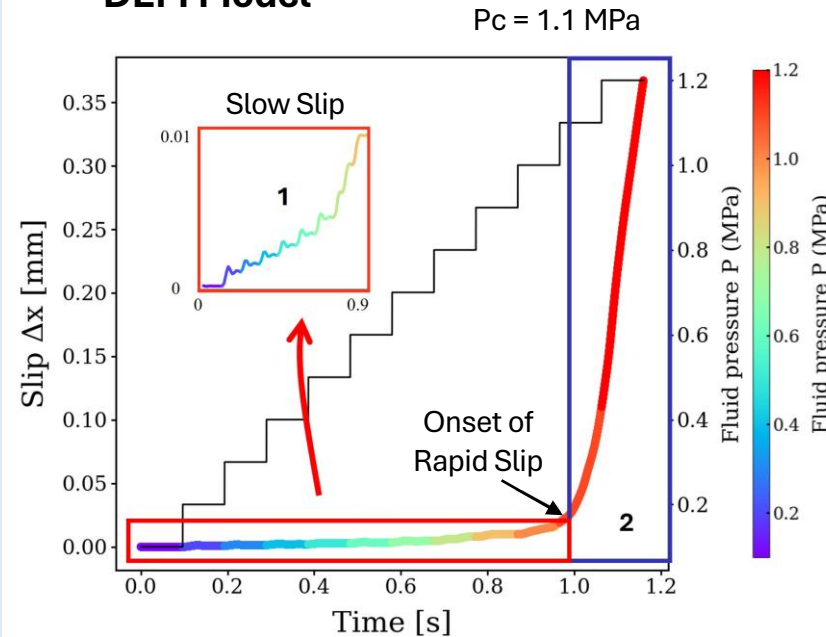


Loading Protocol :



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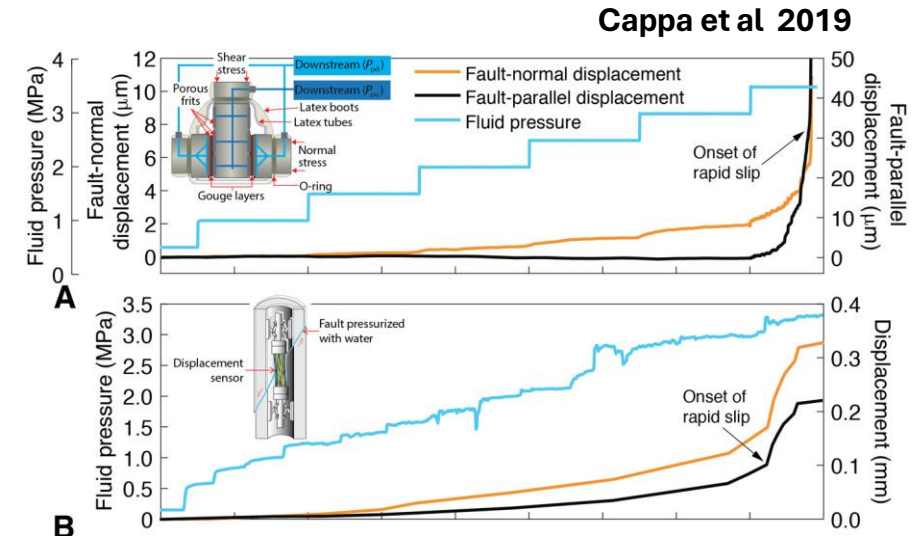
DEM Model



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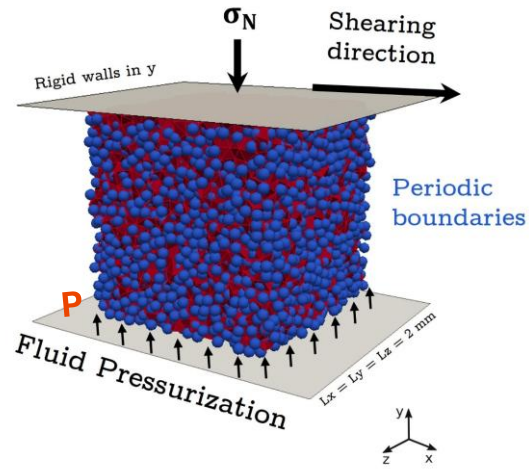
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Laboratory (A) and in situ (B) experiments

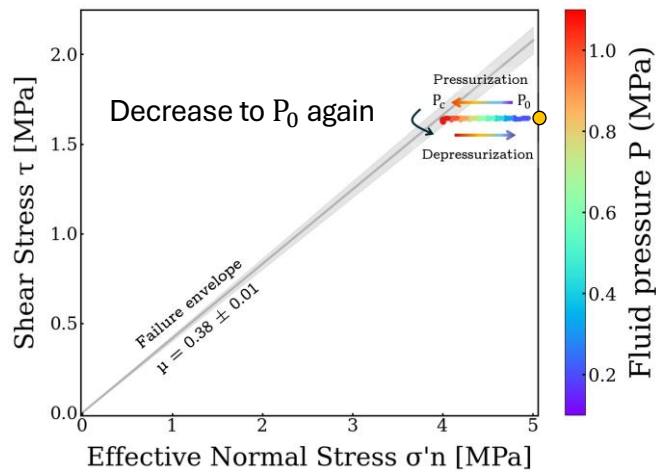


The DEM emergent behavior shows **great similarities with those observed in laboratory and in situ studies**

Pore scale Finite Volume (PFV) method in Yade to apply fluid forces to grains

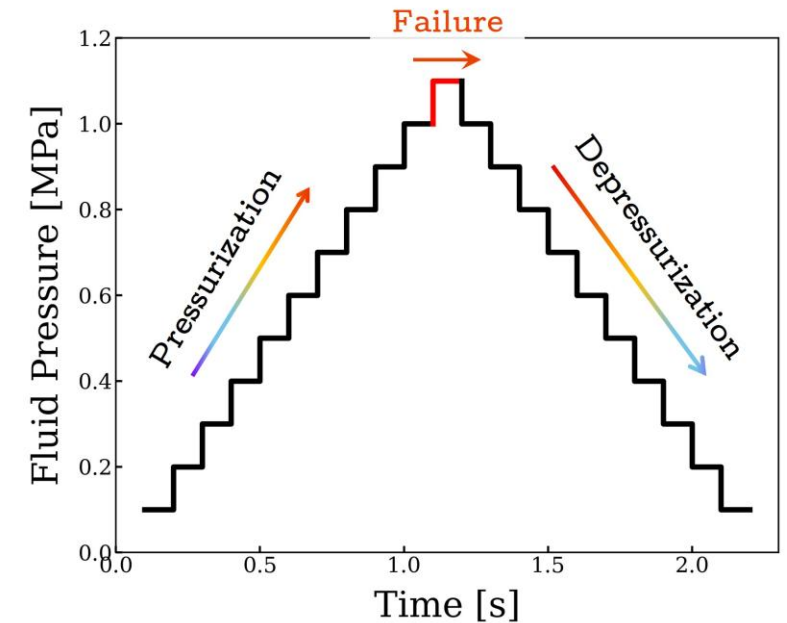
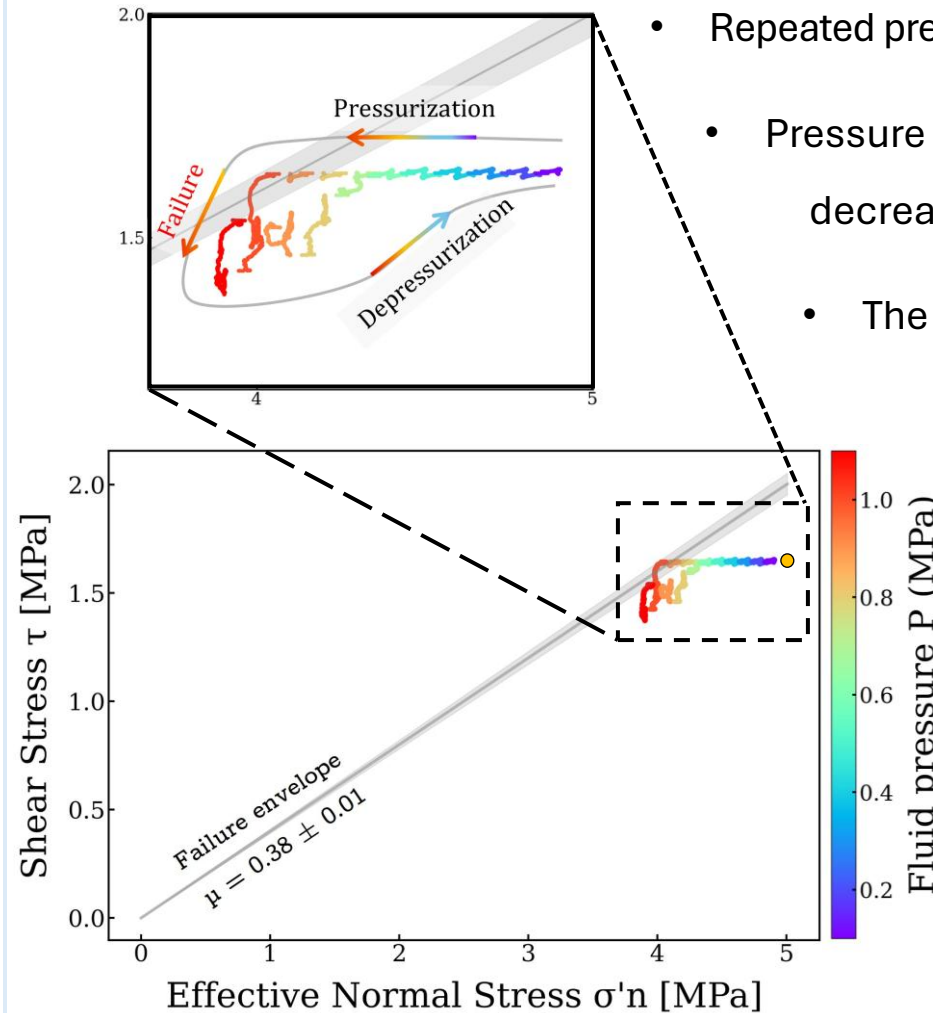


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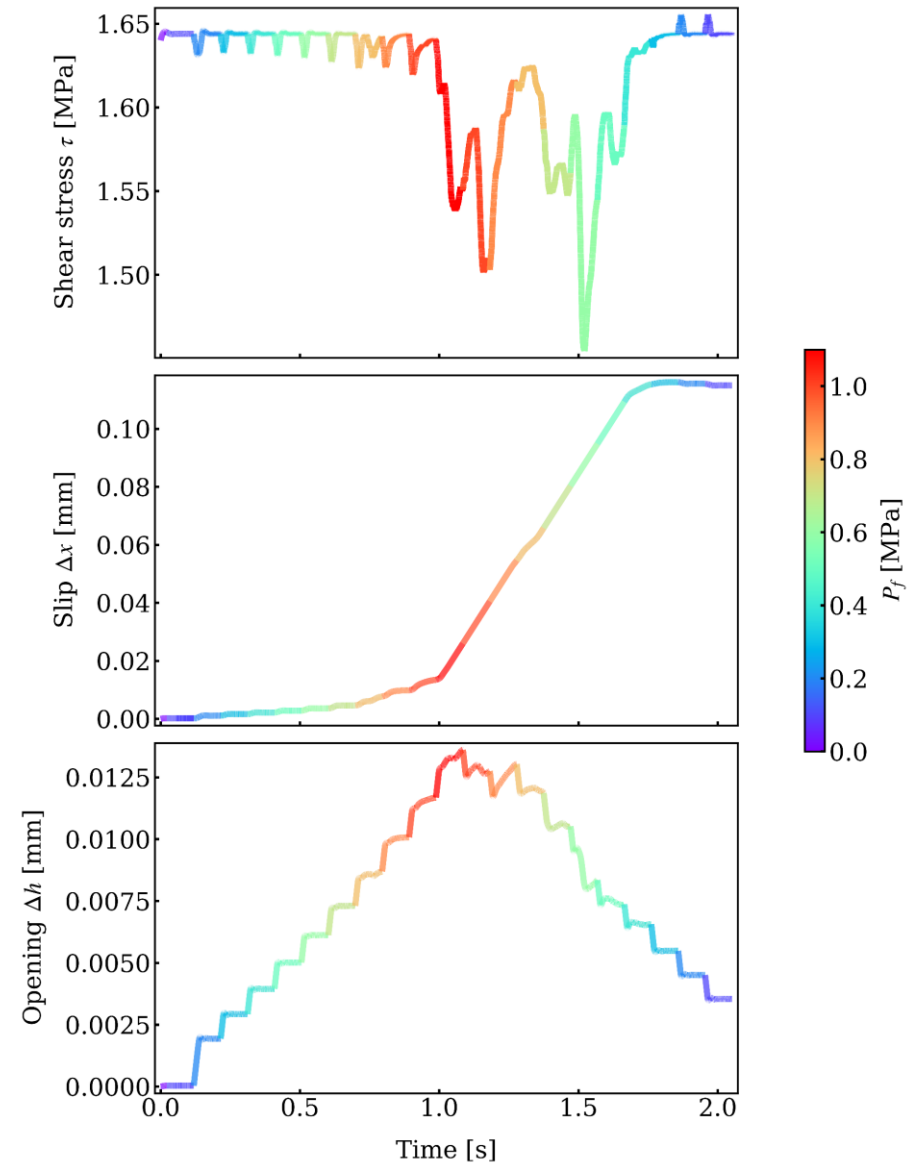


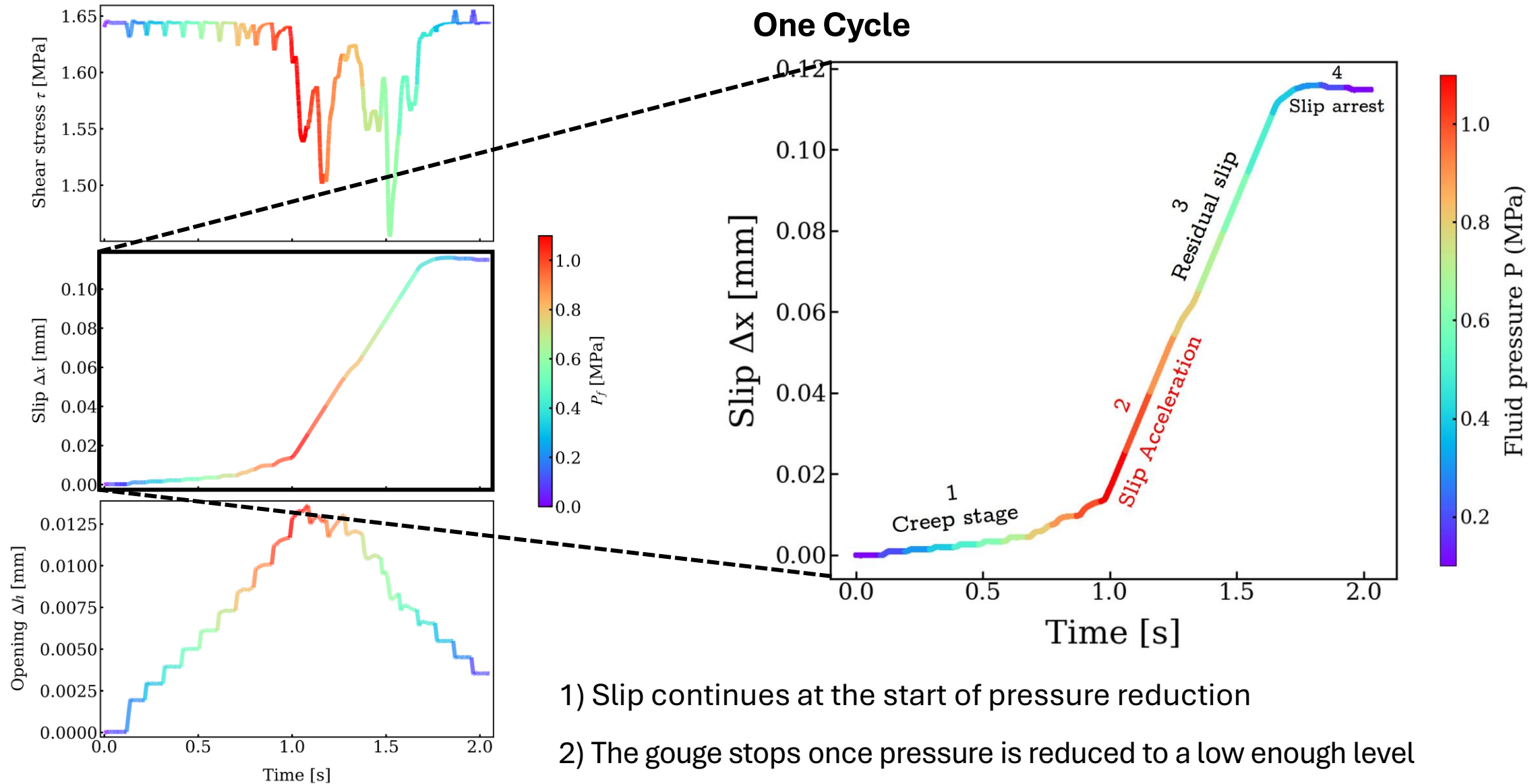
2) Cyclic Injection (Fault Valve Behavior)

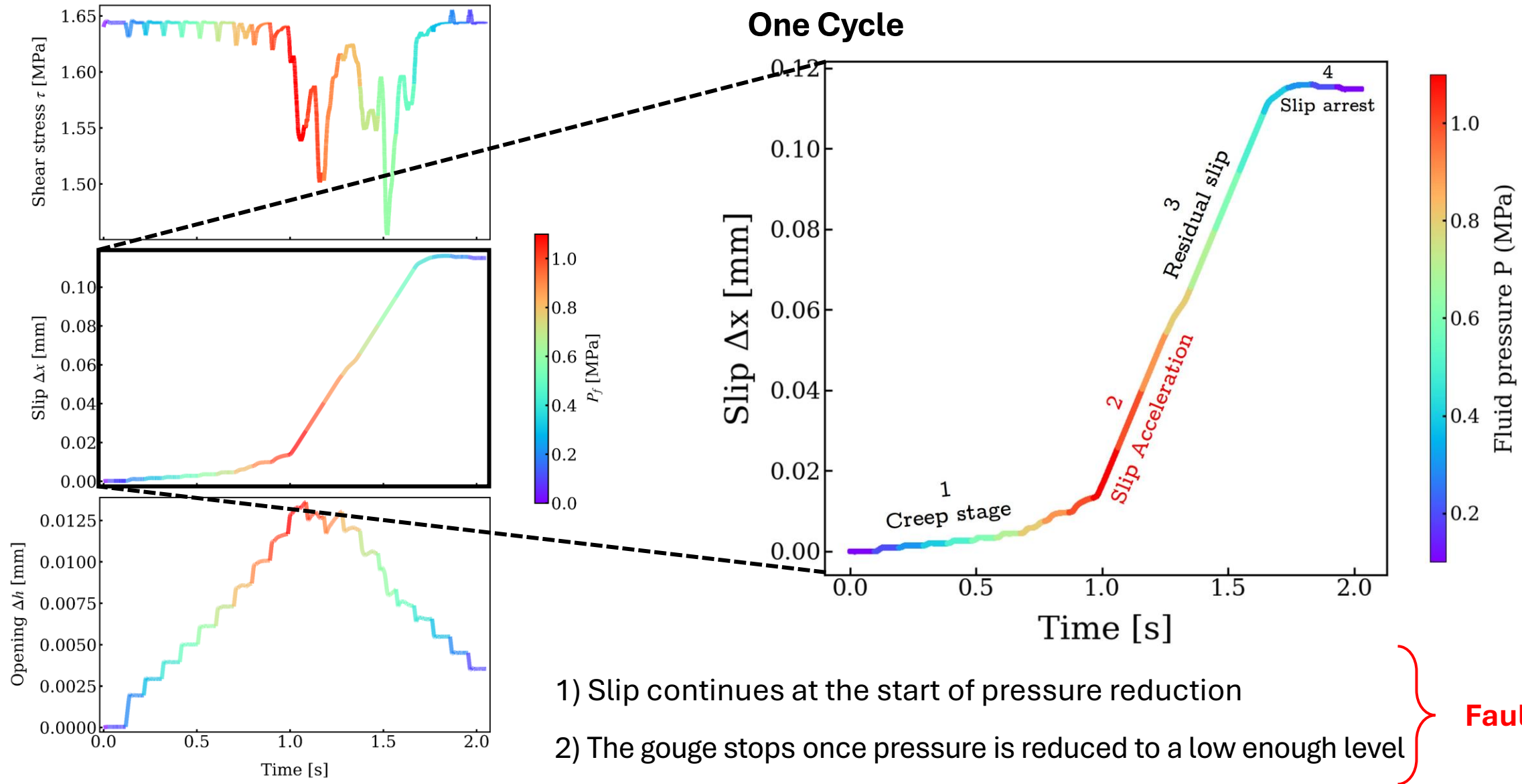
- Repeated pressurization–depressurization sequence
- Pressure is increased from P_0 until failure P_c and decreased again to P_0
- The goal is to reproduce fault-valve-like cycles



One Cycle



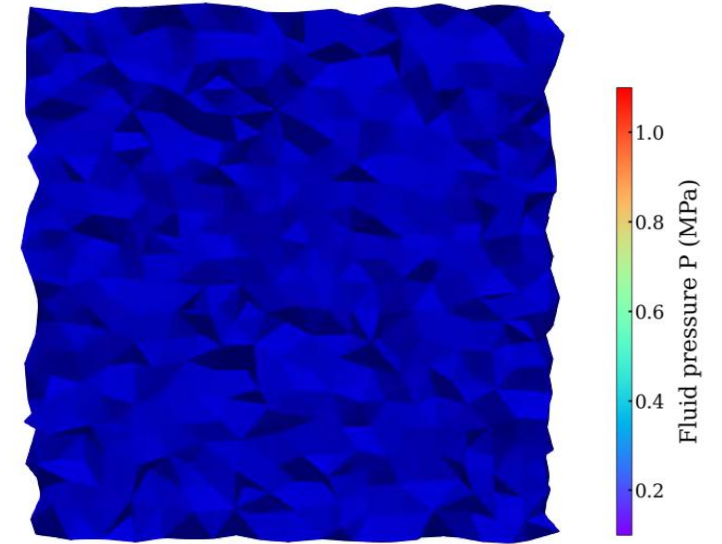
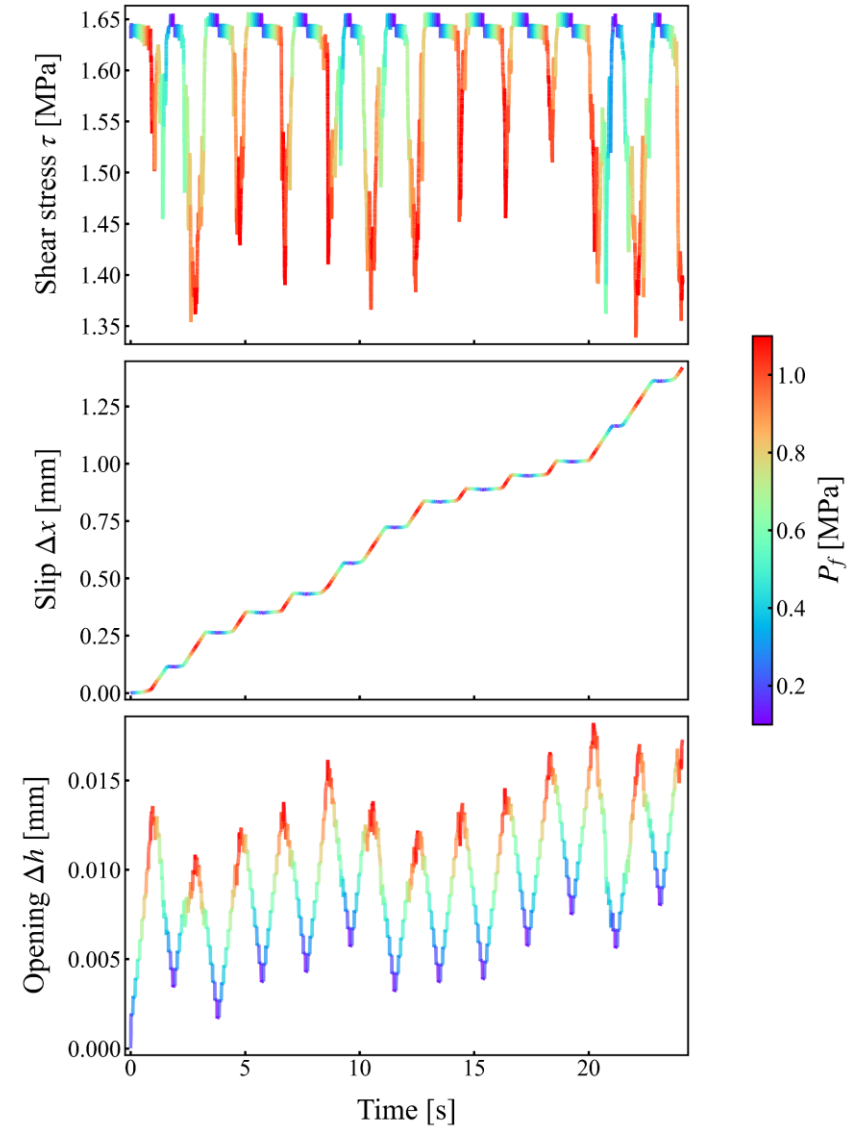




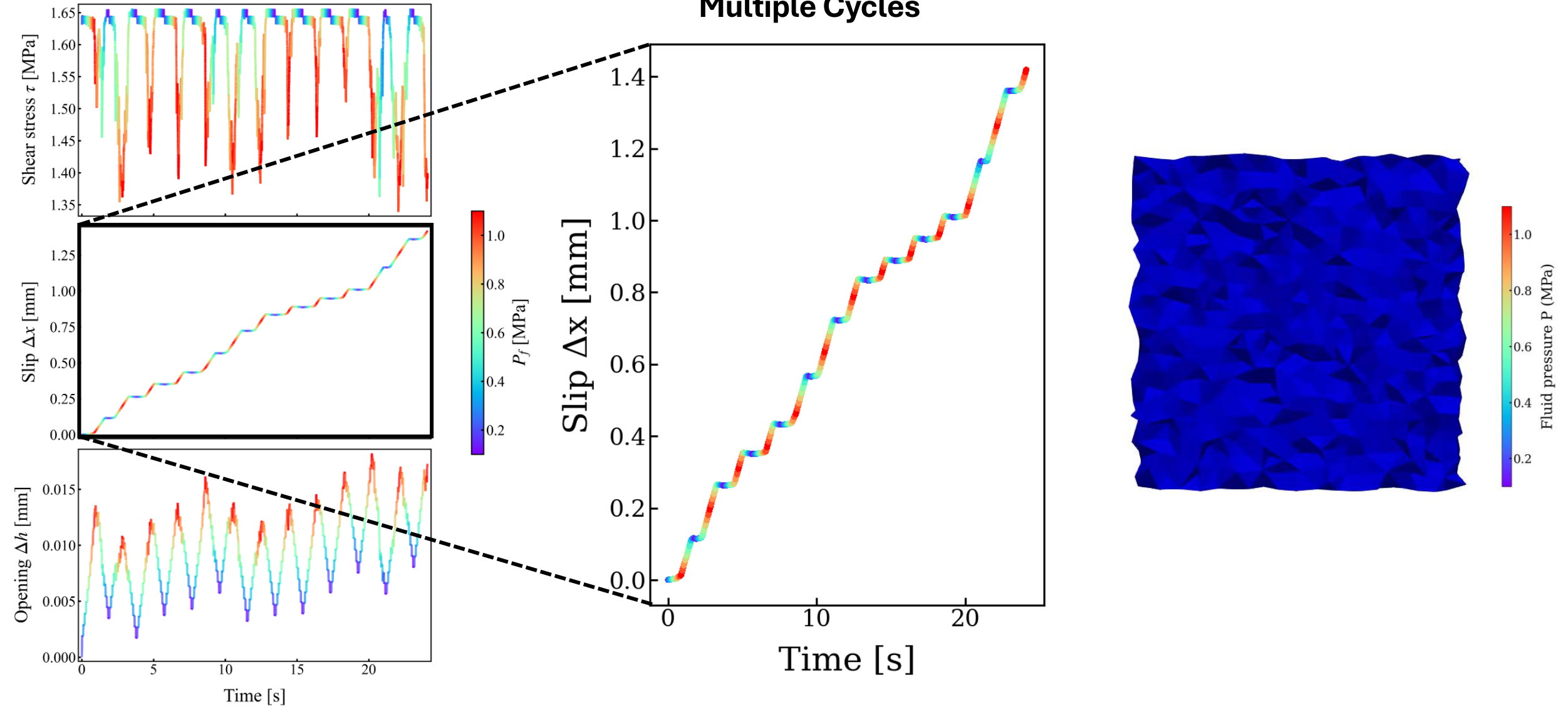
- 1) Slip continues at the start of pressure reduction
- 2) The gouge stops once pressure is reduced to a low enough level

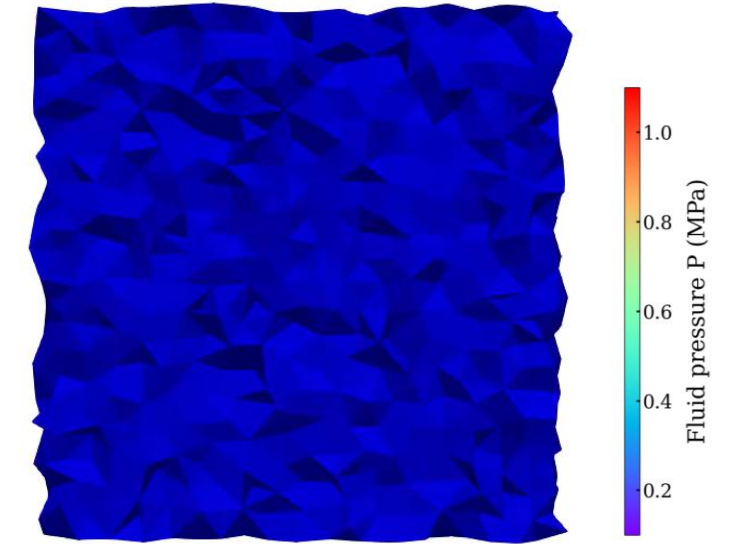
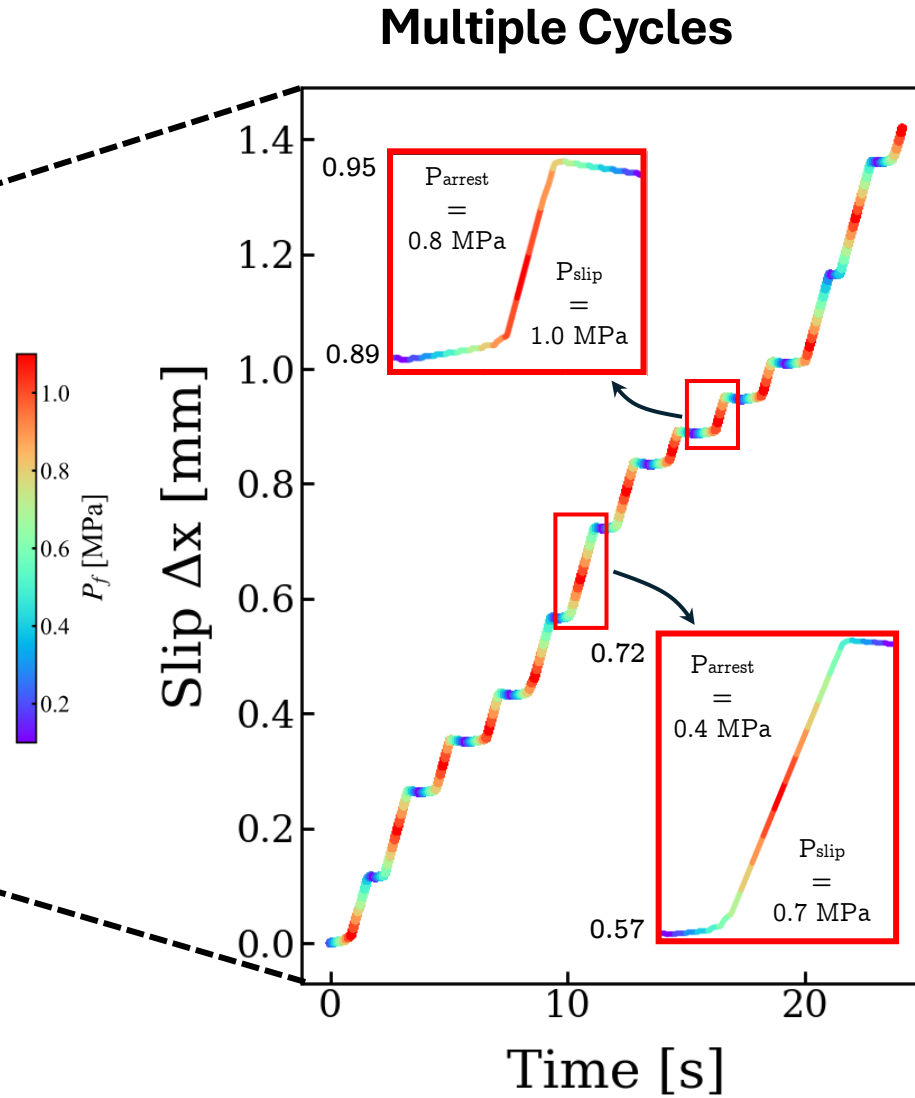
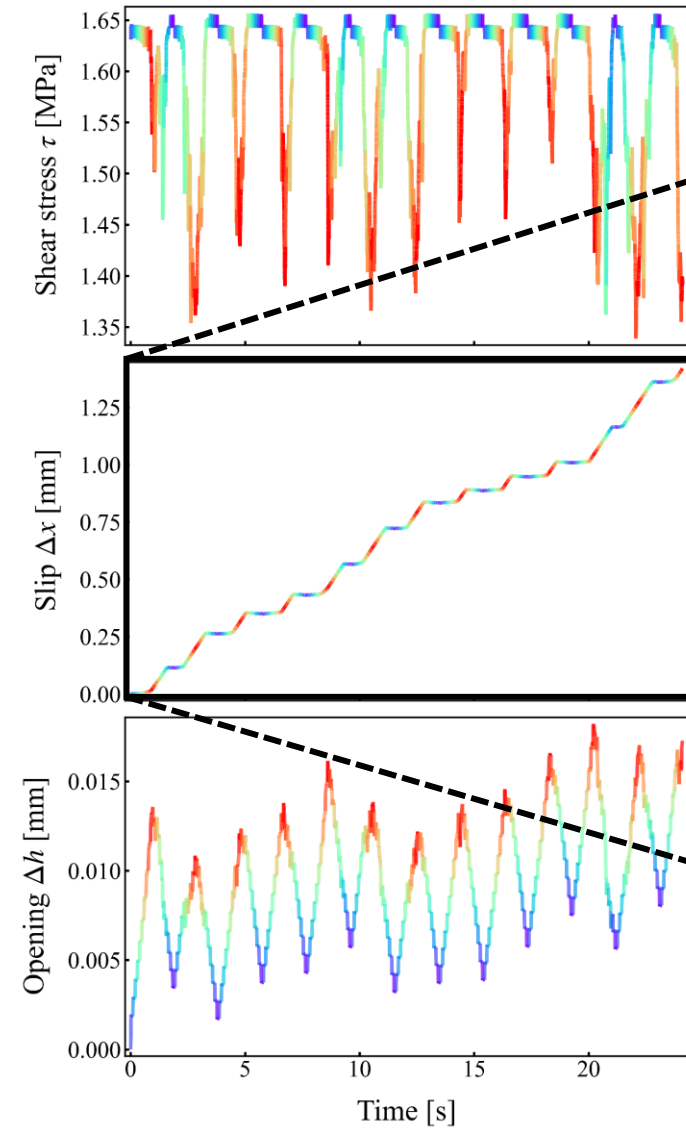
} **Fault Valve !**

Multiple Cycles

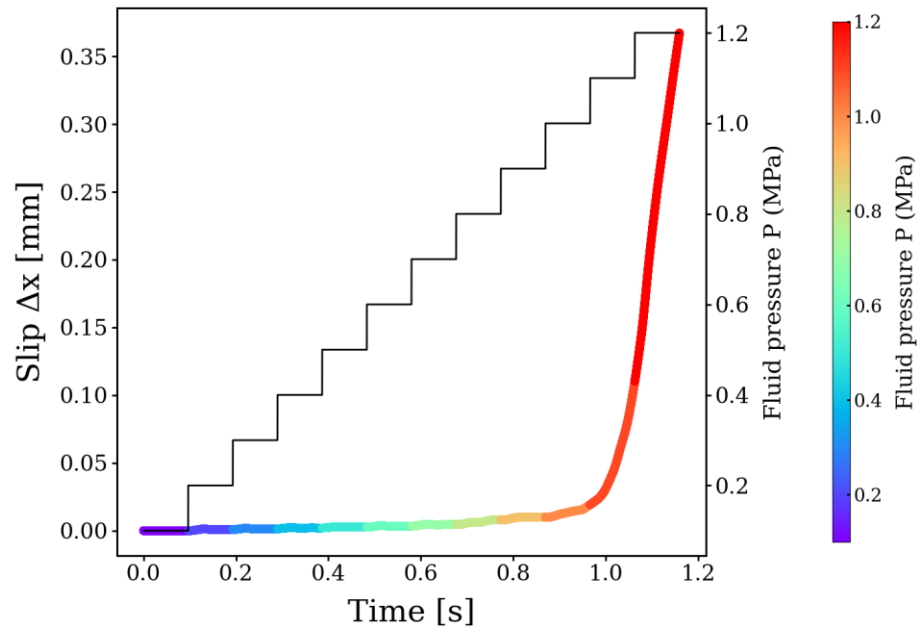


Multiple Cycles



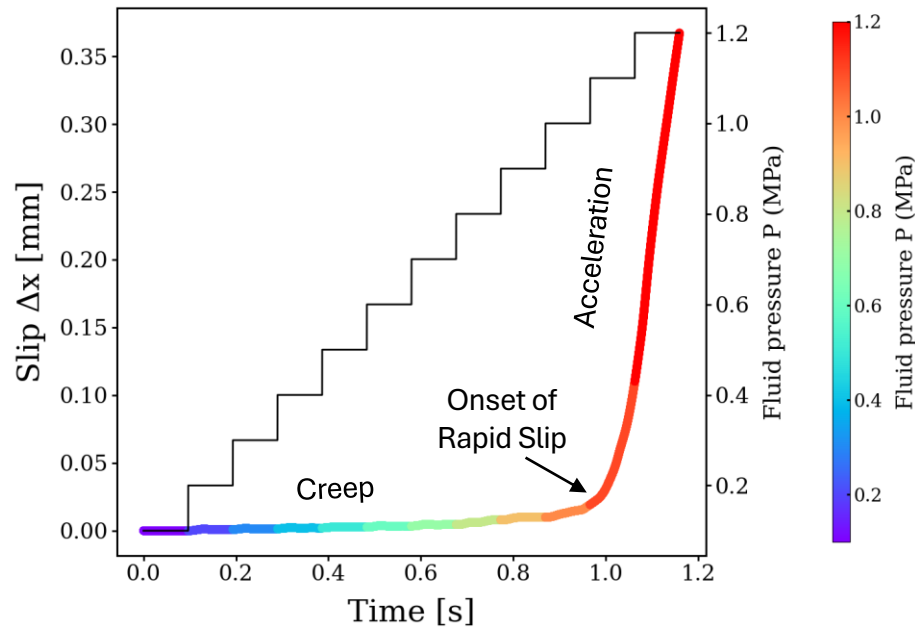


Strong variability in both onset and slip magnitude



- The maximum seismic moment is recovered from the measured slip associated with each pressure step increase
- Previous studies suggest a direct scaling :

$$M_{0,\max} = G\Delta V \quad (\text{McGarr2014})$$



Maximum seismic moment :

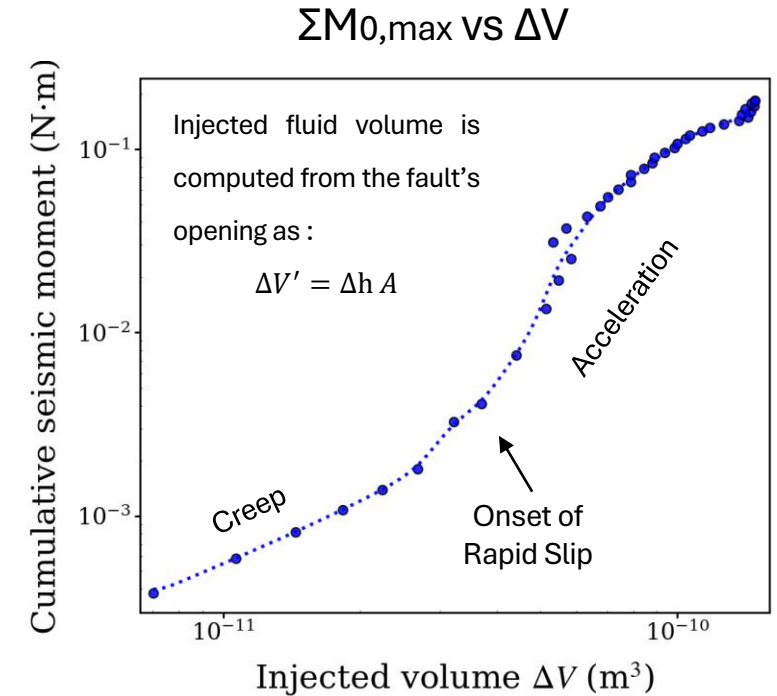
$$M_{0,max} = A G \Delta x$$



G = Shear modulus

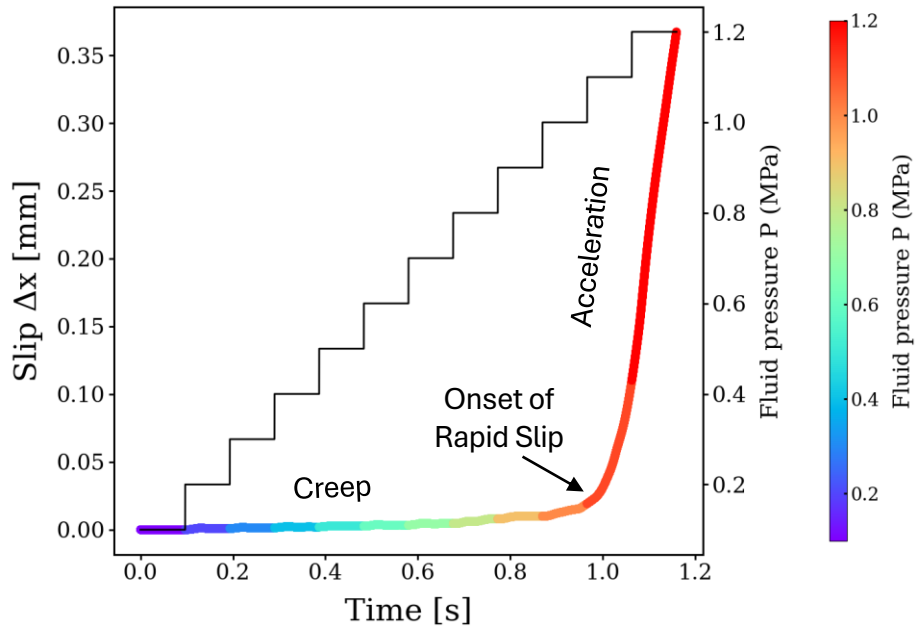
A = Area of the rupture

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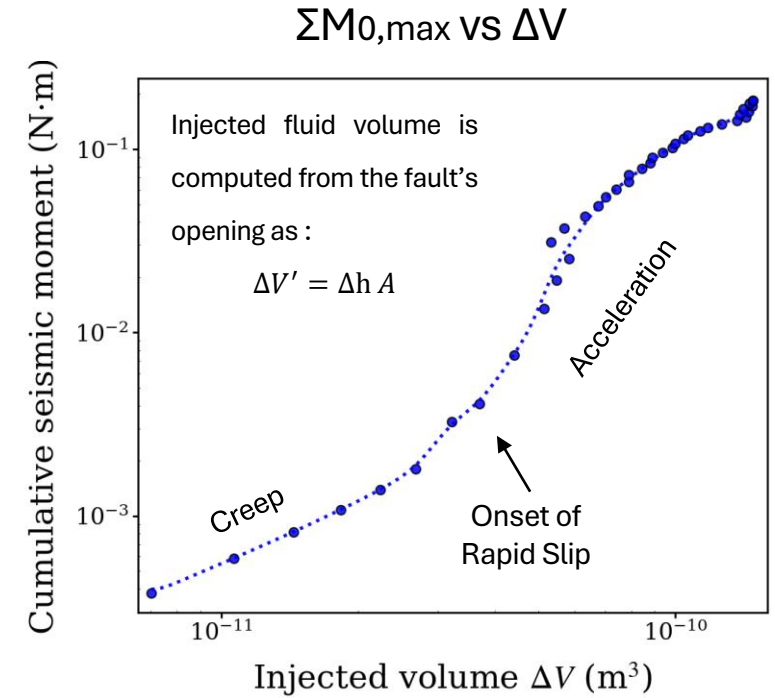
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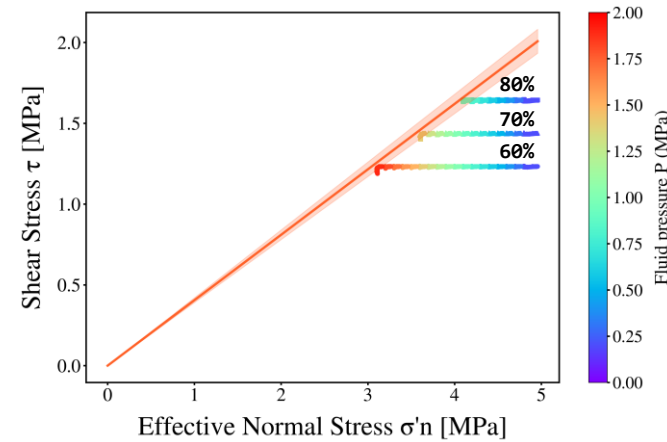
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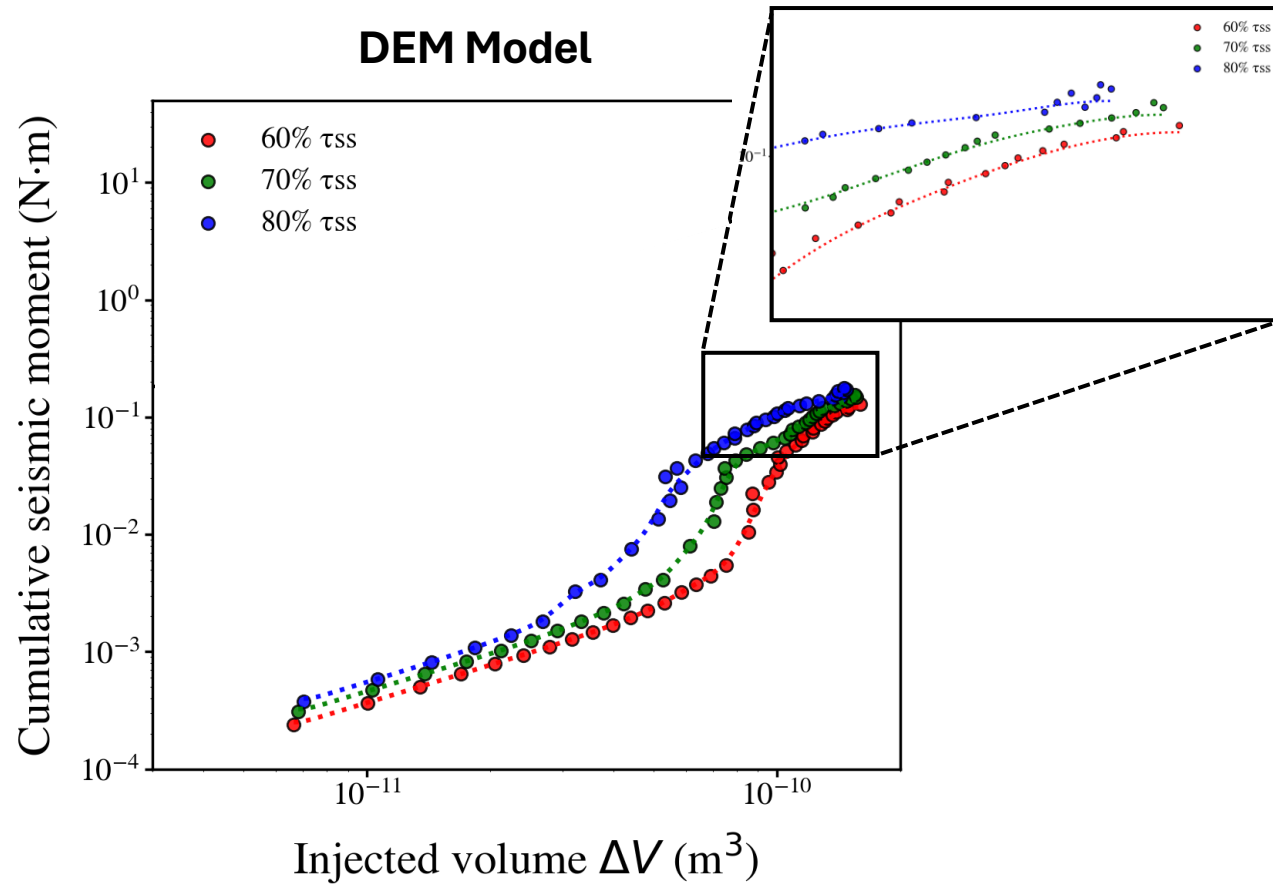
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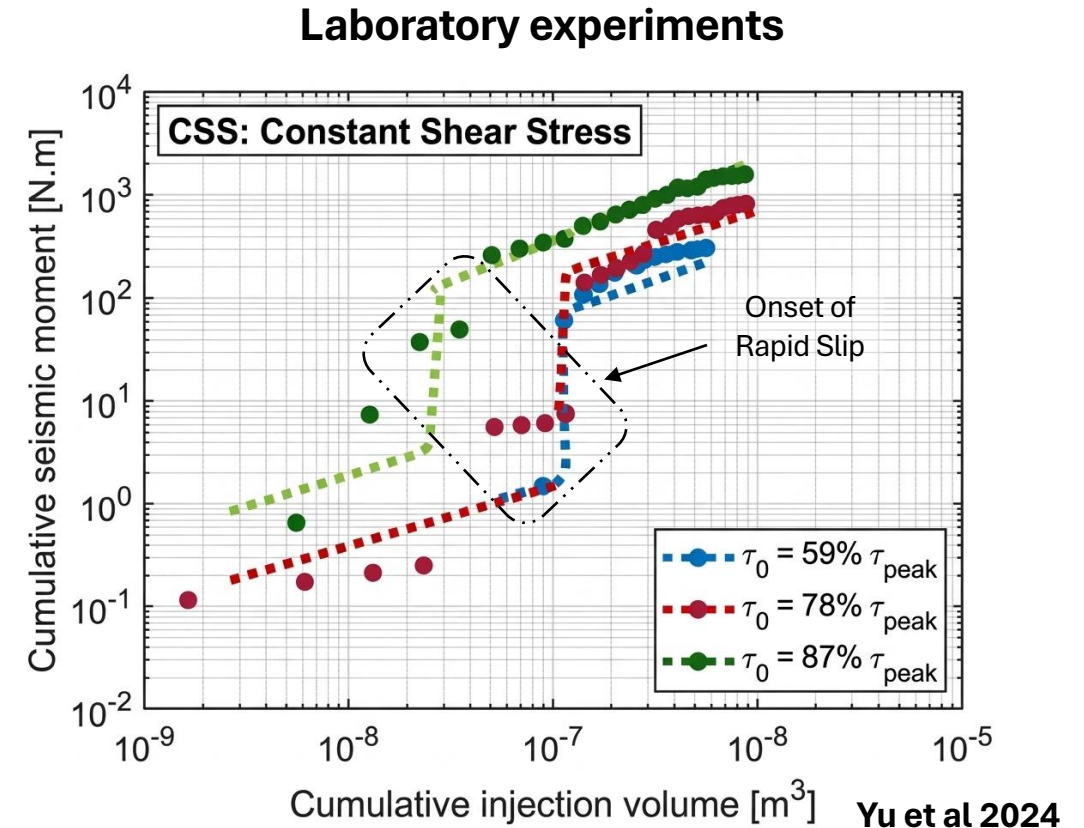
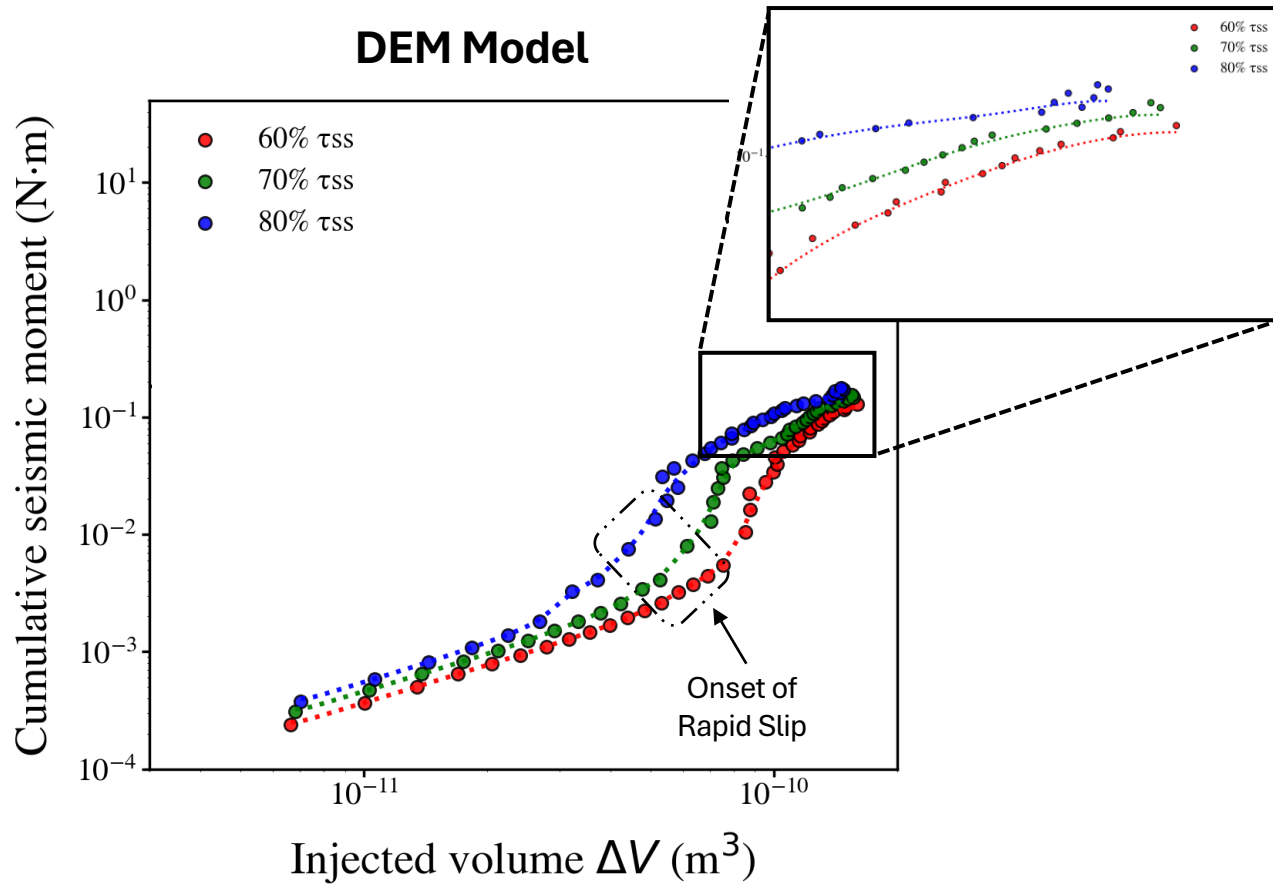


↓

Compare seismic potential under different initial shear stress levels before injection



- Higher pre-stress increases seismic potential by reducing the critical volume required for fault reactivation.



- Higher pre-stress increases seismic potential by reducing the critical volume required for fault reactivation.

- Our model confirms laboratory observations from previous studies.

1. DEM–PFV reproduces key fault HM behaviors

Stick-slip during direct shear and fluid-induced reactivation during pressurization.

2. Cyclic injection produces fault-valve-like cycles

- Repeated reactivation – arrest sequences with residual slip
- Reactivation pressure and slip magnitude vary strongly from cycle to cycle.

3. DEM-based seismic moment scaling

The model reproduces observed seismic moment trends, with initial shear stress as the key control on seismic potential.

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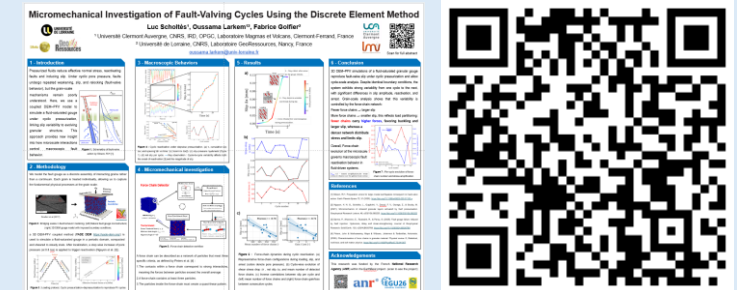
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Want to know more ?



Everything is related to the evolving microstructure of the gouge !



Thank you !

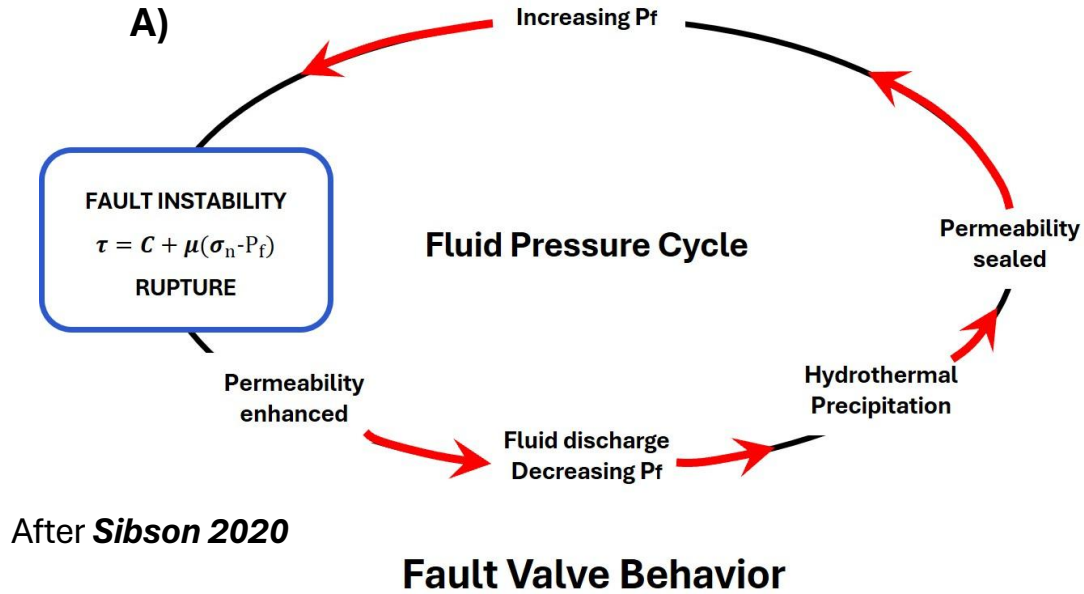


Full abstract



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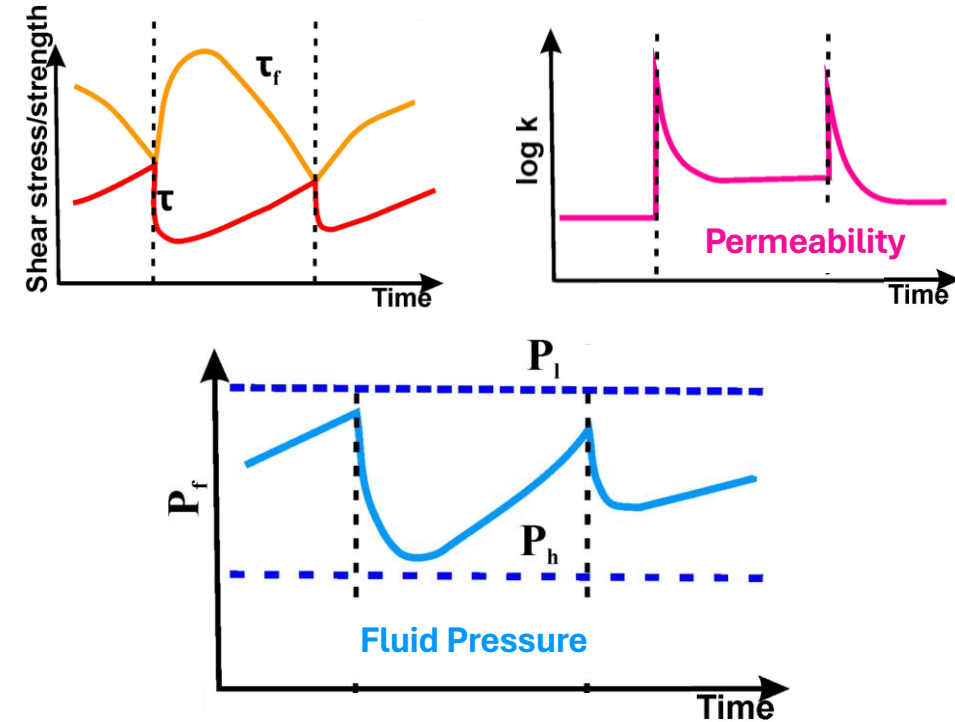
Using the **DEM×PFV** formulation we aim to : **Simulate the Fault Valve Behavior**



After *Sibson 2020*

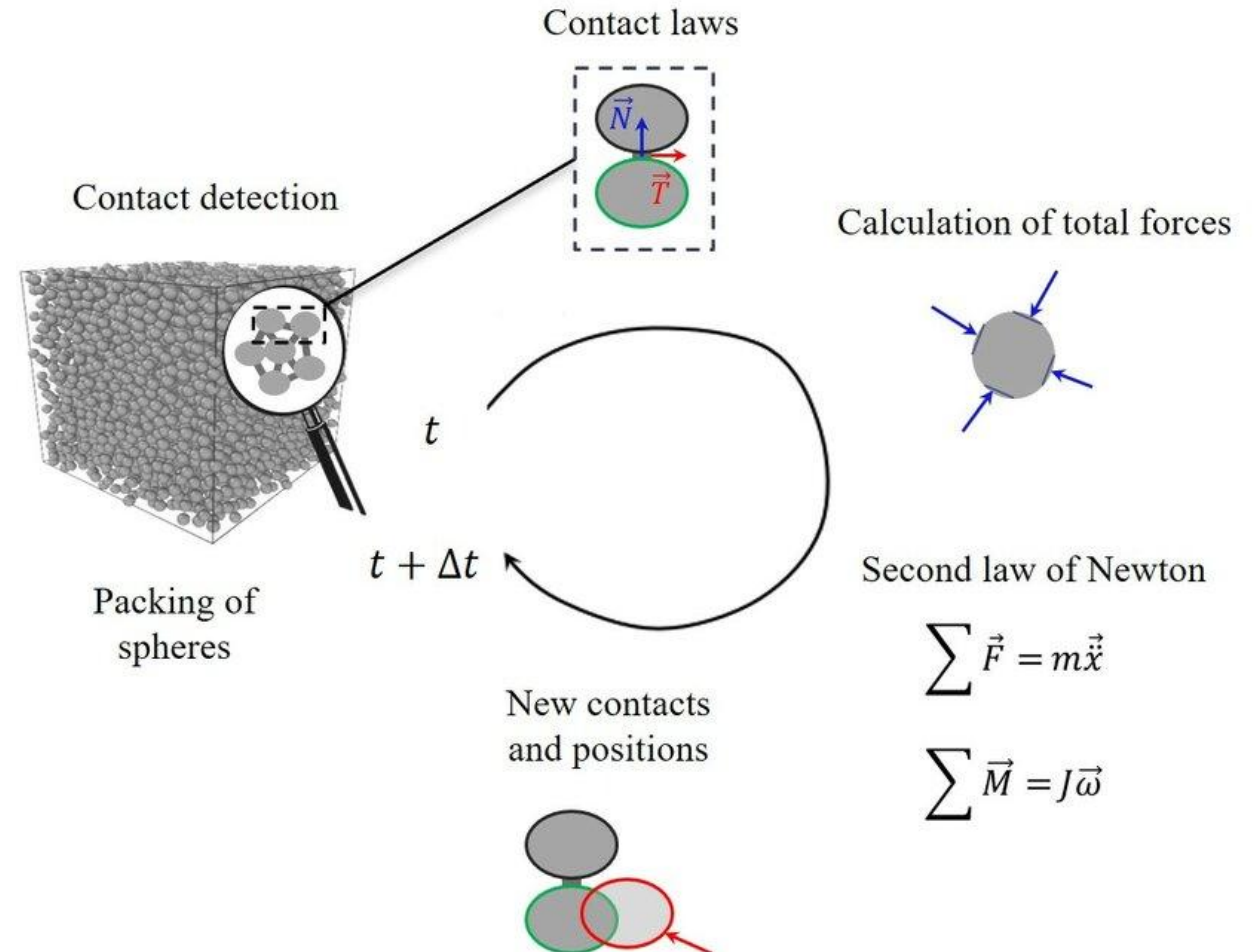
Fluid Pressure, Shear Stress, and Permeability, all go through cycles of build-up and release

B) Fluid pressure, frictional strength and permeability cycles resulting from valving action



Therefore, we simulate **Cyclic Injection** tests to reproduce and analyze these recurring fault valve processes (pressurization and release cycles)

- 1) DEM represents materials as individual *particles* that interact at contact points.
- 2) Detect contacts between particles and apply *contact laws* (normal and tangential forces).
- 3) Calculate total forces on each particle and apply *Newton's laws* of motion.
- 4) Update particle *positions and velocities*, then repeat for the next time step.



Radi, Kaoutar. (2019). Bioinspired materials : Optimization of the mechanical behavior using Discrete Element Method.



We use a 3D DEM formulation implemented in **Yade DEM**

Interactions are governed by **linear elastic contact** laws and **Coulomb friction**.

- **Normal Contact Force F_n :**

$$F_n = \min(k_n(u_n - u_n^p), a_n)$$

k_n : normal stiffness

a_n : normal adhesive strength

- **Tangential (Shear) Force F_s :**

$$F_s = k_s \cdot u_s$$

k_s : shear stiffness

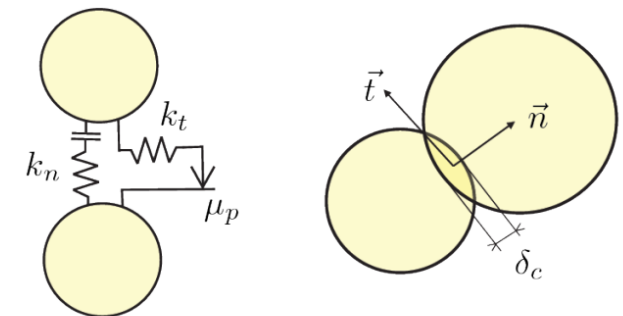
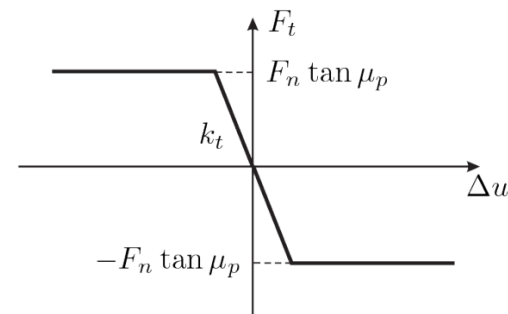
u_s : relative tangential displacement

- **Maximum Shear Force (F_s^{max} - Mohr-Coulomb type):**

$$F_s^{max} = F_n \cdot \tan(\varphi) + a_s$$

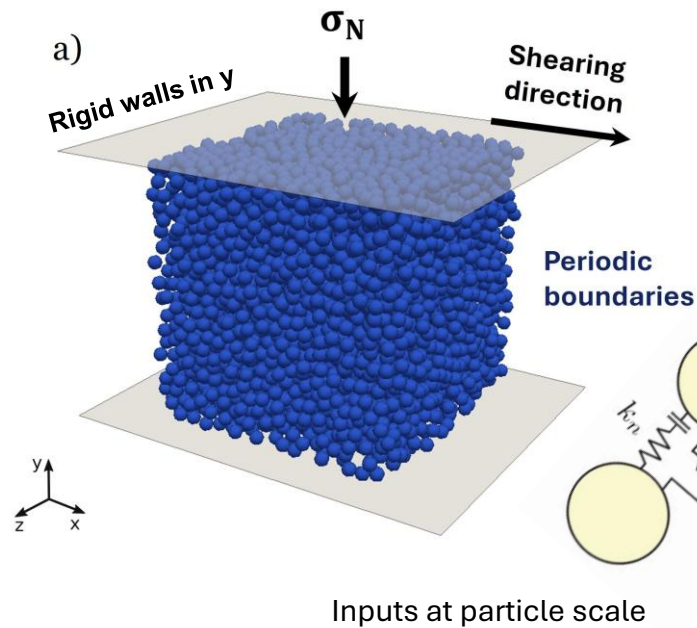
φ : friction angle

a_s : shear adhesion



Contact Interaction

Scholtès (2008)

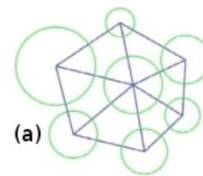


We impose properties at the grain scale and look for emergent properties.

Outputs



Hydraulic Properties



Mechanical Properties

Imposed	Tracked
Particle Properties: E, ν , friction angle . . .	Boundary Forces: total and tangential forces
Boundary Conditions: Applied σ_n , Shear Velocity	Particle States: positions, velocities
	Inter-particle Forces: normal (F_n), shear (F_s)

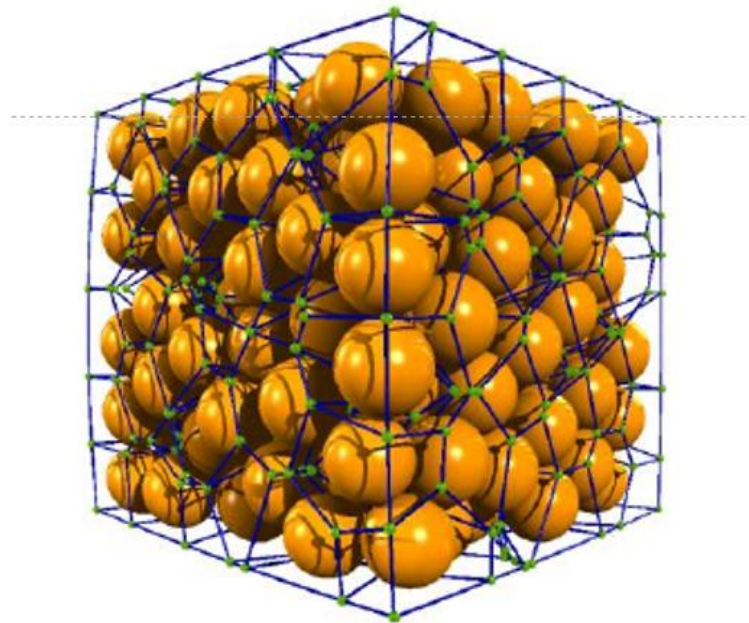
Stresses	Method
Wall Stresses	From recorded forces on boundary walls: $\sigma_{ij}^{wall} = \frac{F_{boundary}}{A_{boundary}}$
Contact Stresses	Summation over all inter-particle contacts, averaged over volume: $\sigma_{ij}^{contact} = \frac{1}{V} \sum_c F_i^c L_j^c$

Imposed	Tracked / Computed
Fluid Properties: Viscosity (μ), Fluid Bulk Modulus. . . etc	Pore Pressures: P_k solved from mass conservation equations.
Boundary Conditions: Imposed pressure P_f or fluid flux.	Fluxes: q_{ij} calculated using local Poiseuille flow between neighboring pores.
Pore Network: Defined by particle configuration (geometry of pores via triangulation).	Pore-scale average velocities:
	$\mathbf{v}_{avg}^k = \frac{1}{V_k} \sum_{j \in N(k)} (q_{kj} \cdot \mathbf{r}_{kj})$
	Global flow average velocity: Volume-averaged over all pores.
	Fluid forces on particles: F_p, F_v .
	Permeability: via Darcy's Law:
	$\mathbf{v}_{avg} = -\frac{k}{\mu} \nabla P$

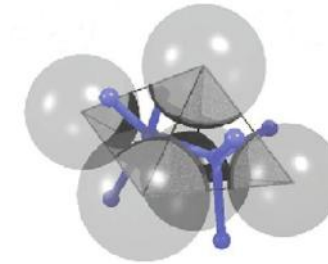
Parameter	Value
Particle density ρ	2600 kg/m ³
Particle Young's modulus E	1 GPa
Particle Poisson's ratio ν	0.25
Particle Friction angle	30°
Mean diameter D_p	0.1 mm
Normal load σ_N	5 MPa
Shear velocity V	2×10^{-5} m/s
Initial porosity n_0	0.428

[Chareyre et al, TIPM 2011; Scholtès et al, CMT 2015]

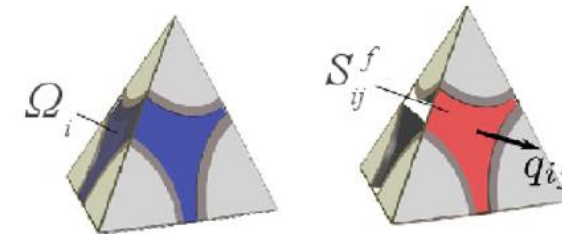
Pore space partition through a regular **Delaunay triangulation** (Laguerre Voronoï tessellation) + a **Finite Volume** scheme



Pore/Pipe network
(interporal Darcy flow)



Fluid flow in a deformable medium



$$\dot{P}_i = \frac{-K_f}{V_{f,i}} \left[V_{p,i} + \sum_{j=1}^4 k_{ij} (P_i - P_j) \right]$$