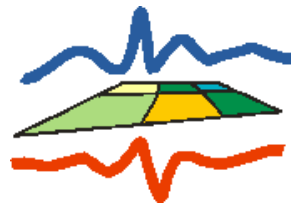
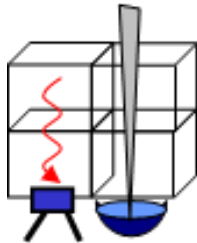


# Doppler Wind profiler uncertainty in a turbulent atmosphere

Jan H. Schween

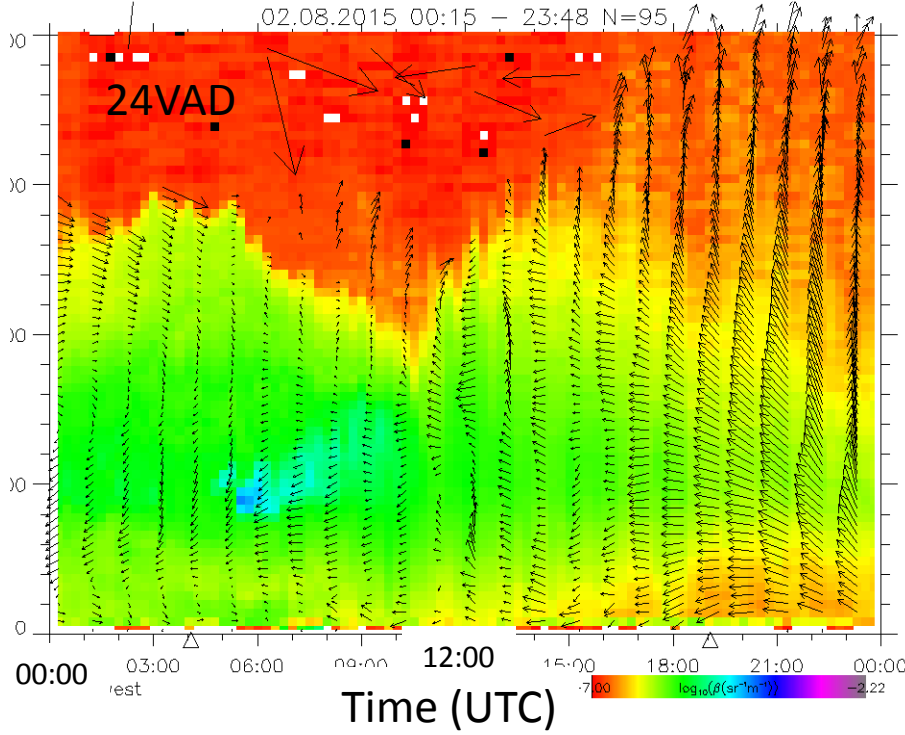
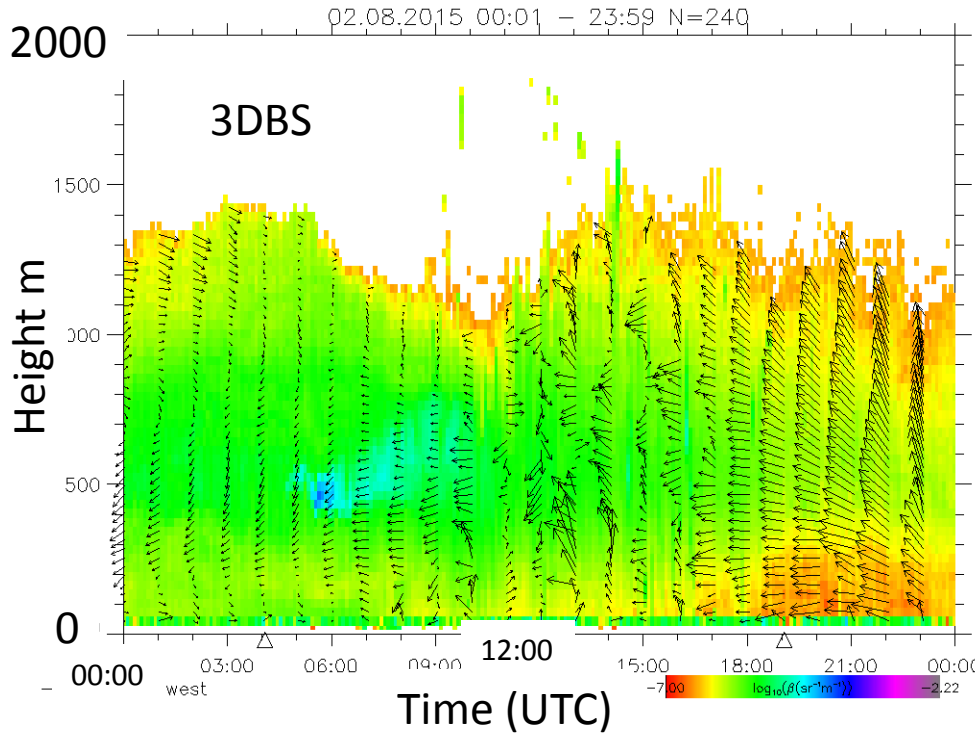
Inst. f. Geophysics and Meteorology

University of Cologne



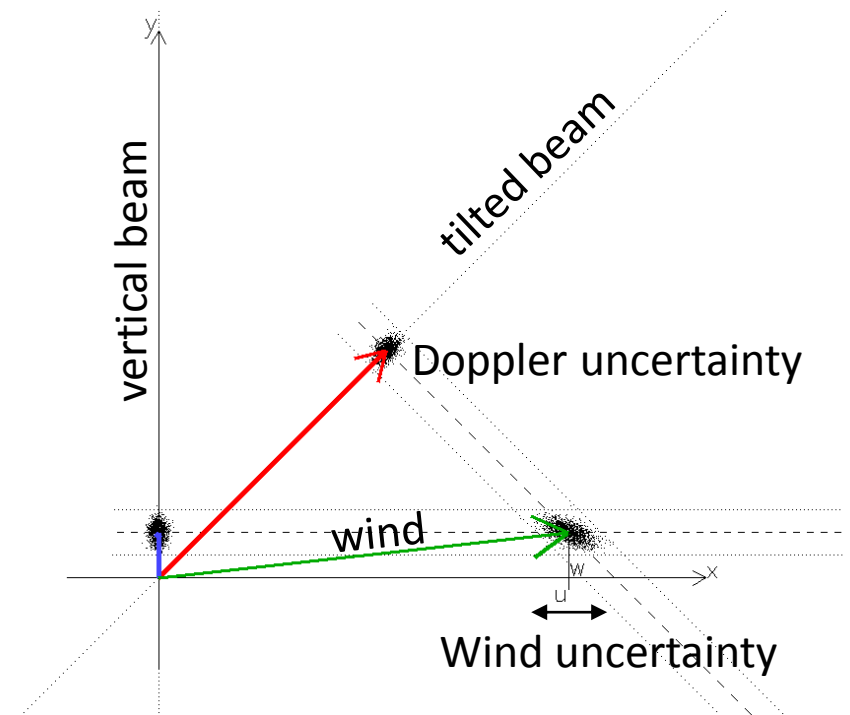
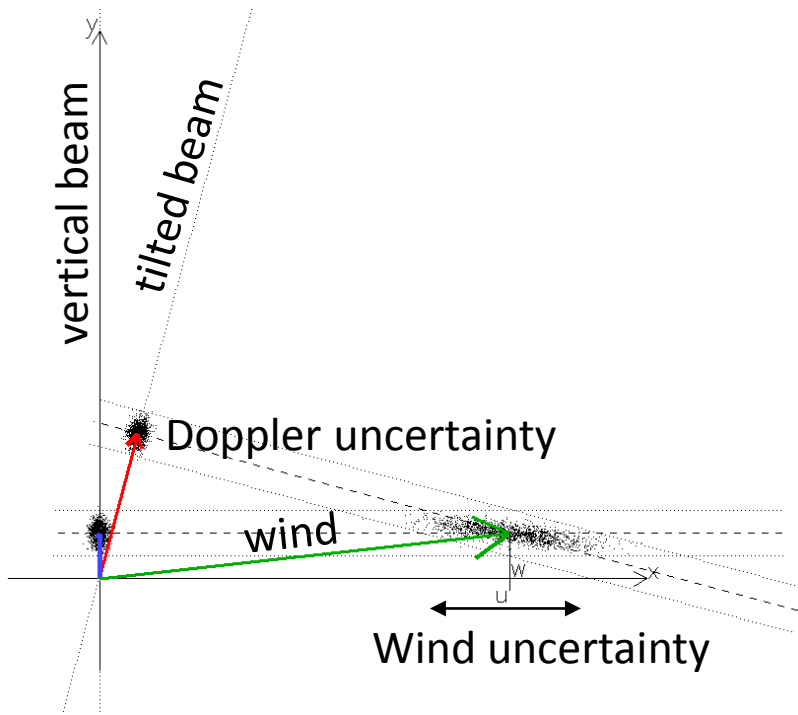
# Motivation

- More and more Doppler wind profiler available (radar, sodar, lidar) -> e-prof
- providing wind data to assimilation requires uncertainty estimates
- Current uncertainty estimate consider only Doppler uncertainty – not turbulence



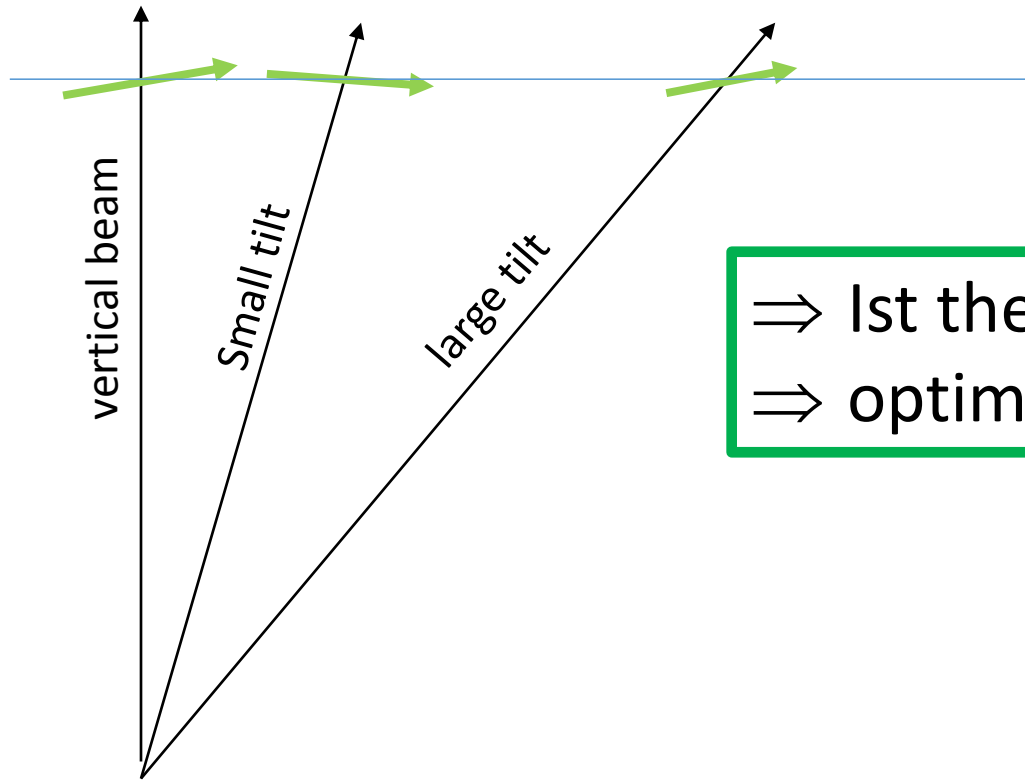
# Motivation: large tilt

- To get horizontal wind component beams must be tilted
- The larger the tilt the smaller the uncertainty
- => tilt should be large !



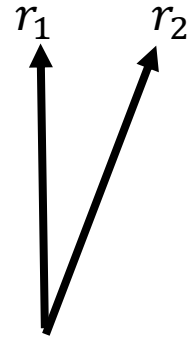
# Motivation: small tilt

- Large tilt => large separation => different wind
- Tilt should be small !



⇒ Ist there an optimum tilt ?  
⇒ optimal scan ?

# Two beams + turbulence



- One vertical and one tilted beam
- Differences in wind speeds due to separation
- Gaussian error propagation
- Separation introduces auto- and cross-covariances between  $u, u$  and  $u, w$  etc. at the two locations of the vertical beam ( $r_1$ ) and the tilted beam ( $r_2$ ):
  - If there is upwind at  $r_1$  there might be also upwind at  $r_2$   
 $\Rightarrow C_{ww}(r_1, r_2) = \overline{w'_{r1} w'_{r2}} / \overline{w'^2_{r1}}$
  - If there is upwind at  $r_1$  horizontal wind speed at  $r_1$  might be lower  
 $\Rightarrow C_{uw}(r_1, r_2) = \overline{u'_{r1} w'_{r2}} / \overline{u'_{r1} w'_{r1}}$
  - ...

# assumptions

## homogeneity of the turbulent field

$$\Rightarrow \dots \overline{u'^2_{s1}} = \overline{u'^2_{s0}} = \overline{u'^2} \text{ and } \overline{u'_{s1}w'_{s1}} = \overline{u'_{s0}w'_{s0}} = \overline{u'w'}$$

- horizontal **isotropy for form** of  $C_{uu}$ ,  $C_{uw}$  etc.  
 $\Rightarrow$  depend only on scalar distance
- All normalized auto- and cross-covariances are the **same**:

$$C_{uu}(r) = C_{uw}(r) = C(r)$$

- Especially the last is a very strong assumption. But we believe deviations are small enough to allow for the use in this *uncertainty estimate*

# Two beams: equation

- Equation for one vertical one tilted beam

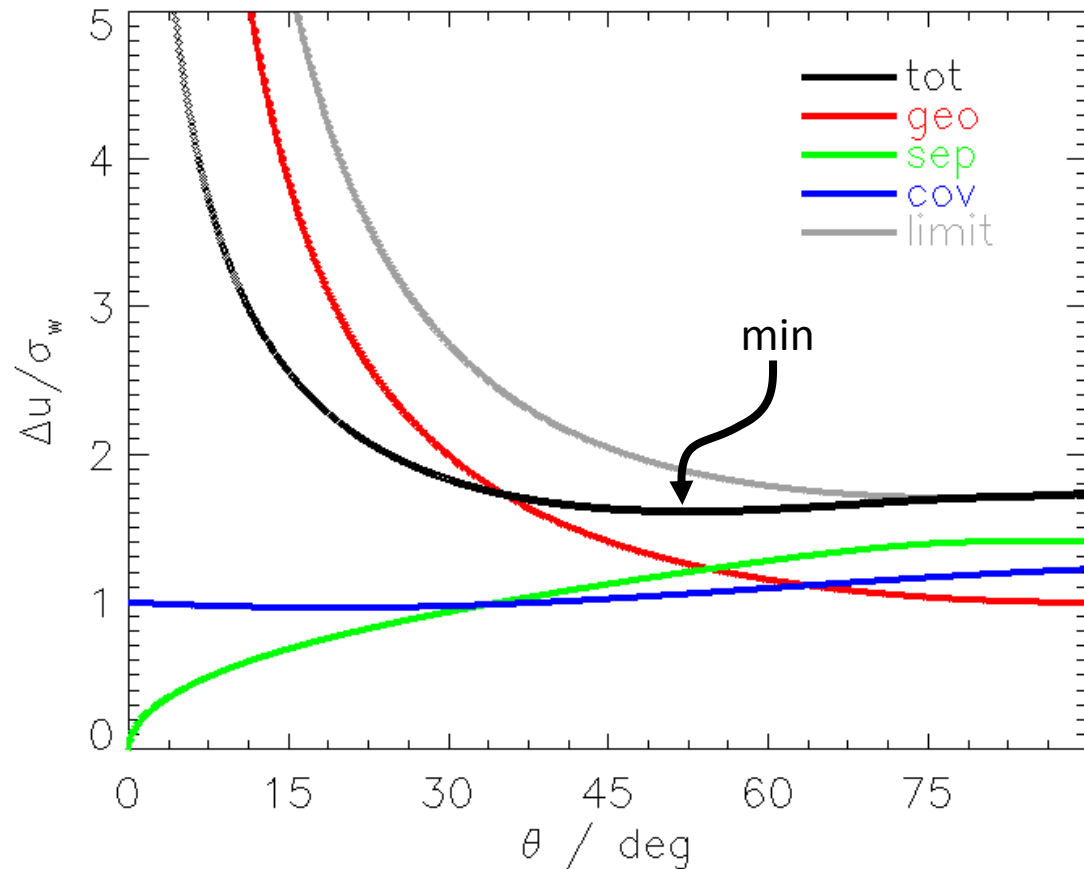
$$\left(\frac{\Delta u_{rs}}{\sigma_w}\right)^2 = \underbrace{\frac{1}{s_\theta^2}}_{\text{Geometry}} \cdot \underbrace{2[1 - C(r_{01})]}_{\text{separation}} \cdot \underbrace{\left(s_\theta^2 \cdot \frac{\overline{u'^2}}{\sigma_w^2} + 2s_\theta c_\theta \cdot \frac{\overline{u'w'}}{\sigma_w^2} + c_\theta^2\right)}_{\text{Effect of (co-)variances}}$$

$$s_\theta = \sin \theta, c_\theta = \cos \theta$$

- Similar equations can be derived for any arbitrary scan pattern

# Two Beams:

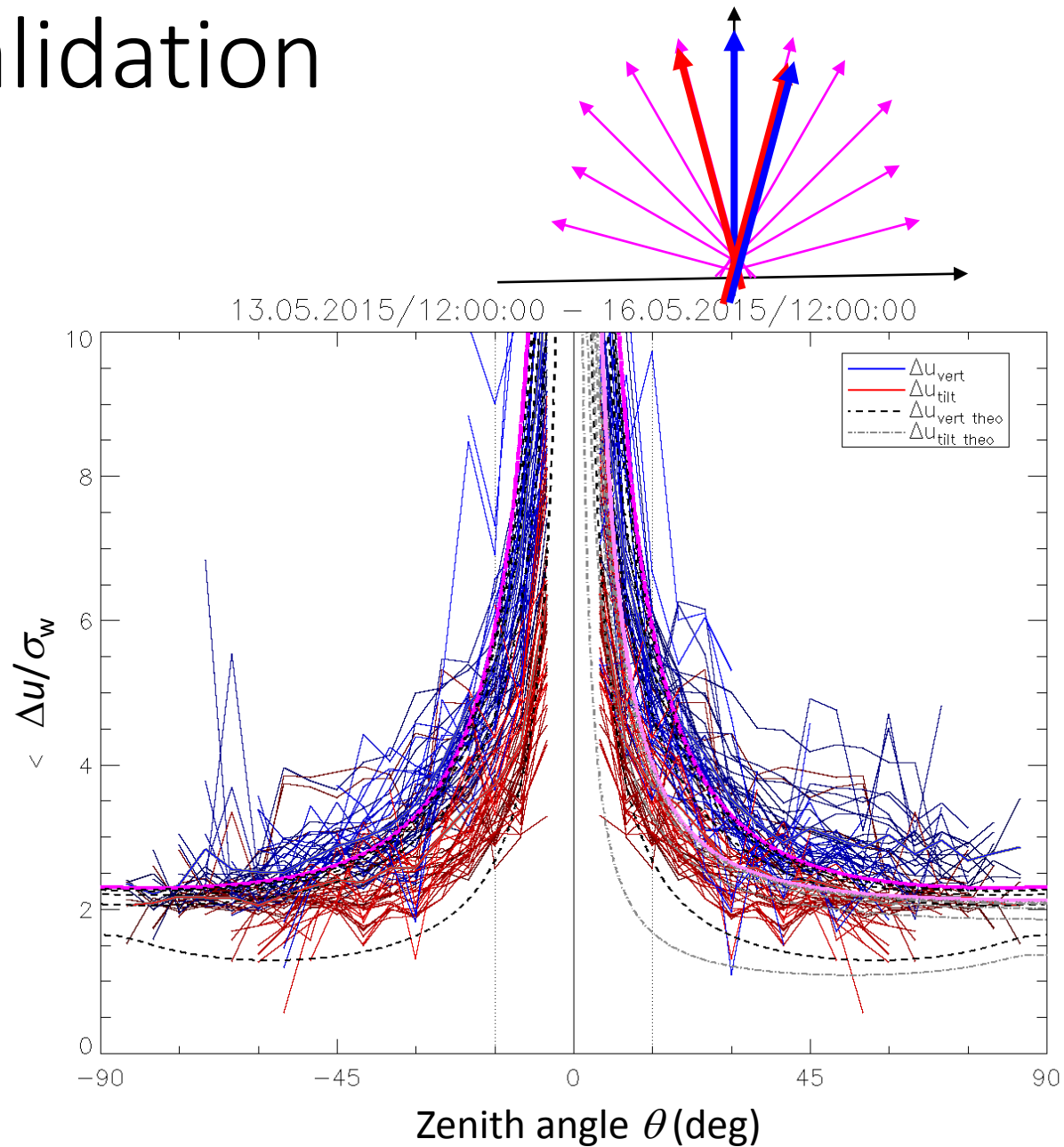
- $C(r)=\exp(-r/L)$   
 $r = z \cdot \tan \theta$ ,  $z = L = 300\text{m}$ ,  
 $uu/\sigma_w^2=1.2$ ,  $uw/\sigma_w^2=-0.2$
- **geometry factor** dominates
- Effect of **(co-)variances** is small => we do not need to know  $uw$  etc. exactly
- Weak Minimum at  $\sim 50\text{deg}$
- uncertainty of 2-tilted beams is smaller than 1tilt+1vertical

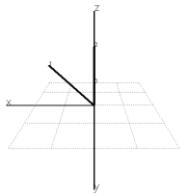




# Two Beams: Validation

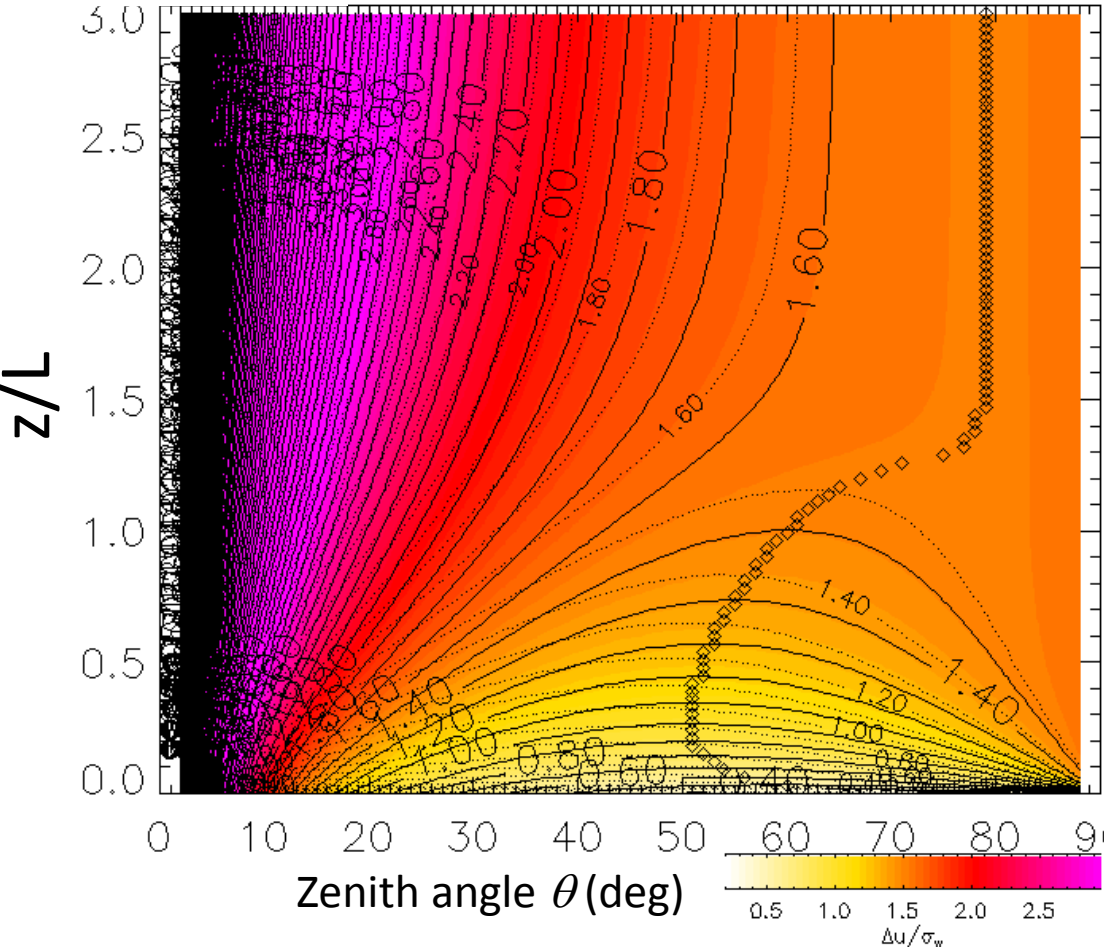
- RHI-> two beams
    - 1 tilted 1 vertical
    - 2 tilted
  - As a  $f(\theta, z)$
  - Difference to VAD-36
  - RMSE over 4days
- Principal form confirmed with very large errors at zenith and decay towards low elevations
- 2 tilted is better than 1tilted
- asymmetry for 1tilted beam => inhomogeneity





# Many beams: 3 DBS

DBS 3

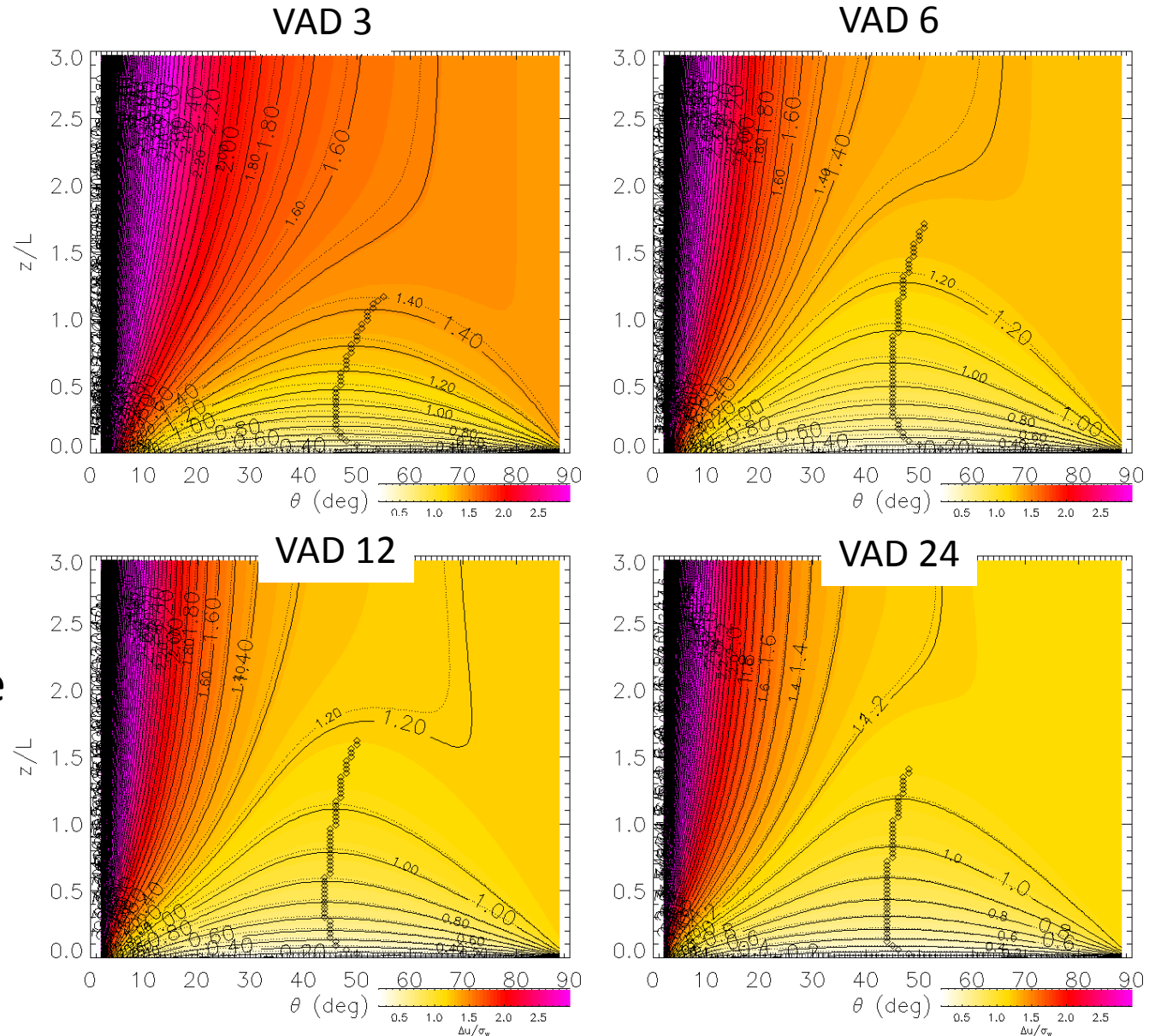


$\Delta u / \sigma_w$

- With  $\Delta D / \sigma_w = 0.25$   
(Color shading and solid lines)
- No Doppler uncty.  
( $\Delta D = 0$ , dotted)
- Elevation of minimum  
(symbol)
- Doppler uncertainty plays only minor role
- Minimum at zenith angles around 55deg
- But minimum is weak

# Many beams: ...

- Increasing the number of beams reduces uncertainty but follows not  $1/\sqrt{N}$  law
- Minimum remains at +/- the same place and stays weak
- Larger zenith angle decreases uncty. but effect diminishes above  $\sim 30$ deg.



# Conclusions

- Uncertainty estimate requires knowledge of
  - covariance matrix of the wind,
  - spatial auto- and cross-correlations of the wind components
  - we solved this with simplifications/assumptions
- DBS-3 scan has larger uncertainty than VAD-3
- More beams decrease uncertainty
  - but effect is less than  $1/\sqrt{N}$  law and
  - diminishes with increasing  $N$
  - gain for  $N > 12$  is minimal
- Uncertainty decreases with increasing zenith angles
  - effect is for  $\theta > 30^\circ$  small
  - there is a weak minimum around 55deg at low heights.

# Thank you

