



GRACE/GRACE-FO
Science Team Meeting
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GFZ Potsdam, Germany



MOMENTUM TRANSFER EVENTS IN LRI DATA: DETECTION AND ANALYSIS

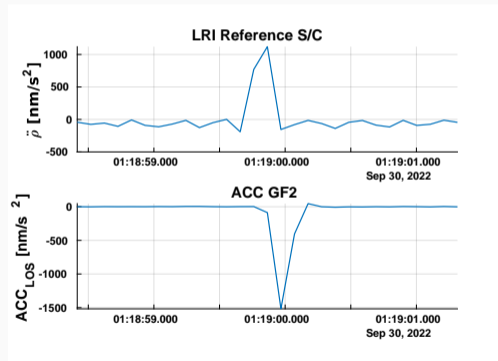
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Momentum Transfer Events in GRACE-FO

- MTEs: Events that show changes in range rate in LRI and similar disturbance in ACC.
- They are sporadic and sudden changes in momentum (around 3 seconds long).
- Possible causes: impacts by meteoroids or debris.

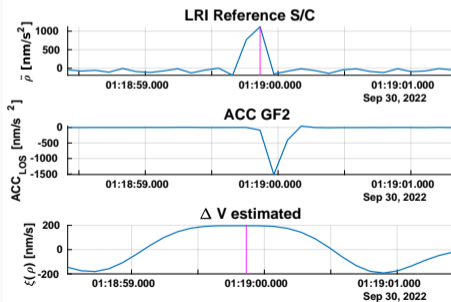




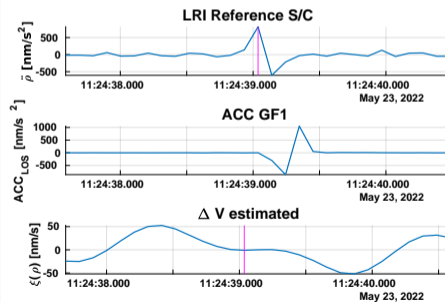
Types of MTEs detected

- Changes in range rate = Δv

High Δv



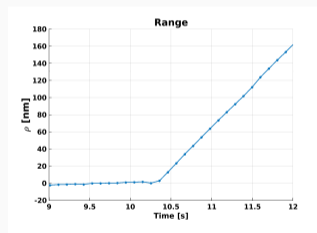
Low Δv





Detection: Δv estimation filter, $\xi(\rho)$

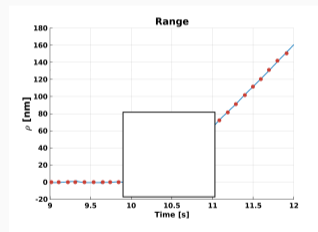
- The LRI range data, ρ , is passed through a Δv estimation filter, $\xi(\rho)$.





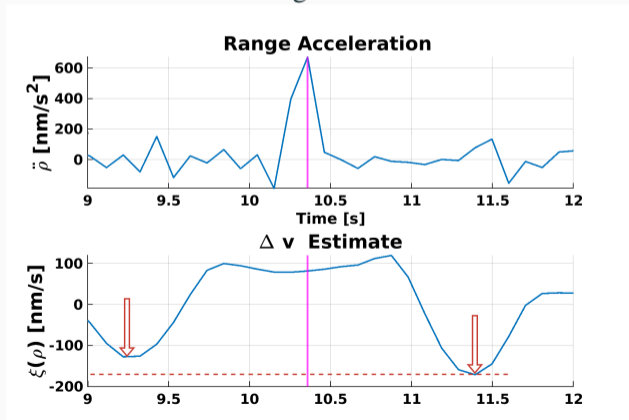
Detection: Δv estimation filter, $\xi(\rho)$

- The LRI range data, ρ , is passed through a Δv estimation filter, $\xi(\rho)$.
- Samples before and after the event used for a least squares fit.
- The change in the range rate, Δv is thus estimated.



Detection: Moving Mean

Moving mean = 1

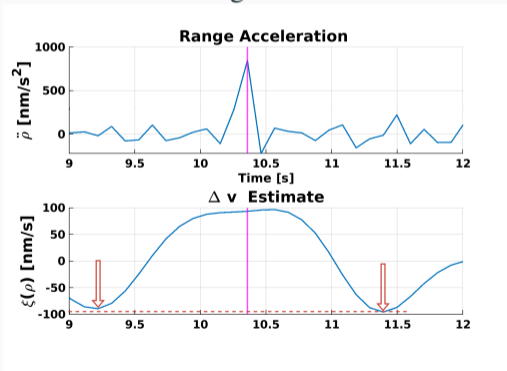




Detection: Moving Mean

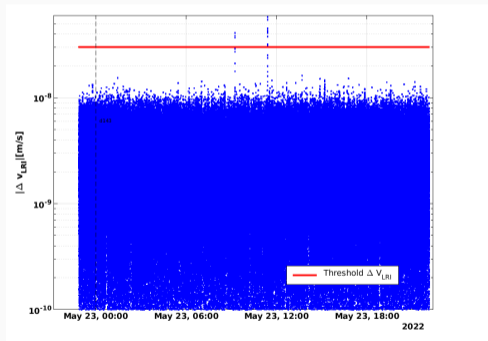
- A moving average is applied to range, ρ before passing it through the filter.
- This is to reduce the filter artefacts in the final Δv time series.
- Moving averaged data should not spill into the actual event.

Moving mean = 5



Detection: Threshold

- Events above a selected Δv threshold are collected and called MTE candidates.
- The range accelerations for these candidates are cross correlated with ACC_{LOS} .
- The events where correlation is high are deemed the final MTEs detected.





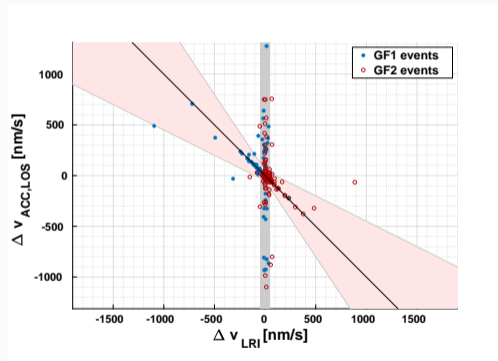
Preliminary Results

- The following parameter set was chosen:
 - Filter length = 3s
 - Number of points for the least squares fit = 9
 - Moving mean parameter = 5
 - Δv threshold: 45 nm/s
- MTE candidates over 5 years of LRI range data: 1664
- MTEs detected: GF1 - 104 , GF2 - 139



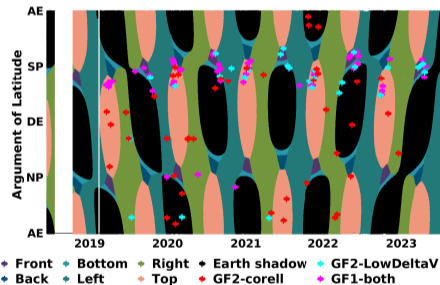
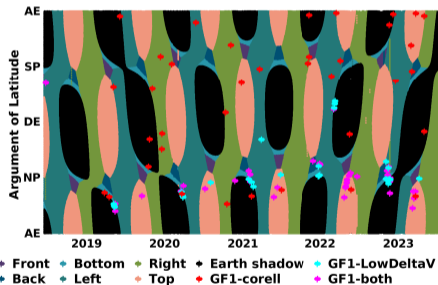
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Preliminary Results: Surfaces of S/C illuminated by the sun





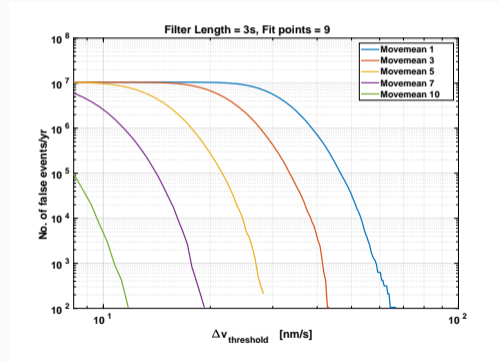
Detection: Optimisation parameters

- Simulating different amplitudes of Δv in the LRI data, to check the detection output for the following parameters:
 - **Filter length:** 2 s, 3 s or 4 s
 - **Number of fit points selected for the least squares fit:** 5, 9, 15.
 - **Number of sample points for the moving mean:** 1, 3, 5, 7, 10
 - **Δv threshold:** 10 nm/s to 60 nm/s



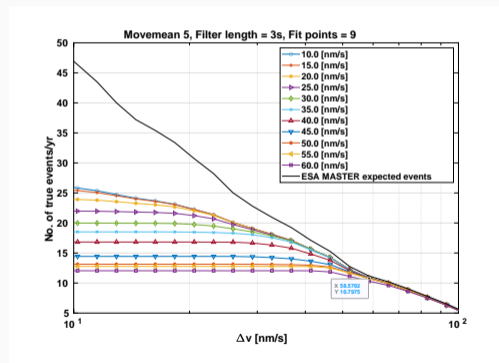
Number of False Events

- Simulate the filter response for LRI instrument noise.
- Determine the number of detected events per year for each threshold value and moving mean parameter - Falsely detected events.
- Repeated for the 9 combinations of filter length and number of points for fit.



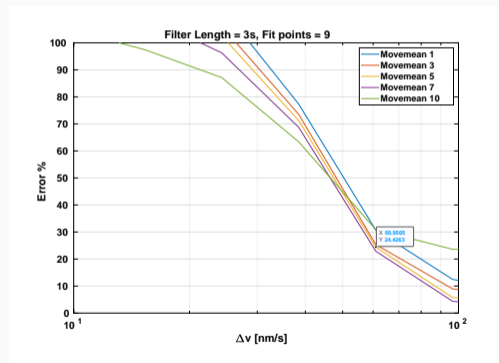
Number of True events

- With ESA MASTER v8.0.3, the number of events expected to appear for a GRACE-FO like orbit is calculated.
- For each parameter (moving mean parameter, filter length, fit points, threshold), number of events expected to be detected is calculated.



Error in Δv estimation

- Accuracy of the estimation of the Δv for filter length and number of points for fit combination and for each moving mean parameter.
- For chosen parameters at $\Delta v = 60$ nm/s, the error is 24.4%





Better Detection Parameters

- Compared to the preliminary results, the following parameters have **higher number of true events per year** and the **lower number of false events** for $\Delta v = 60$ nm/s :
 - Filter length = 3s
 - Number of points for the least squares fit = 5
 - Moving mean parameter = 7
 - Δv threshold: 30 nm/s
 - **Error = 23.5%**



Summary

- MTEs are events that appear as sporadic and short changes in range rate while also showing a similar signature in the accelerometers either S/C.
- The algorithm for detection used least squares fit formulated into a filter to estimate the Δv time series using the LRI range data, ρ .
- Simulations were performed over four optimization parameters to get the highest true detected events per year and the lowest falsely detected events per year.
- In addition, the error of Δv estimated for different combinations of the parameters was calculated.
- Analysing these values, a better combination of detection parameters compared to the ones used in the preliminary results, are deduced. Subsequently, they will be used to estimate Δv over the 5 year LRI range data.